

**Technical Report No. 34**  
**CURRENT GENERALIZED COMPUTER PROGRAMS**  
**USED IN GRASSLAND BIOME ANALYSES**

**Coordinated by D. M. Swift**

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**GRASSLANDS BIOME**

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## INTRODUCTION

This report deals with the functioning programs which are available at the Natural Resource Ecology Laboratory at CSU and have been useful in the IBP Grasslands Biome activities. These include generalized statistical programs as well as generalized mathematical programs such as routines for solving differential equations.

All programs are described in general terms so that investigators not familiar with programming may evaluate their utility to various types of data. Those programs which are not frequently used or which are deemed most useful to the field investigator or the modeler are discussed in some detail. The reader will note that most of the programs can be set up and run very simply by merely adding a few control cards and a data deck to the source deck. Others, however, require a user-supplied subroutine, which presupposes that the potential user have a knowledge of FORTRAN programming. FORTRAN listings are included for these programs unless such listings are readily obtainable from some other source. Programs less frequently used or of less general interest are discussed briefly in Appendix I.

## REGRES1

### INTRODUCTION

REGRES1 is a general multiple regression and correlation program which can handle up to 60 variables with 9999 observations per variable. It is written in FORTRAN extended and operates on both the SCOPE and NCAR compilers. It provides summary statistics on the input variables as well as correlation and regression analyses. Deviations from the model are calculated. Options within the program allow reading data from cards or tape, variable format or standard format, names for variables generated or names read in, a variety of transgenerations, regression through the origin or not through the origin, and weighted or nonweighted regression.

This is a fairly quick program which can be used for multiple correlation and regressions in cases where screening of variables is not required.

Information in this report was drawn liberally from ORNL-TM-1288, REGRESS - A multiple regression and correlation program with graphic output for model evaluation, George M. Van Dyne, published by Oak Ridge National Laboratory.

### HOW TO USE THE PROGRAM

The sequence of input is given below. Systems cards vary from computer center to computer center and are not described herein, except that the program as compiled here requires a standard input tape, a standard output tape for printing, two scratch tapes for intermediate calculations and storage, and an output tape for the Calcomp plotter. Three tapes, logical units 2, 3, and 4, need to be specified on the job card. The "Glorius" dump system is utilized, thus requiring one of the standard scratch tapes.

## Sequence of Input to REGRESSI

REGRESSI	
Program	System cards are required before and after the program deck
Control card	Always required
Name card(s)	
Variable format card(s)	
Transgeneration card(s)	Each of these may or may not be required as specified by the control card
Constant card(s)	
Data deck	Data may be read from cards or from tape 4 as specified by the control card
Plot dimension card(s)	Required only if type 9 plots are specified on the control card
Control card	
.	Repeat as above following control card for as many sets of data as desired
.	
.	
Blank card	After last data deck

The control card is described below. The control card always must be read by REGRESSI but the actual information required may be minimal. For example, if a standard input format is used, if no transgenerations are required, if no plots are to be made, and if the data is to be unweighted and not through the origin, then all that is required is the number of observations (NOBS) and the number of variables before transgeneration (N). If the number of variables after transgeneration is left blank, it is assumed that the number of variables after transgeneration is the same as the number before transgeneration (NA = N).

A variable can be an independent variable, a dependent variable, or a weighting factor. If no transgenerations are to be made the dependent variable must be the right-most one which is read.

The control card, the input format, the transgenerations, and the constants are read and are printed on the output for purposes of checking the results.

If variable names are read in, they should be read in order of the variables after transgeneration rather than before transgeneration. These variable names are listed in the printed and graphic output and may be checked readily. If no variable names are called for, then numbers 1 through 60 are generated for variable names.

Variable formats are allowed for the input by making NCARDS  $\geq 1$  thereby specifying the number of cards to be read containing the variable format. For example, if NCARDS = 1 and the following format is used

(3F5.1,21X,F7.2)

then four variables would be read per input card. The left parenthesis should be in column 1 of the format card.

#### Description of the control card for REGRESSI

Columns in cards	Designation on printed output	Designation in program	Meaning and coded values
1-2	Printed statement	NTAPE	Controls the source of the data: < 0 means read data from tape 4; 0 means read the data from cards; and > 0 means read the data from cards and write it on tape 4. If NTAPE > 0 then NTAPE should be the number of cards per data point (see Appendix example).
3-6	OBS	NOBS	Number of data points ( $2 \leq NOBS \leq 9999$ ).
7, 8	NBE	N	Number of variables before transgeneration ( $2 \leq N \leq 61$ ).
9, 10	NAF	NA	Number of variables after transgeneration ( $2 \leq NA \leq 60$ ).
12	WT	IWT	< 1 do not weight data; $\geq 1$ weight data.

14	PLT	I PLOT	$\leq 1$ do not plot = 2 plot deviations against variables = 3 plot independent variables against each other = 4 plot dependent variables against independent variables = 5 do as 2 + 3 = 6 do as 2 + 4 = 7 do as 3 + 4 = 8 do as 2 + 3 + 4 $\geq 9$ plot each independent variable with the dependent variable which is adjusted for the variation of all other independent variables from their means (see text for description of plot dimension card).
16	ORG	I ORIGIN	$\leq 1$ not through the origin $\geq 2$ through the origin
18	NAM	I NAME	= 1 generate numbers for names = 2 read names of variables
20	FMT	NCARDS	= 0 read data according to standard format 1 2 number of variable format card to read = : . 9
21, 22	TRN	NTRAN	= 0 no transgenerations 1 2 number of transgeneration codes = : to read (up to 10 codes per card) 99
23,24	CON	NCON	= 0 no constants 1 2 number of constants to be read = : (up to 8 constants per card) 99
25-80	IDENTIFICATION	ID	Alphanumeric identification of the problem

If NCARDS  $\leq 0$  then the data are read according to a standard format of

10X,10F7.0

"Transgenerations," meaning transformations of variables and generation of new variables, are described below. Each transgeneration is defined by an 8 digit code and up to 10 transgeneration codes are read in on a card. The first 2 digits of the transgeneration code define the type of transgeneration which is to be made, the second two digits define the index of the variable after transgeneration, the next two digits define the index of the variable before transgeneration, and the last two digits, if required, define the index of a second variable involved in the transgeneration or the index of the constant involved.

An example transgeneration is as follows:

05030102

This means to use transgeneration 5 and make variable 3 from variable 1 times variable 2. Caution must be taken not to eliminate a variable while in the process of transgenerations.

Constants are read with an F10.0 format, thus allowing up to 8 constants per card.

If weighted regression is to be run it is the user's responsibility to transfer the weight to variable 61. For example, if the weight was the 6th of 6 variables read in, the transgeneration would be as follows:

01610600

If weighted regression is not run a 1 is automatically placed in variable 61 which is used as the weighting factor. If the regression is not weighted the output will show that the number of data equals the sum of weights. The number of variables printed on the output should be equal to the number of variables after transgenerations.

Transgeneration codes (n, i, j, k)\*

Code	Meaning
01	$x_i = x_j$
02	$= x_j \times x_k$
03	$= x_j \div x_k$
04	$= x_j + x_k$
05	$= x_j - x_k$
06	$= \frac{1}{x_j}$
07	$= x_j + c_k$
08	$= x_j \div c_k$
09	$= c_k \div x_j$
10	$= x_j \times c_k$
11	$= \frac{c_k}{x_j}$
12	$= \log_e x_j$
13	$= \log_{10} x_j$
14	$= e^{x_j}$
15	$= \sin x_j$
16	$= \arctan x_j$
17	$= \sin(x_j - c_k) + 1$
18	$x_i = \max(x_j, x_k)$

\* where n = transformation code

i = index of the variable after transgeneration

j = index of the variable before transgeneration

k = index of a second variable or constant used in  
the transgeneration

## OUTPUT

The sequence of output is constant and generally is self explanatory (see Appendices II-IV). The upper triangular portions of the sums of squares and cross-product matrix and the correlation matrices are given in the output. To be comparable to the standard notation of writing an upper triangular matrix, each row of the output should be adjusted to the right as shown in the following hypothetical example:

Program Output Form				Conventional Form			
1.00	.26	.35	.78	1.00	.26	.35	.78
1.00		.75	.61		1.00	.75	.61
1.00			.41			1.00	.41
1.00							1.00

## PROGRAM OPERATION

Most of the routines used herein are found in regression programs and in statistical textbooks. A complete "well commented" listing of REGRESSI is given in Appendix I, therefore, only special features of the program will be discussed.

The structure of the program and the subroutines and sequence of use of subroutines is as follows:

REGRESS

INVERT

TRANSFRM

TRANSFRM is a subroutine which will make the required transgenerations.

INVERT is a subroutine which is called to invert correlation matrices.

Some important steps in the input sequence are as follows:

1. After clearing certain storage areas and setting certain counters, the control card is read and the number of variables before transgeneration

(N) is evaluated. If  $N \leq 1$ , control is transferred to the exit to return to the monitor. A message is printed indicating the END OF RUN. If  $N \geq 2$  the control card values are printed.

2. If name cards are not to be read then NAME (I) is set equal to I for all I. Otherwise names are read in a 10A8 format.

3. If a variable format card(s) is (are) not needed the data are read according to a standard format of 10X,10F7.0. Otherwise the variable data input format, IFMT, is read.

4. If transgenerations are to be made the necessary transgeneration codes are read and printed. Then if constants are to be read, they are read and printed.

5. The data are read, according to the format (IFMT) defined above, in a list of X(I) with  $I = 1, \dots, N$ .

6. Data normally are read from cards (NTAPE = 0), but they may be read from tape 4 (NTAPE  $\geq 1$ ) or they may be read from cards and written onto tape 4 (NTAPE  $\leq -1$ ). If data are read from cards and written onto tape 4 or if they are read from tape 4, then NTAPE should be the number of card images (80 column units) to be read per observation. If transgenerations are to be made, the transgeneration subroutine (TRANSFRM) is called to make them. Calling the transgeneration subroutine involves giving a list of X's, the transgeneration codes, and constants (if required). If the data are not to be weighted then X(61) is automatically set equal 1. Otherwise, a transgeneration must be made to set some given X into X(61).

7. After the transgenerations have been made the list of X's is searched and compared to he values stored as the maximum and minimum values for each X(I). If a given X(I) is larger or smaller than the one previously stored that value is replaced.

8. The count of data points is then incremented by 1 and the string of X's is written on scratch tape (tape 2), and the weighting factor is added to the sum of weights. The weighted sums, sums of squares, and sums of cross-products are accumulated while reading the data in.

The above procedures are repeated until all the observations, NOBS, have been read.

The ranges and corrected sums of squares are then calculated. The corrected sums of squares defined as XX(I) and XY(I), and the total sum of squares, TOTSS, are set aside for later use. The coefficients of variation, CV(J), standard errors, SE(J), and standard deviations, X(J), of the variables are then calculated. These statistics are printed in table form and are identified by either the generated name-numbers of the alphabetic names which were read in (see Appendices II-IV).

Calculations proceed with formation of a matrix of simple correlation coefficients which is then printed. This simple correlation matrix (composed of all independent variables plus the dependent variable) is inverted by a Gauss-Jordan elimination method (subroutine INVERT) and the inverse of the matrix is printed.

A comparison of the computational scheme used in this program with other commonly used schemes is given in Table 1. An essential point is that this program inverts the complete or augmented matrix of correlation coefficients rather than the predictor matrix of correlation coefficients. The highest order partial correlation coefficients among the variables are calculated according to the method in Table and then are printed. A check is made to see if the regression is to be through the origin. If not, (IORIGIN < 0), the regression coefficients are calculated by the method described in

Table 1. If the regression is through the origin ( $IORIGIN \geq 1$ ) then a matrix of "pseudo" correlation coefficients is formed and inverted before the regression coefficients are calculated.

The standard error of estimate, SY, the square of the multiple correlation coefficient, RSQ, the standard partial regression coefficients, BPRIME(J), the partial regression coefficients, B(J), the standard errors of the partial regression coefficients, S(J), and "t" tests of the regression coefficient, T(J), are calculated next.

If the regression is not through the origin the constant term (B0) is set equal to XBAR(N) and the regression coefficients are multiplied by the mean values for each independent variable and summed for all independent variables. This value is subtracted from B0 to give the intercept value. The "t" test of the intercept is calculated as the value of the intercept divided by the standard error of estimate. If the regression is to be through the origin, the intercept value is set equal to 0 and the "t" test for the intercept is also set equal to 0.

Values are predicted for each data point (using the regression equation) from the independent variables which are read in from a scratch tape. This predicted value is compared to the observed value for the independent variable to obtain the deviation. The deviation is checked against the maximum and minimum deviations that have been obtained up to that point and these are replaced if necessary. The data are again written onto a scratch tape (to save the input variables as remaining after transgeneration), along with the predicted value for the independent variable, and the deviation.

Regression coefficients are printed with their standard errors, "t" values, and simple and partial correlations. A test statistic for "outliers" is calculated. This is the absolute difference of the maximum and minimum

deviations from the model divided by the standard error of the estimate.

The analysis of variance is printed and in the process the analysis of variance for each variable (as if it were a simple linear regression) is calculated.

#### Sample Run of Program

The sample is a regression of streamflow in the Cache La Poudre River on various snow course measurements for 15 years of record. As they appear on the data cards; item 1 is water equivalent, Cameron Pass snow course, April, in inches (name-CPA); item 2 is water equivalent, Cameron Pass snow course, May, in inches (name-CPM); item 3 is water equivalent, Big South snow course, April, in inches (name-BSA); and item 4 is stream flow, April through September, in thousands of acre feet (name-POUDRE). Before the regression was performed, item 1 (CPA) and item 2 (CPM) were transgenerated into a single variable (CPAM) such that  $CPAM = CPA + 2(CPM)$ . The regression then had two independent variables (CPAM and BSA) and the dependent (POUDRE). A listing of the program control cards and the data deck from this run is attached, along with the resultant output.

Table 1. A comparison of procedures used in multiple regression analysis<sup>1,2</sup>

Symbol	This Program	Alternatives
Matrix to be inverted	$\sim$	$\sim$
Standard partial regression coefficients	$b_j^*$	$\frac{-r_{-1}^{-1}}{r_{yy}}$
Partial regression coefficients	$b_j^*$	$\sqrt{\frac{\Sigma x_j^2}{\Sigma y^2}} \cdot \frac{b_j}{\sqrt{\frac{\Sigma x_j^2}{\Sigma y^2}}} \cdot \frac{\sum (a_{-1,j} \cdot \Sigma x_i y)}{\sum (a_{-1,j} \cdot \Sigma y)}$
Standard errors of regression coefficients	$s_{b_i}$	$s_y \cdot \sqrt{\frac{r_{-1}^{-1} \cdot r_{yy}^{-1} \cdot (r_{yy}^{-1})^2}{\Sigma x_j^2 \cdot r_{yy}^{-1}}} \cdot s_y \cdot \sqrt{\frac{a_{-1,jj}}{a_{jj}}}$
Standard error of estimate	$s_y$	$\sqrt{\frac{\Sigma y_i^2 \cdot \sum b_j \cdot (\Sigma x_j y)}{N-k-1}} \cdot \sqrt{\frac{\Sigma y_1^2 \cdot R_m^2 \cdot \Sigma y_1^2}{N-k-1}}$
Multiple correlation coefficient	$R_m$	$\sqrt{1 - \frac{1}{r_{yy}^{-1}}} \cdot \sqrt{\frac{\sum (b_j \cdot \Sigma x_j y)}{\sum y^2}}$
Partial correlation coefficients	$r_{ij}^*$	$\frac{-r_{1,j}^{-1}}{\sqrt{\frac{r_{ii} \cdot r_{jj}^{-1}}{r_{ii} \cdot r_{jj}^{-1}}}}$

<sup>1</sup> Derived from Goulsen (1952), Kelley (1947), Efranyson (1960, Steel and Torrie (1963), and Friedman and Fooths (1955).

<sup>2</sup>Let:  $\Sigma x_i^2$  be the corrected sum of squares for variable  $X_i$ ;  $\Sigma x_i y$  be the corrected sum of cross-products for  $X_i Y$ ;  $R$  be a matrix of simple linear correlation coefficients  $r_{ij}$  composed of independent variables and the dependent variable (augmented) where  $r_{iy}$  is a correlation of an  $X_i$  with  $Y$ ; inverse elements be denoted by  $r_{ij}^{-1}$ ;  $P$  be a matrix of simple linear correlation coefficients among only the independent variables (predictors);  $S$  be a complete moment matrix of sums of squares and cross products composed of elements  $\Sigma x_i^2$ ,  $\Sigma x_i x_j$ ,  $\Sigma x_i y$ ,  $\Sigma y^2$ , and  $A$  be a matrix of sums of squares and cross products only of  $\Sigma x_i^2$  and  $\Sigma x_i x_j$  with elements  $i=1, \dots, k$  independent variables; and  $N$  be the number of observations or data points.

```

PROGRAM REGRESI
1(INPUT,OUTPUT,TAPE5=INPUT,TAPE6=OUTPUT,TAPE2=202B,TAPE3=202B,TAPE4
2=202B)
C      TAPE 57 IS USED FOR THE GLORIUS DUMP PROCEDURE
C      NO GDUMP UNTIL ROUTINE IS SUPPLIED

C=====
DIMENSION X(61), SUMX(60), XBAR(60), DMAX(60), DMIN(60), RNG(60)

C SEPTEMBER 1965 VERSION -- GEORGE M. VAN DYNE
C REVISED 4/6/67 FOR CDC 6400: L J BLEDSOE
C REVISED 9/29/69 FOR SCOPE: DAVID M. SWIFT
C      PLOT ON TAPE 9
C      NO PLOTS UNTIL SUBROUTINES ARE REVISED
C      SCRATCH TAPES 3 AND 2 (2=56)
C      WRITE DATA ON OR READ DATA FROM TAPE 4
DIMENSION SIGMAX(60), SE(60), CV(60), SAVER(60), BPRIME(60), B(60)
DIMENSION S(60), T(60), XX(60), XY(60), FSS(60)
DIMENSION IFMT(90), NAME(60), ID(7), CARD(100), XLABEL(4)
DIMENSION NT(99), NI(99), NJ(99), NK(99), C(99), ZZ(14)
DIMENSION A(60,60), R(60,60), RPRIME(60,60), UNCOR(60,60)
DIMENSION V1(3600), V2(3600), V3(3600)
COMMON V1,V2,V3

EQUIVALENCE (UNCOR,V1),(A,V2),(R,RPRIME,V3)

C=====
C BEGIN PROGRAM BY SETTING UP NECESSARY COUNTERS AND CLEARING STORAGE AREAS
1 REWIND 3 $ REWIND 4
00 4444 I=1,4
4444 XLABEL(I)=0,
00 4445 I=1+14
4445 ZZ(I)=0.
WT=TOTAL*DEVMIN=DEVMAX=SMALL=I=J=NTAPE=N0BS=N=NA*IWT=IPLOT=0
I0RIGN=INAME=NCARDS=NTRAN=NCON=JVAR=MTAPE=KKK=W=NN=TOTSS=PHI=DIV=0
XN=SY=HSU=RMULT=RDETR=L=H0=DEVSQ=II=YPRED=JJ=DEV=SSREG=SMREG=0
SMDEV=UFTUT=F=ICOUNT=NPLOTS=LAST=0
DO 222 I=1,60  S  DMAX(I)=-99.E99  S  DMIN(I)=+99.E99
SIGMAX(I)=SE(I)=XBAR(I)=X(I)=S(I)=CV(I)=T(I)=SUMX(I)=B(I)=0.0
BPRIME(I)=XX(I)=FSS(I)=XY(I)=SAVER(I)=0.0
RNG(I)=FSS(I)=0.0
DO 222 J=1,60
222 A(I,J)=R(I,J)=UNCOR(I,J)=0.
DEVMAX=-99.E99  S  DEVMIN=+99.E99  S  SMALL=+99.E99

C=====
C READ CONTROL DATA
KKZ=1
READ 99,NTAPE,N0BS,N,NA,IWT,IPLOT,I0RIGN,INAME,NCARDS,NTRAN,
NCON,ID
IF (NUHS) 5001,5002,5002
5001 KKZ=2 % NUHS=-N0BS
5002 IF (N) 60,60,61
61  WRITE(6,66665),
      WRITE(6,999)N0BS,N,NA,IWT,IPLOT,I0RIGN,INAME,NCARDS,NTRAN,NCON,10

C SEE IF NAMES ARE GIVEN, IF NOT THEN GENERATE NUMBERS FOR NAMES
GO TO (515,514) INAME

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```

515 DO 500 I=1,60
500 NAME(I)=I $ GO TO 516
514 READ 1001, (NAME(I), I=1, NA)

```

C=====  
C CHECK TO SEE IF VARIABLE FORMAT CARDS ARE NEEDED

```

516 JF (INCARDS) 3001, 3001, 3000
3001 IFMT(1)=8H(10X,10F) $ IFMT(2)=8H7,0
IFMT(3)=IFMT(4)=IFMT(5)=IFMT(6)=IFMT(7)=IFMT(8)=IFMT(9)=8H
GO TO 3002
3000 JVAR=8*NCARDS
READ 1000, (IFMT(I), I=1, JVAR)
3002 WRITE(6,66667) (IFMT(I), I=1, JVAR)

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```

1F (NTAPE) 3005,3004,3003
3003 WRITE(6,66662) $ GO TO 3006
3004 WRITE(6,66663) $ GO TO 3006
3005 WRITE(6,66664) $ GO TO 3006
3006 CONTINUE

```

C=====  
C CHECK TO SEE IF TRANSGENERATIONS AND CONSTANTS ARE TO BE READ. IF SO, THEN  
C READ AND PRINT THEM.

```

IF (NTRAN.LE.0) 8022,8020
8020 READ 8100, (NT(I), NI(I), NJ(I), NK(I), I=1, NTRAN)
WRITE(6,8101) (NT(I), NI(I), NJ(I), NK(I), I=1, NTRAN)
IF (NCON.LE.0) 8022*8021
8021 READ 8103, (C(I), I=1, NCON) $ WRITE(6,8104) (C(I), I=1, NCON)
8022 WRITE(6,996)

```

C=====  
C READ DATA, WRITE ON TAPE 4 IF REQUIRED, TRANSGENERATE IF REQUIRED  
C WEIGHT IF REQUIRED, SEARCH FOR EXTREMES  
C LFT NTAPE = THE NUMBER OF CARDS TO BE READ PER DATA POINT, CHANGE TO BE ABLE  
C TO READ WITH AN 8A10 FORMAT AND TO WRITE ON TAPE 4 IN CARD IMAGE  
NTAPE = NTAPE\*8

C SUM COUNTS, WRITE ON TAPE, AND GET SUMS AND SUMS OF SQUARES  
1F (NA) 8066,8066,8067

8066 NA=N

```

8067 KKY=NU_N
DO 8060 KKK=1,KKY
1F (NTAPE) 9002,9001,9003
9003 READ 9100, (CARD(I), I=1, NTAPE)
WRITE(4,9100) (CARD(I), I=1, NTAPE)
DECODE(80,IFMT,CARD) (X(I), I=1, N) $ GO TO 9004
9004 READ 1FMT, (X(I), I=1, N) $ GO TO 9004
9005 READ (4,IFMT) (X(I), I=1, N)
9006 GO TO (5006,5003) KRZ
5003 DO 5004 I=1, N
1F (X(I)) 5004,5005,5004
5004 CONTINUE
GO TO 5006
5005 NOSENDBS=1 $ GO TO 8060
5006 1F (INTRAN) 8061,8061,8062
8062 DO 8063 I=1, NTRAN
8063 CALL TRNSFRM(NT, NI, NJ, NK, C, X, I)
8064 IF (INT) 8064,8064,8065
8064 X(I)=1.0
8065 DO 834 I=1, NA $ 1F (X(I)=DMAX(I)) 831,831,832

```

```

832   DMAX(I)=X(I)
831   IF(X(I)-DMIN(I))833,834,834
833   DMIN(I)=X(I)
834   CONTINUE
     W=X(61)  S  NTOTAL=NTOTAL+1  S  WT=WT+W
     WRITE(3) (X(I),I=1,NA)
     DO 11 I=1,NA  S  SUMX(I)=SUMX(I)+W*X(I)
     DO 11 J=1,NA
11    A(I,J)=A(I,J)+W*X(I)*X(J)
     8060 CONTINUE

     NA=NA
     IF(INTAPE)9006,9006,9007
9007 END FILE 4
9006 CONTINUE

C IF REGRESSION IS TO BE THROUGH THE ORIGIN THEN SAVE THE UNCORRECTED SUM OF
C SQUARES AND CROSS-PRODUCTS
     IF (IORIGN .LE. 1) GO TO 12
874   DO 875 I=1,N  S  XX(I)=A(I,I)  S  XY(I)=A(I,N)  S  DO 875 J=1,N
875   UNCOR(I,J)=A(I,J)

C=====C
C PRINT COUNTS THEN GET MEANS, RANGES, AND CORRECTED SUMS OF SQUARES AND PRINT
12    WRITE(6,202)NTOTAL,N,WT  S  WRITE(6,203)(SUMX(I),I=1,N)  S  WRITE
115,204)
     DO 140 I=1,N
140   WRITE(6,225)(A(I,J),J=1,N)
     REWIND 3  S  WRITE(6,206)
     DO 15 I=1,N  S  XBAR(I)=SUMX(I)/WT
     DO 15 J=1,N
15    A(I,J)=A(I,J)-SUMX(I)*SUMX(J)/WT
     DO 735 I=1,N
735   RNG(I)=DMAX(I)-DMIN(I)
     DO 141 I=1,N
141   WRITE(6,225)(A(I,J),J=1,N)

C=====C
C SET ASIDE CORRECTED SUMS OF SQUARES
     NN=N-1  S  TOTSS=A(N,N)
     IF (IORIGN .GE. 2) GO TO 7131
7130  DO 7131 I=1,N  S  XX(I)=A(I,I)
713   XY(I)=A(I,N)
7131 CONTINUE

C=====C
C CALCULATE STD. DEVIATIONS, STD. ERRORS, AND COEFFICIENTS OF VARIATION
     PHI = NOBS - 1
     DO 20 I=1,N
     SIGMAX(I)=SQRT (A(I,I))  S X(I)=SIGMAX(I)/SQRT (WT-1.)
     SE(I)=X(I)/SQRT (PHI+1.0)
20    CV(I)=100.*X(I)/XBAR(I)

C=====C
C PRINT MEANS, STD. DEV., STD. ERRORS, COEFF. VAR., MAXIMUMS, MINIMUMS, RANGES
     WRITE(6,996)  S  WRITE(6,736)  S  WRITE(6,737)  S  WRITE(6,997)
     DO 739 I=1,N
739   WRITE(6,738)NAME(I),XBAR(I),X(I),SE(I),CV(I),DMAX(I),DMIN(I),RNG(I)
1)

```

## REGRESI FORTRAN EXTENDED VERSION 2.0

03/14/70

\*00-39-34-

```

2202 YPRED=YPRED+B(JJ)*X(JJ)
      UEV=X(N)=YPRED
      IF (UEV-UEVMAX) 748,748,749
749 UEVMAX=UEV
748 IF (UEV-MIN=UEV) 750,751,751
751 UEVMIN=UEV
750 CONTINUE
      IF (ABS (DEV)-ABS (SMALL)) 508,509,509
508 SMALL=DEV
509 UEVSQ=DEVSQ+DEV*DEV
2201 WRITE(2) II,IX(I),IM1:N),YPRED,DEV

```

## C CALCULATE ANALYSIS OF VARIANCE FOR REGRESSION

1F (10RIGN, GE, 2) 22011-22022

2011 10TSS=XX(4)

22027 SSPEGETOTSS-DEVSQ & SMREG=SSREG/XN \$ SMDEV=UEVSQ/PHI  
DFTUT=XN+PHI & F=SMREG/SMDEV

## C PRINT REGRESSION CHARACTERISTICS

1 WRITE(6,996) S WRITE(6,743) S WRITE(6,753) S WRITE(6,754) S  
1 WRITE(6,997)  
C WRITE(6,755) HDETH,RMULT,SY,DEVMAX,DEVMIN,B0,T(N)  
C THE FOLLOWING WAS ADJUSTED BY B A PETTY, 6/8/67.  
C SMALL=(DEVMAX-DEVMIN)/SY  
S12 WRITE(6,513) SMALL

```

C PRINT REGRESSION COEFFICIENTS, STD. ERRORS, T VALUES , AND CORRELATIONS WITH
      WRITE(6,745) S WRITE(6,997)
      IF(N=2)757,756,757
756  RPRIME(1:N) = SAVER(1)
757  DD7461=1:NN
746  WRITE(6,744)NAME(I),B(I),S(I),T(I),BPRIME(I),SAVER(I),RPRIME(I:N)

```

## C POINT ANALYSIS OF VARIANCE OF RE

```
WRITE(6,709)  S  WRITE(6,997)  
WRITE(6,710)SSREG,XN,SMREG,F  S  WRITE(6,711)DEVSQ,PHI,SMDEV
```

INFORMATION

7160 00716 I=1,NN

XX(I)=XY(I)\*XY(I)/XX(I) S FSS(I)=XX(I)\*

716 WRITE(B,994)NAME(I), XX

C READ DATA POINTS AND DEVIATIONS FROM TAPE- CHECK FOR OUTLIERS- PRINT

THE SUM POINTS AND DEVIATIONS FROM TAPE, CHECK FOR OOCILIERS.

DO 147 (REV. 1-15-61) TOTAL

```
READ(2) ICOUNT*(X(I),I=1:N)*YPRED-DEV
```

1F (BHS (REV) #2-8SY) 7A77-7A77-7A88

7499 1F (ABS (DEV) = 3.0 \* SY17500.7500.7488

7500 WRITE(0,992) S GO TO 7477

7488 RITE(6,993)

7477 WRITE(6,200)X(N), YPRED, DEV

747 WRITE(6,204) ITB(X(I),I=1,NN)

~~SFT IF PLOTS ARE CALLED FOR~~



993 FORMAT(86H CHECK THE NEXT DATA POINT AS AN OUTLIER, IT DEVIATES FR  
10M THE MODEL MORE THAN 3 SIGMA)  
994 FORMAT(1H ,4X,A8,14H INDEPENDENTLY,F19.5,5X,1H1,F19.5,F13.3)  
995 FORMAT(1H0, 4H NO., 24X, 21HINDEPENDENT VARIABLES, 33X, 1HY, 10X,  
14HPREDICTED, 5X, 9HDEVIATION)  
996 FORMAT(1H0,119(1H\*))  
997 FORMAT(1H ,119(1H-))  
998 FORMAT(118H VAN DYNE, G. M. 1965 REGRESS - A MULTIPLE REGRESSION A  
IND CORRELATION PROGRAM WITH GRAPHIC OUTPUT FOR MODEL EVALUATION,/\*  
2 ORNL TM 1288\*)  
999 FORMAT(15H CONTROL DATA =, I6, 9I4, 7H....., 7A8)  
8100 FORMAT(40I2)  
8101 FORMAT(20H TRANSGENERATIONS = ,6(I2+1H-,I2+1H-,I2+1H-,I2+5X)/  
1(20X,6(I2,1H-,I2,1H-,I2,1H-,I2,5X)))  
8102 FORMAT(8F10.0)  
8104 FORMAT(13H0CONSTANTS = , 5(F17.5, 3X)/(13X, 5(F17.5, 3X)))  
9104 FORMAT(8A10)  
66662 FORMAT(1H ,\*DATA WERE READ FROM CARDS AND WERE WRITTEN ON TAPE 4\*)  
66663 FORMAT(1H , \*DATA WERE READ FROM CARDS\*)  
66664 FORMAT(1H , \*DATA WERE READ FROM TAPE 4\*)  
66665 FORMAT(1H1,18X+59HORS NBE NAF WGT PLT ORG NAM FMT TRN CON IDE  
INTIFICATION)  
66666 FORMAT(11H0END OF RUN)  
66667 FORMAT(19H INPUT FORMAT WAS =, 8A10)

END

```

      SUBROUTINE INVERT(A,N)
C      MATRIX INVERSION BY GAUSS-JORDAN ELIMINATION
C      THIS SUBROUTINE TAKES MATRIX A OF N BY N DIMENSION, INVERTS IT, STORES IN A
      DIMENSION A(60,60),B(60),C(60),LZ(60)
      DO 10 J=1,N
10    LZ(J)=J
      DO 20 I=1,N
20    K=I
      Y=A(I,I)
      L=I-1
      LP=I+1
      IF(N-LP)14,11,11
11    DO 13 J=LP,N
        W=A(I,J)
        IF(ABS(W)-ABS(Y))13,13,12
12    K=J
        Y=W
13    CONTINUE
14    DO 15 J=1,N
        C(J)=A(J,K)
        A(J,K)=A(J,I)
        A(J,I)=C(J)/Y
        A(I,J)=A(I,J)/Y
15    B(J)=A(I,J)
        A(I,I)=1.0/Y
        J=LZ(I)
        LZ(I)=LZ(K)
        LZ(K)=J
        DO 19 K=1,N
        IF(I-K)16,19,16
16    DO 18 J=1,N
        IF(I=J)17,18,17
17    A(K,J)=A(K,J)-B(J)*C(K)
18    CONTINUE
19    CONTINUE
20    CONTINUE
      DO 400 I=1,N
        IF(I-LZ(I))100,200,100
100   N=I+1
        DO 500 J=N,N
        IF(I-LZ(J))500,600,500
500   M=LZ(I)
        LZ(I)=LZ(J)
        LZ(J)=M
        DO 700 L=1,N
        C(L)=A(I,L)
        A(I,L)=A(J,L)
700   A(J,L)=C(L)
500   CONTINUE
200   CONTINUE
      RETURN
      END

```

## SUBROUTINE TRNSFRM(NI,NJ,NK,C,X,I)

C GIVEN A ONE-DIMENSIONAL ARRAY X AND ARRAYS OF TRANSGENERATION CODES (NI, NJ  
C NI AND NK) AND A LIST OF CONSTANTS C AND AN INDEX I THIS SUBROUTINE WILL  
C PERFORM A VARIETY OF TRANSGENERATIONS (TRANSFORMATIONS + GENERATION)  
C N1 = THE TYPE OF TRANSGENERATION  
C N2 = THE INDEX (SUBSCRIPT) OF THE VARIABLE IN ARRAY X AFTER TRANSGENERATION  
C N3 = INDEX OF THE VARIABLE BEFORE TRANSGENERATION  
C N4 = THE INDEX OF A SECOND VARIABLE OR OF A CONSTANT USED IN TRANSGENERATION  
DIMENSIONNT(99),NI(99),NJ(99),NK(99),X(61),C(99)  
N1=NT(1)  
N2=N1(1)  
N3=NJ(1)  
N4=NK(1)  
GOTO(1,2,3,4,5,6,7,8,9,10,11,12,13,14,15,16,17,19)N1  
1 X(N2)=X(N3) \$ GO TO 99  
2 X(N2)=X(N3)\*X(N4) \$ GOTO99  
3 X(N2)=X(N3)/X(N4) \$ GOTO99  
4 X(N2)=X(N3)+X(N4) \$ GOTO99  
5 X(N2)=X(N3)-X(N4) \$ GOTO99  
6 X(N2)=1.0/X(N3) \$ GOTO99  
7 A(N2)=X(N3)+C(N4) \$ GOTO99  
8 X(N2)=X(N3)/C(N4) \$ GOTO99  
9 X(N2)=C(N4)/X(N3) \$ GOTO99  
10 X(N2)=X(N3)\*C(N4) \$ GOTO99  
11 X(N2)=X(N3)\*\*C(N4) \$ GOTO99  
12 IF(X(N3).EQ.0)18,40  
13 X(N2)=0.0 \$ GOT099  
14 X(N2)= ALOG(X(N3)) + GOTO99  
15 X(N2)= ALOG(X(N3))+.4342917 \$ GOT099  
16 IF(X(N3).EQ.0)18,41  
17 A(N2)=EXP (X(N3)) \$ GOT099  
18 TEMP=X(N3)\*.0174533  
X(N2)=SIN (TEMP) \$ GO TO 99  
19 X(N2)=ATAN (X(N3)) \$ GO TO 99  
20 IF(A(N3).LT.C(N4))20,21  
21 A(N3)=A(N3)+360  
22 TEMP=X(N3)-C(N4)  
TEMP=TEMP/57.29578  
X(N2)=SIN (TEMP)+1.0  
GO TO 99  
23 IF(X(N3).GE.X(N4))22,23  
24 X(N2)=X(N3)  
GO TO 99  
25 X(N2)=X(N4)  
99 RETURN  
END

SUBROUTINE SORT (X,KEY,NO)  
C ACCEPT AN ARRAY OF N (NO) VALUES (X) AND SORT THEM INTO ASCENDING ORDER.  
C STORE THEIR ORIGINAL SUBSCRIPTS IN ARRAY KEY.  
DIMENSION KEY(61),X(61)

```

DO 1 I=1,NO
1   KEY(I)=I
MU=NO
2   IF(MU=15) 21,21,23
21  IF(MU=1) 9,9,22
22  MU=2*(MU/4)+1
      GO TO 24
23  MU=2*(MU/8)+1
24  KO=NO-MU
      JO=1
25  I=JO
26  IF(X(I)=X(I+MU)) 28,28,27
27  TEMP=X(I)
2701 K(I)=X(I+MU)
2702 X(I+MU)=TEMP
2703 KEMP=KEY(I)
2704 KEY(I)=KEY(I+MU)
2705 KEY(I+MU)=KEMP
      I=I-MU
      IF(I=1) 28,26,26
28  JO=JO+1
      IF(JO-KO) 25,25,2
9   RETURN
END
```

SORT	3
SORT	4
SORT	5
SORT	6
SORT	7
SORT	8
SORT	9
SORT	10
SORT	11
SORT	12
SORT	13
SORT	14
SORT	15
SORT	16
SORT	17
SORT	18
SORT	19
SORT	20
SORT	21
SORT	22
SORT	23
SORT	24
SORT	25
SORT	26

NE DRAW FORTRAN EXTENDED VERSION 2.0

03/14/70

\*00.39.34

```
SUBROUTINE DRAW(X)
DIMENSION X(16)
C
DUMMY
WRITE(6,100)
100 FORMAT(*0 NO PLOTS UNTIL SUBROUTINES ARE SUPPLIED*)
RETURN
END
```

NE CORRECT FORTRAN EXTENDED VERSION 2.0

03/14/70

\*00,39,34.

SUBROUTINE CORRECT(X)  
DIMENSION X(13)  
C DUMMY  
RETURN  
END

INPUT DECK FOR SAMPLE RUN OF REGRES1

0 15 4 3 0 0 0 2 1 4 1 SAMPLE OUTPUT OF REGRES1 - SNOW COURSES VS. STREAMF  
CPAM BSA POUDRE  
(F4.1,2(F5.1),1X,F3.0)  
10020201040101020102030001030400  
2.0  
20.8 22.1 0.4 147 CPA,CPM,BSA,POUDRE 53  
25.1 17.6 1.6 106 CPA,CPM,BSA,POUDRE 54  
19.3 17.3 0.2 133 CPA,CPM,BSA,POUDRE 55  
30.5 38.9 2.3 202 CPA,CPM,BSA,POUDRE 56  
29.7 36.1 5.0 378 CPA,CPM,BSA,POUDRE 57  
29.4 32.9 4.0 256 CPA,CPM,BSA,POUDRE 58  
30.9 29.7 5.0 228 CPA,CPM,BSA,POUDRE 59  
29.2 26.0 2.8 199 CPA,CPM,BSA,POUDRE 60  
22.3 27.5 2.8 317 CPA,CPM,BSA,POUDRE 61  
38.9 36.5 2.1 274 CPA,CPM,BSA,POUDRE 62  
20.1 19.8 2.4 146 CPA,CPM,BSA,POUDRE 63  
35.4 32.2 1.9 176 CPA,CPM,BSA,POUDRE 64  
27.7 34.3 4.1 325 CPA,CPM,BSA,POUDRE 65  
21.1 21.9 0.0 110 CPA,CPM,BSA,POUDRE 66  
27.6 33.9 0.5 242 CPA,CPM,BSA,POUDRE 67

CONTROL DATA = 15 4 3 R U P T DFG NAM FMT TAN CUN IDENTIFICATION  
 INPUT FORMAT WAS 8(4.1,5F5.1),1A1,1A1  
 DATA WERE READ FROM CARDS  
 TRANSGENERATIONS = 100 - P= 2- 1 4- 1- 1- 2 1- 2- 3- 0 1- 3- 4- 0  
 CONSTANTS = 2.00000

NO. OF DATA = 15	NO. OF VARIABLES = 3	SUM OF WEIGHTS = 15.00000
SUMS OF VARIABLES		
1261.0000	3.11900	3239.30000
<b>RAW SUMS OF SQUARES AND CROSS-PRODUCTS MATRIX</b>		
111297.26000	3174.37000	287597.70000
120.07000	093.10000	
745489.00000		
<b>RESIDUAL SUMS OF SQUARES AND CROSS-PRODUCTS MATRIX</b>		
5221.92933	227.69400	15214.39333
38.43610	1.354.06000	
96080.93333		

#### CHARACTERISTICS OF INPUT 1-414

VARIABLE	MEAN	SD	SE	CV	MAX	MIN	RNG
UPAM	44.09333	14.31395	4.98662	22.9624	111.90000	53.00000	58.00000
BSA	2.03400	1.65693	.42782	70.80912	5.00000	0.00000	5.00000
PQUURE	215.93333	32.64277	21.38991	38.36497	378.00000	106.00000	272.00000

#### SIMPLE LINEAR CORRELATION MATRIX

UPAM	1.0000	.2076	.2745
BSA	1.0000	.7144	
PQUURE	1.0000		

#### INVERSE OF CORRELATION MATRIX

1.00000	.70275	.7119375
1.00000	-1.33712	
2.06700		

#### HIGHEST OTHER PARTIAL CORRELATIONS

UPAM	1.0000	.6531	.5211
BSA	1.0000	.5241	
PQUURE	1.0000		

#### CHARACTERISTICS OF OUTLIER ANALYSIS

COEF.	MULT.	STANDARD ERROR	MAXIMUM DEVIATIONS FROM THE MODEL	Y INTERCEPT	T OF CONSTANT
UPAM	1.0000	.0531	.5211	-.00000	
BSA	1.0000	.0541	.5211		
PQUURE	1.0000				
83.50	.7475	.50000	.50000	1.72.57430	-63.88621
TEST STATISTIC FOR OUTLIERS (1st TEST)					
VARIABLE	CUFFT INERT	STL. UNKNOWN	TEST OF B	STL. COEFFICIENT	SIMPLE R
UPAM	1.00000	.053100	2.01315	.43449	.6795
BSA	.747500	.054100	2.39766	.44612	.7040

SOURCE	SUM OF SQUARES	DF	MEAN SQUARES	F
BUT 10 AT GRASSLAND OF AL. /	01110.33444	C.	30555.16742	10.485
DEVIATIONS FROM REGRESSION	34970.59849	12.	2914.21654	
GRAM INDEPENDENTLY	44357.155H4	1	44357.15588	11.149
BSA INDEPENDENTLY	*7816.19484	1	*7816.19486	12.772
TOTAL	96080.43331	14.		

NO.	INPUT-CLIENT VARIABLES	Y	PREDICTED	DEVIATION
1	65.0000	*40600	147.0000	13.6919
2	60.3000	1.6300	106.0000	-47.6729
3	53.9000	*2000	133.0000	25.3759
4	108.3000	*3000	202.0000	-58.07981
5	101.9000	5.0000	378.0000	64.9453
6	95.4000	4.0000	256.0000	-20.01347
7	90.3000	5.0000	228.0000	-63.88621
8	81.2000	*5.0000	199.0000	-22.67525
9	77.3000	*2.0000	317.0000	102.9330
10	111.4000	*1.0000	276.0000	12.05177
11	59.7000	2.4000	146.0000	-25.02306
12	99.8000	1.9000	176.0000	-58.55610
13	96.3000	*1.0000	325.0000	43.71593
14	64.4000	0.0000	110.0000	-13.52243
15	95.4000	*5000	242.0000	49.53132

END OF RUN  
 VAN DYNE • G. M. 1965 REGRESSION & MULTIPLE REGRESSION AND CORRELATION PROGRAM WITH GRAPHIC OUTPUT FOR MODEL EVALUATION  
 OKNL TM 12AB

## AUTOREG

### INTRODUCTION

Many economic and biological phenomena involve a process of gradual adjustment to change. Because of this process, the current value of one variable depends on present and past values of other variables. Models which describe this process are known as distributed-lag functions. It is also possible that, if the observations of the dependent variable are taken in a time sequence, consistent measurement errors will be made. If either of these conditions exist, the application of a least squares method to the data will result in a lack of fit caused from autocorrelation in the error term.

AUTOREG is a flexible regression system which allows for distributed lag functions and autoregressive errors. It is capable of estimating the parameters of models which are either linear or nonlinear in the parameter space under the statistical assumption of either independent errors or first order autoregressive errors. Conditional regressions may also be run using any of seven combinations of models and error assumptions.

AUTOREG was written in 1965 by Jack E. Martin for use on the IBM 7040 and 7090/94 computer systems. It has been converted for use on the NCAR and SCOPE systems of the CDC 6400 computer.

The most general form of the equations analyzed is as follows:<sup>1/</sup>

---

<sup>1/</sup> The derivation of equation 1 is presented in *The use of distributed lag models containing two lag parameters in the estimation of elasticities of demand*, J. Farm Econ. 45:1474-1481, December 1963.

## SECTION A

$$\begin{aligned}
 1. \quad Y_t &= a_0(1 - \lambda)(1 - \mu)(1 - \beta) + \sum_{i=1}^A a_i X_{it} - (\mu + \beta) \sum_{i=1}^A a_i X_{it-1} \\
 &\quad + \mu\beta \sum_{i=1}^A a_i X_{it-2} + \sum_{j=1}^B b_j Z_{jt} - (\lambda + \beta) \sum_{j=1}^B b_j Z_{jt-1} \\
 &\quad + \lambda\beta \sum_{j=1}^B b_j Z_{jt-2} + (\lambda + \mu + \beta) Y_{t-1} \\
 &\quad - [(\lambda + \mu) \beta + \lambda\mu] Y_{t-2} + \lambda\mu\beta Y_{t-3} \\
 &\quad + \sum_{k=1}^C d_k D_{kt} + e_t
 \end{aligned}$$

where

$Y_{t-m}$  = the current and lagged values of the dependent variable  
( $m = 0, 1, 2, 3$ )

$X_{it-m}$  = the current and lagged values of the exogenous variables  
associated with the lag parameter  $\lambda$  ( $m = 0, 1, 2$ )

$Z_{jt-m}$  = the current and lagged values of the exogenous variables  
associated with the lag parameter  $\lambda$  ( $m = 0, 1, 2$ )

$D_{kt}$  = the current exogenous and/or dummy variables which are  
not associated with a lag

$e_t$  = the errors in the equation

$a_0(1-\lambda)(1-\mu)(1-\beta)$  = the pure constant term

$a_i$  = the parameters of the set of exogenous variables,  $X_{it}$ ,  
( $i = 1, \dots, A$ )

2.  $b_j$  = the parameters of the set of exogenous variables,  $Z_{jt}$ ,  
 $(j = 1, \dots, B)$
- $\lambda$  = the lag parameter associated with the set of exogenous variables,  
 $X_{it}$
- $\mu$  = the lag parameter associated with the set of exogenous variables,  
 $Z_{jt}$
- $\beta$  = the first order autocorrelation coefficient
- $d_k$  = the parameters associated with the set of exogenous variables,  
 $D_{kt}$

The estimation procedure used is presented in more detail by Fuller and Martin<sup>2/</sup> and includes a modification to insure convergence.<sup>3/</sup>

This is known as a two lag model with autoregressive errors (model 7). The other six models may be considered by restricting the values of the parameters as follows:

1. A two lag model with independent errors is obtained by setting the parameter  $\beta$  equal to zero.
2. A Nerlove model with autoregressive errors may be derived by either setting  $y$  equal to zero and omitting the  $Z$  terms or  $\lambda$  equal to zero and omitting the  $X$  terms.
3. A static model with autoregressive errors results when  $\lambda = y = 0$  and either the  $X$  terms or the  $Z$  terms are omitted from the general equation.

<sup>2/</sup> Wayne A. Fuller and James E. Martin, *The effects of autocorrelated errors on the statistical estimation of distributed lag models*, J. Farm Econ. 43: 71-82, February 1961.

<sup>3/</sup> Wayne A. Fuller and James E. Martin, *A Note on The effects of autocorrelated errors on the statistical estimation of distributed lag models*, J. Farm Econ. 44:407-410, May 1962.

4. A Nerlove model with independent errors by restricting  $\beta = 0$  in addition to the restrictions in model 2.
5. A first difference model with independent errors results from setting  $\beta = 1$  in addition to the restrictions specified by model 3.
6. A static model with independent errors has no X or Z terms and  $\lambda = y = \beta = 0$ .

#### METHOD OF OPERATION

The method used is described in detail in the program document by James E. Martin<sup>4/</sup> and will be omitted here.

#### INPUT REQUIREMENTS

The concept used in this program is that of a "Problem" which may consist of one or more "Jobs" or regressions. Thus, a "Problem Card" causes the program to read a set of data and indicates the total number of regressions or Jobs which are to be run using these data. Two "Control Cards" and an appropriate number of "Start Vector Cards" are associated with each Job.

A given Problem must consist of the following cards in the order specified:

- a. Problem Card (one card)
- b. Data Deck (the number of cards may vary)
- c. Control Card 1 (one card)
- d. Control Card 2 (one card)
- e. Start Vector Card(s) (the number of cards depends on the number of parameters in the Job)

Additional Jobs may be run using the same Data Deck by repeating items c, d, and e above for each additional Job.

---

<sup>4/</sup> James E. Martin, *Computer algorithms for estimating the parameters of selected classes of nonlinear, single equation models*. May 1968.

## INPUT FORMATS

### Problem Card

This card controls the parameters which specify the number of variables, the number of observations per variable and the number of Jobs which are associated with a given Data Deck. The format of the Problem Card is as follows:

Cols. 1-5 ... the Problem Number

Cols. 6-10 ... the Number of variables in the Data Deck

Cols. 11-20 ... the Number of observations per variable in  
15 the Data Deck

Cols. 16-20 .... the Number of Jobs to be run using this  
Data Deck

Cols. 21-80 ... Blank or any identifying information the  
user wishes to use.

All values which are punched into columns 1-20 of the Problem Card must be right justified integer values. Columns 21-80 may contain any alphanumeric information.

### Data Deck

The Data Deck is punched in row order starting with the first observation on each variable. Seven observations are punched per card using FORTRAN FORMAT (7F10.4).

In order for the Data Deck to conform with the MRHS-1 and MRHS-2 programs, the variables in the Data Deck must appear as column vectors in the following order:

$$3. [X_{11}, X_{21}, \dots, X_{A1}, Z_{11}, Z_{21}, \dots, Z_{B1}, D_{11}, D_{21}, \dots, D_{C1}, Y_{11}, Y_{21}, \dots, Y_{Y1}]$$

where the subscripts A and B denote the total number of current exogenous variables associated with lag parameters  $\lambda$  and  $\mu$ , respectively. The variables  $D_{it}$  ( $i = 1, \dots, C$ ) represent the exogenous variables which are not

associated with the lag parameters  $\lambda$  and  $\mu$ . The subscript C is the total number of  $D_{lt}$  variables. Note: The y dependent variables,  $Y_{lt}$  ( $i = 1, \dots, y$ ) must always appear on the right hand side of the exogenous variables in the Data Deck.

### Control Card 1

This card defines most of the major parameters which control the type of estimation which is to be employed for the Job, the size of the Job, etc. The card format is as follows:

- |       |           |   |
|-------|-----------|---|
| Cols. | 1- 5 ...  | Job Number  |
| Cols. | 6- 7 ...  | The total number of exogenous variables associated with lag parameter $\lambda$ ( $A \geq 0$ )  |
| Cols. | 8- 9 ...  | The total number of exogenous variables associated with lag parameter $\mu$ ( $B \geq 0$ )  |
| Cols. | 10-11 ... | The total number of exogenous variables and/or dummy variables which are not associated with a lag parameter ( $C \geq 0$ )   |
| Cols. | 12-13 ... | The column number of the variable in the Data Deck which is to be used as the dependent variable for this Job.  |
| Cols. | 14-15 ... | The total number of parameters or rows to be controlled or skipped, NSKIP ( $NSKIP \geq 0$ )  |
| Cols. | 16-17 ... | "01" for least squares estimation, otherwise, the maximum number of iterations to be performed in a nonlinear estimation Job ("25" is suggested for nonlinear Jobs) |
| Col.  | 18 ...    | "1" if the calculation of the pure constant term is desired, otherwise, "0" when regressions through the origin are desired   |
| Col.  | 19 ...    | "1" if the calculation of the predicted values, residuals and Durbin-Watson "d" statistic is desired, otherwise, "0"  |

Col. 20 ... "1" if a listing of the correlation matrix is desired, otherwise, "0". Note: This option is available only when Col. 31 of Control Card 1 contains "0"

Cols. 21-30 ... The "test criterion" to be used to halt the iterative process in nonlinear Jobs. The value of the "test criterion" is punched using FORTRAN FORMAT (F10.4). ("0.001" is recommended for most nonlinear Jobs)

Col. 31 ... "0" if the Job to be run is: (1) the first Job in a Problem (2) involves a different dependent variable from the preceding Job or (3) involves a different computation on the pure constant term from the preceding Job, otherwise, "1"

Cols. 32-80 ... Blank or any identifying information the user wishes to punch into this card.

#### Control Card 2

This card specifies the actual row numbers (or parameter numbers) of those parameters which are to be controlled or skipped. The order or numbering of the parameters in any given Job is always assumed to be:  $a_i$  ( $i = 1, \dots, A$ ) provided  $A > 0$ ;  $b_j$  ( $j = 1, \dots, B$ ) provided  $B > 0$ ;  $\lambda$ ;  $\mu$ ;  $\beta$ ; and  $d_k$  ( $k = 1, \dots, C$ ) provided  $C > 0$ . Thus, the programs are written such that the first  $r$  parameters,  $r = A + B \geq 0$ , are the total number of rows for the parameters of the current exogenous variables,  $X_{it}$  and  $Z_{jt}$ , row  $r + 1$  is assumed to be the parameter  $\lambda$ , row  $r + 2$  is assumed to be the parameter  $\mu$ , row  $r + 3$  is assumed to be the parameter  $\beta$ , and row  $r + 3 + k$ , ( $k \geq 0$ ) is assumed to be the parameter of the  $k$ th current exogenous or dummy variable,  $D_{kt}$ , if such a variable is included in the Job being run.

The format for Control Card 2 is FORTRAN FORMAT (15(12,2X)). Thus, the card is punched in the following manner:

Cols. 1-2 ... The actual row number of the first parameter to be controlled or skipped.

Cols. 3-4 ... Blank

Cols. 5-6 ... The actual row number of the second parameter to be controlled or skipped

Cols. 7-8 ... Blank

.

.

etc.

.

Cols. 61-80 ... Blank

*Note:* The number of parameters which are punched into Control Card 2 and which are to be controlled or skipped *must agree* with the number punched into columns 14-15 of Control Card 1.

#### Start Vector Card(s)

The total number of Start Vector Card(s), NSVC, required for a given Job depends upon the number of parameters involved and may differ from Job to Job. The number of Start Vector Card(s) required for each Job is determined by rounding NSVC to the largest integer value where:

$$4. \text{ NSVC} = \frac{\text{A} + \text{B} + \text{C} + 3}{8}$$

The Start Vector Card(s) contain(s) all initial parameter estimates. Therefore, the order of the initial parameter estimates *must be identical* to the actual row numbers described under Control Card 2 for each parameter. The format used for punching the initial parameter estimates in the Start Vector Card(s) is FORTRAN FORMAT (8F10.5). All columns of the last Start Vector Card which are not required for initial parameter estimates may be left blank. *Note:* In all least squares estimation Jobs, the appropriate

number of blank card(s) may be used as Start Vector Card(s). In all non-linear estimation jobs, the user's best estimate of each parameter value should be punched into the appropriate locations of the Start Vector Card(s). The nearer the user's initial estimates are to the final parameter estimates, the shorter will be the computing time for the job.

#### OUTPUT

At the conclusion of the run, the printed output will consist of:

1. For each Problem: Problem Card
2. A listing of the input data
3. For each Job: Control Card 1
4. The Correlation Matrix if "1" appears in column 20 of Control Card 1 printed in lower triangular form
5. For each trial: k, IDF, TSS, SSE, MSE, SSR, R Square
6. For each trial: values of parameter estimates
7. For the last iteration:  $i$ ,  $\theta_i$ ,  $\Delta\theta_i$ , Test<sub>i</sub>, Variance<sub>i</sub>, Stand Er<sub>i</sub>, Student t<sub>i</sub>
8. For each Job:
  - a. The dimensions of the inverse matrix
  - b. The inverse matrix at the last iteration
  - c. The pure constant term if "1" appears in column 18 of Control Card 1
  - d. The  $a_0$  term
  - e. The error routine and Durbin-Watson "d" if "1" appears in column 19 of Control Card 1.
  - f. The means of the variables at times  $t$ ,  $t-1$ ,  $t-2$ , and  $t-3$

where

$k$  = the denominator in the geometric series 1, 1/2, 1/4, ...  
 $IDF$  = the degrees of freedom  
 $TSS$  = the total sum of squares  
 $SSE$  = the sum of squares for error  
 $MSE$  = the mean square error  
 $SSR$  = the sum of squares for regression  
 $R$  square =  $R^2$   
 $i$  = the parameter row number  
 $\theta_i$  = the estimate of the  $i$ th parameter  
 $\Delta\theta_i$  = the change in the  $i$ th parameter  
 $Test_i = (\Delta\theta_i)^2 / Var(\theta_i)$   
 $Variance_i$  = the variance of the  $i$ th parameter  
 $Stand Er_i$  = the standard error of the  $i$ th parameter estimate  
 $Student t_i$  = the student "t" test of the  $i$ th parameter estimate against zero. All printed output will possess column headings above the numerical data and/or estimate.

#### ERROR CONDITIONS

The following list of error conditions are checked by the programs:

Error 107 = columns 6-7 of Control Card 1 contain a negative punch.  
Error 135 = columns 8-9 of Control Card 1 contain a negative punch.  
Error 191 = columns 10-11 of Control Card 1 contain a negative punch.  
Error 453 = columns 14-15 of Control Card 1 contain a negative punch.  
Error 524 = singular matrix, matrix cannot be inverted.  
Error 727 = the test value in columns 21-30 of Control Card 1 is negative.

Should an error condition occur, all subsequent Jobs and Problems contained in the same run in which the error occurs will be terminated.

#### LISTING AND EXAMPLE PROBLEM

The example problem shown is a two-lag model with autoregressive errors -- equation 1. There are 27 observations for each of seven variables, which include two variables associated with the lag  $\lambda$ , two variables associated with the lag  $y$ , two non-lagged variables, and the dependent variable, Y.

```

PROGRAM AUTOREG(INPUT,OUTPUT,TAPE5=INPUT,TAPE6=OUTPUT)
DIMENSION KZ(15), T(35), VB(35), E(47), C(35,35), B(35,47), A(12),
L X(47,47), XM(47), TSQR(35), FTSQR(35), STUDT(35), Y(375,8), XS(47
2), IDENT(35), KDENT(4)
DIMENSION VALUES(9,100)
COMMON A,T,IN1,IN2,IN3

C-----
C-----SSE3=SSE1= A MAGIC NUMBER WHICH IS ATTEMPTED UPPER LIMIT OF SS ERR
DATA SSE3/3776777777777777777777B/
C-----
C-----TEST1 IS AN ARBITRARILY SMALL NUMBER USED IN CHECKING MATRIX INVER
1 TEST1=0.0000000001
NN=0
C-----READ AND PRINT DATA AND CONTROL CARDS.
READ (5,143) IPROB,NVAR,NOBS,NJOBS
IF (IPROB.EQ.-0) GO TO 138
WRITE (6,144) IPROB,NVAR,NOBS,NJOBS
WRITE (6,174) NVAR,NOBS
C-----Y(I,J) IS THE ARRAY OF ORIGINAL VARIABLES.
DO 2 I=1,NOBS
READ (5,145) (Y(I,J),J=1,NVAR)
2 WRITE (6,173) (Y(I,J),J=1,NVAR)
3 SSE2=SSE3
READ (5,147) JOBNO,IA,IB,ID,IRHS,NSKIP,ISS1,ISS2,IERR,ICORR,TEST,
NAME1,(KDENT(I),I=1,4)
WRITE (6,146)
WRITE (6,148) JOBNO,IA,IB,ID,IRHS,NSKIP,ISS1,ISS2,IERR,ICORR,TEST,
NAME1,(KDENT(I),I=1,4)

C-----
C-----SET UP INDICES
C-----IA= NUMBER OF X VARIABLES ASSOCIATED WITH A LAG PARAMETER
C-----IB = NUMBER OF Z VARIABLES ASSOCIATED WITH A LAG PARAMETER
C-----ID = NUMBER OF UNLAGGED D VARIABLES
C-----IL = NUMBER OF LAGGED VARIABLES
C-----IX = TOTAL NUMBER OF VARIABLES INCLUDING GERATED ONES
IL=IA+IB
IX=3*IL+ID+4
INFM1=IL+ID+3
IN1=IL+1
IN2=IL+2
IN3=IL+3
INF=INFM1+1
IM1=3*IL+1
IM2=IM1+1
IM3=IM2+1
OBS=NOBS-3

C-----
IF (NAME1.EQ.1) GO TO 15
DO 4 I=1,IX
DO 4 J=1,IX
X(I,J)=0.0
XS(I)=0.0
4 XM(I)=0.0

C-----
C-----GENERATE NEEDED LAGGED INDEPENDENT AND/OR DEPENDENT VARIABLES.
C-----STORE APPROPRIATE SQUARES AND CROSS PRODUCTS IN XS(IX)

```

```

C-----FINALLY PUT THE SUM OF SQUARES AND CROSS PRODUCTS INTO X(IX,IX).      A 57
   DO 10 I=4,NOBS
   IF (IL.EQ.0) GO TO 6
   DO 5 K=1,IL
   E(3*K-2)=Y(I,K)
   E(3*K-1)=Y(I-1,K)
   E(3*K)=Y(I-2,K)
5    CONTINUE
6    E(IM1)=Y(I-1,IRHS)
   E(IM2)=Y(I-2,IRHS)
   E(IM3)=Y(I-3,IRHS)
   IF (ID.EQ.0) GO TO 8
   DO 7 L=1,ID
   M=IL+L
   N=IM3+L
7    E(N)=Y(I,M)
8    E(IX)=Y(I,IRHS)
   DO 9 M=1,IX
   XS(M)=XS(M)+E(M)
   DO 9 N=1,IX
9    X(M,N)=X(M,N)+E(M)*E(N)
10   CONTINUE
C-----
11   IF (ISS2.NE.1) GO TO 12
C-----
C-----GET X = SUM OF SQUARES + CROSS PRODUCTS CORRECTED
12   DO 11 I=1,IX
   DO 11 J=1,IX
11   X(I,J)=X(I,J)-(XS(I)*XS(J))/OBS
C-----
C-----CALCULATE AND PRINT CORRELATION MATRIX IF REQUESTED.
C-----CORRELATION MATRIX IS C(IX,IX)
13   IF (ICORR.NE.1) GO TO 16
   DO 13 I=1,IX
   DO 13 J=1,IX
13   C(I,J)=X(I,J)/((X(I,I)*X(J,J))**0.5)
   WRITE (6,150)
   WRITE (6,149) (I,I=1,IX)
   DO 14 I=1,IX
14   WRITE (6,151) I,(C(I,J),J=1,I)
C-----
15   IDF=NOBS-IL-ID-6+NSKIP-ISS2
C-----
C-----START WITH ITERATION = 1
C-----READ CONTROL CARDS 3 AND 4, COEF. EST. = T(INFM1)
16   IY=1
   DF=IDF
   READ (5,152) (KZ(I),I=1,NSKIP)
   READ (5,153) (T(I),I=1,INFM1)
   DO 17 I=1,INFM1
17   VALUES(I,1)=T(I)
C-----
C-----CALCULATE MEANS OF ALL VARIABLES.
   DO 18 I=1,IX
18   XM(I)=XS(I)/OBS
   DO 19 I=1,IX

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## AUTO REGRESSION PROGRAM WITH TWO LAG DISTRIBUTION

PAGE 3

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19   E(I)=0.0
C-----
20   CALL ACOM
C-----
C-----WRITE HEADER FOR ITERATIVE PROCEDURES
21   WRITE (6,176)
22   WRITE (6,155)
23   WRITE (6,154)
C-----
C-----B=AXX
24   DO 21 I=1,INF
25   DO 21 J=1,IX
26   B(I,J)=0.
27   IF (IA) 22,25,23
28   K=107
29   GO TO 139
30   DO 24 I=1,IA
31   DO 24 J=1,IX
32   B(I,J)=B(I,J)+X(3*I-2,J)+A(2)*X(3*I,J)-A(1)*X(3*I-1,J)
33   B(IN2,J)=B(IN2,J)+T(I)*(A(4)*X(3*I,J)-X(3*I-1,J))
34   B(IN3,J)=B(IN3,J)+T(I)*(A(3)*X(3*I,J)-X(3*I-1,J))
35   B(INF,J)=B(INF,J)+T(I)*(A(1)*X(3*I-1,J)-X(3*I-2,J)-A(2)*X(3*I,J))
36   IF (IB) 26,29,27
37   K=135
38   GO TO 139
39   DO 28 I=1,IB
40   DO 28 J=1,IX
41   M=(3*IA)+(3*I-2)
42   K=IA+I
43   B(K,J)=B(K,J)+X(M,J)+A(6)*X(M+2,J)-A(5)*X(M+1,J)
44   B(IN1,J)=B(IN1,J)+T(K)*(A(4)*X(M+2,J)-X(M+1,J))
45   B(IN3,J)=B(IN3,J)+T(K)*(A(7)*X(M+2,J)-X(M+1,J))
46   B(INF,J)=B(INF,J)+T(K)*(A(5)*X(M+1,J)-X(M,J)-A(6)*X(M+2,J))
47   DO 30 J=1,IX
48   B(IN1,J)=B(IN1,J)+X(IM1,J)+A(2)*X(IM3,J)-A(1)*X(IM2,J)
49   B(IN2,J)=B(IN2,J)+X(IM1,J)+A(6)*X(IM3,J)-A(5)*X(IM2,J)
50   B(IN3,J)=B(IN3,J)+X(IM1,J)+A(10)*X(IM3,J)-A(9)*X(IM2,J)
51   B(INF,J)=B(INF,J)+A(11)*X(IM2,J)-A(8)*X(IM1,J)-A(12)*X(IM3,J)
52   IF (ID) 31,34,32
53   K=191
54   GO TO 139
55   DO 33 I=1,1D
56   DO 33 J=1,IX
57   M=IM3+I
58   K=IN3+I
59   B(INF,J)=B(INF,J)-T(K)*X(M,J)
60   B(K,J)=X(M,J)
61   DO 35 J=1,IX
62   B(INF,J)=B(INF,J)+X(IX,J)
C-----
C-----C=BA
63   DO 36 I=1,INF
64   DO 36 J=1,INF
65   C(I,J)=0.
66   IF (IA) 37,40,38
67   K=303

```

```

      GO TO 139                                A 169
38   DO 39 J=1,IA                            A 170
      DO 39 I=1,INF                           A 171
          C(I,J)=C(I,J)+B(I,3*j-2)+A(2)*B(I,3*j)-A(1)*B(I,3*j-1)    A 172
          C(I,IN2)=C(I,IN2)+T(J)*(A(4)*B(I,3*j)-B(I,3*j-1))           A 173
          C(I,IN3)=C(I,IN3)+T(J)*(A(3)*B(I,3*j)-B(I,3*j-1))           A 174
39   C(I,INF)=C(I,INF)+T(J)*(A(1)*B(I,3*j-1)-A(2)*B(I,3*j)-B(I,3*j-2)) A 175
40   IF (IB) 41,44,42                          A 176
41   K=337                                     A 177
      GO TO 139                                A 178
42   DO 43 J=1,IB                            A 179
      DO 43 I=1,INF                           A 180
          K=IA+J                               A 181
          M=(3*IA)+(3*j-2)                     A 182
          C(I,K)=C(I,K)+B(I,M)+A(6)*B(I,M+2)-A(5)*B(I,M+1)           A 183
          C(I,IN1)=C(I,IN1)+T(K)*(A(4)*B(I,M+2)-B(I,M+1))           A 184
          C(I,IN3)=C(I,IN3)+T(K)*(A(7)*B(I,M+2)-B(I,M+1))           A 185
43   C(I,INF)=C(I,INF)+T(K)*(A(5)*B(I,M+1)-B(I,M)-A(6)*B(I,M+2)) A 186
44   DO 45 I=1,INF                           A 187
          C(I,IN1)=C(I,IN1)+B(I,IM1)+A(2)*B(I,IM3)-A(1)*B(I,IM2)     A 188
          C(I,IN2)=C(I,IN2)+R(I,IM1)+A(6)*B(I,IM3)-A(5)*B(I,IM2)     A 189
          C(I,IN3)=C(I,IN3)+B(I,IM1)+A(10)*B(I,IM3)-A(9)*B(I,IM2)    A 190
45   C(I,INF)=C(I,INF)+A(11)*B(I,IM2)-A(8)*B(I,IM1)-A(12)*B(I,IM3) A 191
      IF (ID) 46,49,47                          A 192
46   K=397                                     A 193
      GO TO 139                                A 194
47   DO 48 I=1,INF                           A 195
      DO 48 J=1,1D                            A 196
          M=IM3+J                             A 197
          N=IN3+J                             A 198
          C(I,N)=B(I,M)                      A 199
48   C(I,INF)=C(I,INF)-T(N)*B(I,M)          A 200
49   DO 50 I=1,INF                           A 201
50   C(I,INF)=C(I,INF)+B(I,IX)              A 202
      C-----                                A 203
      C-----SET TO SKIP OR FIX THETAS        A 204
          IF (NSKIP) 51,54,52                A 205
51   K=453                                     A 206
      GO TO 139                                A 207
52   DO 53 I=1,NSKIP                         A 208
          J=KZ(I)                            A 209
          DO 53 K=1,INF                      A 210
          C(J,K)=0.                         A 211
53   C(K,J)=0.                            A 212
      C-----                                A 213
      C-----INVERT MATRIX                  A 214
54   DO 62 J=1,INFM1                         A 215
      DO 55 I=1,NSKIP                         A 216
          IF (J-KZ(I)) 55,62,55               A 217
55   CONTINUE                                  A 218
          SAVE=C(J,J)                      A 219
          IF (SAVE-TEST1) 56,58,58             A 220
56   IF (SAVE+TEST1) 58,58,57               A 221
57   K=524                                     A 222
      GO TO 139                                A 223
58   PIVOT=1.0/SAVE                         A 224

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## AUTO REGRESSION PROGRAM WITH TWO LAG DISTRIBUTION

PAGE 5

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      C(J,J)=-1.0          A 225
      DO 59 I=1,INFM1      A 226
  59   E(I)=-C(I,J)*PIVOT A 227
      C(J,J)=SAVE          A 228
      DO 60 K=1,INF        A 229
      TEMP=C(J,K)          A 230
      C(J,K)=0.             A 231
      DO 60 I=1,INFM1      A 232
  60   C(I,K)=C(I,K)+E(I)*TEMP A 233
      DO 61 I=1,INFM1      A 234
  61   C(I,J)=E(I)         A 235
  62   CONTINUE            A 236
      IV=1                 A 237
C-----
C-----ADJUST PARAMETER ESTIMATES.          A 238
      DO 63 I=1,INFM1      A 239
  63   T(I)=T(I)+C(I,INF) A 240
      SSE1=SSE2            A 241
C-----
  64   CALL ACOM            A 242
C-----
C-----COMPUTE SSE          A 243
      DO 76 J=1,IX          A 244
      E(J)=X(IX,J)+A(11)*X(IM2,J)-A(8)*X(IM1,J)-A(12)*X(IM3,J) A 245
      IF (IA) 65,68,66       A 246
  65   K=607                A 247
      GO TO 139              A 248
  66   DO 67 I=1,IA          A 249
      M=3*I-2                A 250
  67   E(J)=E(J)+T(I)*(A(1)*X(M+1,J)-X(M,J)-A(2)*X(M+2,J)) A 251
  68   IF (IB) 69,72,70       A 252
  69   K=617                A 253
      GO TO 139              A 254
  70   DO 71 I=1,IB          A 255
      M=(3*IA)+(3*I-2)       A 256
      K=IA+I                 A 257
  71   E(J)=E(J)+T(K)*(A(5)*X(M+1,J)-X(M,J)-A(6)*X(M+2,J)) A 258
  72   IF (ID) 73,76,74       A 259
  73   K=627                A 260
      GO TO 139              A 261
  74   DO 75 I=1,ID          A 262
      M=IM3+I                A 263
      N=IN3+I                A 264
  75   E(J)=E(J)-T(N)*X(M,J) A 265
  76   CONTINUE              A 266
      SSE2=E(IX)+A(11)*E(IM2)-A(8)*E(IM1)-A(12)*E(IM3) A 267
      IF (IA) 77,80,78       A 268
  77   K=641                A 269
      GO TO 139              A 270
  78   DO 79 I=1,IA          A 271
      M=3*I-2                A 272
  79   SSE2=SSE2+T(I)*(A(1)*E(M+1)-E(M)-A(2)*E(M+2)) A 273
  80   IF (IB) 81,84,82       A 274
  81   K=653                A 275
      GO TO 139              A 276
  82   DO 83 I=1,IB          A 277

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M=(3*IA)+(3*I-2) A 281
K=IA+I A 282
83 SSE2=SSE2+T(K)*(A(5)*E(M+1)-E(M)-A(6)*E(M+2)) A 283
84 IF (ID) 85,88,86 A 284
85 K=665 A 285
GO TO 139 A 286
86 DO 87 I=1,1D A 287
M=IM3+I A 288
N=IN3+I A 289
87 SSE2=SSE2-T(N)*E(M) A 290
88 DF=IDF A 291
ESSM=SSE2/DF A 292
TMESS=X(IIX,IIX)-SSE2 A 293
RSQR=TMESS/X(IIX,IIX) A 294
C----- A 295
C-----IY = ITERATION ON TEST FOR COEFFICIENT CHANGES. A 296
C-----IV = ITERATION ON TEST FOR SS ERROR CHANGES A 297
C-----IDF = DEGREES OF FREEDOM. A 298
C-----X = SUM OF SQUARES MATRIS A 299
C-----SSE2 = SUM OF SQUARES FOR ERROR. A 300
C----- A 301
C-----CHECK FOR REDUCTION IN SS ERROR A 302
C-----IF SS ERROR IS SMALL ENOUGH THEN GO ON, A 303
C----- OTHERWISE HALVE THE INCREMENT IN PARAMETER CHANGES AND ITERATE. A 304
IF (SSE1-SSE2) 89,89,92 A 305
89 IV=2*IV A 306
IF (IV-9999) 90,90,92 A 307
90 DO 91 I=1,INFM1 A 308
C-----ADD 1/2 OF THETA CHANGE EACH ITERATION UNTIL SS ERROR IS REDUCED F A 309
C(I,INF)=C(I,INF)/2. A 310
91 T(I)=T(I)-C(I,INF) A 311
GO TO 64 A 312
C----- A 313
92 CONTINUE A 314
C----- A 315
C-----T(I) = THETA A 316
C-----C(I,INF) = DTHETA A 317
C-----E(I) = TEST A 318
C-----VB(I) = VARIANCE A 319
C-----FTSQR(I) = STD. ERROR A 320
C-----STUDT(I) = STUDENT T A 321
SMS=IV*IV A 322
DO 95 I=1,INFM1 A 323
IF (C(I,I)) 93,94,93 A 324
93 VR(I)=C(I,I)*ESSM A 325
TSQR(I)=T(I)*T(I) A 326
E(I)=((C(I,INF)*C(I,INF))*SMS)/VR(I) A 327
FTSQR(I)=TSQR(I)/VB(I) A 328
STUDT(I)=SQRT(FTSQR(I)) A 329
FTSQR(I)=SQRT(VB(I)) A 330
GO TO 95 A 331
94 VB(I)=0. A 332
C(I,INF)=0. A 333
E(I)=0. A 334
FTSQR(I)=0. A 335
STUDT(I)=0.0 A 336

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```

95      CONTINUE          A 337
C----- A 338
      ITEST=0          A 339
      DO 97 I=1,INFM1    A 340
      IF (E(I)-TEST) 97,97,96   A 341
96      ITEST=1          A 342
97      CONTINUE          A 343
C----- A 344
      IF (ISS1-IY) 98,101,98   A 345
98      IY=IY+1          A 346
      DO 99 I=1,INFM1    A 347
99      VALUES(I,IY)=T(I)   A 348
      WRITE (6,156) IY,IV,IDE,XIX,IX),SSE2,ESSM,TMESS,RSQR   A 349
C----- A 350
C-----IF ITEST IS TOO LARGE GO THROUGH ANOTHER ITERATION   A 351
C-----THAT IS, IF ANY PARAMETER CHANGE IS LARGER THAN ALLOWABLE MINIMUM   A 352
      IF (ITEST) 100,101,20   A 353
100     K=727          A 354
      GO TO 139          A 355
C----- A 356
C-----PRINT PARAMETER ESTIMATES          A 357
101     WRITE (6,175)        A 358
C-----IDENT(II) IS THE LIST OF PARAMETER IDENTIFIERS.        A 359
      IADD=1000000000000000B   A 360
      IDENT(1)=6HX 1          A 361
      DO 102 II=2,IA          A 362
102     IDENT(II)=IDENT(II-1)+IADD   A 363
      IDENT(IA+1)=6HZ 1          A 364
      LL=IA+2          A 365
      DO 103 II=LL,IL          A 366
103     IDENT(II)=IDENT(II-1)+IADD   A 367
      IDENT(IL+1)=6HLAMBDA   A 368
      IDENT(IL+2)=6HMU       A 369
      IDENT(IL+3)=6HBETA     A 370
      IDENT(IL+4)=6HD 1       A 371
      LL=IL+5          A 372
      DO 104 II=LL,INFM1    A 373
104     IDENT(II)=IDENT(II-1)+IADD   A 374
C----- A 375
C-----PRINT VALUES FOR EACH ITERATION          A 376
      PRINT 140          A 377
      PRINT 141, (IDENT(I),I=1,INFM1)   A 378
      DO 105 J=1,IY          A 379
      K=J-1          A 380
105     PRINT 142, K,(VALUES(I,J),I=1,INFM1)   A 381
      PRINT 175          A 382
      WRITE (6,176)          A 383
      WRITE (6,157)          A 384
      DO 106 I=1,INFM1    A 385
106     WRITE (6,158) I,IDENT(I),T(I),C(I,INF),E(I),VB(I),FTSQR(I),STUDT(I)   A 386
      1)          A 387
      WRITE (6,159) INFM1,INFM1   A 388
C----- A 389
C-----PRINT THE INVERSE MATRIX          A 390
      DO 107 I=1,INFM1    A 391
107     WRITE (6,160) (C(I,J),J=1,I)   A 392

```

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C----- A 393
C-----CALCULATE THE CONSTANT TERM A 394
CONST=0. A 395
IF (ISS2-1) 121,108,121 A 396
108 CONST=XM(IX) A 397
IF (IA) 109,112,110 A 398
109 K=738 A 399
GO TO 139 A 400
C----- A 401
110 DO 111 I=1,IA A 402
111 CONST=CONST+T(I)*(A(1)*XM(3*I-1)-XM(3*I-2)-A(2)*XM(3*I)) A 403
112 IF (IB) 113,116,114 A 404
113 K=743 A 405
GO TO 139 A 406
C----- A 407
114 DO 115 I=1,IB A 408
M=(3*IA)+(3*I-2) A 409
K=IA+I A 410
115 CONST=CONST+T(K)*(A(5)*XM(M+1)-XM(M)-A(6)*XM(M+2)) A 411
116 CONST=CONST+A(11)*XM(IM2)-A(8)*XM(IM1)-A(12)*XM(IM3) A 412
IF (ID) 117,120,118 A 413
117 K=760 A 414
GO TO 139 A 415
C----- A 416
118 DO 119 I=1,ID A 417
M=IM3+I A 418
N=IN3+I A 419
119 CONST=CONST-T(N)*XM(M) A 420
120 WRITE (6,161) CONST A 421
C----- A 422
C-----CALCULATE AO=CONST/(1-LAMBDA)(1-MU)(1-BETA) A 423
DENOM=(1-T(IL+1))*(1-T(IL+2))*(1-T(IL+3)) A 424
AO=CONST/DENOM A 425
WRITE (6,162) AO A 426
121 IF (IERR.NE.1) GO TO 131 A 427
C----- A 428
C-----CALCULATE PREDICTED VALUES OF Y A 429
C----- A 430
DO 128 I=4,NQBS A 431
Y(I,NVAR+1)=CONST A 432
IF (IA.EQ.0) GO TO 123 A 433
DO 122 J=1,IA A 434
122 Y(I,NVAR+1)=Y(I,NVAR+1)+T(J)*(Y(I,J)-A(1)*Y(I-1,J)+A(2)*Y(I-2,J)) A 435
123 IF (IB.EQ.0) GO TO 125 A 436
DO 124 J=1,IB A 437
M=IA+J A 438
124 Y(I,NVAR+1)=Y(I,NVAR+1)+T(M)*(Y(I,M)-A(5)*Y(I-1,M)+A(6)*Y(I-2,M)) A 439
125 IF (ID.EQ.0) GO TO 127 A 440
DO 126 J=1,ID A 441
M=IL+J A 442
N=IN3+J A 443
126 Y(I,NVAR+1)=Y(I,NVAR+1)+T(N)*Y(I,M) A 444
127 Y(I,NVAR+1)=Y(I,NVAR+1)+A(8)*Y(I-1,IRHS)-A(11)*Y(I-2,IRHS)+A(12)*Y A 445
1(I-3,IRHS) A 446
128 CONTINUE A 447
C----- A 448

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SSDIF=0.0          A 44
C----- A 45
C-----PRINT OBSERVATIONS, PREDICTED VALUES AND DEVIATIONS. A 45
    WRITE (6,176) A 45
    WRITE (6,163) A 45
SDEV1=0.0          A 45
DO 130 I=4,NOBS   A 45
    DEV1=Y(I,IRHS)-Y(I,NVAR+1) A 45
    SDEV1=SDEV1+DEV1*DEV1 A 45
    N=I-3             A 45
    WRITE (6,164) N,Y(I,IRHS),Y(I,NVAR+1),DEV1 A 45
    IF (I.EQ.4) GO TO 129 A 46
    SSDIF=SSDIF+(DEV2-DEV1)*(DEV2-DEV1) A 46
129   DEV2=DEV1   A 46
130   CONTINUE   A 46
C----- A 46
    DUBWA=SSDIF/SDEV1 A 46
    WRITE (6,165) DUBWA A 46
C----- A 46
C-----PRINT MEANS OF VARIABLES A 46
131   WRITE (6,166) A 46
    IF (IA.EQ.0) GO TO 133 A 47
    DO 132 I=1,IA A 47
    LL=3*(I-1)+1 A 47
    LU=3*I           A 47
132   WRITE (6,167) I,(XM(II),II=LL,LU) A 47
133   IF (IR.EQ.0) GO TO 135 A 47
    DO 134 I=1,IB A 47
    LL=3*IA+3*(I-1)+1 A 47
    LU=3*(IA+I)       A 47
134   WRITE (6,168) I,(XM(II),II=LL,LU) A 47
135   LL=3*IL+1      A 48
    LU=LL+2          A 48
    WRITE (6,170) XM(IX),(XM(II),II=LL,LU) A 48
    IF (ID.EQ.0) GO TO 137 A 48
    DO 136 I=1,ID A 48
    II=3*(IL+1)+I   A 48
136   WRITE (6,169) I,XM(II) A 48
137   WRITE (6,171) JOBNO A 48
    NN=NN+1          A 48
    IF (NN=NJOBS) 3,1,138 A 48
C----- A 49
138   CALL EXIT   A 49
C----- A 49
C-----TERMINATE DUE TO AN ERROR. A 49
139   WRITE (6,172) K A 49
C-----INPUT-OUTPUT FORMATS. A 49
C----- A 49
140   FORMAT (1H0,*VALUES OF PARAMETER ESTIMATES AT EACH ITERATION*) A 49
141   FORMAT (1H0,5X,9(A6,8X)//) A 49
142   FORMAT (1H ,13,9(1X,E13.6)) A 49
143   FORMAT (5I5)            A 50
144   FORMAT (48H1PROBLEM NUMBER - NO. VAR. - NO. OBS. - NO. JOBS/5X,I5, A 50
    17X,I5,6X,I5,6X,I5) A 50
145   FORMAT (7F10.4)          A 50
146   FORMAT (6H1JOBNO,2X,1HA,3H 8 ,3H C ,5H RHS ,7H NSKIP ,7H NITER ,6H A 50

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1 CONS ,5H ERR ,6H CORR ,12H TEST ,8H NWSSCP ,/)	A 505
147 FORMAT (I5,6I2,3I1,F10.4,I1,4A10)	A 506
148 FORMAT (1X,I5,I3,I2,I3,I4,I6,I7,I6,I6,I5,4X,F10.8,I6,10X,4A10,//)	A 507
149 FORMAT (1H0,3X,2I6/)	A 508
150 FORMAT (20H CORRELATION MATRIX)	A 509
151 FORMAT (1H I3,3X,2I6.3)	A 510
152 FORMAT (I5(I2,2X))	A 511
153 FORMAT (8F10.5)	A 512
154 FORMAT (* ITER STEP IDF#,5X,*TSS*,14X,*SSE*,14X,*MSE*,14X,*SSR*, 1 12X,*R SQUARE*)//)	A 513
155 FORMAT (*-ITERATIVE CALCULATIONS FOR COEFFICIENT DETERMINATION*)//)	A 514
156 FORMAT (1X,3I5,E15.8,4(2X,E15.8))	A 515
157 FORMAT (2IX,5HTHETA11X,7HD THETA12X,4HTEST11X,8HVARIANCE9X,8HSTAND 1 ER8X,9HSTUDENT T//)	A 516
158 FORMAT (1IX,I5,3X,A6,6(2X,E15.8))	A 517
159 FORMAT (23H-SIZE OF INVERSE MATRIXI10,I10/15H INVERSE MATRIX//)	A 518
160 FORMAT (I10(2X,E11.4))	A 519
161 FORMAT (//10H CONSTANT=E15.8//)	A 520
162 FORMAT (*0*,6X,*AO=*,E15.8)	A 521
163 FORMAT (I10X,10HOBSERVED Y,7X,11HPREDICTED Y,7X,8HRESIDUAL)	A 522
164 FORMAT (1IX,I4,3X,E15.8,2X,E15.8,2X,E15.8)	A 523
165 FORMAT (23H- DURBIN-WATSON D ,F10.8)	A 524
166 FORMAT (*-VARIABLE MFANS AT*,15X,*T*,15X,*T-1*,14X,*T-2*,14X,*T-3* 1)	A 525
167 FORMAT (*0 VARIABLE NO. X*,I1,4X,3(2X,E15.8))	A 526
168 FORMAT (*0 VARIABLE NO. Z*,I1,4X,3(2X,E15.8))	A 527
169 FORMAT (*0 VARIABLE NO. D*,I1,6X,E15.8)	A 528
170 FORMAT (*0 DEPENDENT VARIABLE*,1X,4(2X,E15.8))	A 529
171 FORMAT (13H END OF J08N017/1H1)	A 530
172 FORMAT (6H ERRORI4)	A 531
173 FORMAT (1H ,10F10.4)	A 532
174 FORMAT (1H0,*ORIGINAL DATA HAVE*,I5,* VARIABLES FOR*,I5,* OBSERVAT 1IONS.*)	A 533
175 FORMAT (1H0)	A 534
176 FORMAT (1H1)	A 535
END	A 536
	A 537
	A 538
	A 539
	A 540

## SUBROUTINE ACOM

C-----	B 1
C-----ACOM CALCULATES COEFFICIENTS FROM THE PARAMETER ESTIMATES.	B 2
DIMENSION A(12), T(35)	B 3
COMMON A,T,IN1,IN2,IN3	B 4
1 A(1)=T(IN2)+T(IN3)	B 5
A(2)=T(IN2)*T(IN3)	B 6
A(3)=T(IN2)	B 7
A(4)=T(IN3)	B 8
A(5)=T(IN1)+T(IN3)	B 9
A(6)=T(IN1)*T(IN3)	B 10
A(7)=T(IN1)	B 11
A(8)=A(1)+A(7)	B 12
A(9)=T(IN1)+T(IN2)	B 13
	B 14

AUTO REGRESSION PROGRAM WITH TWO LAG DISTRIBUTION

PAGE 1

```
A(10)=T(IN1)*T(IN2)
A(11)=A(9)*A(4)+A(10)
A(12)=A(10)*A(4)
RETURN
END
```

B  
B  
B  
B  
B

01 7 27 1 THIS IS THE GENERATED TEST DECK FOR MRHS-1 PROBCARE  
 52.625 59.250 .2888 45.567 46.2357 31.333 2701.12  
 55.375 61.833 .2888 35.567 45.2354  
 50.166 56.583 .2888 35.5674 45.234 31.333 2560.81  
 50.0000 62.0000 23.0000 45.0000 24.0000 24.0000 933.2568  
 50.0000 62.0000 23.0000 54.0000 19.0000 16.0000 1578.2488  
 54.0000 57.0000 27.0000 56.0000 30.0000 36.0000 2250.1733  
 55.0000 60.0000 54.0000 37.0000 35.0000 42.0000 2953.6896  
 55.0000 28.0000 45.0000 37.0000 34.0000 42.0000 3425.0970  
 47.0000 51.0000 27.0000 56.0000 14.0000 38.0000 3840.4712  
 49.0000 62.0000 54.0000 25.0000 8.0000 39.0000 3954.8383  
 61.0000 62.0000 45.0000 38.0000 12.0000 27.0000 3979.7188  
 64.0000 62.0000 47.0000 35.0000 31.0000 36.0000 4062.9793  
 60.0000 59.0000 48.0000 57.0000 30.0000 33.0000 4302.4975  
 55.0000 61.0000 6.0000 54.0000 40.0000 45.0000 4445.2611  
 61.0000 65.0000 24.0000 35.0000 32.0000 30.0000 4444.0656  
 56.0000 64.0000 45.0000 37.0000 31.0000 26.0000 4449.2607  
 59.0000 60.0000 58.0000 67.0000 24.0000 19.0000 4490.5426  
 54.0000 61.0000 23.0000 45.0000 30.0000 26.0000 4221.8082  
 54.0000 62.0000 34.0000 56.0000 20.0000 33.0000 4214.8520  
 53.0000 63.0000 26.0000 35.0000 12.0000 38.0000 4007.9200  
 53.0000 3.0000 26.0000 45.0000 14.0000 28.0000 3702.0653  
 54.0000 62.0000 37.0000 48.0000 22.0000 42.0000 3955.2186  
 55.0000 66.0000 56.0000 45.0000 32.0000 40.0000 4225.5609  
 56.0000 69.0000 34.0000 67.0000 36.0000 36.0000 4525.6412  
 54.0000 69.0000 37.0000 56.0000 43.0000 20.0000 4538.4640  
 59.0000 64.0000 26.0000 75.0000 33.0000 22.0000 4652.2580  
 66.0000 66.0000 47.0000 70.0000 34.0000 14.0000 4632.4896  
 1 2 2 2 7 099111 0.00010TWO LAG MODEL WITH AUTOREGRESSIVE ERRORS CONCARD2  
 2.2748 2.9439 4.1488 5.4830 0.1549 0.6837 0.4563 5.4936  
 7.1704

PROBLEM NUMBER - NO. VAR. - NO. OBS. - NO. JOBS  
 1            7            27            1

ORIGINAL DATA HAVE 7 VARIABLES FOR 27 OBSERVATIONS.

52.6250	59.2500	.2888	45.5670	46.2357	31.3330	2701.1200
55.3750	61.8330	.2888	35.5670	45.2354	-0.0000	-0.0000
50.1660	56.5830	.2888	35.5674	45.2340	31.3330	2560.8100
50.0000	62.0000	23.0000	45.0000	24.0000	24.0000	933.2568
50.0000	62.0000	23.0000	54.0000	19.0000	16.0000	1578.2488
54.0000	57.0000	27.0000	56.0000	30.0000	36.0000	2250.1733
55.0000	60.0000	54.0000	37.0000	35.0000	42.0000	2953.6896
55.0000	28.0000	45.0000	37.0000	34.0000	42.0000	3425.0970
47.0000	51.0000	27.0000	56.0000	14.0000	38.0000	3840.4712
49.0000	62.0000	54.0000	25.0000	8.0000	39.0000	3954.8383
61.0000	62.0000	45.0000	38.0000	12.0000	27.0000	3979.7188
64.0000	62.0000	47.0000	35.0000	31.0000	36.0000	4062.9793
60.0000	59.0000	48.0000	57.0000	30.0000	33.0000	4302.4975
55.0000	61.0000	6.0000	54.0000	40.0000	45.0000	4445.2611
61.0000	65.0000	24.0000	35.0000	32.0000	30.0000	4444.0656
56.0000	64.0000	45.0000	37.0000	31.0000	26.0000	4449.2607
59.0000	60.0000	58.0000	67.0000	24.0000	19.0000	4490.5426
54.0000	61.0000	23.0000	45.0000	30.0000	26.0000	4221.8082
54.0000	62.0000	34.0000	56.0000	20.0000	33.0000	4214.8520
53.0000	63.0000	26.0000	35.0000	12.0000	38.0000	4007.9200
53.0000	3.0000	26.0000	45.0000	14.0000	28.0000	3702.0653
54.0000	62.0000	37.0000	48.0000	22.0000	42.0000	3955.2186
55.0000	66.0000	56.0000	45.0000	32.0000	40.0000	4225.5609
56.0000	69.0000	34.0000	67.0000	36.0000	36.0000	4525.6412
54.0000	69.0000	37.0000	56.0000	43.0000	20.0000	4538.4640
59.0000	64.0000	26.0000	75.0000	33.0000	22.0000	4652.2580
66.0000	66.0000	47.0000	70.0000	34.0000	14.0000	4632.4896

JOBSNO	A	B	C	RHS	NSKIP	NITER	CONS	ERR	CORR	TEST	NWSSCP	TWO LAG MODEL WITH AUTOREGRESSIVE ERRORS
	1	2	2	7	0	99	1	1	1	.000010000	0	
ION MATRIX												
1	1.000											
2	.500	1.000										
3	.013	.444	1.000									
4	.207	.094	.049	1.000								
5	.358	.173	.072	.030	1.000							
6	.225	.333	.160	.078	.019	1.000						
7	.328	.055	.454	.103	.043	.394	1.000					
8	.181	.360	.003	-.058	.085	-.005	.151	1.000				
9	.199	.343	.345	.024	-.033	-.062	-.039	.342	1.000			
10	.205	.208	.291	.167	.126	.393	-.166	.169	.097	1.000		
11	.082	.094	.139	.356	.138	.086	-.179	-.110	.287	.203	1.000	
12	.230	-.131	-.012	-.179	.342	-.094	.021	-.161	.028	.148	.087	1.000
13	.451	.498	.485	.135	.129	.049	.115	.298	.549	.131	.176	.204
14	.638	.467	.356	.106	.103	.053	.081	.353	.496	.189	.178	.195
15	.441	.428	.439	.139	.090	.080	.004	.113	.400	.191	.163	.135
16	.410	.559	.228	.267	.331	.218	-.023	.136	.145	.338	.403	.086
18	.487	.528	.390	.146	.082	-.005	.731	.471	.632	.182	.725	.244

ITERATIVE CALCULATIONS FOR COEFFICIENT DETERMINATION

ITER	STEP	IDF	TSS	SSE	MSE	SSR	R SQUARE
2	1	14	.21607277E+08	.44189524E+08	.31563945E+07	-.22582246E+08	-.10451223E+01
3	1	14	.21607277E+08	.29256298E+07	.20897356E+06	.18681647E+08	.86459979E+00
4	1	14	.21607277E+08	.82266863E+06	.5919016E+05	.20778609E+08	.96164863E+00
5	1	14	.21607277E+08	.76844337E+06	.54888012E+05	.20819834E+08	.96443590E+00
6	1	14	.21607277E+08	.76638981E+06	.54884986E+05	.20318897E+08	.96443838E+00
7	1	14	.21607277E+08	.76638592E+06	.54884709E+05	.20818891E+08	.96443856E+00

VALUES OF PARAMETER ESTIMATES AT EACH ITERATION

	X 1	X 2	Z 1	Z 2	LAMBDA	MU	BETA	P 1	P 2
1	.117564E+02	.481304E-01	.861885E+01	.548309E+01	.154900E+00	.683700E+00	.456300E+00	.549360E+01	.717040E+01
2	.12089E+02	-.771418E+00	.801591E+01	.950675E+01	-.305561E+00	.147477E+01	-.614552E+02	.101065E+02	.282291E+02
3	.129914E+02	-.992371E-00	.810461E+01	.107036E+02	-.406335E-01	.101422E+01	-.529201E+00	.600216E+01	.285559E+02
4	.111774E+02	-.838607E-00	.820632E+01	.112166E+02	.248978E+00	.908576E+00	-.586731E+00	.686755E+01	.290232E+02
5	.110989E+02	-.860292E-00	.824738E+01	.990003E+01	.233209E+00	.870667E+00	-.570844E+00	.800101E+01	.277886E+02
6	.110476E+02	-.837231E-00	.825452E+01	.985452E+01	.734861E+00	.870752E+00	-.570463E+00	.795202E+01	.280459E+02

		THETA	D THETA	TEST	VARIANCE	STAND E	STUDENT T
1	X 1	.11042581E+02	.542293446E-01	.174788660E-04	.16865013E+03	.12986536E+02	.85030996E+00
3	Z 1	.8254705E+01	.7322533E-02	.33669575E-05	.9190982E+01	.30316659E+01	.27616282E+00
4	Z 2	.98545235E+01	-.45523815E-01	.78626779E-04	.1592533E+02	.39906431E+01	.2085151E+01
5	LAMBDA	.23486122E+00	-.19365600E-02	.93783682E-04	.26357674E+02	.51339725E+01	.19194734E+01
6	MU	.87086305E+00	.11133750E-03	.65312487E-05	.18979583E-02	.43555564E-01	.1989712E+02
7	BETA	-.57046266E+00	.36636801E-03	.21881322E-04	.6134560E-02	.78320853E-01	.72836625E+01
8	O 1	.79790991E+01	.27081245E-01	.19593688E-04	.37430160E+02	.61180193E+01	.13041965E+01
9	O 2	.28010397E+02	-.35456518E-01	.25851905E-04	.486229643E+02	.69734959E+01	.40166938E+01

SIZE OF INVERSE MATRIX      9      9  
INVERSE MATRIX

-.30736E-02							
-.12126E-04	.1675E-03						
-.4377E-03	-.3618E-04	.2902E-03					
-.4056E-03	-.3737E-04	-.2104E-04	.4802E-03				
-.1816E-04	-.2384E-06	-.5321E-05	.8755E-05	.7286F-06			
-.3101E-05	-.3520E-07	.1635E-05	-.1003E-05	-.1718E-06	.3458F-07		
-.4228E-03	+.8377E-05	.3699E-04	-.2991E-03	-.4999E-05	.9957E-08	.1118E-06	
-.6877E-03	-.6502E-04	-.9722E-04	.3553E-03	.8287E-05	-.8320E-07	-.6960E-08	
					-.7012E-07	-.2305E-03	.8860E-03

CONSTANT= -.14312853E+04

A0= -.92237572E+04

	OBSERVED Y	PREDICTED Y	RESIDUAL
1	.93325680E+03	* 1224443E+04	- .3298751E+03
2	* 15782488E+04	* 17450934E+04	- .1664459E+03
3	* 22501733E+04	* 18422301E+04	- .40746325E+03
4	* 29546896E+04	* 29101242E+04	- .4355426E+02
5	* 34220970E+04	* 34206667E+04	- .44302566E+01
6	* 18444712E+04	* 1511894E+04	+ .3285177E+03
7	* 39548383E+04	* 38054180E+04	+ .16942032E+03
8	* 39747188E+04	* 38874829E+04	+ .9225884E+02
9	* 400229793E+04	* 43077602E+04	+ .24480086E+01
10	* 43024975E+04	* 4336190E+04	+ .51121477E+02
11	* 44452611E+04	* 4505113E+04	+ .1255020E+03
12	* 44440656E+04	* 41609302E+04	+ .2813539E+03
14	* 44905426E+04	* 44068240E+04	+ .19059936E+03
15	* 42218082E+04	* 43888772E+04	+ .37185647E+01
16	* 42448520E+04	* 42816810E+04	+ .97069029E+02
17	* 40079200E+04	* 41126563E+04	+ .40671631E+03
18	* 31020653E+04	* 3805997E+04	+ .98534377E+02
19	* 3955211H6E+04	* 41479429E+04	+ .19272426E+03
20	* 42255609E+04	* 43497192E+04	+ .12415835E+03
21	* 45256412E+04	* 46449464E+04	+ .11930519E+03
22	* 45384640E+04	* 43816030E+04	+ .15686101E+03
23	* 46522580E+04	* 45865031E+04	+ .65751877E+02
24	* 46324896E+04	* 46381615E+04	+ .56719138E+01

DURBIN-WATSON D 1.44499196

VARIABLE MEANS AT	T	T-1	T-2	T-3
VARIABLE NO. X1	* 55583333E+02	* 54923583E+02	* 54772542E+02	
VARIABLE NO. X2	* 58333333E+02	* 57940958E+02	* 57850667E+02	
VARIABLE NO. Z1	* 36333333E+02	* 34387033E+02	* 33315713E+02	
VARIABLE NO. Z2	* 48958333E+02	* 47523642E+02	* 45880600E+02	
DEPENDENT VARIABLE	* 38244324E+04	* 37381124E+04	* 35442684E+04	* 34677124E+04
END OF JOBN0 1	* 31333333E+02			

## Program NLINEAR

### INTRODUCTION

NLINEAR is a generalized program for least-squares computation of nonlinear regressions, originally written by M. P. Lietzke (ORNL-3259, April 4, 1962) for an IBM 7090 computer. It is presented here in a modified form usable on the NCAR and SCOPE systems of a CDC 6400 computer.

The program is set up as a main program and a package of subroutines. The main program controls only input and output, so that the subroutines may be used separately in other FORTRAN programs to provide the complete nonlinear least squares analysis. A user-supplied, problem-specific subroutine must be included to define the functional form of the model to be fit and to define its partial derivatives with respect to the coefficients.

NLINEAR will provide a least squares fit to any function, linear or nonlinear, with up to eight coefficients and up to five independent variables. Weighting factors may either be defined or computed. The user must furnish a subroutine to define the function to be fitted and the partial derivatives with respect to the coefficients. The standard output of the calling program includes the values of the coefficients, the standard error in each coefficient, the variance of fit, and a point by point solution of the equation for each data point. The variance in the dependent variable is also computed for each data point. In addition, the inverse matrix may be printed out at the option of the user, as may the values of the parameters at each iteration.

### PROGRAM OPERATION

The calling program reads the data as outlined in Table 1, calls subroutine NLLS to compute the regression, prints appropriate error messages

if any are detected, prints the output, and checks to see if there is another set of data to be processed.

A listing of the complete program and associated subroutines is given below, as is a set of sample input and output.

Table 1. Input Data

Card No.	Field	Variable	Type	
1	1-72	Title	ALPHA	Up to 72 alphameric characters which will appear on each page of output.
2	1-4	NDP	INT	Number of data points $1 < \text{NDP} \leq 250$ .
	5-6	NP	INT	Number of coefficients $1 \leq \text{NP} \leq 8$ .
	7-8	NX	INT	Number of independent variables $1 \leq \text{NX} \leq 5$ .
	9-12	NIT	INT	Number of iterations allowed on given case.
	13-22	EPS	REAL	Epsilon, the maximum allowed fractional difference between successive values of the coefficients at convergence.
	23	ITP	INT	= 0, do not list parameters at each iteration = 1, list parameters at each iteration
	24	NINV	INT	= 0, do not list inverse matrix; = 1, list inverse matrix.
				The above variables are read with an (12A6/14,212,14,F10.0,211) format.
3	1-10	FACT	REAL	Step size of iterations Read with an (E 10.3) format.
4	1-80	FMT	Alpha	Variable format for the data (cards 6 - on below) Read with an (10 A 8) format.

Card No.	Field	Variable	Type	
5	1-10	GPI(1)	REAL	Guess on first coefficient
	11-20	GPI(2)	REAL	Guess on second coefficient.
	21-30	GPI(3)	REAL	Guess on third coefficient
	:	:	:	:
	61-70	GPI(6)	REAL	Guess on sixth coefficient
5	1-10	GPI(7)	REAL	Guess on seventh coefficient (omitted if NP < 7)
		Read with an (6 E 10.0) format		
6 - NDP + 5 ...	X	REAL	Independent variables = NX	
	Y	REAL	dependent variable	
	W	REAL	weighting factor (blank if none)	
		Read according to (FMT) above.		

The above sequence may be repeated for as many data sets as desired.

Two trailer cards must follow the last data set, the first containing ENDIT  
in columns 1-5, the second blank or any numeric characters.

#### Subroutine NLLS

The generalized least squares subroutine NLLS requires no common storage.  
To use the subroutine with any FORTRAN program it is necessary to include  
the following statements:

```
DIMENSION W(250), X(250,5), Y(250), GPI(8), STDE(8), YCALC(250), VARY(250),  
A(8,8), B(8), XTX(8,8), TB(8), CONV(8), DERIV(8), C(8,8), VMAT(8,8).  
CALL NLLS (W,X,Y,GPI,STDE,YCALC,VARY,NERR,EPS,NIT,NDP,ITP,VARF,VARF1,C,  
COREL,N).
```

The statement following the call of the subroutine NLLS should test the  
error indicator (NERR) and appropriate action should be taken if an error  
has occurred.

Note that the value of the independent variable is doubly subscripted.

The first index refers to the number of the data point and the second to the specified independent variable. For example, X(J,1) would refer to the jth data point of the first independent variable and X(J,5) to the jth data point of the fifth independent variable.

Subroutine NLLS calls a subroutine SUBRT which must be supplied by the user. This subroutine must evaluate the function to be fitted, the partial derivatives of the dependent variable with respect to the coefficients, the difference between the observed and calculated value of the dependent variable, and a statement on the weight to be assigned to each data point.

Subroutine NLLS does not have built-in scaling. Scaling must be done by the user, if necessary, on the data.

The following definitions apply:

W	Weighting factor (input, may be zero)
X	Independent variables
Y	Dependent variable
GP1	Initial guesses on the coefficients
STDE	Standard error in each coefficient
YCALC	Calculated value of Y for each data point using the converged values of the coefficients
VARY	Variance in Y
NERR	Error indicator
	1 = no error
	2 = singular matrix
	3 = non-convergence within the specified number of iterations
	4 = singular inverse matrix

EPS      Maximum allowed percentage difference between successive values  
          of the coefficients at convergence

NIT      Number of iterations to be allowed

NP      Number of coefficients ( $1 \leq NP \leq 8$ )

NDP      Number of data points

VARF      Variance of fit

VARF1       $VARF / \sum_i W_i$

C      Inverse matrix

Subroutine SUBRT

SUBRT must evaluate the model being fit at the point called for, compute the difference between the calculated and the measured values, evaluate the first derivatives of the model with respect to each parameter, and compute or specify the weighting factor to be used.

An example of this user supplied subroutine for a simple exponential model follows, where

$$Y = (A_1) (A_2)^X$$

so that  $\frac{\partial Y}{\partial A_1} = (A_2)^X$

$$\frac{\partial Y}{\partial A_2} = (A_1) (X) (A_2)^{X-1}$$

and assuming that all weights are unity.

```
SUBROUTINE SUBRT (J,W,X,U,GP1,DERIV,YC,F1,W1)
DIMENSION W(250),X(250,5),Y(250),GP1(8),DERIV(8)
YC=GP1(1)*GP1(2)**X(J,1)
G1=Y(J)-YC
DERIV(1)=GP1(2)**X(J,1)
DERIV(2)=GP1*X(J,1)*GP1(2)**(X(J,1)-1.)
W1=1.
RETURN
END
```

The following definitions apply:

- J Index on data point
- W Weighting factor (input, may be zero)
- X Independent variable
- Y Dependent variable (observed value)
- GP1 Guess on value of coefficient. Thus GP1(1)= $a_0$  and GP1(2)= $a_1$ , in the example above.
- DERIV Partial derivative of dependent variable with respect to coefficient.
- YC Value of dependent variable computed using the current guesses on the coefficients.
- F1 Difference between the observed and calculated value of the dependent variable.
- WI Weight assigned to data point.

In case specific weights are read in for each data point then the statement

$$WI = W(J)$$

would be made in the subroutine. In the event weights are to be computed, then the appropriate statement would be included in SUBRT. If all weights are unity then WI = 1.0.

Any subroutine SUBRT written would have the same arguments and dimension statement as in the example.

#### SAMPLE RUN OF PROGRAM

A listing of program NLINEAR follows along with a sample input and the resultant output.

```

PROGRAM NLNEAR
  I (INPUT,OUTPUT,TAPE5=INPUT,TAPE6=OUTPUT)
C PROGRAM MODIFIED FROM LIETZKE, M H 1962 A GENERALIZED LEAST SQUARES PROGRAM
C NONLINEAR LEAST SQUARES
C FOR THE IBM 7090 COMPUTER. ORNL-3259
  DIMENSION          W(250),X(250,5),Y(250),GP(8),GP1(8),TITLE(12),
  1STDE(8),YCALC(250),VARY(250),COREL(8,8),C(8,8)
  INTEGER FMT(10)
  COMMON FACT
  TYPE INTEGER YES, NO

C DEFINITIONS
C EPS MAX ALLOWED PERCENTAGE DIFFERENCE BETWEEN SUCCESSIVE VALUES OF THE
C COEFFICIENTS AT CONVERGENCE (EX. .002-.005)
C NIT NO. OF ITERATIONS TO BE ALLOWED (EX. 50)
C NP NO. OF COEFFICIENTS (1=NP=8)
C NUMBER OF X'S TO BE READ IN (5 FOR THIS PROGRAM)
C NDP NUMBER OF DATA POINTS
C ITP 0 = DO NOT LIST PARAMETERS AT EACH ITERATION
C      1 = LIST PARAMETERS AT EACH ITERATION
C NINV 0 = DO NOT LIST INVERSE OF VARIANCE-COVARIANCE MATRIX
C      1 = LIST MATRIX
C FACT CONTROLS STEP SIZE (E.G. 0.5)
C FMT VARIABLE FORMAT

```

NO=HHNO  
YES=HHYES

C READ TITLE CARD AND CONTROLS AND READ DATA FORMAT

```

20 READ 1, TITLE,NDP,NP,NX,NIT,EPS,ITP,NINV
  IF (TITLE(1).EQ.5)HENDIT) STOP
  READ 3, FACT
  READ 99, FMT

```

C READ INITIAL ESTIMATES OF PARAMETERS
 READ 2, (GP(I),I=1,NP)

C READ WEIGHTS ,Y, X VALUES.

```

DO 18 I=1,NP
18 READ FMT,(X(I,J),J=1,NX),Y(I),W(I)
  PRINT 201, PRINT 202,TITLE, PRINT 203,NDP, PRINT 204,NP
  PRINT 205, NX, PRINT 206,NIT, PRINT 207, EPS
  IF (ITP.EQ.1)32,31
32  PRINT 208, YES
  GO TO 33
33  PRINT 208, NO
34  IF (NINV.EQ.1)34,35
35  PRINT 209, YES
  GO TO 36
36  PRINT 209, NO
  CONTINUE
  PRINT 210, FACT, PRINT 211,FMT

```

C SET ASIDE INITIAL ESTIMATES

```

DO 21 I=1,NP
21 GP1(I)=GP(I)

```

23120205  
23120207

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CALL NLLS(W,X,Y,GP1,STDE,YCALC,VARY,  
INERR,EPS,NIT,NP,NDP,ITR,VARF,VARF1,G,COREL,N)

C CHECK IF AN ERROR HAS OCCURRED

IF (NERR .LE. 4) 501,502  
501 GO TO (30,100,101,102),NERR  
502 NERR=NERR-4 3 PRINT 21,NERR \$100 TO 20

C WRITE OUTPUT TITLE, COEFFICIENTS, ST. ERRORS,

30 WRITE (6,7) TITLE  
DO 130 I=1,NP  
130 WRITE (6,8) I,GP1(I),STDE(I)

C WRITE APPROPRIATE COLUMN HEADINGS

GO TO (50,51,52,53,54),NX  
50 WRITE(6, 9) VARF,VARF1  
GO TO 55  
51 WRITE(6,10) VARF,VARF1  
GO TO 55  
52 WRITE(6,11) VARF,VARF1  
GO TO 55  
53 WRITE(6,12) VARF,VARF1  
GO TO 55  
54 WRITE(6,13) VARF,VARF1

C WRITE OBSERVED AND PREDICTED VALUES AND NO. OF ITERATIONS

55 DO 56 I=1,NDP  
56 WRITE (6,14) Y(I)+YCALC(I),VARY(I),GX(I,J) J=1,NX)  
WRITE (6,153) N

C GIVE INVERSE MATRIX IF REQUESTED

160 IF (NINV) 60,20,60  
60 WRITE (6,15)  
DO 61 I=1,NP  
61 WRITE (6,16) (C(I,J),J=1,NP)

C WRITE CORRELATION MATRIX

WRITE (6,200)  
DO 161 I=1,NP  
161 WRITE (6,16) (COREL(I,J),J=1,NP)  
GO TO 20

C ERROR MESSAGE FOR SINGULAR MATRIX

100 WRITE (6,19) TITLE  
WRITE (6,150)  
GO TO 20

C ERROR MESSAGE FOR NON CONVERGENCE

101 WRITE (6,19) TITLE  
WRITE (6,151) NIT  
GO TO 20

C ERROR MESSAGE FOR SINGULAR INVERSE

231808

231210



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```
102 WRITE (6,19) TITLE
      WRITE (6,152)
      GO TO 20
```

## C FORMATS

```

1  FORMAT(12A6/I4,2I2,I4,F10.0,2I1)
2  FORMAT(6E10,0)
3  FORMAT(E10.3)
7  FORMAT(1H112A6/32H0      PARAMETER      STD ERROR)
8  FORMAT(3H0 A,I1.1PF14.5,E15.5)           VARF1,E15.5/
9  FORMAT(7H0  VARF,1PF15.5,10H      Y(OBS)      Y(CALC)    VAR(Y)      X(1))
10 FORMAT(7H0  VARF,1PF15.5,10H      Y(OBS)      Y(CALC)    VARF1,E15.5/
11 152H0          Y(OBS)      Y(CALC)    VAR(Y)      X(1)
12 214H          X(2)          X(3)          VARF1,E15.5/
13 152H0          Y(OBS)      Y(CALC)    VAR(Y)      X(1)
14 228H          X(2)          X(3)          VARF1,E15.5/
15 152H0          Y(OBS)      Y(CALC)    VAR(Y)      X(1)
16 242H          X(2)          X(3)          VARF1,E15.5/
17 152H0          Y(OBS)      Y(CALC)    VAR(Y)      X(1)
18 256H          X(2)          X(3)          VARF1,E15.5/
19 152H0          Y(OBS)      Y(CALC)    VAR(Y)      X(1)
20 256H          X(2)          X(3)          VAR(Y)      X(4)      X(5)
21 14 FORMAT(1H01P8E14.5)
22 15 FORMAT(//2UH0      INVERSE MATRIX)
23 FORMAT(1H0,10F9.3)
24 19 FORMAT(1H112A6)
25 99 FORMAT(10AB)
26 150 FORMAT(16H0SINGULAR MATRIX)
27 151 FORMAT(2UH0UDID NOT CONVERGE INI4,
28     111H ITERATIONS)
29 152 FORMAT(24H0SINGULAR INVERSE MATRIX)
30 153 FORMAT(13H0CONVERGED INI4,11H ITERATIONS)
31 200 FORMAT(//24H0      CORRELATION MATRIX)
32 201 FORMAT(1H1,*CONTROL VARIABLES*)
33 202 FORMAT(1H0,*TITLE*,2X,12A6)
34 203 FORMAT(1H0,*NP      NUMBER OF DATA POINTS*,15X,I4)
35 204 FORMAT(1H0,*NP      NUMBER OF PARAMETERS*,16X,I2)
36 205 FORMAT(1H0,*NX      NUMBER OF X $*23X,I2)
37 206 FORMAT(1H0,*NIT     NUMBER OF ITERATIONS ALLOWED*,8X,I4)
38 207 FORMAT(1H0,*EPS     ALLOWABLE DIFFERENCE IN ESTIMATES   *,E13.4)
39 208 FORMAT(1H0,*ITP     PRINT CONTROL ITERATIONS*,13X,A8)
40 209 FORMAT(1H0,*NINV    PRINT INVERSE*,24X,A8)
41 210 FORMAT(1H0,*FACT    ADJUSTMENT CORRECTION FACTOR*,9X,F5.3)
42 211 FORMAT(1H0,*FMT     VARIABLE FORMAT*,22X,5AB/5AB)
43 212 FORMAT(1H0*DERRIVATIVE WRT PARAM NO *15* IS ZERO FOR ALL DATA PTS*)
44 END
```

231209

```
SUBROUTINE NLLS(W,X,Y,GP1,STDE,YCALC,VARY,
1NERR,EPS,NIT,NP,NOP,ITP,VARF,VARF1,C,COREL,N)
DIMENSION W(250),X(250,5),Y(250),GP1(8),
1STDE(8),YCALC(250),VARY(250),COREL(8,8),
2A(8,8),B(8),XTX(8,8),TB(8),CONV(8),DERIV(8),C(8,8),
3VMAT(8,8),R(8)
COMMON FACT
```

C SET NERR AS ERROR MESSAGE CONTROL

```
NERR=1
```

14800604

C ZERO OUT VARIABLES

```
DO 118 N=1,NIT
DO 119 L=1,NP
B(L)=0.0
DO 110 M=1,NP
110 A(L,M)=0.0
```

23120213  
23120219  
23120221  
23120223  
23120229

C SEE IF ESTIMATES OF COEFFICIENTS TO BE WRITTEN AT EACH ITERATION

```
IF (ITP)21,21,20
21 WRITE (6+2) N,(GP1(I)+I=1,NP)
```

C CALL USERS SUBROUTINE TO DEFINE FUNCTION AND PARTIAL DERIVATIVES

```
21 DO 111 J=1,NOP
```

```
CALL SUBRT(J,W,X,Y,GP1,DERIV,YC,F1,WI)
```

14800303

C MODIFY THE COEFFICIENTS

```
50 DO 111 L=1,NP
B(L)=B(L)+DERIV(L)*F1*WI
```

23120305  
23120307

C SET UP MATRIX OF SS AND CP AND SET IT ASIDE TO BE INVERTED

```
DO 111 M=L,NP
111 A(L,M)=A(L,M)+DERIV(L)*DERIV(M)*WI
DO 112 M=2,NP
K=M-1
DO 112 I=1,K
112 A(M,I)=A(I,M)
DO 212 L=1,NP
DO 212 M=1,NP
212 XTX(L,M)=A(L,M)
```

23120309  
23120311  
23120313  
23120315  
23120317  
23120319  
23120321  
23120323  
23120325

```
CALL INVERT(XTX,NP,1.0E-30,NEROR,DELTA)
```

C SEE IF MATRIX WAS SINGULAR

```
IF (NEROR)113+114,113
113 NERR=2
GO TO 200
```

14800506

C ALTER ESTIMATES OF COEFFICIENTS AND CHECK FOR CONVERGENCE

```

114 DO 230 I=1,NP
      DO 230 J=1,NP
230 C(I,J)=XTX(I,J)
240 DO 215 I=1,NP
      R(I)=0.0
      DO 215 J=1,NP
215 R(I)=R(I)+XTX(I,J)*R(J)
      DO 216 I=1,NP
      BETA=FACT#GPI(I)
      COR=SIGN(AMIN1(ABS(R(I)),ABS(BETA)),R(I))
216 TB(I)=GPI(I)*COR
      DO 116 I=1,NP
      CONV(I)=ABS(GPI(I)/TB(I)-1.0)
      IF(CONV(I)-EPS)116,116,117
116 CONTINUE
      GO TO 120
117 DO 118 I=1,NP
118 GPI(I)=TB(I)
      NEPR=3
      GO TO 200

```

C GO BACK TO USERS SUBROUTINE THEN CALCULATE ST. DEV., VARIANCE, E.T.C.

```

120 DO 121 I=1,NP
121 GPI(I)=TB(I)
      SUMW=0.0
      VARF=0.0
      DO 122 J=1,NDP
      CALLSUBRT(J,W,X,Y,GPI,DERIV,YC,F1,WI)
      VARF=VARF+WJ*F1**2
122 SUMW=SUMW+WI
      VARF=VARF/(FLOAT(NDP)-FLOAT(NP))
      VARF1=VARF/SUMW
123 DO 123 I=1,NP
      DO 123 J=1,NP
      COREL(I,J)=C(I,J)/SQRT(C(I,I)*C(J,J))
124 VMAT(1,J)=C(I,J)*VARF
      DO 129 I=1,NP
129 STD(E)=SQRT(VMAT(1,E))
      DO 136 J=1,NDP
      CALL SUBRT(J,W,X,Y,GPI,DERIV,YC,F1,WI)
      VY=0.0
      CALC(J)=YC
      DO 135 I=1-NP
      DO 135 K=1,NP
134 VY=VY+(DERIV(I)*DERIV(K)*VMAT(I,K))
13K VMAT(J)=VY
200 RETURN
      END
      FORMAT(1H01ITERATION15,5X,10HPARAMETERS/(1H01P7E15,7))

```

SUBROUTINE INVERT(A,N,EPS,NEROR,DELTA)

C MATRIX INVERSION BY GAUSS-JORDAN ELIMINATION

DIMENSION A(8,N),B(R),C(8),LZ(8)

```

DELTA=1.0
NEROR=0
DO 10 J=1,N
10 LZ(J)=J
DO 20 I=1,N
K=I
Y=A(I,I)
L=I-1
LP=I+1
IF(N-LP)14,11,11
11 DO 13 J=LP,N
W=A(I,J)
IF(ABS(W)-ABS(Y),13,13,12
13 K=J
Y=W
13 CONTINUE
14 DELTA=DELTA*Y
DO 15 J=1,N
C(J)=A(J,K)
A(J,K)=A(J,I)
A(I,J)=C(J)/Y
A(I,I)=A(I,J)/Y
15 B(J)=A(I,J)
A(J,I)=1.0/Y
J=LZ(I)
LZ(I)=LZ(K)
LZ(K)=J
DO 19 K=1,N
1F(I-K)16,19,16
16 DO 18 J=1,N
1F(I-J)17,18,17
17 A(K,J)=A(K,J)-B(J)*C(K)
18 CONTINUE
19 CONTINUE
20 CONTINUE
IF(ABS(DELTA)-EPS)R0,80,81
80 NEROR=1
GO TO R2
81 DO 200 I=1,N
IF(I-LZ(I))100,200,100
100 K=I+1
IF(I=N)800,200,200
800 DO 500 J=K,N
IF(I-LZ(J))500,600,500
500 M=LZ(I)
LZ(I)=LZ(J)
LZ(J)=M
DELTA=-DELTA
DO 700 L=1,N
C(L)=A(I,L)
A(I,L)=A(J,L)
700 A(J,L)=C(L)
500 CONTINUE

```

JTINE INVERT FORTRAN EXTENDED VERSION 2.0

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\*01.07.3

20e CONTINUE  
82 RETURN  
END

JTINE SURRT FORTRAN EXTENDED VERSION 2.0

03/14/70

\*01.07.39.

```
SUBROUTINE SUBRT (J,W,X,Y,GPI,DERIV,YC,F1,WI)
DIMENSION W(250),X(250,5),Y(250),GPI(8),DERIV(8)
YC=GPI(1)*GPI(2)**X(J,1)
F1=Y(J)-YC
DERIV(1)=GPI(2)**X(J,1)
DERIV(2)=GPI(1)*X(J,1)*GPI(2)**(X(J,1)-1.)
WI=1.
RETURN
END
```

INPUT DECK FOR SAMPLE RUN OF NLINEAR

EXAMPLE - EXPONENTIAL FIT OF DUCK WEED GROWTH

14 2 1 30 .00500

0.5

(3F5.0)

79. 1.4

0 100

1 127

2 171

3 233

4 323

5 452

6 654

7 918

8 1406

9 2150

10 2800

11 4140

12 5760

13 8250

ENDIT

00000

## CONTROL VARIABLES

TITLE	EXAMPLE - EXPONENTIAL FIT OF DUCK WEED GROWTH	
NDP	NUMBER OF DATA POINTS	14
NP	NUMBER OF PARAMETERS	2
NX	NUMBER OF X'S	1
NIT	NUMBER OF ITERATIONS ALLOWED	30
EPS	ALLOWABLE DIFFERENCE IN ESTIMATES	.5000E-02
ITP	PRINT CONTROL ITERATIONS	NO
NINV	PRINT INVERSE	NO
FACT	ADJUSTMENT CORRECTION FACTOR	.500
FMT	VARIABLE FORMAT	(1F5.0)

EXAMPLE - EXPONENTIAL FIT OF DUCK WEED GROWTH

PARAMETER	STD ERROR		
A1	8.38948E+01		
A2	1.42329E+00		
VARF	3.23843E+03		
VARF1	2.31817E+02		
Y(OBS)	Y(CALC)	VAR(Y)	X(I)
1.00000E+02	8.38948E+01	1.29524E+01	0.
1.27000E+02	1.19407E+02	2.21084E+01	1.00000E+00
1.71000E+02	1.69950E+02	3.71463E+01	2.00000E+00
2.33000E+02	2.41889E+02	5.12440E+01	3.00000E+00
3.23000E+02	3.44274E+02	9.86746E+01	4.00000E+00
4.52000E+02	4.90007E+02	1.54493E+02	5.00000E+00
6.54000E+02	6.97422E+02	2.33233E+02	6.00000E+00
9.18000E+02	9.92634E+02	3.35733E+02	7.00000E+00
1.40600E+03	1.41281E+03	4.53302E+02	8.00000E+00
2.15000E+03	2.01083E+03	5.60498E+02	9.00000E+00
2.80000E+03	2.86200E+03	6.16632E+02	1.00000E+01
4.14000E+03	4.07346E+03	6.15447E+02	1.10000E+01
5.76000E+03	5.79771E+03	8.08301E+02	1.20000E+01
8.25000E+03	8.25183E+03	2.46155E+03	1.30000E+01

CONVERGED IN 3 ITERATIONS

## Furnival's SCREEN

### INTRODUCTION

This program was developed as a partial solution for the problem of selecting from a large group of independent variables a small number to be used as predictors in a regression equation. This program enables the user to compute all possible regressions within given constraints. Obviously it is not feasible to compute all possible regressions when the number of independent variables is large, but it is perfectly feasible to compute more than the one regression produced by a step-wise program. This program allows the user to restrict regression computation to combinations of independent variables which meet one or more of four optional constraints.

1. A number of independent variables may be fixed or forced to appear in every regression. This is designed for use when the investigator is sure that one or more variables must appear in the final regression equation.
2. The maximum number of independent variables appearing in any regression may be limited to less than the total number of independent variables.
3. Independent variables may be placed in sets such that if one variable in a set is present in a regression, all variables in that set will be present. This constraint effectively reduces the dimensions of a screening problem because a set of variables is treated essentially as a single variable by the program. R-squares are computed only for those regressions which either include every variable of a set or will fit every variable of a set.
4. Variables may be placed in groups such that if one member of a group is present in a regression no other member of a group will be present. The members of a group may be either individual variables or sets of

variables. This constraint is especially useful when one wishes to screen a number of possible transforms of each of several basic variables with the intention of retaining no more than one transform of each variable in the final prediction equation.

The description of the constraints above give ample evidence as to the value and the utility of this program in reducing a large number of measured variables to a smaller workable group. The output does not give the regression coefficient, any measure of the correlation between independent variables, i.e., partial r-squares, or other statistics about the data which would be necessary in a final analysis. Thus this program should be viewed as but one step in obtaining a prediction equation from a raw set of independent variables. One other utility of this program is the fact that it allows the user to compute regressions against up to four dependent variables.

The primary limitation of the program is that the number of regressions to be computed must be less than the quantity

$$\frac{15,000}{NY + 1}$$

where NY is the number of independent variables. Therefore, when none of the four optional constraints given above is employed, the maximum number of independent variables is limited to 12 for one or two, 11 for three through six, and 10 for seven or eight dependent variables. With the inclusion of one or more constraints decreasing the number of regressions below the allowable maximum, then the total number of dependent and independent variables may be as large as 50.

The program is written in FORTRAN and operates on the CDC 6400 computer utilizing the NCAR or SCOPE compilers.

## Input Control Cards With Options for Constraints

*Card preparation.*

<u>Card</u>	<u>Column</u>	<u>Description</u>
1	1-72	Job title, alphanumeric.
2	1	Label card ( $b = 1$ = labels furnished by program, $1 =$ labels on card 5).
2	2	Set card ( $b = 1$ = all sets have one variable, $1 =$ set sizes on card 7).
3	3	Group card ( $b = 1$ = all groups have one set, $1 =$ group sizes on card 8).
4	4	Intercept flag ( $b = 1$ = intercepts, $1 =$ no intercept).
5	5	Format card ( $b = 1$ = no second format card, $1 =$ more formats on card 4).
	6-10	Number of observations.
	19-20	Number (of sets) of independent variables not fixed.
	30	Number of dependent variables ( $b = 1$ ).
	39-40	Number (of sets) of fixed independent variables ( $b = 0$ ).
	49-50	Large number (of sets) of independent variables not fixed to be included in any regression ( $b = 1$ ).
	59-60	Total number of variables before transformations ( $b = 1$ = same as after transformations).
	61-62	Number of transformations per observation ( $b = 1$ ).
3	1	Left parenthesis.
	2-72	Format of data (only E or F type formats are permitted). Followed by right parenthesis.
4	1-72	Continuation of data format (omit card 4 if column 5 of card 2 is blank).

<u>Card</u>	<u>Column</u>	<u>Description</u>
5	1- 4	Alphanumeric label for the first set of independent variables.
	5- 8	Same for second set. Continue for labels of all independent variable(s); omit if column 1 of card 2 is blank.
6	1-72	Continuation of labels if needed.
7	1- 2	Number of variables in first set of independent variables.
	3- 4	Same for second set. Continue for all variables in remaining sets using two columns for each set. (Omit card 7 if column 2 of card 2 is blank.)
8	1- 2	Number of groups of independent variables.
	3- 4	Number of sets of independent variables in first group.
	5- 6	Number of sets of independent variables in second group.
		Continue for all groups of variables using two columns for each group. (Omit card 8 if column 3 of card 2 is blank.)
9		Transformation control cards. (Omit these cards if columns 61-62 of card 2 is blank or zero.) For each transformation there must be one transformation control card. At the end of the transformation procedure, the dependent variables must follow all the independent variables. A list of transformations is included below.
	1- 2	Number of the transformation from the list (below).
	3- 4	Number of the resultant (transformed) variable.
	5- 6	Number of the first variable in the transformation (on the right of the "=" sign).
	7- 8	Number of the second variable (if two variables are involved in the transformation).
	or	
	7-14	Constant term (c) punched with decimal point.

<u>Card</u>	<u>Column</u>	<u>Description</u>
10		Your observational data deck.
11	1- 4	Punch DONE or QUIT. Punch QUIT if this is the last or only data set to be processed. If another data set and set of control cards follow, punch DONE.

A few points on the above control cards may need further clarification. For example, on the second control card, the number of variables referred to in columns 39-40 refer to the total number of variables, both dependent and independent. In connection with the labels, the labeling of independent variables is by sets, and one set receives one label regardless of the number of variables in the set. A label must be supplied for each dependent variable also. Card 7 also needs some additional explanation. The rules that must be followed are as follows:

1. Each independent variable whether fixed or unfixed must be assigned to a set.
2. Fixed variables and variables that are not fixed cannot be assigned to the same set.
3. The number of variables in each set must be punched on card 7 even though a particular set may contain only one variable.
4. The number of variables are punched in the order in which the sets occur in the observation vector.

The group constraint card, control card 8, is similar to that described for the set constraint. The major difference is that fixed variables are ignored in the group constraint; group assignment begins with the first variable not fixed. Basic rules to follow are listed as follows, the parenthesized material is meaningful only when the set constraint is also used:

1. Each (set of) independent variable that is not fixed must be assigned to a group.
2. The number (of sets) of variables in each group must be punched on card 8 even though some groups may contain only one (set of variables).
3. The number (of sets) of variables are punched in the order in which groups occur in the observation vector.

The following transformations may be called by the numbers given on the left (enter this number in columns 1-2 of card 9).

**t = resultant variable (columns 3-4 of card 9).**

**u = first variable in the transformation (columns 5-6 of card 9).**

**v = second variable in the transformation, if used (columns 7-8 of card 9).**

**c = constant, punched with decimal point (columns 7-14 of card 9).**

01	$t = u$
02	$t = c * u$
03	$t = c + u$
04	$t = u + v$
05	$t = u * v$
06	$t = u/v$
07	$t = 1/u$
08	$t = u^c$
09	$t = \ln_e u$
10	$t = e^u$
11	$t = \log_{10} u$

```
12      t = original value of u regardless of previous  
           transformations on u  
13      t = sin (u)  
14      t = cos (u)  
15      t = u/c  
16      t = |u|  
17      call user written subroutine TR0BS
```

#### SAMPLE RUN OF PROGRAM

Following is a listing of SCREEN, a sample input deck and the output generated.

PROGRAM

SCREEN FORTRAN EXTENDED VERSION 2.0

03/14/70

```
      PROGRAM SCREEN
      1 (INPUT,OUTPUT,TAPE5=INPUT,TAPE6=OUTPUT,TAPE1)
CMAIN SCREEN PROGRAM 5/12/64
      DIMENSION NR(30),NV(30),Z(50,17),ND(51),A(14000),NS(31),NDA(31),
05   ISS(10),R(50,9),X(50,),T(30),FMT(24),ISF(30),RA(10),IT(17),NW(50),
      ZNRX(30),SC(51),TY(1),MSC(31),D(31),NG(30),NDG(18),TT(12),NAD(31),
      3KNT(30),NK(17),RN(30),NU(17),C(20),NT(30)
      COMMON/BANK/NR,NV,IT,ND,A,NS,NDA,SS,R,X,T,FMT,Z,ISF,RA,NRX,SC,IA,
10   1IB,IN,IM,KC,LN,PZ,NFA,KNT,N,NP,NY,KRT,NSET,NOB,NCP,MSM,NGX,DF,
      2D,TY,NS,NG,NVR,IS,TE,NYT,TT,NAD,NDG,NO,C,NT,NIF,ZERO,RN,ON,NK,
      3NYY,NVS,LA,NW,LMA
      COMMON/L1/DONE
      INTEGER DONE
      XADF(I,J,NN)=NN-(IND-I+1)*(NP-I))/2-(NP-J)
15   C
      C
      1 CALL ROMNT
      CTEST FOR CONTROL CARD ERROR
      1F(PZ) 3,4,3
20   3 GO TO 1
      4 CALL INITL
      C
      C
      CSKIP MEAN FOR ZERO INTERCEPT
25   C
      IF(NIF) 6,5,6
      CSUMS OF SQUARES AROUND MEAN
      C
      5 IS=1
      1E=1
      CALL MEAN
      6 DO 37 I=NYT,NP
          II=XADF(I,I,NAD(1))
      K=I-NYT+1
35   37 SS(K)=A(II)
      7 IF(NF) 9,14,9
      C
      CFIXED VARIABLES
      C
      9 IS=2
      DO 10 J=1,NF
      1E=ND(I,S)
      J=NF-M+1
      CALL MEAN
      IS=IE+1
45   CCOMPUTE R-SQUARES FOR FIXED SETS
      DO 43 I=NYT,NP
          II=XADF(I,I,NAD(1))
          K=I-NYT+1
      43 R(J,K+1)=1.0-A(II)/SS(K)
          R(J,1)=DF
          IN NW(J)=0
      C
      CFIRST X AFTER FIXED,SKIP COUNTER
      C
      14 D(1)=DF
      IM=1
      IN=0
      KC=LN
      LB=NSET
```

```

LA=LB
NV(1)=1
GO TO 61

C
65 COUNTER LOOP
C
38 J=1
39 DO 40 I=J,KRT
IF(KNT(I)) 40,41,40
40 KNT(I)=1
GO TO 42
41 KNT(I)=0
GO TO 600
42 IN=NKS-I
KC=NV(IN)-LM
CTEST FOR LIMIT AND OLD ILLEGAL GROUP COMBINATION
IF(KC) 20,21,20
20 IF(ISF(IN)) 21,193,21
CSTEP COUNTER
80 21 J=I
GO TO 39

C
CTEST FOR AND WRITE FULL BLOCK
C
85 193 IM=IN+1
NV(IM)=NV(IN)+1
IF(LB+I-50) 197,197,196
194 WRITE(1)LB
WRITE(1)(NW(L),(R(L,M),M=1,NYY),L=1+LB)
LB=0
197 LH=LB+1
LA=LB

C
CMAJOR REDUCTION LOOP
C
95 61 DO 127 IA=IM,NKS
IA=IA
N=NK(IA)
IB=IA+1
ISF(IA)=""
100 CCHECK FOR NEW ILLEGAL GROUP COMBINATION
MOT=IA-IN
IF(MOT-MSC(IM)) 66,46,68
66 ISF(IA)=1
LB=LB+1
LA=LB
GO TO 127
68 CALL MJLOOP

C
110 CLOAD BLOCKS, STEP LOADING INDEX, AND COUNT REGRESSIONS
C
NW(LA)=NV(IA)
K(LA,1)=U(IB)
LA=LA+1
115 K=NV(IA)
NO(K)=NO(K)+1
127 NV(IB)=NV(IA)
GO TO 38

C
CWRITE PARTIAL BLOCK AT END OF COMPUTATIONS

```

PROGRAM

SCREEN FORTRAN EXTENDED VERSION 2.0

03/14/70

001

```
C
125      600 WRITE(1)LB
              WRITE(1)(NW(L), (R(L,M), M=1,NYY), L=1,LB)
C
COVERALL R-SQUARES
C
130      IF (NXS-LM) 601,201,601
601  LS=NFA+2
      IE=NP-NY
      CALL MEAN
      DO 116 I=NYT, NP
              I1=XADEF(I,I,NAD(1))
      K=I-NYT+1
      116 RA(K)=1.0-A(I1)/SS(K)
C
135  CMAIN PRINT LOOP
C
140      201 NVA=99
              WRITE(1)NVA
              REWIND 1
              CALL MPRINT
C --- CHECK FOR QUIT CARD SIGNIFYING END OF RUN
      IF (DONE.EQ.4HQUIT) STOP
      GO TO 1
END
```

SIBFTC BAT11 DECK

SUBROUTINE CTEST(I,J,K,L)  
 DIMENSION NR(30),NV(30),Z(50,17),ND(51),A(14000),NS(31),NDA(31),  
 1SS(10),R(50,9),X(50),T(30),FMT(24),ISF(30),RA(10),IT(17),NW(50),  
 2NRX(30),SC(51),TY(1n),MSC(31),D(31),NG(30),NDG(18),TT(12),NAD(31),  
 3KNT(30),NK(17),RN(30),GN(30),NO(17),C(20),NT(30)  
 COMMON/SANK/NR,NV,IT,ND,A,NS,NDA,SS,R,X,T,FMT,Z,ISF,RA,NRX,SC,IA,  
 1IB,IN,IM,KC,LM,PZ,NF,NFA,KNT,N,NP,NY,KRT,NSET,NOB,NCP,MSC,NGX,DF,  
 2D,TY,NS,NG,NVR,IS,IE,NYT,TT,NAD,NDG,NO,C,NT,NIF,ZERO,RN,ON,NK,  
 3NYY,IVS,LA,NW,LMA

C

1 DATA ASK/IH\*/  
 2 IF(I=K) 4,2,4  
 2 IF(J=1) 5,5,4  
 4 C(L)=ASK  
 PZ=1  
 5 RETURN  
 END

05

10

15

51BFTC BASIC DECK

```
SUBROUTINE MATOUT (A,NVS,NY,T,TY,TT)
DIMENSION A(14000),T(30),TY(10),TT(12)
A(1)=A(1)
NVS=NVS
NY=NY
T(1)=T(1)
TY(1)=TY(1)
TT(1)=TT(1)
RETURN
END
```

05

10

```

5      STHFTC BAT13 DECK
       SUBROUTINE INITL
       DIMENSION NR(30),NV(30),Z(50,17),ND(5),A(14000),NS(31),NDA(31),
       1SS(10),R(50,9),X(50),T(30),FMT(24),ISF(30),RA(10),IT(17),NW(50),
       2NRX(30),SC(51),TY(10),MSC(31),D(31),NG(30),NDG(18),TT(12),NAD(31),
       3KNT(30),NK(17),RN(30),GN(30),NU(17),C(20),NT(30)
       COMMON/HANK/NR,NV,IT,ND,A,NS,NDA,SS,R,X,T,FMT,Z,ISF,RA,NRX,SC,IA,
       1IB,IN,IM,KC,LN,PZ,NF,NFA,KNT,N,NP,NY,KPT,NSET,NOB,NCP,MSK,NGX,DF,
       2D,TY,NS,NG,NVR,IS,TE,NYT,TT,NAD,NDG,NO,C,NT,NIF,ZERO,RN,BN,NK,
       3NY,NVS,LA,NW,MA
       XADF(I,J,NN)=NN-((NP-I+1)*(NP-I))/2-(NP-J)

15     C
       1 REWIND 1
       UF=1.0

20     C
       COMPUTE NUMBER OF FIXED X'S
       C
       NFA=0
       IF (NF) 9,11,9
       9 DO 10 I=1,NF
       10 NFA=NFA+NRX(I)

25     C
       INDEX OF FIRST Y
       C
       11 NYT=NP-NY+1
       C
       C
       MOVE SET SIZES UP, ZERO COUNTR, COMPUTE ORDERS AND LAST ADDRESSES OF SUB-
       CMATRICES
       C
       KRT=NXS-1
       NN=(NP+1)*NP
       NAD(1)=NN/2
       NS(1)=VS-NFA
       DO 33 I=1,NXS
       KNT(I)=0
       INF=I+NF
       NR(I)=NRA(INF)
       NS(I+1)=NS(I)-NR(I)
       NN=(NS(I)-1)*NS(I)
       33 NAD(I+1)=NAD(I)+NN/2

35     C
       COMPUTE DETERMINANT DIVIDERS
       C
       DO 35 I=1,NP
           IJ=XADF(I,I,NAD(1))
       35 SC(I)=A(IJ)

40     C
       COMPUTE NUMBER SETS REMAINING IN GROUP AND INDEX OF FIRST X IN NEXT
       CGROUP
       C
       MBD
       NZ=NFA+2
       MSC(1)=1
       55 L=0
       DO 20 I=1,NGX
           JE=NG(I)
           DO 21 J=1,JE
               L=L+1
               MSC(L+1)=NG(I)-J

```

## SUBROUTINE INITL FORTRAN EXTENDED VERSION 2.0

03/14/70

```

21 NZ=NZ+NR(L)
   DO 20 K=1,JE
      M=M+1
20  NOA(M)=NZ
65
C
CCOMPUTE INDEX OF LAST X IN SET
C
   L=1
   NZ=1
70
DO 22 I=1,NSET
   NZ=NZ+NRX(I)
   JE=NRX(I)
   DO 22 J=1,JE
      L=L+1
22  ND(L)=NZ
   DO 23 I=NYT,NP
23  ND(I)=NP
C
CZERO REGRESSION COUNTS
80
C
   DO 24 I=1,LM
24  NO(I)=0
C
CTERMINAL INDICES FOR IDENTIFICATION
85
CSET DIGITS FOR FIXED TAPE WRITE,COMPUTE NUMBER OF FIXED XS
   IT(1)=NXS+1
   LMA=L,M-1
   NYY=NY+1
   DO 25 I=1,LMA
      NGY=NGY-1+1
25  IT(I+1)=IT(I)-NG(NGY)
   DO 26 I=LM+1?
26  IT(I+1)=1
   RETURN
95
END

```

```

SIBFTC BAT14 DECK
SUBROUTINE MEAN
DIMENS(UN, NR(30), NV(30), Z(50,17), ND(51), A(14000), NS(31), NDA(31),
1SS(10), R(50,9), X(50), T(30), FMT(24), ISF(30), RA(10), IT(17), NW(50),
2NRX(30), SC(51), TY(10), MSC(31), D(31), NG(30), NDG(18), TT(12), NAD(31),
3KNT(30), NK(17), RN(30), GN(30), NO(17), C(20), NT(30)
COMMON/RANK/NR,NV,IT,ND,A,NS,NDA,SS,R,X,T,FMT,Z,ISF,RA,NRX,SC,IA,
1IB,IN,M,KC,LN,PZ,NF,NFA,KNT,N,NP,NY,KRT,NSET,NOB,NCP,MSC,NGX,DF,
2U,TY,NXS,NG,NVR,IS,TE,NYT,TT,NAD,NDG,NO,C,NT,NIF,ZERO,RN,GN,NK,
3NYY,NVS,LA,NW,LMA
XADF(I,J,NN)=NN-((NP-I+1)*(NP-J))/2-(NP-J)

C
C
1 DO 50 I=IS,IE
JS=I+1
DO 41 J=JS,np
IJ=XADF(I,J,NAD(1))
II=XADF(I,I,NAD(1))
B=A(IJ)/A(II)
DO 41 K=J,np
JK=XADF(J,K,NAD(1))
IK=XADF(I,K,NAD(1))
*1 A(JK)=A(JK)-B*A(IK)
CCOMPUTE DETERMINANTS
50 DF=DF*A(II)/SC(I)
RETURN
END

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$IBFTC BAT18 DECK
      SUBROUTINE MILOOP
      DIMENSION NR(30),NV(30),Z(50,17),ND(5),A(14000),NS(31),NDA(31),
      1SS(10),R(50,9),X(50,17),T(30),FMT(24),ISF(30),RA(10),IT(17),NW(50),
      2NRX(30),SC(51),TY(17),MSC(31),U(31),NG(30),NDG(18),TT(12),NAD(31),
      3KNT(30),NK(17),RN(30),GN(30),NU(17),C(20),NT(30)
      COMMON/MANK/NR,NV,IT,NU,A,NS,NDA,SS,R,X,T,FMT,Z,ISF,RA,NRX,SC,IA,
      1IB,IN,IM,KC,LN,PZ,NF,NFA,KNT,N,NP,NY,KHT,NSET,NOB,NCP,MSC,NGX,DF,
      2D,TY,NXS,NG,NVR,IS,TE,NYT,TT,NAD,NDG,NO,C,NT,NIF,ZERO,RN,GN,NK,
      3NY,NVS,LA,NW,LMA
      J XADF(I,J,NN)=NN=((NP-1+1)*(NP-1))/2-(NP-J)

      C
      C
      80 IS=NP-N+1
      JE=ND(IS)
      IE=JE
      JT=NDA(IA)
      D(1B)=D(IM)
      IF(KC+2) 40,40,29

      C
      C
      CNOT LAST SET
      C
      40 DO 25 I=IS,IE
      JS=I+1
      IF(IS=IE) 11,10,11
      CFIRST OF ONE
      10 L=IM
      GO TO 18
      11 IF(I=IS) 13,12,13
      CFIRST OF MORE THAN ONE
      12 L=IM
      GO TO 16
      13 IF(I=IE) 15,14,15
      CLAST
      14 L=IB
      GO TO 18
      CMIDDLE
      15 L=JB
      GO TO 16
      C
      C
      CROWS IN SET
      C
      16 DO 17 J=JS,IE
      IJL=XADF(I+J,NAD(L))
      IIL=XADF(I,I,NAD(L))
      B=A(IJL)/A(IIL)
      CCOLUMNS IN SET
      DO 23 K=J,JE
      JKB=XADF(J+K,NAD(1B))
      JKL=XADF(J+K,NAD(L))
      IKL=XADF(I+K,NAD(L))
      23 A(JKB)=A(JKL)-B*A(IKL)
      CCOLUMNS NOT IN SET
      DO 17 K=JT,NP
      JKB=XADF(J+K,NAD(1B))
      JKL=XADF(J+K,NAD(L))
      IKL=XADF(I+K,NAD(L))
      17 A(JKB)=A(JKL)-B*A(IKL)

```

```

C
CROWS NOT IN SET
C
65    18 DO 22 J=JT,NP
          IJL=XADF(I,J,NAD(L))
          IIL=XADF(I,I,NAD(L))
          B=A(IJL)/A(IIL)
          IF(KC+2) 26,24,26
CNOT NEXT TO LAST SET *DO ALL COLUMNS
70    26 KS=J
          GO TO 21
CNEXT TO LAST SET, PREPARE TO SKIP TO YS
    24 KS=NYT
C
75    CTEST FOR MORE XS
        KE=ND(J)
        IF(KE=NP) 19,26,19
CCOLUMNS IN NEXT SET
    19 DO 20 K=J,KE
          JKB=XADF(J,K,NAD(IB))
          JKL=XADF(J,K,NAD(L))
          IKL=XADF(I,K,NAD(L))
          20 A(JKB)=A(JKL)-B*A(IKL)
CCOLUMNS OF YS OR ALL COLUMNS
    21 DO 22 K=KS,NP
          JKB=XADF(J,K,NAD(IB))
          JKL=XADF(J,K,NAD(L))
          IKL=XADF(I,K,NAD(L))
          22 A(JKB)=A(JKL)-B*A(IKL)
CCOMPUTE DETERMINANTS
    25 D(IB)=D(IB)*A(IIL)/SC(I)
          GO TO 55
C
C
95    CLAST SET
C
    29 DO 50 I=IS,IE
CTEST FOR LAST X OF SET
        IF(I=IE) 30,33,30
100   C
CROWS OF XS
C
    30 JS=I+1
        DO 32 J=JS,IE
          IJM=XADF(I,J,NAD(IM))
          IIM=XADF(I,I,NAD(IM))
          B=A(IJM)/A(IIM)
CCOLUMNS OF XS
        DO 31 K=J,IE
          JKM=XADF(J,K,NAD(IM))
          IKM=XADF(I,K,NAD(IM))
          31 A(JKM)=A(JKM)-B*A(IKM)
CCOLUMNS OF YS
        DO 32 K=NYT,NP
          JKM=XADF(J,K,NAD(IM))
          IKM=XADF(I,K,NAD(IM))
          32 A(JKM)=A(JKM)-B*A(IKM)
C
CROWS AND COLUMNS OF YS
120   C

```

```

33 DO 37 J=NYT,NP
      IJM=XADF(I,J,NAD(IM))
      IIM=XADF(I,I,NAD(IM))
      B=A(IJM)/A(IIM)
125     IF(I==IS) 35,34,35
      CFIRST X,YS ABOVE
      34 L=IM
      GO TO 36
      CNOT FIRST X,YS BELOW
130     35 L=IB
      36 DO 37 K=J,NP
            JKB=XADF(J,K,NAD(IB))
            JKL=XADF(J,K,NAD(L))
            IKM=XADF(I,K,NAD(IM))
135     37 A(JKR)=A(JKL)-B*A(IKM)
      CCOMPUTE DETERMINANT
      50 D(IB)=D(IB)*A(IIM)/SC(I)
      C
      C
140     CR SQUARES
      C
      55 DO 60 L=NYT,NP
            LL=XADF(L,L,NAD(IB))
            K=L-NYT+1
145     60 R(LA,K+1)=1.0-A(LL)/SS(K)
      RETURN
      END

```

```

SIBFTC BATES DECK
      SUBROUTINE MPRINT
      DIMENSION NR(30),NV(30),Z(50,17),ND(51),A(14000),NS(31),NDA(31),
      1SS(10),R(50,9),X(50),T(30),FMT(24),ISF(30)*RA(10)*IT(17)*NW(50),
      2NRX(30),SC(31),TY(10),MSC(31),U(31),NG(30),NDG(18)*T(12)*NAD(31),
      3KNT(30),NK(17),RN(30),GN(30),NO(17),C(20),NT(30)
      COMMON/RANK/NR,NV,IT*ND,A*NS,NDA,SS,H,X,T,FMT,Z,ISF*RA,NRX,SC,IA,
      1IB,IN,IM,KU,LN,PZ,NF*NFA,KNT,N,NP,NY,KHT,NSET,NOB,NCP,MSC*NGX,DF,
      2D,TY,NXS,NG,NVR,IS,IE,NYT,TT,NAD,NG,NO,C,NT,NIF,ZERO,RN,GN,NK,
      3NYY*NVS*LA*NW*LMA
      DATA BLANK/1H /
C
C PRINT TITLE AND COLUMN HEADINGS
C
15   1 WRITE(6,2) (TT(I),I=1,12)
2   2 FORMAT(1H112A6)
      WRITE(6,501)(TY(JT),JT=1,NY)
501  FORMAT(25H0REGRESSION SCREEN OUTPUT/46H COEFFICIENTS OF COLINEARIT
     1Y AND DETERMINATION//28X,28H IDENTIFICATION OF VARIABLES,20X,6HC 0
     2F C,2X,8A6)
C
C SET TERMINAL INDICES
C
25   IT1=IT(1)
     IT2=IT(2)
     IT3=IT(3)
     IT4=IT(4)
     IT5=IT(5)
     IT6=IT(6)
     IT7=IT(7)
     IT8=IT(8)
     IT9=IT(9)
     IT10=IT(10)
     IT11=IT(11)
     IT12=IT(12)
     IT13=IT(13)
     IT14=IT(14)
     IT15=IT(15)
     IT16=IT(16)
     IT17=IT(17)
C
C COMPUTE STORAGE ADDRESSES
C
30   NDG(1)=NF*NYY-NY
     DO 3 I=1,LM
3   3 NDG(I+1)=NDG(I)+NO(I)*NYY
C
C RELOAD TAPE
C
40   7 READ(1)LB
     IF(LB=99) 4,8,4
4   4 READ(1)(NW(L)+(P(L,M)*M=1,NYY)*L=1,LB)
     DO 6 L=1,LB
       J=NW(L)+1
       K=NDG(J)
       DO 5 M=1,NYY
         A(K)=B(L,M)
5   5 K=K+1
6   6 NDG(J)=NDG(J)-NYY
     GO TO 7

```

```

C
C INITIALIZE FOR BLOCK PRINT
C
65      9 KA=0
          KB=0
          KD=1
          L=0
          IF(NF) 9,14,9
C
70      CLABEL FIXED SETS
C
75      9 KD=0
          DO 12 I=1,NF
          M=17-I
          DO 10 J=1,M
          10 Z(I,J)=BLANK
          DO 11 J=1,I
          K=M+J
          11 Z(I,K)=T(J)
C
80      12 DO 12 J=1,NYY
          KA=KA+1
          12 R(J,J)=A(KA)
C
85      CREINDEX LABELS
          14 D(1)=BLANK
          DO 13 I=1,IXS
          J=I+NF
          13 D(I+1)=T(J)
C
90      CIIDENTIFICATION LOOP
C
95      DO 40 I17=1,IT17
          IS16=I17+MSC(I17)+1
          DO 41 I16=IS16,IT16
          IS15=I16+MSC(I16)+1
          DO 42 I15=IS15,IT15
          IS14=I15+MSC(I15)+1
          DO 43 I14=IS14,IT14
          IS13=I14+MSC(I14)+1
          DO 45 I13=IS13,IT13
          IS12=I13+MSC(I13)+1
          DO 46 I12=IS12,IT12
          IS11=I12+MSC(I12)+1
          DO 47 I11=IS11,IT11
          IS10=I11+MSC(I11)+1
          DO 48 I10=IS10,IT10
          IS9=I10+MSC(I10)+1
          DO 49 I9=IS9,IT9
          IS8=I9+MSC(I9)+1
          DO 50 I8=IS8,IT8
          IS7=I8+MSC(I8)+1
          DO 51 I7=IS7,IT7
          IS6=I7+MSC(I7)+1
          DO 52 I6=IS6,IT6
          IS5=I6+MSC(I6)+1
          DO 53 I5=IS5,IT5
          IS4=IS5+MSC(I5)+1
          DO 54 I4=IS4,IT4
          IS3=I4+MSC(I4)+1

```

```

      DO 55 I3=IS3,IT3
      IS2=I3+MSC(I3)+1
      DO 56 I2=IS2,IT2
      IS1=I2+MSC(I2)+1
      DO 21 I1=IS1,IT1
      IF(I1=1) 16,30,16
      30 IF(NF) 31,21,31
      31 L=NF
      GO TO 20
      16 L=L+1
      KB=KB+1

C
C LABELS
C
135      Z(L,1)=D(I17)
      Z(L,2)=D(I16)
      Z(L,3)=D(I15)
      Z(L,4)=D(I14)
      Z(L,5)=D(I13)
140      Z(L,6)=D(I12)
      Z(L,7)=D(I11)
      Z(L,8)=D(I10)
      Z(L,9)=D(I9)
      Z(L,10)=D(I8)
145      Z(L,11)=D(I7)
      Z(L,12)=D(I6)
      Z(L,13)=D(I5)
      Z(L,14)=D(I4)
      Z(L,15)=D(I3)
      Z(L,16)=D(I2)
      Z(L,17)=D(I1)

C
C LOAD PRINT BLOCK
C
155      DO 23 I=1,NYY
      KA=KA+1
      23 R(L,I)=A(KA)

C
C PRINT FULL BLOCK
C
160      22 IF(KB=NO(KD)) 24,25,24
      24 IF(L=50) 21,20,21
      25 KB=0
      20 GO TO (61,62,63,64,65,66,67,68),NY
      61 WRITE(6,71)(KD,(Z(K,M),M=1,17),(R(K,MA),MA=1,NYY),K=1,L)
      GO TO 69
      62 WRITE(6,72)(KD,(Z(K,M),M=1,17),(R(K,MA),MA=1,NYY),K=1,L)
      GO TO 69
      63 WRITE(6,73)(KD,(Z(K,M),M=1,17),(R(K,MA),MA=1,NYY),K=1,L)
      GO TO 69
      64 WRITE(6,74)(KD,(Z(K,M),M=1,17),(R(K,MA),MA=1,NYY),K=1,L)
      GO TO 69
      65 WRITE(6,75)(KD,(Z(K,M),M=1,17),(R(K,MA),MA=1,NYY),K=1,L)
      GO TO 69
      66 WRITE(6,76)(KD,(Z(K,M),M=1,17),(R(K,MA),MA=1,NYY),K=1,L)
      GO TO 69
      67 WRITE(6,77)(KD,(Z(K,M),M=1,17),(R(K,MA),MA=1,NYY),K=1,L)
      GO TO 69
      68 WRITE(6,78)(KD,(Z(K,M),M=1,17),(R(K,MA),MA=1,NYY),K=1,L)
      GO TO 69

```

## SUBROUTINE MPRINT FORTRAN EXTENDED VERSION 2.0

03/14/70

\*01

```
71 FORMAT (I3,17A4,2XE9.2, F6.3)
72 FORMAT (I3,17A4,2XE9.2,2F6.3)
73 FORMAT (I3,17A4,2XE9.2,3F6.3)
185 74 FORMAT (I3,17A4,2XF9.2,4F6.3)
75 FORMAT (I3,17A4,2XF9.2,5F6.3)
76 FORMAT (I3,17A4,2XE9.2,6F6.3)
77 FORMAT (I3,17A4,2XE9.2,7F6.3)
78 FORMAT (I3,17A4,2XE9.2,8F6.3)
190 69 L=0
      IF(KB) 21,28,2]
28 KD=KD+1
      WRITE(6,39)
39 FORMAT (1H0)
195 21 CONTINUE
56 CONTINUE
55 CONTINUE
54 CONTINUE
53 CONTINUE
200 52 CONTINUE
51 CONTINUE
50 CONTINUE
49 CONTINUE
48 CONTINUE
205 47 CONTINUE
46 CONTINUE
45 CONTINUE
43 CONTINUE
42 CONTINUE
41 CONTINUE
40 CONTINUE
CPRINT OVERALL R SQUARES
C
215 414 IF(NXS-LM) 414,418,414
414 NI=NVS-NY
      WRITE(6,415)NI,DF,(RA(I),I=1,NY)
415 FORMAT(1H0,20X,4H ALL,I3,22H INDEPENDENT VARIABLES,23X,E9.2,8F6.3)
418 RETURN
      END
```

```

SIBFTC BAT16 DECK
      SUBROUTINE RDMNT
      DIMENSION NR(30),NV(30),Z(50,17),ND(51),A(14000),NS(31),NDA(31),
05    ISS(10),R(50,9),X(50),T(30),FMT(24),ISF(30),RA(10),IT(17),NW(50),
     2NRX(30),SC(51),TY(10),MSC(31),D(31),NG(30),NDG(18),TT(12),NAD(31),
     3KNT(30),NK(17),RN(30),GN(30),NO(17),C(20),NT(30)
      DIMENSION QT(30),TQ(8)
      COMMON/BANK/NR,NV,IT,ND,A,NS,NDA,SS,R,X,T,FMT,Z,ISF,RA,NRX,SC,IA,
10    IIB,IM,IM,KC,LN,PZ,NF,NFA,KNT,N,NP,NY,KAT,NSET,NOB,NCP,MSC,NGX,DF,
     2D,TY,NXS,NG,NVR,IS,IE,NYT,TT,NAD,NDG,NO,C,NT,NIF,ZERO,RN,GN,NK,
     3NYY,NVS,LA,NW,LMA
      DATA BLANK/1H /
      DATA QT/4H 1,4H 2,4H 3,4H 4,4H 5,4H 6,4H 7,4H 8,4H
15    1 9,4H 10,4H 11,4H 12,4H 13,4H 14,4H 15,4H 16,4H 17,4H 18
     2,4H 19,4H 20,4H 21,4H 22,4H 23,4H 24,4H 25,4H 26,4H 27,4H
     3 28,4H 29,4H 30/
      DATA TQ/4H Y1,4H Y2,4H Y3,4H Y4,4H Y5,4H Y6,4H Y7,4H Y8/
      XAOF(I,J,NN)=NN-((NP-I+1)*(NP-J))/2-(NP-J)

20  C
      CREAD TITLE,CONSTANTS
      C
      300 PZ=0
      READ(5,205)(TT(I),I=1,12)
25  205 FORMAT(12A6)
      WRITE(6,206)(TT(I),I=1,12)
206 FORMAT(1H1,12A6)
      DATA ZERO/1H /
      DO 11 I=1,20
11  C(I)=BLANK
      READ(5,200)NTF,NRF,NGF,NIF,NFF,NOB,NXS,NY,NF,LN,NVR,NTRAN
200 FORMAT(5I1,I5,5I10,I2)
      57 IF(NY) 19,1R,19
      18 NY=1
      19 NSET=NF+NXS

35  C
      CSET OR READ SET LABELS
      C
      22 READ(5,203)(FMT(I),I=1,12)
      IF(NFF) 23,24,23
      23 READ(5,203)(FMT(I),I=13,24)
203 FORMAT(12A6)
      24 IF(NTF) 27,26,27
      26 DO 2160 I=1,30
2160 T(I)=WT(I)
      DO 2161 I=1,8
2161 TY(I)=TQ(I)
      GO TO 28
      27 READ(5,201)(T(I),I=1,NSET),(TY(I),I=1,NY)
201 FORMAT(1B44/1B4)
50  C
      CSET OR READ SET SIZES
      C
      28 IF(NRF) 31,29,31
      29 DO 30 I=1,NSET
      30 NRX(I)=1
      GO TO 32
      31 READ(5,202)(NRX(I),I=1,NSET)
202 FORMAT(36I2)

60  C
      CSET OR READ GROUP SIZES

```

```

C
32 IF(NGF) 76,74,76
74 NGX=NXS
DO 75 I=1,NGX
65    75 NG(I)=1
      GO TO 54
76 READ(5,207) NGX,(NG(I),I=1,NXS,
207 FORMAT(3612)
54 IF(LM) 81,6,81
6 LM=NGX

C
CSUM SETS BY GROUP AND XS BY SET
C
81 MXY=0
DO 77 I=1,NGX
77 MXY=MXY+NG(I)
NVS=NY
DO 47 I=1,MSET
47 NVS=NVS+NHS(I)
NP=NVS+1
IF(NVR) 71,70,71

C
CCOMPUTE NUMBER OF REGRESSIONS,LOGICAL PRODUCTS OR BINOMIAL COEFF
70 NVR=NVS
C
85 71 RGK=0.0
      KGT=NGX-1
      IF(NGF) 72,90,72

C
CSUM LOGICAL PRODUCTS FOR GROUPS
C
CINITIALIZE AND COMPUTE NUMBER OF REGRESSIONS WITH SINGLE X
72 DO 50 I=1,NGX
      GN(I)=NG(I)
      RN(I)=GN(I)
      RGK=RGK+RN(I)
      NT(I)=1
50 KNT(I)=0
CCOUNTER LOOP
100 38 J=1
39 DO 40 I=J,KGT
      IF(KNT(I)) 40,41,40
41 KNT(I)=1
      GO TO 42
40 KNT(I)=0
      GO TO 98
42 IN=NGX-I
      IM=IN+1
CTEST FOR LIMIT
110 KC=INT(IM)-LM
      IF(KC) 193,21,193
CSTEP COUNTER
21 J=I
      GO TO 39
115 194 DO 51 I=IM,NGX
      RN(I)=RN(IN)*GN(I)
      RGK=RGK+RN(I)
51 NT(I)=NT(IN)+1
      GO TO 38
120 C

```

CSUM BINOMIAL COEFF FOR SETS

C

90 DO 95 I=1,LM

E=NXS

F=1.0

G=1.0

DO 94 J=1,1

G=G\*E/F

E=E-1.0

94 F=F+1.0

95 RGK=RGK+G

C

CTEST CONTROL CONSTANTS

C

98 XP=NY+1

XPP=14000.,/XP

DATA QQQQQ/1H\*/

IF(RGK-XPP) 96,96,97

97 C(13)=QQQQQ

PZ=1

96 CALL CTEST(INTF,0,1,1)

CALL CTEST(NRF,0,1,2)

CALL CTEST(NGF,0,1,3)

CALL CTEST(NIF,0,1,14)

CALL CTEST(NOB,4,99999,15)

CALL CTEST(NXS,2,30,4)

CALL CTEST(NFF,0,1,5)

CALL CTEST(NY,1,B+6)

CALL CTEST(NF,0,17,7)

CALL CTEST(NSET,2,30,16)

CALL CTEST(LM,2,17,R)

CALL CTEST(NGX,LM+NYS,10)

CALL CTEST(NVR,0,50,11)

CALL CTEST(NVS,0,50,9)

CALL CTEST(MXY,NXS,NXS,12)

C

CPRTN CONTROL INFORMATION

C

WRITE(6,101)C(1),NTF

101 FORMAT(4DHUCONSTANTS READ OR COMPUTED FROM CONTROL CARDS//1H ,A1,I  
19,42H=NTF (LABEL CARD FLAG,MUST BE ZERO OR ONE))

WRITE(6,102)C(2),NRF

102 FORMAT(1H ,A1,I9,40H=NRF (SET CARD FLAG,MUST BE ZERO OR ONE))

WRITE(6,120)C(3),NGF

120 FORMAT(1H ,A1,I9,42H=NGF (GROUP CARD FLAG,MUST BE ZERO OR ONE))

WRITE(6,124)C(14),NIF

124 FORMAT(1H ,A1,I9,41H=NIF (INTERCEPT FLAG,MUST BE ZERO OR ONE))

WRITE(6,105)C(5),NFF

105 FORMAT(1H ,A1,I9,43H=NFF (FORMAT CARD FLAG,MUST BE ZERO OR ONE))

WRITE(6,103)C(15),NOB

103 FORMAT(1H ,A1,I9,56H=NOB (NUMBER OF OBSERVATIONS,MUST BE GREATER T  
1HAN THREE))

WRITE(6,104)C(4),NXS

104 FORMAT(1H ,A1,I9,98H=NXS (NUMBER OF SETS OF INDEPENDENT VARIABLES  
1NOT FIXED,MUST BE GREATER THAN ONE AND LESS THAN 31))

WRITE(6,106)C(6),NY

106 FORMAT(1H ,A1,I9,59H=NY (NUMBER OF DEPENDENT VARIABLES,MUST BE LE  
1SS THAN NINE))

WRITE(6,107)C(7),NF

107 FORMAT(1H A1,I9, 73H=NF (NUMBER OF SETS OF FIXED INDEPENDENT VARI

```

        1ABLES•MUST BE LESS THAN 1B))
        WRITE(A,150)C(16),NSET
150 FORMAT(1H ,A1,I9,101H=NSET(TOTAL NUMBER OF SETS OF INDEPENDENT VAR
185      IABLES,NF•NXS,MUST BE GREATER THAN ONE AND LESS THAN 31))
        WRITE(6,108)C(8),LM
108 FORMAT(1H A1,I9,114H=LM (LARGEST NUMBER OF SETS NOT FIXED TO BE I
      NCLUDED IN ANY REGRESSION,MUST BE GREATER THAN ONE AND LESS THAN 1
      28))
        WRITE(6,116)C(10),NGX
190      116 FORMAT (1H A1,I9,89H=NGX (NUMBER OF GROUPS,MUST BE EQUAL TO OR GRE
      1ATER THAN LM AND LESS THAN OR EQUAL TO NXs))
        WRITE(6,110)C(11),NVR
110 FORMAT(1H A1,I9,76H=NVR (TOTAL NUMBER OF VARIABLES BEFORE TRANSFOR
      MATIONS,MUST BE LESS THAN 51))
        WRITE(6,109)C(9),NVs
109 FORMAT(1H A1,I9,75H=NVS (TOTAL NUMBER OF VARIABLES AFTER TRANSFORM
      ATIONS,MUST BE LESS THAN 51))
        WRITE(6,122)RGK
122 FORMAT(1H ,1X,F9.0,69H=RGK (NUMBER OF REGRESSIONS,MUST BE LESS THA
      LN 14,000 DIVIDED BY NY+1))
        WRITE(6,114)
114 FORMAT(13H0INPUT FORMAT)
        WRITE(6,115)(FMT(I),I=1,12)
115 FORMAT(1M 12A6)
        WRITE(6,123)(TY(I),I=1,NY)
123 FORMAT(22H0DEPENDENT VARIABLE(S)/1H ,8A4)
        WRITE(6,111)
111 FORMAT (43H0SET LARFLS AND NUMBER OF VARIABLES PER SET)
        WRITE(6,112)(T(I),I=1,NSET)
210      112 FORMAT(1H 30A4)
        WRITE(6,113)(NRX(I),I=1,NSET)
113 FORMAT(1H 30I4)
        WRITE(6,119)C(12),(NG(I),I=1,NGX)
119 FORMAT (50H0NUMBER OF SETS PER GROUP,SUM MUST BE EQUAL TO NXs/1H A
      11,I3,29I4)
      IF(PZ) 60,61,60
      CPRINT CONTROL CARD ERROR
      C
      60 WRITE(6,117)
      117 FORMAT(55H0CONTROL CARD ERROR,CHECK PREVIOUS OUTPUT FOR ASTERISKS)
      GO TO 64
      C
      CZERO MATRIX
      C
225      61 K=0
      DO 62 I=1,NP
      DO 62 J=I,NP
      K=k+1
      62 A(K)=0.0
      C
      CDATA INPUT AND OUTPUT OF MATRIX
      C
      64 CALL DATAIN (A,X,FMT,NOB,NVR,NVS,PZ,NTRAN)
      IF(PZ) 45,46,45
      46 CALL MATOUT (A,NVS,NY,T,TY,TT)
      45 RETURN
      END

```

FORTRAN EXTENDED VERSION 2.0

03/14/70

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518FTC BAT17 DECK  
SUBROUTINE TRUBS(X)  
DIMENSION X(75)  
WRITE(6,1)  
1 FORMAT(40H00UMMY SUBROUTINE TRUBS HAS BEEN CALLED.)  
RETURN  
END

## FORTRAN EXTENDED VERSION 2.0

03/14/70

```

SIBFTC BATTY DECK
      SUBROUTINE DATAIN (A,X,FMT,NOB,NVR,NVS,PZ,NTRAN)
      DIMENSION A(14000),X(50),FMT(24)
      COMMON/BANK/DUMMY,NY
      COMMON/L1/DONE
      DIMENSION YTOT(8),YSQTOT(8),DUMMY(15766)
      INTEGER DUNE,WMAR
      FNOB=NOB
      IF (PZ) 20,501,20
10   501 IF (NTRAN) 502,20,502
      20 WRITE(6,1)
      1 FORMAT (36HLISTING OF FIRST THREE SETS OF DATA)
      NP=NVS+1
      JJ=NVR-NY
      DO 101 I=1,8
      YSQTOT(I)=0.0
101   YTOT(I)=0.0
      DO 5 L=1,NVR
      C
20   CREAD DATA
      C
      READ(5,FMT)(X(I),I=1,NVR)
      DO 102 JJJ=1,NY
      JK=JJ+JJJ
      YSQTOT(JJJ)=YSQTOT(JJJ)+X(JK)*X(JK)
102   YTOT(JJJ)=YTOT(JJJ)+X(JK)
      CSKIP MATRIX AND TRANSFORMATION AFTER CONTROL CARD ERROR
      IF (PZ) 5,2,5
      2 IF(L=4)5,12,14
30   CPRINT HEADING FOR LAST SET OF DATA
      12 WRITE(6,13)
      13 FORMAT(28HLISTING OF LAST SET OF DATA/100H IF MISSING,PROGRAM HAS
      1 READ PAST DATA CARDS-CHECK NUMBER OF OBSERVATIONS,FORMAT CARD AND
      2 DATA CARDS)
      DATA WMAR/4HDONE/
      14 IF (L=NOB) 7,6,7
      CPRINT FIRST THREE AND LAST SETS OF DATA
      6 WRITE(4,Y)
      9 FORMAT(1H )
      WRITE(6,6)(X(I),I=1,NVS)
      8 FORMAT(1H ,RE15.7)
      C
      CCOMPUTE MOMENTS
      C
45   7 A(1)=A(1)+1.0
      003 K=1,NP
      1 A(K)=A(K)+X(K-1)
      K=N,NP
      DO 4 I=2,NP
      00 4 J=I,NP
      K=K+1
      4 P(K)=A(K)+X(I-1)*X(I-1)
      5 CONTINUE
      GO TO 502
50   502 CALL TRNSX(X,NVR,NVS,FMT,NTRAN,NOB,A,YTOT,YSQTOT)
      504 DO 400 I=1,NY
400   YSQTOT(I)=YSQTOT(I)-YTOT(I)*YTOT(I)/FNOB
      WRITE(6,300)(I,YSQTOT(I),I=1,NY)
300   FORMAT(1H1.5X,24HCORRECTED SUM OF SQUARES/(10X,1HY,I1,1H#,E15.7)
      1)

```

```
C
C === CHECK FOR DONE OR QUIT CARD
C
65    16 READ(5,204)DONE
      204 FORMAT(A4)
          IF(DONE.EQ.'WMAK' .OR. DONE.EQ.'HQUIT') GO TO 44
          43 IF(PZ) 10,11,11
          11 WRITE(6,118)
          118 FORMAT(101H DONE CARD NOT FOUND AT END OF DATA,CHECK NUMBER OF OBS
                IERATIONS,FORMAT CARD,DATA CARDS,AND DONE CARD)
          PZ=-1
          GO TO 10
        44 RETURN
        END
```

```

SIBFTC BAT10  DFCK
      SUBROUTINE TRNSX(X,NVR,NVS,FMT,NTRAN,NOB,A,YTOT,YSQTOT)
      COMMON/BANK/DUMMY,NY
      DIMENSION A(14000),X(50),FMT(24)
      DIMENSION IFORM(50),IA(50),IB(50),CONS(50),D(50)
      DIMENSION YTOT(8),YSQTOT(8),DUMMY(15766)
      DO 5 I=1,NTRAN
      5 READ (5,4)IFORM(I),IA(I),IB(I),CONS(I)
      4 FORMAT(3I2,F8.6)
      10 M1=1
      NP=NVS+1
      JJ=NVS-NY
      DO 101 I=1,8
      YSQTOT(I)=0.0
      101 YTOT(I)=0.0
      DO 105 L=1,NOR
      71 READ (5,FMT)(X(I),I=1,NVR)
      DO 9 J=1,NVR
      9 D(J)=X(J)
      20 DO 30 I=1,NTRAN
      ITRAN=IFORM(I)
      M=IA(I)
      L=IB(I)
      K=CONS(I)
      GO TO (11,12,13,14,15,16,17,18,19,20,21,22,23,24,25,26,27,28),ITRAN
      11 X(M)=X(L)
      GO TO 30
      12 X(M)=CONS(I)*X(L)
      GO TO 30
      13 X(M)=X(L)+CONS(I)
      GO TO 30
      14 X(M)=X(L)+X(K)
      GO TO 30
      35 15 X(M)=X(L)*X(K)
      GO TO 30
      16 X(M)=X(L)/X(K)
      GO TO 30
      17 X(M)=1./X(L)
      GO TO 30
      18 X(M)=X(L)**CONS(I)
      GO TO 30
      19 X(M)=ALOG (X(L))
      GO TO 30
      45 20 X(M)=EXP (X(L))
      GO TO 30
      21 X(M)=ALOG(X(L))*4.3429448
      GO TO 30
      22 X(M)=D(L)
      GO TO 30
      23 X(M)=SIN (X(L))
      GO TO 30
      24 X(M)=COS (X(L))
      GO TO 30
      55 25 X(M)=X(L)/CONS(I)
      GO TO 30
      26 X(M)=ASIN (X(L))
      GO TO 30
      27 CALL TROBS(X)
      GO TO 30

```

```

28 X(M)=X(L)-X(K)
30 CONTINUE
C
65   GO TO (31+114),MI
31 WRITE(6,32)(D(I),I=1,NVR)
32 FORMAT (32H0FIRST UNTRANSFORMED OBSERVATION/(1X,9E14.7))
      WRITE(6,33)(X(I),I=1,NVS)
33 FORMAT (30H0FIRST TRANSFORMED OBSERVATION/(1X,9E14.7))
CPRINT HEADING FOR LAST SET OF DATA
70   WRITE(6,113)
113 FORMAT (28H0LISTING OF LAST SET OF DATA/100H IF MISSING,PROGRAM HA
      15 READ PAST DATA CARDS-CHECK NUMBER OF OBSERVATIONS,FORMAT CARD AN
      20 DATA CARDS)
      MI=2
75   114 IF(LI=NOB)107,106,107
CPRINT LAST SET OF DATA
106  WRITE(6,109)(D(I),I=1,NVR)
109 FORMAT (14H UNTRANSFORMED/(1X,9E14.7))
      WRITE(6,108)(X(I),I=1,NVS)
108 FORMAT (12H TRANSFORMED/(1X,9E14.7))
C
C COMPUTE MOMENTS
C
85   107 DO 102 JJJ=1,NY
      JK=JJ+JJJ
      YSTOT(JJJ)=YSTOT(JJJ)+X(JK)*X(JK)
107  YTOT(JJJ)=YTOT(JJJ)+X(JK)
      A(1)=A(1)+1.0
      DO 103 KI=2,NP
103  A(KI)=A(KI)+X(KI-1)
      KI=NP
      DO 104 II=2,NP
      DO 104 JI=II,NP
      KI=KI+1
104  A(KI)=A(KI)+X(II-1)*X(JI-1)
105  CONTINUE
      RETURN
      END

```

INPUT DECK FOR SAMPLE RUN OF SCREEN

TEST RUN OF SCREEN

1 15 2  
(F4.1,2(F5.1),1X,F3.0)

4 4

CPAMBSA P0UD

0202022.0

03010102

010203

010304

20.8 22.1 0.4 147

25.1 17.6 1.6 106

19.3 17.3 0.2 133

30.5 38.9 2.3 202

29.7 36.1 5.0 378

29.4 32.9 4.0 256

30.9 29.7 5.0 228

29.2 26.0 2.8 199

22.3 27.5 2.8 317

38.9 36.5 2.1 274

20.1 19.8 2.4 146

35.4 32.2 1.9 176

27.7 34.3 4.1 325

21.1 21.9 0.0 110

27.6 33.9 0.5 242

QUIT

## CONSTANTS READ IN COMPUTED FROM CONTROL CARDS

L1N1F (LABEL CARD FLAG•MUST BE ZERO OR ONE)  
 -L2N1F (SET CARD FLAG•MUST BE ZERO OR ONE)  
 -G1N1F (GROUP CARD FLAG•MUST BE ZERO OR ONE)  
 -G2N1F (INTERCEPT FLAG•MUST BE ZERO OR ONE)  
 -G3N1F (FORMAT CARD FLAG•MUST BE ZERO OR ONE)  
 15N0B (NUMBER OF OBSERVATIONS•MUST BE GREATER THAN THREE)  
 2E1AS (NUMBER OF INDEPENDENT VARIABLES NOT FIXED•MUST BE GREATER THAN ONE AND LESS THAN 31)  
 1E1Y (NUMBER OF DEPENDENT VARIABLES•MUST BE LESS THAN NINE)  
 -G4N1F (NUMBER OF SETS OF FIXED INDEPENDENT VARIABLES•MUST BE LESS THAN 18)  
 2E1LM (LARGEST NUMBER OF SETS OF INDEPENDENT VARIABLES•N+NKS MUST BE GREATER THAN 31)  
 2E1L1 (LARGEST NUMBER OF SETS NOT FIXED TO BE INCLUDED IN ANY REGRESSION•MUST BE GREATER THAN ONE AND LESS THAN 18)  
 2E1N1A (NUMBER OF GROUPS•MUST BE EQUAL TO OR GREATER THAN LM AND LESS THAN OR EQUAL TO NKS)  
 4E1N1H (TOTAL NUMBER OF VARIABLES BEFORE TRANSFORMATIONS•MUST BE LESS THAN 51)  
 3E1N1V (TOTAL NUMBER OF VARIABLES AFTER TRANSFORMATIONS•MUST BE LESS THAN 51)  
 3E1N1R (NUMBER OF REGRESSIONS•MUST BE LESS THAN 10,000 DIVIDED BY NY+1)

INPUT FORMAT  
(+4.1)2(F5.1)1X\*F5.6)

DEPENDENT VARIABLE(S)

POUD

SET LABELS AND NUMBER OF VARIABLES PER SET  
CPAMUSA

1

NUMBER OF SETS PER GROUP•SUM MUST BE EQUAL TO NKS  
1

FIRST UNTRANSFORMED OBSERVATION

•204000E+02 •221000E+02 •400000E+00 •1470000E+03

FIRST TRANSFORMED OBSERVATION

•226000E+02 •400000E+00 •1470000E+03

LISTING OF LAST SET OF DATA

IF MISSING, PROGRAM HAS READ LAST DATA CARD•CHECK NUMBER OF OBSERVATIONS, FORMAT CARD AND DATA CARDS

UNTRANSFORMED  
•276000E+02 •339000E+02 •500000E+00 •2420000E+03TRANSFORMED  
•296000E+02 •500000E+00 •2420000E+03

CORRECTED SUM OF SQUARES

Y1= •9608093E+05

TEST RUN OF SCHIFF:

REGRESSION SCREEN OUTPUT  
COEFFICIENTS OF COLINEARITY AND DETERMINATION

	C OF C	POUD
CPAM	*35E-01	*182
BSA	.32E+00	.496

CPAMUSA	*91E-02	.515
---------	---------	------

## MATEXP

### INTRODUCTION

MATEXP is a general purpose program for the solution of systems of ordinary differential equations by the matrix exponential method. It was written in 1967 by S. J. Ball and R. K. Adams for the IBM 7090 and has been converted for use on both the NCAR and SCOPE systems of the CDC 6400 computer.

MATEXP has several advantages over standard numerical integration routines. It gives virtually exact solutions to constant-coefficient homogeneous equations and to non-homogeneous equations for which the forcing functions are constant during the computation interval. The method has also been extended to nonlinear equations and equations with time varying coefficients. This use makes it particularly effective for systems analysis in both the engineering and ecological areas. It has also been very effective when used to calculate the sensitivities of the time response of a system to changes in parameter values.

### METHOD OF OPERATION

A detailed explanation of the program operation is described in ORNL-TM-1933 entitled *MATEXP, a general purpose digital computer program for solving ordinary differential equations by the Matrix Exponential Method* by S. J. Ball and R. K. Adams. With reference to this article, only the types of systems which the program is capable of solving will be mentioned here.

The most basic type of system is the linear, homogeneous system of the type:

$$\frac{dX}{dt} = AX$$

where X is the column vector of state variables and A represents the matrix of coefficients. If the system is non-homogeneous but linear, it is expressed as

$$\frac{dx}{dt} = AX + Z,$$

where Z is the disturbance, or forcing function, vector. The methods of operation are very similar for these two systems. However, if either the coefficient matrix or the disturbance vector becomes nonlinear, the method of solution is changed somewhat and a user supplied subroutine is required which will recalculate the necessary coefficients, or forcing functions, at each time interval. This subroutine is entitled DSTRB in the ORNL report. An example of the nonlinear problem is shown in the program listing.

#### INPUT REQUIREMENTS

The MATEXP program consists of the main program and two subroutines OUTPUT and DSTRB, plus any other subroutines called by DSTRB. Even if DSTRB is not used, a dummy must be included.

For each case run on MATEXP, the data will include (if appropriate):

1. MATEXP Control Card
2. Coefficient matrix (A)
3. Initial Condition Vector (XIC)
4. Any data read in by subroutine DSTRB
5. Fixed forcing function vector (Z).

#### Input Data Formats - MATEXP Main Program

##### 1. Control Card

Column	1-2	6-7	11-20	21-30	31-40	41-50	51-60	61-62
Format	I2	3X	I2	3X	F10.0	F10.0	F10.0	F10.0
Input	NE		LL	P	TZERO	T	TMAX	PLTINC

Control Card - (continued)

Column	63-64	65-66	67-69	70	71-72	73-74	75-80
Format	I2	I2	I3	I1	I2	I2	F6.0
Input	ICSS	JFLAG	ITMAX	LASTCC	IIZ	ICONTR	VAR

NE        number of equations  
LL        coefficient matrix tag number  
P        precision of C and HP (recommend  $10^{-6}$  or less).  
TZERO     zero time  
T        computation time interval  
TMAX     maximum time  
PLTINC    printing time interval  
MATYES    coefficient matrix (A) control flag:  
    1 = use previous A and T  
    2 = read new coefficients to alter A  
    3 = read entire new A (nonzero values)  
    4 = DISTRB to calculate entire new A  
    5 = read some, DISTRB to calculate others  
    6 = IDISTRB to alter some A elements  
ICSS     initial condition vector (XIC) flag:  
    1 = read in all new nonzero values  
    2 = read new values to alter previous vector  
    3 = use previous vector  
    4 = vector = 0  
    5 = use last value of X vector from previous run  
JFLAG     forcing function (Z) flag:  
    1 thru 4 = same as for ICSS for constant Z  
    5 = call DISTRB at each time step for variable Z

ITMAX maximum number of terms in series approximation of exp (AT)  
LASTCC nonzero for last case (blank otherwise).  
IIZ row of Z if only one nonzero, otherwise = 0  
ICONTR for internal control options:  
0 = read new control card for next case  
1 = go to 212 call DISTRB for new A or T  
-1 = go to 215 call DISTRB for new initial conditions  
VAR maximum allowable value of largest coefficient matrix element  
\*T (Recommend VAR = 1.0)

2. Coefficient Matrix A Format 4(213, E12.3) - Include if MATYES = 2, 3, or 5.

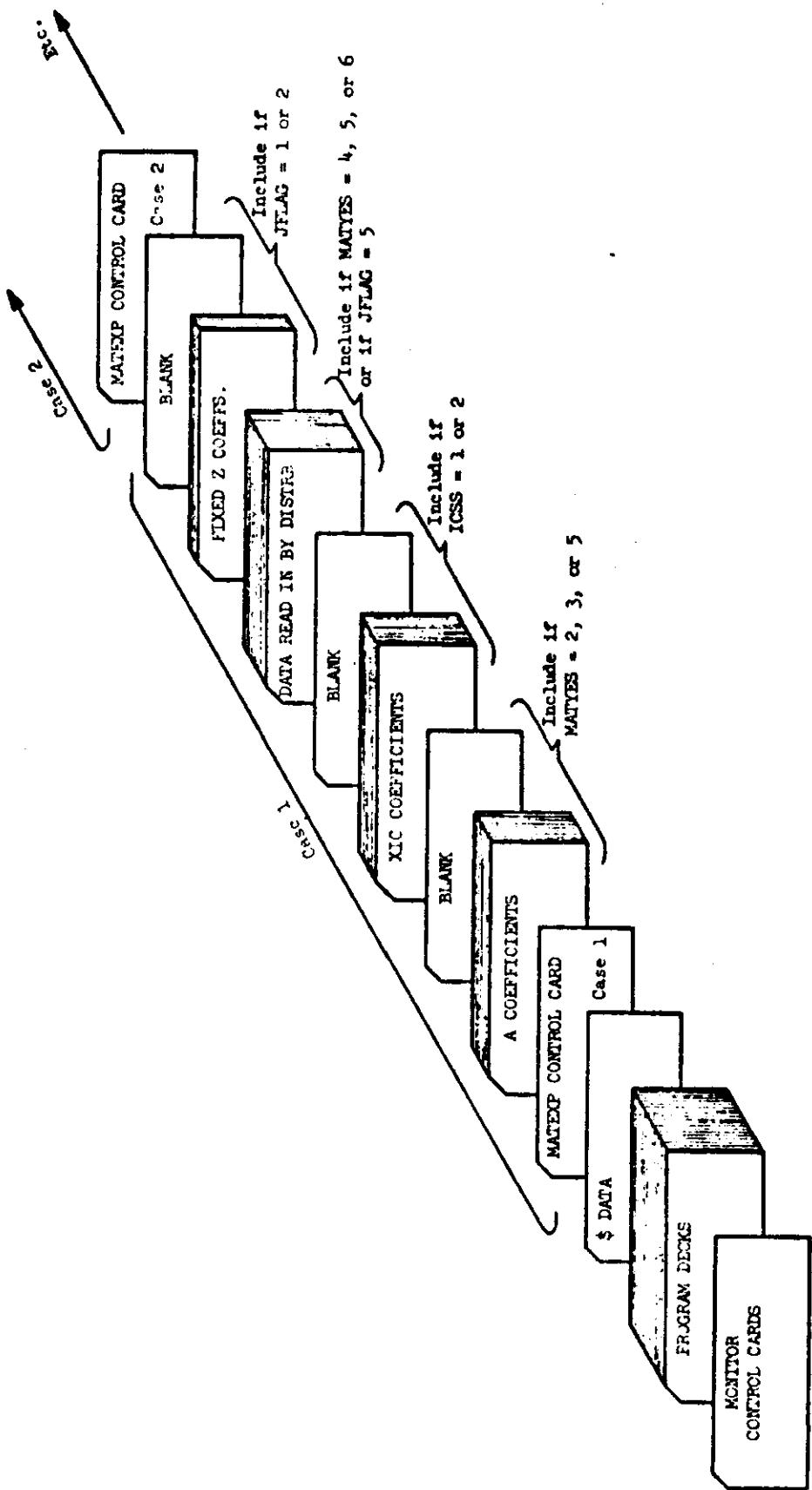
Column	1-3	4-6	7-18	
Format	I3	I3	E12.3	Repeat
Input	Row No.	Col. No.	COEFFICIENT	4 per card

Notes: 1. All row and column number entries on a card must be nonzero.  
2. Insert blank card after all coefficient matrix data is read in.  
3. Data can be entered in floating point (F) format with decimal point.

3. Initial Condition Vector XIC Format (12, 5(I3, E12.3)) - Include if ICSS = 1 or 2

Column	1-2	3-5	6-17	
Format	I2	I3	E12.3	Repeat Cols. 3-17,
Input	MM	Row No.	I.C. Value	5 per card

Notes: 1. All row number entries on a card must be nonzero.  
2. Insert blank card after all XIC data is read in.  
3. Data can be entered in F format.



MATEXP Data Arrangement

4. Disturbance Vector Z Format (I2, 5(I3, E12.3)) - Include if JFLAG = 1 or 2

Column	1-2	3-5	6-17	
Format	I2	I3	E12.3	Repeat Cols. 3-17,
Input	KK	Row No.	Z Value	5 per card

Note: See notes under 3.

To aid in understanding the MATEXP program, Fig. 1 summarizes the data arrangement.

SAMPLE LISTING AND OUTPUT

The listing shown is the solution for a sample ecology problem with nonlinear coefficients designed by B. C. Patten. A detailed description of this model is also included with the ORNL report.

```

PROGRAM MATEXP
C----PROGRAM MATEXP FOR THE 7090 - FORTRAN 4
C----A 1
C----A 2
C----THIS PROGRAM CALCULATES THE SOLUTION OF A MATRIX OF FIRST
C----ORDER, SIMULTANEOUS DIFFERENTIAL EQUATIONS W/ CONSTANT COEFFICIENT
C----OF THE FORM DX/DT = AX + Z.
C----A 3
C----A 4
C----A 5
C----THE METHOD IS PAYNTER-S MATRIX EXPONENTIAL METHOD
C----A 6
C----A 7
C----THE SOLUTION IS GIVEN FOR INCREMENTS OF THE INDEPENDENT
C----VARIABLE (T) FROM TZERO THROUGH TMAX
C----A 8
C----A 9
C----A 10
C----COMPUTES MATRICES C = EXP(A*T) AND
C----A 11
C----A 12
C----HP = (C-I)*A INVERSE
C----A 13
C----SOLUTION X(N*T) = C*X((N-1)*T)+HP*Z((N-1)*T)
C----A 14
C----SERIES CALCULATION OF C AND HP MONITORED TO
C----A 15
C----ASSURE SPECIFIED SIGNIFICANCE.
C----A 16
C----IF T IS REDUCED FOR C AND HP CALCS.,
C----A 17
C----ORIGINAL ARGUMENTS ARE RESTORED BY -
C----A 18
C----C(2*T)=C(T)*C(T)
C----A 19
C----HP(2*T)=HP(T)+C(T)*HP(T)
C----A 20
C----A 21
C----OUTPUT FROM THE PROGRAM IS PRINTED AT INTERVALS PLTINC.
C----A 22
C----THE PROGRAM USES SUBROUTINES DISTRB AND OUTPUT
C----A 23
C----A 24
C----INPUT FOR THE PROGRAM CONSISTS OF
C----ONE CONTROL CARD
C----A 25
C----THE COEFFICIENT MATRIX A (UP TO 60 X 60)
C----A 26
C----THE INITIAL CONDITION VECTOR X
C----A 27
C----A FIXED DISTURBANCE VECTOR Z
C----A 28
C----A 29
C----A VARYING Z CAN BE GENERATED BY DISTRB
C----A 30
C----VARIABLE COEFFICIENT EQUATIONS MAY BE SOLVED BY APPROPRIATE
C----A 31
C----FUDGING OF THE DISTURBANCE FUNCTION SUBROUTINE.
C----A 32
C----A 33
C----CONTROL CARD INPUT INFORMATION
C----NE=NO. OF EQUATIONS (I2)
C----A 34
C----A 35
C----LL=COEFF. MATRIX TAG NO. (I2)
C----A 36
C----P=PRECISION OF C AND HP (F10.0) - RECOMMEND 1.OE-6 OR LESS
C----A 37
C----TZERO=ZERO TIME (F10.0)
C----A 38
C----T=COMPUTATION TIME INTERVAL (F10.0)
C----A 39
C----TMAX=MAXIMUM TIME (F10.0)
C----A 40
C----PLTINC=PRINTING TIME INTERVAL (F10.0)
C----A 41
C----MATYES=COEFF. MATRIX (A) CONTROL FLAG (I2)
C----A 42
C----A 43
C----1=USE PREVIOUS A AND T
C----A 44
C----2=READ NEW COEFF.S TO ALTER A
C----A 45
C----3=READ ENTIRE NEW A (NON-ZERO VALUES)
C----A 46
C----4=DISTRB TO CALC. ENTIRE NEW A
C----A 47
C----5=READ SOME, DISTRB TO CALC. OTHERS
C----A 48
C----6=DISTRB TO ALTER SOME A ELEMENTS
C----A 49
C----ICSS=INITIAL CONDITION VECTOR (XIC) FLAG (I2)
C----A 50
C----1=READ IN ALL NEW NON-ZERO VALUES
C----A 51
C----2=READ NEW VALUES TO ALTER PREVIOUS VECTOR
C----A 52
C----3=USE PREVIOUS VECTOR
C----A 53
C----4=VECTOR=0
C----A 54
C----5=USE LAST VALUE OF X VECTOR FROM PREVIOUS RUN
C----A 55

```

```

C----- JFLAG=FORCING FUNCTION (Z) FLAG (I2) A 56
C----- 1 THRU 4=SAME AS FOR ICSS FOR CONSTANT Z A 57
C----- 5=CALL DISTRB AT EACH TIME STEP FOR VARIABLE Z A 58
C----- ITMAX = MAX. NO. OF TERMS IN SERIES APPROX. A 59
C----- OF EXP(AT). (I3) A 60
C----- LASTCC = NON-ZERO FOR LAST CASE (I1) A 61
C----- IIZ = ROW NO. OF Z IF ONLY ONE NON-ZERO, A 62
C----- OTHERWISE =0 (I2) A 63
C-----ICONTR - FOR INTERNAL CONTROL OPTIONS (I2) - A 64
C----- 0=READ NEW CONTROL CARD FOR NEXT CASE A 65
C----- 1=GO TO 212 CALL DISTRB FOR NEW A OR T A 66
C----- -1=GO TO 215 CALL DISTRB FOR NEW I.C.-S A 67
C-----VAR = MAX. ALLOWABLE VALUE OF LARGEST COEFF. MATRIX ELEMENT * T A 68
C----- (RECOMMEND VAR=1.0) (F6.0) A 69
C----- DIMENSION A(60,60), C(60,60), HP(60,60), OPT(60,60), X(60), Y(60), A 70
C----- 1 Z(60), XIC(60), TQP(60) A 71
C----- COMMON C,HP,A,OPT,X,Z,Y,ITMAX,KK,LL,MM,JJFLAG,XIC,NI,TIME,TMAX,TZE A 72
C----- 1R0,NE,TQP,T,IIZ,ICONTR,PLTINC,MATYES,ICSS,JFLAG,PLT A 73
C----- A 74
C----- K=CASE NUMBER A 75
C----- NI=0 ON 1-ST PASS. SET TO 1 ON 1-ST CALL OF OUTPUT. A 76
C----- K=1 A 77
C----- NI=0 A 78
C----- A 79
C----- A 80
1 READ (5,94) NE,LL,P,TZERO,T,TMAX,PLTINC,MATYES,ICSS,JFLAG,ITMAX,LA A 81
  1STCC,IIZ,ICONTR,VAR A 82
  IF(NE.EQ.0) STOP A 83
C----- A 84
C----- COEFFICIENT MATRIX INPUT A 85
  GO TO (7,4,2,2,2,7), MATYES
2 DO 3 I=1,NE A 86
  DO 3 J=1,NE A 87
3 A(I,J)=0.0 A 88
  IF (MATYES-4) 4,7,4 A 89
4 DO 6 I=1,1379 A 90
C----- MATRIX ELEMENTS 5(ROW, COLUMN, VALUE) A 91
C----- ALL I AND J ENTRIES ON CARD MUST BE NON-ZERO. A 92
C----- A BLANK CARD IS REQUIRED AFTER ALL ELEMENTS ARE READ IN. A 93
  READ (5,95) I1,J1,D1,I2,J2,D2,I3,J3,D3,I4,J4,D4 A 94
  IF (I1) 7,7,5 A 95
5 A(I1,J1)=D1 A 96
  A(I2,J2)=D2 A 97
  A(I3,J3)=D3 A 98
6 A(I4,J4)=D4 A 99
C----- A 100
C----- INITIAL CONDITION VECTOR XIC INPUT A 101
7 GO TO (8,10,15,13,15), ICSS A 102
8 DO 9 I=1,NE A 103
9 XIC(I)=0.0 A 104
10 DO 12 I=1,15 A 105
C----- ALL ROW (I) ENTRIES MUST BE NON-ZERO A 106
C----- A BLANK CARD IS REQUIRED AFTER ALL ELEMENTS ARE READ IN. A 107
  READ (5,96) MM,I11,D11,I12,D12,I13,D13,I14,D14,I15,D15 A 108
  IF (I11) 15,15,11 A 109
C----- A 110

```

## MATRIX EXPONENTIAL PROGRAM FOR SYSTEMS OF DIF. EQS.

PAGE 3

```

11   XIC(I11)=D11          A 111
     XIC(I12)=D12          A 112
     XIC(I13)=D13          A 113
     XIC(I14)=D14          A 114
12   XIC(I15)=D15          A 115
C-----
13   MM=0                  A 116
   DO 14 I=1,NE            A 117
14   XIC(I)=0.0             A 118
15   IF (ICSS-5) 16,18,16   A 119
16   DO 17 I=1,NE            A 120
17   X(I)=XIC(I)           A 121
18   IF (MATYES-3) 20,20,19  A 122
19   CALL DISTRB           A 123
20   JJFLAG=0              A 124
C-----QPTMP = MAX. PERMISSIBLE ELEMENT OF QPT FOR 8 DECIMAL COMPUTER
C-----MATRIX CALC. LOSES SIGNIFICANCE IF LARGEST
C----- ELEMENT IN SERIES APPROX. MATRIX QPT IS
C----- GREATER THAN P*1.0E8
   QPTMP=P*1.0E8
C-----WRITE (6,97) K,NE,P,T,PLTINC,MATYES,ICSS,JFLAG,ICTR,ITMAX,I1Z,VA
   1R,QPTMP
C-----PLTINC=PLTINC*0.9999
C-----JFK=0
   IF (MATYES-1) 66,66,21
C-----SCAN MATRIX FOR MAX. AND MIN. NON-ZERO ELEMENTS.
21   IMAX=1                A 139
   JMAX=1                A 140
   AMAX=ABS(A(1,1))       A 141
   DO 23 I=1,NE            A 142
   DO 23 J=1,NE            A 143
   IF (AMAX-ABS(A(I,J))) 22,23,23
22   AMAX=ABS(A(I,J))       A 144
   IMAX=I                 A 145
   JMAX=J                 A 146
23   CONTINUE               A 147
   IMIN=IMAX               A 148
   JMIN=JMAX               A 149
   AMIN=AMAX               A 150
   DO 26 I=1,NE            A 151
   DO 26 J=1,NE            A 152
   IF (A(I,J)) 24,26,24
24   IF (ABS(A(I,J))-AMIN) 25,26,26
25   AMIN=ABS(A(I,J))       A 153
   IMIN=I                 A 154
   JMIN=J                 A 155
26   CONTINUE               A 156
   RATIO=AMAX/AMIN         A 157
C-----AMIN = MINIMUM NON-ZERO ELEMENT
   ISTOR=0                A 158
   ADT=AMAX*T              A 159
   DO 28 I=1,11             A 160
                                A 161
                                A 162
                                A 163
                                A 164
                                A 165
                                A 166

```

```

      IF (VAR-ADT) 27,29,29          A 167
27    ISTOR=ISTOR+1                A 168
28    ADT=ADT*0.5                 A 169
29    T=ADT/AMAX                  A 170
C-----COMPUTATION INTERVAL T IS HALVED ISTOR          A 171
C----- TIMES (10=MAX.) SO MAX. ELEMENT IN A*T          A 172
C----- IS LESS THAN VAR.          A 173
      WRITE (6,98) IMAX,JMAX,A(IMAX,JMAX),ADT,T,IMIN,JMIN,A(IMIN,JMIN),R  A 174
      1ATIO
C-----
      IF (ISTOR-10) 31,30,30          A 175
30    WRITE (6,99)
      GO TO 91
C-----CALCULATION OF MATRIX EXPONENTIALS C AND HP          A 176
31    DO 32 I=1,NE                A 177
      DO 32 J=1,NE                A 178
32    C(I,J)=0.                  A 179
C-----
      DO 33 I=1,NE                A 180
33    C(I,I)=1.                  A 181
C-----
C-----SKIP HP CALCS. FOR HOMOGENEOUS EQUATIONS          A 182
      IF (JFLAG-4) 34,37,34          A 183
34    DO 35 I=1,NE                A 184
      DO 35 J=1,NE                A 185
35    HP(I,J)=0.                  A 186
C-----
      DO 36 I=1,NE                A 187
36    HP(I,I)=T                  A 188
C-----
37    PE=0.0                      A 189
C-----
      DO 38 I=1,NE                A 190
      DO 38 J=1,NE                A 191
38    QPT(I,J)=C(I,J)            A 192
C-----
C-----NOW FORM THE MATRIX EXPONENTIALS C=EXP(A*T) AND HP=(C-I)*A INVERS  A 193
C-----          A 194
      AL=1.0                      A 195
C-----
      DO 50 KL=1,ITMAX             A 196
C-----          A 197
      KLM=KL                      A 198
      ALL=T/AL                     A 199
      AL=AL+1.0                    A 200
      TALLL=T/AL                   A 201
C-----          A 202
      DO 40 I=1,NE                A 203
C-----          A 204
C-----          A 205
      DO 39 J=1,NE                A 206
      TQP(J)=0.0                   A 207
      DO 39 KX=1,NE                A 208
39    TQP(J)=TQP(J)+QPT(I,KX)*A(KX,J)          A 209
C-----          A 210
      DO 40 J=1,NE                A 211
C-----          A 212
C-----          A 213
      DO 39 J=1,NE                A 214
      TQP(J)=0.0                   A 215
      DO 39 KX=1,NE                A 216
      TQP(J)=TQP(J)+QPT(I,KX)*A(KX,J)          A 217
39    TQP(J)=TQP(J)+QPT(I,KX)*A(KX,J)          A 218
C-----          A 219
      DO 40 J=1,NE                A 220
C-----          A 221
      DO 39 J=1,NE                A 222

```

## MATRIX EXPONENTIAL PROGRAM FOR SYSTEMS OF DIF. EQS.

PAGE 5

```

40      QPT(I,J)=TQP(J)*ALL          A 223
C-----
C-----OPT=MATRIX TERM IN SERIES APPROX. =((A*T)**K)/K FACTORIAL A 224
C-----
        DO 41 I=1,NE                A 225
        DO 41 J=1,NE                A 226
41      C(I,J)=C(I,J)+QPT(I,J)    A 227
C-----
        IF (JFLAG-4) 42,45,42      A 228
C-----
42      IF (ITMAX-KL) 45,45,43    A 229
43      DO 44 I=1,NE                A 230
        DO 44 J=1,NE                A 231
44      HP(I,J)=HP(I,J)+QPT(I,J)*TALLL A 232
C-----
C-----
C-----FIND MAX ABS ELEMENT IN QPT AND CALL IT PMK            A 233
C-----LARGEST QPT ELEMENT USUALLY IN ROW IMAX, COLUMN JMAX A 234
45      PMK=ABS(QPT(IMAX,JMAX))   A 235
        IF (QPTMP-PMK) 53,53,46    A 236
46      IF (PMK-P) 47,47,50      A 237
C-----SCAN OTHER QPT ELEMENTS ONLY WHEN QPT(IMAX, JMAX) IS LESS THAN P A 238
47      DO 48 I=1,NE                A 239
        DO 48 J=1,NE                A 240
48      PMK=AMAX1(PMK,ABS(QPT(I,J))) A 241
        IF (PMK-P) 49,49,50      A 242
C-----
C-----PRESENT MAX. QPT ELEMENT SHOULD BE LESS THAN          A 243
C-----HALF PREVIOUS MAX. TO INSURE CONVERGENCE             A 244
49      IF (PE-2.*PMK) 50,51,51    A 245
50      PE=PMK                  A 246
C-----
51      WRITE (6,100) KLM          A 247
C-----
C-----
        IF (ITMAX-1) 66,66,52      A 248
52      IF (KLM-ITMAX) 56,53,53    A 249
C-----
53      T=T*0.5                  A 250
        JFK=JFK+1                A 251
        IF (JFK-7) 55,54,54      A 252
54      WRITE (6,101) PMK          A 253
        GO TO 91                A 254
55      WRITE (6,102) KLM,PMK,T   A 255
        GO TO 31                A 256
56      ISTOK=ISTOK+JFK          A 257
C-----ORIGINAL ARGUMENTS OF C AND HP MATRICES RESTORED IF ISTOK GREATER A 258
        IF (ISTOK) 66,66,57      A 259
57      WRITE (6,103) ISTOK        A 260
        DO 65 KR=1,ISTOK          A 261
        IF (JFLAG-4) 58,61,58      A 262
C-----SKIP HP CALCS. FOR HOMOGENEOUS EQUATIONS           A 263
58      DO 60 I=1,NE                A 264
        DO 59 J=1,NE                A 265
        TQP(J)=0.0                 A 266
        DO 59 KX=1,NE                A 267

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## MATRIX EXPONENTIAL PROGRAM FOR SYSTEMS OF DIF. EQS.

PAGE 6

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59      TQP(J)=TQP(J)+HP(I,KX)*C(KX,J)          A 279
       DO 60 J=1,NE
60      HP(I,J)=TQP(J)+HP(I,J)                  A 280
C-----
61      DO 62 I=1,NE
       DO 62 J=1,NE
62      QPT(I,J)=0.0                            A 281
       DO 63 I=1,NE
       DO 63 J=1,NE
       DO 63 KX=1,NE
63      QPT(I,J)=QPT(I,J)+C(I,KX)*C(KX,J)    A 282
       DO 64 I=1,NE
       DO 64 J=1,NE
64      C(I,J)=QPT(I,J)                        A 283
65      T=2.0*T                                A 284
C-----
C-----C(I,J) IS THE MATRIX EXPONENTIAL C=EXP(A*T)   A 285
C-----AND HP(I,J) IS THE ((C-I)*A INVERSE) MATRIX   A 286
C-----NOW WE READ (OR CALL SUBROUTINE FOR) DISTURBANCE VECTOR   A 287
C-----
66      TIME=TZERO                           A 288
       PLT=0.
       GO TO (69,71,76,74,67), JFLAG            A 289
67      IF (MATYES-3) 68,68,76                A 290
68      CALL DISTRB
       IIZ=IIZ
       GO TO 76
C-----
69      DO 70 I=1,NE                          A 291
70      Z(I)=0.0                            A 292
71      DO 73 I=1,15                          A 293
C-----ALL ROW (I) ENTRIES MUST BE NON-ZERO        A 294
C-----A BLANK CARD IS REQUIRED AFTER ALL ELEMENTS ARE READ IN.   A 295
       READ (5,96) KK,I21,D21,I22,D22,I23,D23,I24,D24,I25,D25
       IF (I21) 76,76,72
72      Z(I21)=D21                           A 296
       Z(I22)=D22                           A 297
       Z(I23)=D23                           A 298
       Z(I24)=D24                           A 299
73      Z(I25)=D25                           A 300
C-----
74      KK=0                                A 301
       DO 75 I=1,NE                          A 302
75      Z(I)=0.0                            A 303
C-----
C-----ON 1-ST CALL OF OUTPUT NI SET TO 1          A 304
76      CALL OUTPUT                         A 305
C-----
C-----NOW COMES THE EQUATION SOLUTION BASED ON   A 306
C-----X(NT)=M*X(NT-1)+((M-I)A INV.)*Z(NT-1)   A 307
C-----
77      IF (JFLAG-4) 82,78,80                A 308
78      DO 79 I=1,NE                          A 309
       Y(I)=C(I,1)*X(1)
       DO 79 J=2,NE
79      Y(I)=Y(I)+C(I,J)*X(J)              A 310
                                         A 311
                                         A 312
                                         A 313
                                         A 314
                                         A 315
                                         A 316
                                         A 317
                                         A 318
                                         A 319
                                         A 320
                                         A 321
                                         A 322
                                         A 323
                                         A 324
                                         A 325
                                         A 326
                                         A 327
                                         A 328
                                         A 329
                                         A 330
                                         A 331
                                         A 332
                                         A 333
                                         A 334

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        IF (I1Z) 87,87,83
80      IF (JJFLAG) 81,82,81
81      CALL DISTRB
82      IF (I1Z) 85,85,78
C-----ONLY ONE Z-TERM CALC. IF I1Z IS GREATER THAN ZERO
83      DO 84 I=1,NE
84      Y(I)=Y(I)+HP(I,I1Z)*Z(I1Z)
      GO TO 87
85      DO 86 I=1,NE
      Y(I)=C(I,1)*X(1)+HP(I,1)*Z(1)
      DO 86 J=2,NE
86      Y(I)=Y(I)+C(I,J)*X(J)+HP(I,J)*Z(J)
87      DO 88 I=1,NE
88      X(I)=Y(I)
C-----
C-----ONE TIME INCREMENT OF THE SOLUTION HAS JUST BEEN FOUND
C-----NOW PLOT AND PRINT IF PLTINC INTERVAL HAS ELAPSED
C-----
        JJFLAG=1
        TIME=TIME+T
        PLT=PLT+T
        IF (PLT-PLTINC) 90,89,89
89      CALL OUTPUT
        PLT=0.
90      IF (TIME-TMAX) 77,91,91
91      IF (LASTCC) 93,92,93
92      K=K+1
        NI=0
        PLT=0.0
        IF (ICONTR) 68,1,19
93      STOP
C-----
94      FORMAT (2(I2,3X),5F10.0,3I2,I3,I1,2I2,F6.0)
95      FORMAT (4(2I3,E12.3))
96      FORMAT (I2,5(I3,E12.3))
97      FORMAT (12H1MATEXP CASE,I3/17H NO. OF EQUATIONS,I3/20H SPECIFIED P
        1RECISION,F12.8/6H TIME ,8HINTERVAL,F18.8/15H PLOT INCREMENT,F17.8/
        2/16H CONTROL FLAGS -/1H ,5X,6HMATYES,I4/1H ,5X,4HICSS,I6/1H ,5X,5H
        3JFLAG,I5/1H ,5X,6HICONTR,I4/34HOMAX. TERMS IN EXPONENTIAL APPROX.,
        4I5/13H SINGLE Z ROW,I4/20H MAX. ALLOWABLE A*DT,F9.3/27H MAX. ALLOW
        5ARBLE OPT ELEMENT,F11.3)
98      FORMAT (3I1HOMAX.COEFF. MATRIX ELEMENT = A(,I2,1H,,I2,3H) =,E15.4/1
        13H MAX. A*DT = ,F12.8,2X,14HWITH DELTA T =,F15.8/30HOMINIMUM NON-7
        2ZERO ELEMENT = A(,I2,1H,,I2,3H) =,E15.4/18H RATIO AMAX/AMIN =,E15.4
        3)
99      FORMAT (34HOA*DT STILL GREATER THAN ALLOWABLE,19H AFTER 10 HALVING
        1S.)
100     FORMAT (44HOND. OF TERMS IN SERIES APPROX. OF MATEXP = ,I2)
101     FORMAT (32H07 TRIES AT HALVING T N.G., PMK=,F12.6)
102     FORMAT (21HOMAX. ELEMENT IN TERM,I3,8HOF QPT =,E11.3/35H TRY HALVE
        1D TIME INTERVAL DELTA T =,F15.8)
103     FORMAT (26HOTOTAL NO. OF T HALVINGS =,I3)
      END

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```

SUBROUTINE VARCO (XTR,TX) B 1
C----FOR USE WITH DISTRB AND MATEXP FOR B 2
C----VARIABLE Z-S. GIVES 1-ST ORDER EXTRAP. B 3
C----FOR AVG. X AND TIME, PLUS RESTART B 4
C----ON 1-ST INTERVAL. DISTRB FORM = B 5
C---- CALC. MATRIX COEFF.-S, ETC. IF NI=0 B 6
C---- CALL VARCO(XTR,TX) B 7
C---- CALC. Z-S USING XTR(I)-S AND TX (TIME). B 8
C---- B 9
DIMENSION A(60,60), C(60,60), HP(60,60), QPT(60,60), X(60), Y(60), B 10
1 Z(60), XIC(60), TQP(60) B 11
COMMON C,HP,A,QPT,X,Z,Y,ITMAX,KK,LL,MM,JJFLAG,XIC,NI,TIME,TMAX,TZE B 12
1R0,NE,TQP,T,IIZ,ICONTR,PLTINC,MATYES,ICSS,JFLAG,PLT B 13
DIMENSION XTR(60), XL(60) B 14
C---- B 15
IF (NI) 1,1,3 B 16
C----FIRST ENTRY B 17
1 NV=1 B 18
TX=TZERO+0.5*T B 19
DO 2 I=1,NE B 20
2 XTR(I)=XIC(I) B 21
GO TO 8 B 22
3 IF (NV) 6,6,4 B 23
C----SECOND FNTRY B 24
4 NV=0 B 25
TIME=TZFR0 B 26
PLT=0.0 B 27
DO 5 I=1,NE B 28
XL(I)=XIC(I) B 29
XTR(I)=0.5*(XL(I)+X(I)) B 30
5 X(I)=XIC(I) B 31
GO TO 8 B 32
C----ENTRIES AFTER SECOND B 33
6 TX=TIME+0.5*T B 34
DO 7 I=1,NE B 35
XTR(I)=X(I)+0.5*(X(I)-XL(I)) B 36
7 XL(I)=X(I) B 37
8 RETURN B 38
END B 39

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SUBROUTINE DFG (XD,ZD) C 1
C---- C 2
C----EQUIVALENT TO 8 DFG-S WITH UP TO 32 C 3
C----POINTS EACH. CALLED BY DISTRB. C 4
C---- C 5
C----INPUTS ARE C 6
C---- NDFGS NO. OF DFG-S USED C 7
C---- NPTS NO. OF POINTS IN EACH DFG C 8
C---- XP INDEPENDENT VARIABLE DFG POINTS C 9
C---- ZP DEPENDENT VARIABLE DFG POINTS C 10
C---- C 11

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C-----XD IS THE INPUT VARIABLE AND ZD THE OUTPUT
C-----          C 12
      DIMENSION A(60,60), C(60,60), HP(60,60), OPT(60,60), X(60), Y(60),
1   Z(60), XIC(60), TQP(60)          C 13
      COMMON C,HP,A,QPT,X,Z,Y,ITMAX,KK,LL,MM,JJFLAG,XIC,NI,TIME,TMAX,TZF
1R0,NE,TQP,T,IIZ,ICONTR,PLTING,MATYES,ICSS,JFLAG,PLT          C 14
      DIMENSION XP(32,8), ZP(32,8), SL(32,8), NPTS(8), JP(8), ZD(8), XD(
18)          C 15
C-----          C 16
C-----          C 17
      IF (NI) 6,1,6          C 18
C-----FIRST CALL COMP.          C 19
C-----          C 20
1   READ (5,18) NDFGS,NPTS          C 21
      DO 2 I=1,NDFGS          C 22
      NP=NPTS(I)          C 23
      RFAD (5,19) (XP(J,I),ZP(J,I),J=1,NP)          C 24
2   WRITE (6,20) I,(XP(J,I),ZP(J,I),J=1,NP)          C 25
      DO 3 I=1,NDFGS          C 26
      M=NPTS(I)-1          C 27
      DO 3 J=1,M          C 28
3   SL(J,I)=(ZP(J+1,I)-ZP(J,I))/(XP(J+1,I)-XP(J,I))          C 29
C-----          C 30
      DO 5 I=1,NDFGS          C 31
      DO 4 J=2,32          C 32
      IF (XD(I)-XP(J,I)) 5,5,4          C 33
4   CONTINUE          C 34
5   JP(I)=J          C 35
C-----          C 36
C-----CALCS. MADE EACH TIME          C 37
6   DO 17 I=1,NDFGS          C 38
      J=JP(I)          C 39
7   IF (XD(I)-XP(J,I)) 8,14,12          C 40
8   IF (XD(I)-XP(J-1,I)) 9,11,16          C 41
9   J=J-1          C 42
10  IF (J-1) 10,10,8          C 43
11  J=2          C 44
12  GO TO 15          C 45
11  ZD(I)=ZP(J-1,I)          C 46
13  GO TO 17          C 47
12  J=J+1          C 48
13  IF (NPTS(I)-J) 13,7,7          C 49
13  J=NPTS(I)          C 50
14  GO TO 15          C 51
14  ZD(I)=ZP(J,I)          C 52
15  GO TO 17          C 53
15  WRITE (6,21) I          C 54
C-----          C 55
16  ZD(I)=ZP(J-1,I)+SL(J-1,I)*(XD(I)-XP(J-1,I))          C 56
C-----JP(I) STORES VALUE OF XD LOCATION          C 57
C----- TO USE AS FIRST TRY NEXT TIME.          C 58
17  JP(I)=J          C 59
C-----          C 60
      RETURN          C 61
C-----          C 62
18  FORMAT (I2,8X,8I3)          C 63
C-----          C 64
C-----          C 65
C-----          C 66
C-----          C 67

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19	FORMAT (8E10.3)	C 68
20	FORMAT (4H0DFG,I3,17H XP AND ZP INPUTS/(1H0,4(2E12.4,4X)))	C 69
21	FORMAT (4H0DFG,I3,16H RANGE EXCEEDED.)	C 70
	END	C 71

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SUBROUTINE TRLG (XT,W,ZT)                                D  1
C-----                                                 D  2
C-----VARIABLE TRANSPORT LAG GENERATOR - FORTRAN IV      D  3
C-----                                                 D  4
C-----USES UP TO 300 POINT APPROXIMATION FOR             D  5
C-----UP TO 6 VARIABLES. USES INVENTORY CALC.            D  6
C-----                                                 D  7
C-----INPUTS FOR EACH LAG (TOTAL = NLAGS)                D  8
C----- 1. INPUT FUNCTION XT(I)                           D  9
C----- 2. MASS FLOWRATE W(I)                            D 10
C----- 3. INITIAL VALUE OF LAG TIME TI(I)              D 11
C----- 4. MINIMUM EXPECTED VALUE OF MASS FLOW WMIN(I) D 12
C-----                                                 D 13
C-----OUTPUTS ARE LAGGED FUNCTIONS ZT(I)                 D 14
C-----                                                 D 15
      DIMENSION XT(6), W(6), TI(6), WMIN(6), ZT(6), XS(300,6), PS(300,6) D 16
      1, KT(6), JT(6), XJMP(6), JMP(6), NJMP(6)           D 17
C-----                                                 D 18
      COMMON NI,T                                         D 19
C-----NI = 1-ST CALL FLAG (= 0 ON 1-ST CALL)          D 20
C-----T = COMPUTATION TIME INTERVAL                   D 21
C-----                                                 D 22
      IF (NI) 5,1,5                                     D 23
C-----FIRST CALL COMP.                               D 24
1      READ (5,27) NLAGS, TI, WMIN                    D 25
      WRITE (6,28) TI, WMIN                           D 26
      DO 4 I=1,NLAGS                                 D 27
      XJMP(I)=1.0                                    D 28
      XS(1,I)=XT(I)                                 D 29
      PS(1,I)=W(I)*TI(I)                           D 30
      XNSP=PS(1,I)/(WMIN(I)*T)                      D 31
      DO 2 M=1,10                                  D 32
      P1=XJMP(I)*XNSP                            D 33
      IF (300.0-P1) 2,3,3                           D 34
2      XJMP(I)=XJMP(I)+1.0                         D 35
C-----                                                 D 36
3      JMP(I)=IFIX(XJMP(I))                        D 37
      KT(I)=2                                      D 38
      JT(I)=1                                      D 39
4      NJMP(I)=1                                    D 40
      NV=-1                                       D 41
C-----                                                 D 42
C-----CALCS. MADE EACH TIME                       D 43
5      NV=NV+1                                     D 44
C-----** NOTE - IF A RESTART FEATURE IS USED (WHERE THE INITIAL TIME D 45
C-----STEP CALCULATION IS REPEATED), THE FLAG NV AND STATEMENT 33 WILL D 46

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## MATRIX EXPONENTIAL PROGRAM FOR SYSTEMS OF DIF. EQS.

PAGE 11

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C----- OMIT THE TRLG CALC. THIS 1-ST CALL OMISSION MAY BE DELETED BY      D 47
C----- REMOVING STATEMENT 33.                                              D 48
      IF (NV) 6,26,6                                                       D 49
6       DO 25 I=1,NLAGS                                                 D 50
          IF (NJMP(I)-JMP(I)) 7,8,8                                     D 51
7       NJMP(I)=NJMP(I)+1                                              D 52
          GO TO 25                                                       D 53
8       NJMP(I)=1                                                       D 54
      KT=KT(I)                                                       D 55
      JT=JT(I)                                                       D 56
      XS(K,I)=XT(I)                                                   D 57
      PS(K,I)=XJMP(I)*W(I)*T                                         D 58
C----- J=NO. OF ELEMENT AT EXIT. K=NO. AT ENTRANCE                      D 59
      IF (PS(J,I)-PS(K,I)) 12,9,21                                     D 60
9       ZT(I)=XS(J,I)                                                 D 61
          IF (J-300) 11,10,10                                         D 62
10      JT(I)=1                                                       D 63
          GO TO 22                                                       D 64
11      JT(I)=J+1                                                    D 65
          GO TO 22                                                       D 66
C-----                                                       D 67
12      COLLT=XS(J,I)                                                 D 68
      COLLP=PS(J,I)                                                 D 69
      DO 16 M=1,300                                                 D 70
          IF (J-300) 14,13,13                                         D 71
13      J=0                                                       D 72
14      J=J+1                                                    D 73
      PQ=COLLP+PS(J,I)                                              D 74
C-----                                                       D 75
      IF (PQ-PS(K,I)) 15,17,20                                     D 76
15      COLLT=(COLLT*COLLP+XS(J,I)*PS(J,I))/PQ                     D 77
C-----                                                       D 78
16      COLLP=COLLP+PS(J,I)                                         D 79
C-----                                                       D 80
17      ZT(I)=(COLLT*COLLP+XS(J,I)*PS(J,I))/PQ                     D 81
C-----                                                       D 82
      IF (J-300) 19,18,18                                         D 83
18      JT(I)=1                                                       D 84
          GO TO 22                                                       D 85
19      JT(I)=J+1                                                    D 86
          GO TO 22                                                       D 87
C-----                                                       D 88
20      PS(J,I)=PQ-PS(K,I)                                         D 89
      ZT(I)=(COLLT*COLLP+XS(J,I)*PS(J,I))/(COLLP+PS(J,I))           D 90
      JT(I)=J                                                       D 91
          GO TO 22                                                       D 92
C-----                                                       D 93
21      ZT(I)=XS(J,I)                                                 D 94
      PS(J,I)=PS(J,I)-PS(K,I)                                         D 95
C-----                                                       D 96
22      IF (K-300) 24,23,23                                         D 97
23      KT(I)=1                                                       D 98
          GO TO 25                                                       D 99
24      KT(I)=K+1                                                    D 100
25      CONTINUE                                                       D 101
C-----                                                       D 102

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## MATRIX EXPONENTIAL PROGRAM FOR SYSTEMS OF DIF. EQS.

PAGE 12

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26   RETURN
C-----
27   FORMAT (I2/(6E10.3))
28   FORMAT (26HOTRLG INPUTS - TI AND WMIN/(1H0,6E18.5))
END
D 103
D 104
D 105
D 106
D 107

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SUBROUTINE FFLAG (XT,ZT,NLAGS,TI)
C-----FIXED TRANSPORT LAG SUBROUTINE
      DIMENSION A(60,60), C(60,60), HP(60,60), QPT(60,60), X(60), Y(60),
      Z(60), XIC(60), TQP(60)
      COMMON C,HP,A,QPT,X,Z,Y,ITMAX,KK,LL,MM,JJFLAG,XIC,NI,TIME,TMAX,TZE
      IRO,NE,TQP,T,I1Z,ICONTR,PLTINC,MATYES,ICSS,JFLAG,PLT
      DIMENSION XT(15), ZT(15), XS(15,200), TI(15), KT(15), XFR(15), OMX
      I(15), NSP(15)
      IF (NI.NE.0) GO TO 3
C-----FIRST CALL CALCS.
      DO 2 I=1,NLAGS
      KT(I)=3
      XSAMP=TI(I)/T
      NSAMP=IFIX(XSAMP)
      XSAMI=FLOAT(NSAMP)
      XFR(I)=XSAMP-XSAM
      OMX(I)=1.0-XFR(I)
      NSP(I)=NSAMP+1
      IF (NSP(I).GT.200) WRITE (6,11) I,NSP(I)
C-----SET ALL INITIAL VALUES TO ZERO
      NPTS=NSP(I)
      DO 1 J=1,NPTS
      1 XS(I,J)=0.0
      2 CONTINUE
      3 DO 10 I=1,NLAGS
      K=KT(I)
      NS=NSP(I)
      IF (NS-K) 6,4,4
      4 ZT(I)=XS(I,K-1)*OMX(I)+XS(I,K-2)*XFR(I)
      5 XS(I,K-2)=XT(I)
      K=K+1
      GO TO 10
      6 IF (NS-K+2) 9,8,7
      7 ZT(I)=XS(I,NS)*OMX(I)+XS(I,NS-1)*XFR(I)
      GO TO 5
      8 ZT(I)=XS(I,1)*OMX(I)+XS(I,NS)*XFR(I)
      GO TO 5
      9 K=3
      GO TO 4
      10 KT(I)=K
      RETURN
C-----
11   FORMAT (4HOLAG,I3,6H NEEDS,I5,9H SAMPLES.)
END
E 1
E 2
E 3
E 4
E 5
E 6
E 7
E 8
E 9
E 10
E 11
E 12
E 13
E 14
E 15
E 16
E 17
E 18
E 19
E 20
E 21
E 22
E 23
E 24
E 25
E 26
E 27
E 28
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E 40
E 41
E 42
E 43
E 44

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        SUBROUTINE DISTRB
C-----
C-----DISTRB SUBROUTINE FOR BERNIE-S NONLINEAR WORMS
C-----
      DIMENSION A(60,60), C(60,60), HP(60,60), QPT(60,60), X(60), Y(60),
     1 Z(60), XIC(60), TQP(60)
      COMMON C,HP,A,QPT,X,Z,Y,ITMAX,KK,LL,MM,JJFLAG,XIC,NI,TIME,TMAX,TZE
     1 R0,NE,TQP,T,IIZ,ICONTR,PLTINC,MATYES,ICSS,JFLAG,PLT
C-----
C-----XIC DATA READ IN NORMALLY
      IF (NI.EQ.0.AND.ICONTR.EQ.0) GO TO 2
      IF (NI.NE.0) GO TO 4
C-----A MATRIX TO BE RECALCULATED
      NI=1
      ICONTR=0
      TMAX=TMAXS
      Z(1)=Z1S
      Z(2)=Z2S
      Z(3)=0.0
      Z(4)=0.0
      TAU21=T21P*X(2)
      TAU32=T32P*X(3)
      TAU43=T43P*X(4)
      DO 1 I=2,4
1      XIC(I)=X(I)
      GO TO 3
C-----INITIAL CALCS. - MATRIX ELEMENTS
C-----READ IN PARAMETERS RHO,TAU,GMU, AND GLAM. ALSO Z
2      READ (5,8) RH001,RH002,RH003,RH004,RH005
      READ (5,8) TAU21,TAU32,TAU43
      READ (5,8) GMU51,GMU52,GMU53,GMU54
      READ (5,8) GLAM01
      READ (5,8) Z(1),Z(2)
C-----CALC. FIXED MATRIX ELEMENTS
      A(4,4)=-(RH004+GMU54)
      A(5,1)=GMU51
      A(5,2)=GMU52
      A(5,3)=GMU53
      A(5,4)=GMU54
      A(5,5)=-RH005
C-----X(2), 3, AND 4 AND Z1,2 AND TMAX SAVED
      X2S=XIC(2)
      X3S=XIC(3)
      X4S=XIC(4)
      Z1S=Z(1)
      Z2S=Z(2)
      TMAXS=TMAX
C-----RECALC VARIABLE A-S
3      A(1,1)=-(RH001+TAU21+GMU51+GLAM01)
      A(2,1)=TAU21
      A(2,2)=-(RH002+TAU32+GMU52)
      A(3,2)=TAU32
      A(3,3)=-(RH003+TAU43+GMU53)
      A(4,3)=TAU43
C-----CALC. TAU-PRIMES
      T21P=TAU21/XIC(2)

```

```

T32P=TAU32/XIC(3)          57
T43P=TAU43/XIC(4)          58
GO TO 7                     59
C-----CALC. FUDGED Z-S      60
4   Z(1)=Z1S-(T21P*X(2)-TAU21)*X(1)    61
Z(2)=Z2S+(T21P*X(2)-A(2,1))*X(1)-(T32P*X(3)-TAU32)*X(2) 62
Z(3)=(T32P*X(3)-A(3,2))*X(2)-(T43P*X(4)-TAU43)*X(3)    63
Z(4)=(T43P*X(4)-A(4,3))*X(3)          64
C-----RECALC. MATEXP WHEN ABS(X/X0).GT.XLIM      65
XLIM=1.1                    66
DO 5 I=2,4                  67
XMAT=ABS(X(I)/XIC(I))-XLIM 68
IF (XMAT.GE.0.0) GO TO 6    69
5   CONTINUE                 70
GO TO 7                     71
C-----RESTART W/ NEW MATEXP-S IF X OUT OF LINEAR RANGE 72
6   ICONTR=1                73
WRITE (6,9) I,XMAT          74
TMAX=TIME                   75
TZERO=TIME+T               76
7   RETURN                   77
C----- 78
8   FORMAT (8F10.0)          79
9   FORMAT (2HOX,I2,*OUTOFLINEARRANGE-XMAT=*,F6.5) 80
END                         81

```

## SUBROUTINE OUTPUT

```

DIMENSION A(60,60), C(60,60), HP(60,60), QPT(60,60), X(60), Y(60),
1 Z(60), XIC(60), TQP(60)
COMMON C,HP,A,QPT,X,Z,Y,ITMAX,KK,LL,MM,JJFLAG,XIC,NI,TIME,TMAX,TZE
1R0,NE,TQP,T,IIZ,ICONTR,PLTINC,MATYES,ICSS,JFLAG,PLT
IF (NI-1) 1,7,8
1   NC=10                   6
DO 2 NCM=1,51,10            7
WRITE (6,12) LL,((A(I,J),J=NCM,NC),I=1,NE)        8
IF (NE-NC) 3,3,2            9
2   NC=NC+10                10
3   NC=10                   11
DO 4 NCM=1,51,10            12
WRITE (6,13) ((C(I,J),J=NCM,NC),I=1,NE)        13
IF (NE-NC) 5,5,4            14
4   NC=NC+10                15
5   NC=10                   16
DO 6 NCM=1,51,10            17
WRITE (6,14) ((HP(I,J),J=NCM,NC),I=1,NE)        18
IF (NE-NC) 7,7,6            19
6   NC=NC+10                20
7   WRITE (6,15)              21
NI=2                        22
8   WRITE (6,16) TIME        23
NF=1                        24

```

## MATRIX EXPONENTIAL PROGRAM FOR SYSTEMS OF DIF. EQS.

PAGE 1

```

9      NL=MINO(NF+4,NE)
      WRITE (6,17) (X(I),I=NF,NL)
      IF (JFLAG.NE.5) GO TO 10
      WRITE (6,18) (Z(I),I=NF,NL)
10     IF (NL.EQ.NE) GO TO 11
      NF=NF+5
      WRITE (6,19)
      GO TO 9
11     RETURN
C-----
12     FORMAT (2HOA,I2/(1H ,10E11.3))
13     FORMAT (2HOC/(1H ,10E11.3))
14     FORMAT (3HOHP/(1H ,10E11.3))
15     FORMAT (1H-,*TIME*,6X,*0*,23X,*SOLUTIONVECTOR*,21X,*0*,22X,*DISTUR
     1BANCEVECTOR*/)
16     FORMAT (1H ,E10.3,*0*)
17     FORMAT (1H+,15X,5E11.3,*0*)
18     FORMAT (1H+,75X,5E11.3)
19     FORMAT (12X,*0*)
      END

```

## SAMPLE DATA DECK FOR MATEXP

PAGE 16

05	.000001	0.0	0.01	3.0	0.01	4 1 5 320 0 0	1
	1 3421.26	2 213.44		3 62.06	4 8.87	5 24.38	
2.23	8.86	5.10	1.466	188.6			
0.84	1.79	0.339					
1.01	5.13	0.74	0.676				
2.0							
20810.	486.						

MATEXP CASE 1  
 NO. OF EQUATIONS 5  
 SPECIFIED PRECISION .000000100  
 TIME INTERVAL .01000000  
 PLOT INCREMENT .01000000

CONTROL FLAGS -

MATES 4  
 ICSS 1  
 JFLAG 5  
 ICONTR 0

MAX. TERMS IN EXPONENTIAL APPROX. 32

SINGLE Z ROW 0  
 MAX. ALLOWABLE A\*DT 1.000  
 MAX. ALLOWABLE QPT ELEMENT 100.000

MAX. COEFF. MATRIX ELEMENT = A( 5, 5) = -1.880E+02  
 MAX. A\*DT = .94300000 WITH DELTA T = .00500000

MINIMUM NON-ZERO ELEMENT = A( 4, 3) = 3.3900E-01  
 RATIO AMAX/AMIN = 5.5634E+02

NO. OF TERMS IN SERIES APPROX. OF MATEXP = 10

TOTAL NO. OF T HALVINGS = 1

A=0

-6.080E+00	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.
8.400E-01	-1.578E+01	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.
0.	1.790E+00	-6.179E+00	0.	0.	0.	0.	0.	0.	0.	0.	0.
0.	0.	3.390E-01	-2.142E+00	0.	0.	0.	0.	0.	0.	0.	0.
1.010E+00	5.130E+00	7.400E-01	6.760E-01	-1.886E+02	0.	0.	0.	0.	0.	0.	0.

C

9.410E-01	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.
7.533E-03	8.540E-01	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.
6.849E-05	1.604E-01	9.401E-01	0.	0.	0.	0.	0.	0.	0.	0.	0.
7.888E-08	2.801E-05	3.252E-03	9.788E-01	0.	0.	0.	0.	0.	0.	0.	0.
4.484E-03	2.088E-02	3.205E-03	2.999E-03	1.517E-01	0.	0.	0.	0.	0.	0.	0.

H/P

9.702E-03	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.
3.507E-05	9.251E-03	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.
2.337E-07	8.523E-05	9.697E-03	0.	0.	0.	0.	0.	0.	0.	0.	0.
2.0000E-10	9.526E-08	1.649E-05	9.894E-03	0.	0.	0.	0.	0.	0.	0.	0.
2.925E-05	1.412E-04	2.112E-05	1.936E-05	4.498E-03	0.	0.	0.	0.	0.	0.	0.

TIME

SOLUTION VECTOR

0.	3.421E+03	2.134E+02	6.206E+01	8.870E+00	2.438E+01	2.081E+04	4.860E+02	0.	0.	0.	0.
1.0000E-02	3.421E+03	2.134E+02	6.205E+01	8.890E+00	2.444E+01	2.081E+04	4.860E+02	0.	0.	0.	0.
3.0000E-02	3.422E+03	2.133E+02	6.203E+01	8.910E+00	2.440E+01	2.081E+04	4.851E+02	-1.362E-01	4.778E-02	0.	0.
4.0000E-02	3.422E+03	2.132E+02	6.192E+01	8.930E+00	2.440E+01	2.081E+04	4.842E+02	-2.330E-01	9.551E-02	0.	0.
5.0000E-02	3.422E+03	2.131E+02	6.192E+01	8.951E+00	2.440E+01	2.081E+04	4.834E+02	-4.401E-01	1.432E-01	0.	0.
6.0000E-02	3.422E+03	2.130E+02	6.192E+01	8.971E+00	2.440E+01	2.081E+04	4.826E+02	-6.012E-01	1.908E-01	0.	0.
7.0000E-02	3.422E+03	2.130E+02	6.192E+01	8.991E+00	2.440E+01	2.081E+04	4.819E+02	-7.837E-01	2.383E-01	0.	0.
8.0000E-02	3.422E+03	2.129E+02	6.190E+01	9.011E+00	2.439E+01	2.082E+04	4.812E+02	-9.694E-01	2.857E-01	0.	0.
9.0000E-02	3.422E+03	2.129E+02	6.187E+01	9.031E+00	2.439E+01	2.082E+04	4.805E+02	-1.164E+00	3.330E-01	0.	0.
1.0000E-01	3.422E+03	2.128E+02	6.184E+01	9.071E+00	2.439E+01	2.082E+04	4.800E+02	-1.367E+00	3.802E-01	0.	0.
1.1000E-01	3.422E+03	2.128E+02	6.182E+01	9.090E+00	2.439E+01	2.082E+04	4.795E+02	-1.577E+00	4.272E-01	0.	0.
1.2000E-01	3.422E+03	2.127E+02	6.179E+01	9.110E+00	2.439E+01	2.082E+04	4.791E+02	-1.796E+00	4.740E-01	0.	0.
1.3000E-01	3.423E+03	2.127E+02	6.175E+01	9.130E+00	2.439E+01	2.082E+04	4.787E+02	-2.021E+00	5.206E-01	0.	0.

0.	3.421E+03	2.134E+02	6.206E+01	8.870E+00	2.438E+01	2.081E+04	4.860E+02	0.	0.	0.	0.
1.0000E-02	3.421E+03	2.134E+02	6.205E+01	8.890E+00	2.444E+01	2.081E+04	4.860E+02	0.	0.	0.	0.
3.0000E-02	3.422E+03	2.133E+02	6.203E+01	8.910E+00	2.440E+01	2.081E+04	4.851E+02	-1.362E-01	4.778E-02	0.	0.
4.0000E-02	3.422E+03	2.132E+02	6.192E+01	8.930E+00	2.440E+01	2.081E+04	4.842E+02	-2.330E-01	9.551E-02	0.	0.
5.0000E-02	3.422E+03	2.131E+02	6.192E+01	8.951E+00	2.440E+01	2.081E+04	4.834E+02	-4.401E-01	1.432E-01	0.	0.
6.0000E-02	3.422E+03	2.130E+02	6.192E+01	8.971E+00	2.440E+01	2.081E+04	4.826E+02	-6.012E-01	1.908E-01	0.	0.
7.0000E-02	3.422E+03	2.130E+02	6.192E+01	8.991E+00	2.440E+01	2.081E+04	4.819E+02	-7.837E-01	2.383E-01	0.	0.
8.0000E-02	3.422E+03	2.129E+02	6.190E+01	9.011E+00	2.439E+01	2.082E+04	4.812E+02	-9.694E-01	2.857E-01	0.	0.
9.0000E-02	3.422E+03	2.129E+02	6.187E+01	9.031E+00	2.439E+01	2.082E+04	4.805E+02	-1.164E+00	3.330E-01	0.	0.
1.0000E-01	3.422E+03	2.128E+02	6.184E+01	9.071E+00	2.439E+01	2.082E+04	4.800E+02	-1.367E+00	3.802E-01	0.	0.
1.1000E-01	3.422E+03	2.128E+02	6.182E+01	9.090E+00	2.439E+01	2.082E+04	4.795E+02	-1.577E+00	4.272E-01	0.	0.
1.2000E-01	3.422E+03	2.127E+02	6.179E+01	9.110E+00	2.439E+01	2.082E+04	4.791E+02	-1.796E+00	4.740E-01	0.	0.
1.3000E-01	3.423E+03	2.127E+02	6.175E+01	9.130E+00	2.439E+01	2.082E+04	4.787E+02	-2.021E+00	5.206E-01	0.	0.

0.	3.421E+03	2.134E+02	6.206E+01	8.870E+00	2.438E+01	2.081E+04	4.860E+02	0.	0.	0.	0.
1.0000E-02	3.421E+03	2.134E+02	6.205E+01	8.890E+00	2.444E+01	2.081E+04	4.860E+02	0.	0.	0.	0.
3.0000E-02	3.422E+03	2.133E+02	6.203E+01	8.910E+00	2.440E+01	2.081E+04	4.851E+02	-1.362E-01	4.778E-02	0.	0.
4.0000E-02	3.422E+03	2.132E+02	6.192E+01	8.930E+00	2.440E+01	2.081E+04	4.842E+02	-2.330E-01	9.551E-02	0.	0.
5.0000E-02	3.422E+03	2.131E+02	6.192E+01	8.951E+00	2.440E+01	2.081E+04	4.834E+02	-4.401E-01	1.432E-01	0.	0.
6.0000E-02	3.422E+03	2.130E+02	6.192E+01	8.971E+00	2.440E+01	2.081E+04	4.826E+02	-6.012E-01	1.908E-01	0.	0.
7.0000E-02	3.422E+03	2.130E+02	6.192E+01	8.991E+00	2.440E+01	2.081E+04	4.819E+02	-7.837E-01	2.383E-01	0.	0.
8.0000E-02	3.422E+03	2.129E+02	6.190E+01	9.011E+00	2.439E+01	2.082E+04	4.812E+02	-9.694E-01	2.857E-01	0.	0.
9.0000E-02	3.422E+03	2.129E+02	6.187E+01	9.031E+00	2.439E+01	2.082E+04	4.805E+02	-1.164E+00	3.330E-01	0.	0.
1.0000E-01	3.422E+03	2.128E+02	6.184E+01	9.071E+00	2.439E+01	2.082E+04	4.800E+02	-1.367E+00	3.802E-01	0.	0.
1.1000E-01	3.422E+03	2.128E+02	6.182E+01	9.090E+00	2.439E+01	2.082E+04	4.795E+02	-1.577E+00	4.272E-01	0.	0.
1.2000E-01	3.422E+03	2.127E+02	6.179E+01	9.110E+00	2.439E+01	2.082E+04	4.791E+02	-1.796E+00	4.740E-01	0.	0.
1.3000E-01	3.423E+03	2.127E+02	6.175E+01	9.130E+00	2.439E+01	2.082E+04	4.787E+02	-2.021E+00	5.206E-01	0.	0.

1.400E-01	3.423E+03	2.127E+02	6.1172E+01	9.150E+00	2.439E+01	2.082E+04	4.781E+02	-2.492E+00	6.133E-01
1.500E-01	3.423E+03	2.126E+02	6.1169E+01	9.169E+00	2.439E+01	2.082E+04	4.778E+02	-2.731E+00	6.594E-01
1.600E-01	3.423E+03	2.126E+02	6.1155E+01	9.189E+00	2.439E+01	2.082E+04	4.776E+02	-2.988E+00	7.052E-01
1.700E-01	3.423E+03	2.126E+02	6.1162E+01	9.208E+00	2.439E+01	2.082E+04	4.775E+02	-3.248E+00	7.507E-01
1.800E-01	3.423E+03	2.126E+02	6.1158E+01	9.227E+00	2.439E+01	2.082E+04	4.774E+02	-3.504E+00	7.960E-01
1.900E-01	3.423E+03	2.126E+02	6.1155E+01	9.247E+00	2.439E+01	2.082E+04	4.774E+02	-3.769E+00	8.411E-01
2.000E-01	3.423E+03	2.126E+02	6.1151E+01	9.266E+00	2.439E+01	2.082E+04	4.774E+02	-4.039E+00	8.859E-01
2.100E-01	3.423E+03	2.125E+02	6.1147E+01	9.285E+00	2.439E+01	2.082E+04	4.774E+02	-4.312E+00	9.304E-01
2.200E-01	3.423E+03	2.125E+02	6.1143E+01	9.304E+00	2.439E+01	2.082E+04	4.775E+02	-4.589E+00	9.746E-01
2.300E-01	3.423E+03	2.125E+02	6.1139E+01	9.323E+00	2.439E+01	2.082E+04	4.776E+02	-4.869E+00	1.019E+00
2.400E-01	3.423E+03	2.125E+02	6.1135E+01	9.342E+00	2.439E+01	2.082E+04	4.778E+02	-5.151E+00	1.062E+00
2.500E-01	3.424E+03	2.125E+02	6.1131E+01	9.360E+00	2.439E+01	2.082E+04	4.781E+02	-5.433E+00	1.106E+00
2.600E-01	3.424E+03	2.125E+02	6.1127E+01	9.379E+00	2.439E+01	2.082E+04	4.783E+02	-5.712E+00	1.149E+00
2.700E-01	3.424E+03	2.125E+02	6.1123E+01	9.397E+00	2.439E+01	2.082E+04	4.786E+02	-6.014E+00	1.191E+00
2.800E-01	3.424E+03	2.126E+02	6.1119E+01	9.416E+00	2.439E+01	2.082E+04	4.790E+02	-6.305E+00	1.234E+00
2.900E-01	3.424E+03	2.126E+02	6.1115E+01	9.434E+00	2.439E+01	2.082E+04	4.793E+02	-6.597E+00	1.276E+00
3.000E-01	3.424E+03	2.126E+02	6.1111E+01	9.452E+00	2.439E+01	2.082E+04	4.798E+02	-6.890E+00	1.318E+00
3.100E-01	3.424E+03	2.126E+02	6.107E+01	9.470E+00	2.439E+01	2.082E+04	4.802E+02	-7.184E+00	1.359E+00
3.200E-01	3.424E+03	2.126E+02	6.1031E+01	9.488E+00	2.439E+01	2.082E+04	4.807E+02	-7.479E+00	1.400E+00
3.300E-01	3.424E+03	2.126E+02	6.099E+01	9.506E+00	2.439E+01	2.082E+04	4.812E+02	-7.773E+00	1.441E+00
3.400E-01	3.424E+03	2.127E+02	6.094E+01	9.523E+00	2.439E+01	2.082E+04	4.817E+02	-8.068E+00	1.482E+00
3.500E-01	3.424E+03	2.127E+02	6.090E+01	9.541E+00	2.439E+01	2.082E+04	4.823E+02	-8.362E+00	1.522E+00
3.600E-01	3.424E+03	2.127E+02	6.086E+01	9.558E+00	2.440E+01	2.082E+04	4.829E+02	-8.657E+00	1.562E+00
3.700E-01	3.424E+03	2.127E+02	6.082E+01	9.576E+00	2.440E+01	2.082E+04	4.835E+02	-8.950E+00	1.601E+00
3.800E-01	3.424E+03	2.128E+02	6.078E+01	9.593E+00	2.440E+01	2.082E+04	4.842E+02	-9.242E+00	1.641E+00
3.900E-01	3.424E+03	2.128E+02	6.074E+01	9.610E+00	2.440E+01	2.082E+04	4.849E+02	-9.533E+00	1.680E+00
4.000E-01	3.424E+03	2.128E+02	6.070E+01	9.627E+00	2.440E+01	2.082E+04	4.856E+02	-9.823E+00	1.718E+00
4.100E-01	3.424E+03	2.129E+02	6.066E+01	9.644E+00	2.440E+01	2.082E+04	4.863E+02	-1.011E+01	1.756E+00
4.200E-01	3.424E+03	2.129E+02	6.062E+01	9.661E+00	2.440E+01	2.082E+04	4.870E+02	-1.040E+01	1.794E+00
4.300E-01	3.424E+03	2.130E+02	6.058E+01	9.677E+00	2.440E+01	2.082E+04	4.878E+02	-1.068E+01	1.832E+00
4.400E-01	3.424E+03	2.130E+02	6.054E+01	9.694E+00	2.440E+01	2.082E+04	4.885E+02	-1.097E+01	1.869E+00
4.500E-01	3.424E+03	2.130E+02	6.050E+01	9.710E+00	2.440E+01	2.082E+04	4.893E+02	-1.125E+01	1.906E+00
4.600E-01	3.424E+03	2.131E+02	6.046E+01	9.727E+00	2.440E+01	2.082E+04	4.901E+02	-1.153E+01	1.943E+00
4.700E-01	3.424E+03	2.131E+02	6.042E+01	9.743E+00	2.440E+01	2.081E+04	4.908E+02	-1.180E+01	1.979E+00
4.800E-01	3.424E+03	2.132E+02	6.039E+01	9.759E+00	2.441E+01	2.081E+04	4.916E+02	-1.207E+01	2.015E+00

X 40011FLINEARRANGE-XMATE=00020  
 4.90CE-01 3.424E+03 2.132E+02 6.035E+01 9.775E+00 2.441E+01  
 4.926E+02 -1.235E+01 2.051E+00 0.

MATEXP CASE 2  
 NO. OF EQUATIONS 5  
 SPECIFIED PRECISION .00000100  
 TIME INTERVAL .01000000  
 PLOT INCREMENT .00999900

CONTROL FLAGS -

PAYLES 4

ICSS 1

JFLAG 5

ICONTK 0

MAX. TERMS IN EXPONENTIAL APPROX. 32

SINGLE T HOW 0

MAX. ALLOWABLE ADT 1.0000

MAX. ALLOWABLE OPT ELEMENT 100.000

MAX. UEFF. MATRIX ELEMENT = AI(5,5) = -1.8860E+02  
 MAX. ADT = .94300000 WITH DELTA T = .00500000

MINIMUM NON-ZERO ELEMENT = AI(4,3) = 3.7358E-01

RATIO MAX/MIN = 5.0485E+02

NO. OF TERMS IN SERIES APPROX. OF MATEXP = 10

TOTAL NO. OF T HALVINGS = 1

SOLUTIONVECTOR

TIME	SOLUTIONVECTOR	DISTURBANCEVECTOR
4.900E-01	3.424E+03	2.132E+02
5.000E-01	3.424E+03	2.133E+02
5.100E-01	3.424E+03	2.133E+02
5.200E-01	3.424E+03	2.134E+02
5.300E-01	3.424E+03	2.134E+02
5.400E-01	3.424E+03	2.135E+02
5.500E-01	3.424E+03	2.135E+02
5.600E-01	3.424E+03	2.136E+02
5.700E-01	3.424E+03	2.136E+02
5.800E-01	3.424E+03	2.137E+02
5.900E-01	3.424E+03	2.137E+02
6.000E-01	3.424E+03	2.138E+02
6.100E-01	3.423E+03	2.138E+02
6.200E-01	3.423E+03	2.139E+02
6.300E-01	3.423E+03	2.139E+02
6.400E-01	3.423E+03	2.140E+02
6.500E-01	3.423E+03	2.140E+02
6.600E-01	3.423E+03	2.141E+02
6.700E-01	3.423E+03	2.141E+02
6.800E-01	3.423E+03	2.142E+02
6.900E-01	3.423E+03	2.142E+02
7.000E-01	3.422E+03	2.143E+02
7.100E-01	3.422E+03	2.143E+02
7.200E-01	3.422E+03	2.144E+02
7.300E-01	3.422E+03	2.144E+02
7.400E-01	3.422E+03	2.145E+02
7.500E-01	3.422E+03	2.145E+02
7.600E-01	3.422E+03	2.146E+02
7.700E-01	3.422E+03	2.146E+02
7.800E-01	3.422E+03	2.147E+02
7.900E-01	3.422E+03	2.147E+02
8.000E-01	3.422E+03	2.147E+02
8.100E-01	3.421E+03	2.148E+02
8.200E-01	3.421E+03	2.149E+02
8.300E-01	3.421E+03	2.149E+02
8.400E-01	3.421E+03	2.149E+02

$H \cdot 4.01E-01$	$2 \cdot 149E+02$	$5 \cdot 937E+01$	$1 \cdot 027E+01$	$2 \cdot 444E+01$	$5 \cdot 147E+02$	$-7 \cdot 050E+00$	$1 \cdot 101E+00$
$8 \cdot 500E-01$	$2 \cdot 150E+02$	$5 \cdot 935E+01$	$1 \cdot 029E+01$	$2 \cdot 444E+01$	$5 \cdot 151E+02$	$-7 \cdot 199E+00$	$1 \cdot 130E+00$
$8 \cdot 600E-01$	$2 \cdot 150E+02$	$5 \cdot 933E+01$	$1 \cdot 030E+01$	$2 \cdot 444E+01$	$5 \cdot 161E+02$	$-7 \cdot 344E+00$	$1 \cdot 159E+00$
$8 \cdot 700E-01$	$2 \cdot 151E+02$	$5 \cdot 932E+01$	$1 \cdot 031E+01$	$2 \cdot 444E+01$	$5 \cdot 168E+02$	$-7 \cdot 486E+00$	$1 \cdot 188E+00$
$8 \cdot 800E-01$	$2 \cdot 151E+02$	$5 \cdot 930E+01$	$1 \cdot 032E+01$	$2 \cdot 444E+01$	$5 \cdot 175E+02$	$-7 \cdot 626E+00$	$1 \cdot 216E+00$
$8 \cdot 900E-01$	$2 \cdot 151E+02$	$5 \cdot 928E+01$	$1 \cdot 034E+01$	$2 \cdot 444E+01$	$5 \cdot 182E+02$	$-7 \cdot 762E+00$	$1 \cdot 245E+00$
$9 \cdot 000E-01$	$2 \cdot 152E+02$	$5 \cdot 926E+01$	$1 \cdot 035E+01$	$2 \cdot 444E+01$	$5 \cdot 189E+02$	$-7 \cdot 896E+00$	$1 \cdot 273E+00$
$9 \cdot 100E-01$	$2 \cdot 152E+02$	$5 \cdot 925E+01$	$1 \cdot 036E+01$	$2 \cdot 444E+01$	$5 \cdot 195E+02$	$-8 \cdot 028E+00$	$1 \cdot 301E+00$
$9 \cdot 200E-01$	$2 \cdot 153E+02$	$5 \cdot 922E+01$	$1 \cdot 037E+01$	$2 \cdot 444E+01$	$5 \cdot 201E+02$	$-8 \cdot 157E+00$	$1 \cdot 329E+00$
$9 \cdot 300E-01$	$2 \cdot 153E+02$	$5 \cdot 920E+01$	$1 \cdot 039E+01$	$2 \cdot 444E+01$	$5 \cdot 208E+02$	$-8 \cdot 283E+00$	$1 \cdot 357E+00$
$9 \cdot 400E-01$	$2 \cdot 154E+02$	$5 \cdot 920E+01$	$1 \cdot 040E+01$	$2 \cdot 444E+01$	$5 \cdot 214E+02$	$-8 \cdot 407E+00$	$1 \cdot 385E+00$
$9 \cdot 500E-01$	$2 \cdot 154E+02$	$5 \cdot 919E+01$	$1 \cdot 041E+01$	$2 \cdot 444E+01$	$5 \cdot 220E+02$	$-8 \cdot 528E+00$	$1 \cdot 413E+00$
$9 \cdot 600E-01$	$2 \cdot 154E+02$	$5 \cdot 917E+01$	$1 \cdot 042E+01$	$2 \cdot 444E+01$	$5 \cdot 226E+02$	$-8 \cdot 648E+00$	$1 \cdot 441E+00$
$9 \cdot 700E-01$	$2 \cdot 155E+02$	$5 \cdot 916E+01$	$1 \cdot 044E+01$	$2 \cdot 444E+01$	$5 \cdot 232E+02$	$-8 \cdot 765E+00$	$1 \cdot 468E+00$
$9 \cdot 800E-01$	$2 \cdot 155E+02$	$5 \cdot 915E+01$	$1 \cdot 045E+01$	$2 \cdot 444E+01$	$5 \cdot 237E+02$	$-8 \cdot 879E+00$	$1 \cdot 496E+00$
$9 \cdot 900E-01$	$2 \cdot 155E+02$	$5 \cdot 913E+01$	$1 \cdot 046E+01$	$2 \cdot 444E+01$	$5 \cdot 243E+02$	$-8 \cdot 992E+00$	$1 \cdot 522E+00$
$1 \cdot 000E+00$	$2 \cdot 156E+02$	$5 \cdot 912E+01$	$1 \cdot 047E+01$	$2 \cdot 445E+01$	$5 \cdot 248E+02$	$-9 \cdot 103E+00$	$1 \cdot 550E+00$
$1 \cdot 010E+00$	$2 \cdot 156E+02$	$5 \cdot 911E+01$	$1 \cdot 049E+01$	$2 \cdot 445E+01$	$5 \cdot 254E+02$	$-9 \cdot 212E+00$	$1 \cdot 578E+00$
$1 \cdot 020E+00$	$2 \cdot 156E+02$	$5 \cdot 910E+01$	$1 \cdot 050E+01$	$2 \cdot 445E+01$	$5 \cdot 259E+02$	$-9 \cdot 319E+00$	$1 \cdot 603E+00$
$1 \cdot 030E+00$	$2 \cdot 157E+02$	$5 \cdot 908E+01$	$1 \cdot 051E+01$	$2 \cdot 445E+01$	$5 \cdot 264E+02$	$-9 \cdot 424E+00$	$1 \cdot 632E+00$
$1 \cdot 040E+00$	$2 \cdot 157E+02$	$5 \cdot 907E+01$	$1 \cdot 052E+01$	$2 \cdot 445E+01$	$5 \cdot 269E+02$	$-9 \cdot 527E+00$	$1 \cdot 659E+00$
$1 \cdot 050E+00$	$2 \cdot 157E+02$	$5 \cdot 906E+01$	$1 \cdot 053E+01$	$2 \cdot 445E+01$	$5 \cdot 274E+02$	$-9 \cdot 628E+00$	$1 \cdot 686E+00$
$1 \cdot 060E+00$	$2 \cdot 158E+02$	$5 \cdot 905E+01$	$1 \cdot 055E+01$	$2 \cdot 445F+01$	$5 \cdot 279E+02$	$-9 \cdot 728E+00$	$1 \cdot 712E+00$
$1 \cdot 070E+00$	$2 \cdot 158E+02$	$5 \cdot 904E+01$	$1 \cdot 056E+01$	$2 \cdot 445E+01$	$5 \cdot 284E+02$	$-9 \cdot 827E+00$	$1 \cdot 739E+00$
$1 \cdot 080E+00$	$2 \cdot 158E+02$	$5 \cdot 903E+01$	$1 \cdot 057E+01$	$2 \cdot 445E+01$	$5 \cdot 289E+02$	$-9 \cdot 924E+00$	$1 \cdot 766E+00$
$1 \cdot 090E+00$	$2 \cdot 158E+02$	$5 \cdot 902E+01$	$1 \cdot 058E+01$	$2 \cdot 445E+01$	$5 \cdot 293E+02$	$-1 \cdot 002E+01$	$1 \cdot 792E+00$
$1 \cdot 100E+00$	$2 \cdot 159E+02$	$5 \cdot 901E+01$	$1 \cdot 059E+01$	$2 \cdot 445E+01$	$5 \cdot 298E+02$	$-1 \cdot 011E+01$	$1 \cdot 819E+00$
$1 \cdot 110E+00$	$2 \cdot 159E+02$	$5 \cdot 900E+01$	$1 \cdot 060E+01$	$2 \cdot 445E+01$	$5 \cdot 302E+02$	$-1 \cdot 021E+01$	$1 \cdot 845E+00$
$1 \cdot 120E+00$	$2 \cdot 159E+02$	$5 \cdot 899E+01$	$1 \cdot 062E+01$	$2 \cdot 445E+01$	$5 \cdot 306E+02$	$-1 \cdot 030E+01$	$1 \cdot 872E+00$
$1 \cdot 130E+00$	$2 \cdot 160E+02$	$5 \cdot 898E+01$	$1 \cdot 063E+01$	$2 \cdot 445E+01$	$5 \cdot 310E+02$	$-1 \cdot 039E+01$	$1 \cdot 898E+00$
$1 \cdot 140E+00$	$2 \cdot 160E+02$	$5 \cdot 897E+01$	$1 \cdot 064E+01$	$2 \cdot 445E+01$	$5 \cdot 314E+02$	$-1 \cdot 048E+01$	$1 \cdot 924E+00$
$1 \cdot 150E+00$	$2 \cdot 160E+02$	$5 \cdot 896E+01$	$1 \cdot 065E+01$	$2 \cdot 445E+01$	$5 \cdot 317E+02$	$-1 \cdot 056E+01$	$1 \cdot 950E+00$
$1 \cdot 160E+00$	$2 \cdot 160E+02$	$5 \cdot 895E+01$	$1 \cdot 066E+01$	$2 \cdot 445F+01$	$5 \cdot 322E+02$	$-1 \cdot 064E+01$	$1 \cdot 976E+00$
$1 \cdot 170E+00$	$2 \cdot 161E+02$	$5 \cdot 894E+01$	$1 \cdot 068E+01$	$2 \cdot 445E+01$	$5 \cdot 326E+02$	$-1 \cdot 074E+01$	$2 \cdot 002E+00$
$1 \cdot 180E+00$	$2 \cdot 161E+02$	$5 \cdot 893E+01$	$1 \cdot 069E+01$	$2 \cdot 445E+01$	$5 \cdot 330E+02$	$-1 \cdot 082E+01$	$2 \cdot 028E+00$
$1 \cdot 190E+00$	$2 \cdot 161E+02$	$5 \cdot 892E+01$	$1 \cdot 070E+01$	$2 \cdot 445E+01$	$5 \cdot 334E+02$	$-1 \cdot 091E+01$	$2 \cdot 054E+00$
$1 \cdot 200E+00$	$2 \cdot 161E+02$	$5 \cdot 891E+01$	$1 \cdot 071E+01$	$2 \cdot 445E+01$	$5 \cdot 337E+02$	$-1 \cdot 099E+01$	$2 \cdot 080E+00$
$1 \cdot 210E+00$	$2 \cdot 161E+02$	$5 \cdot 890E+01$	$1 \cdot 072E+01$	$2 \cdot 445E+01$	$5 \cdot 341E+02$	$-1 \cdot 107E+01$	$2 \cdot 106E+00$
$1 \cdot 220E+00$	$2 \cdot 162E+02$	$5 \cdot 889E+01$	$1 \cdot 073E+01$	$2 \cdot 445E+01$	$5 \cdot 344E+02$	$-1 \cdot 115E+01$	$2 \cdot 132E+00$
$1 \cdot 230E+00$	$2 \cdot 162E+02$	$5 \cdot 888E+01$	$1 \cdot 074E+01$	$2 \cdot 445E+01$	$5 \cdot 348E+02$	$-1 \cdot 123E+01$	$2 \cdot 158E+00$
$1 \cdot 240E+00$	$2 \cdot 162E+02$	$5 \cdot 888E+01$	$1 \cdot 076E+01$	$2 \cdot 445E+01$	$5 \cdot 351E+02$	$-1 \cdot 132E+01$	$2 \cdot 183E+00$

X 40UTLINEARRANGE-XMATT=0.0042  
 $3 \cdot 418E+03 \quad 2 \cdot 162E+02 \quad 5 \cdot 887E+01 \quad 1 \cdot 077E+01 \quad 2 \cdot 445F+01 \quad 2 \cdot 077E+04 \quad 5 \cdot 355E+02 \quad -1 \cdot 140F+01 \quad 2 \cdot 209E+00 \quad 0.$





2.260E+00	3.414E+03	2.176E+02	5.801E+01	1.180E+01	2.447E+01	2.079E+04	5.094E+02	-7.620E+00	2.270E+00	0.
2.270E+00	3.414E+03	2.176E+02	5.800E+01	1.181E+01	2.447E+01	2.079E+04	5.097E+02	-7.693E+00	2.289E+00	0.
2.280E+00	3.414E+03	2.176E+02	5.799E+01	1.182E+01	2.447E+01	2.079E+04	5.099E+02	-7.766E+00	2.308E+00	0.
2.290E+00	3.414E+03	2.176E+02	5.798E+01	1.183E+01	2.447E+01	2.079E+04	5.101E+02	-7.838E+00	2.327E+00	0.
2.300E+00	3.414E+03	2.176E+02	5.797E+01	1.184E+01	2.447E+01	2.079E+04	5.104E+02	-7.910E+00	2.346E+00	0.
2.310E+00	3.414E+03	2.176E+02	5.796E+01	1.184E+01	2.447E+01	2.079E+04	5.106E+02	-7.982E+00	2.365E+00	0.
2.320E+00	3.414E+03	2.176E+02	5.795E+01	1.185E+01	2.447E+01	2.079E+04	5.108E+02	-8.053E+00	2.384E+00	0.
<b>X 40U10SLN4RARRANG-XMAX=.00072</b>										
2.330E+00	3.414E+03	2.177E+02	5.795E+01	1.186E+01	2.447E+01	2.079E+04	5.111E+02	-8.125E+00	2.402E+00	0.

MATEXP CASE 4  
 NO. OF EQUATIONS 5  
 SPECIFIED PRECISION .000000100  
 TIME INTERVAL .0100C000  
 PLOT INCREMENT .00999700

CONTROL FLAGS -  
 NATYES 4  
 SINGLE Z ROW 0  
 MAX. ALLOWABLE A\*DT 1.000  
 MAX. ALLOWABLE OPT ELEMENT 100.000

MAX. TERMS IN EXPONENTIAL APPROX. 32

MAX. A\*DT = .94300000 WITH DELTA T = .005000000  
 MINIMUM NON-ZERO ELEMENT = A( 4, 3) = 4.53331E-01  
 RATIO A(MAX)/A(MIN) = 4.9605E+02

NO. OF TERMS IN SERIES APPROX. OF MATEXP = 10

TOTAL NO. OF T HALVINGS = 1

TIME SOLUTION VECTOR

2.330E+00	3.414E+03	2.177E+02	5.795E+01	1.186E+01	2.447E+01	2.081E+04	4.860E+02	0.	0.
2.340E+00	3.414E+03	2.177E+02	5.794E+01	1.187E+01	2.447E+01	2.081E+04	4.860E+02	0.	0.
2.350E+00	3.414E+03	2.177E+02	5.793E+01	1.188E+01	2.447E+01	2.081E+04	4.862E+02	-7.076E-02	1.884E-02
2.360E+00	3.414E+03	2.177E+02	5.792E+01	1.189E+01	2.447E+01	2.081E+04	4.865E+02	-1.413E-01	3.760E-02
2.370E+00	3.414E+03	2.177E+02	5.791E+01	1.189E+01	2.447E+01	2.081E+04	4.867E+02	-2.115E-01	5.629E-02
2.380E+00	3.414E+03	2.177E+02	5.791E+01	1.190E+01	2.447E+01	2.081E+04	4.869E+02	-2.815E-01	7.491E-02
2.390E+00	3.414E+03	2.178E+02	5.790E+01	1.191E+01	2.447E+01	2.081E+04	4.871E+02	-3.512E-01	9.345E-02
2.400E+00	3.414E+03	2.178E+02	5.789E+01	1.192E+01	2.447E+01	2.081E+04	4.874E+02	-4.206E-01	1.119E-01
2.410E+00	3.414E+03	2.178E+02	5.788E+01	1.193E+01	2.447E+01	2.081E+04	4.876E+02	-4.899E-01	1.303E-01
2.420E+00	3.414E+03	2.178E+02	5.787E+01	1.194E+01	2.447E+01	2.081E+04	4.878E+02	-5.587E-01	1.486E-01
2.430E+00	3.414E+03	2.178E+02	5.787E+01	1.194E+01	2.447E+01	2.081E+04	4.880E+02	-6.273E-01	1.669E-01
2.440E+00	3.414E+03	2.178E+02	5.786E+01	1.195E+01	2.447E+01	2.081E+04	4.883E+02	-6.956E-01	1.851E-01
2.450E+00	3.413E+03	2.178E+02	5.785E+01	1.196E+01	2.448E+01	2.081E+04	4.885E+02	-7.637E-01	2.032E-01
2.460E+00	3.413E+03	2.178E+02	5.784E+01	1.197E+01	2.448E+01	2.081E+04	4.887E+02	-8.315E-01	2.212E-01
2.470E+00	3.413E+03	2.179E+02	5.783E+01	1.198E+01	2.448E+01	2.081E+04	4.889E+02	-8.990E-01	2.392E-01
2.480E+00	3.413E+03	2.179E+02	5.779E+01	1.199E+01	2.448E+01	2.081E+04	4.891E+02	-9.662E-01	2.571E-01
2.490E+00	3.413E+03	2.179E+02	5.778E+01	1.199E+01	2.448E+01	2.081E+04	4.894E+02	-1.033E+00	2.749E-01
2.500E+00	3.413E+03	2.179E+02	5.778E+01	1.200E+01	2.448E+01	2.081E+04	4.896E+02	-1.100E+00	2.927E-01
2.510E+00	3.413E+03	2.179E+02	5.778E+01	1.201E+01	2.448E+01	2.081E+04	4.898E+02	-1.166E+00	3.103E-01
2.520E+00	3.413E+03	2.179E+02	5.778E+01	1.202E+01	2.448E+01	2.081E+04	4.900E+02	-1.233E+00	3.280E-01
2.530E+00	3.413E+03	2.179E+02	5.779E+01	1.203E+01	2.448E+01	2.081E+04	4.902E+02	-1.300E+00	3.455E-01
2.540E+00	3.413E+03	2.179E+02	5.778E+01	1.203E+01	2.448E+01	2.081E+04	4.905E+02	-1.364E+00	3.630E-01
2.550E+00	3.413E+03	2.180E+02	5.777E+01	1.204E+01	2.448E+01	2.081E+04	4.907E+02	-1.429E+00	3.804E-01
2.560E+00	3.413E+03	2.180E+02	5.778E+01	1.205E+01	2.448E+01	2.081E+04	4.909E+02	-1.494E+00	3.977E-01
2.570E+00	3.413E+03	2.180E+02	5.777E+01	1.206E+01	2.448E+01	2.081E+04	4.911E+02	-1.559E+00	4.150E-01
2.580E+00	3.413E+03	2.180E+02	5.776E+01	1.207E+01	2.448E+01	2.081E+04	4.913E+02	-1.623E+00	4.322E-01
2.590E+00	3.413E+03	2.180E+02	5.775E+01	1.207E+01	2.448E+01	2.081E+04	4.915E+02	-1.688E+00	4.493E-01
2.600E+00	3.413E+03	2.180E+02	5.774E+01	1.208E+01	2.448E+01	2.081E+04	4.917E+02	-1.752E+00	4.664E-01
2.610E+00	3.413E+03	2.181E+02	5.773E+01	1.209E+01	2.448E+01	2.081E+04	4.920E+02	-1.815E+00	4.834E-01
2.620E+00	3.413E+03	2.181E+02	5.772E+01	1.210E+01	2.448E+01	2.081E+04	4.922E+02	-1.879E+00	5.003E-01
2.630E+00	3.413E+03	2.181E+02	5.771E+01	1.210E+01	2.448E+01	2.081E+04	4.924E+02	-1.942E+00	5.171E-01
2.640E+00	3.413E+03	2.181E+02	5.770E+01	1.211E+01	2.448E+01	2.080E+04	4.926E+02	-2.005E+00	5.339E-01
2.650E+00	3.413E+03	2.181E+02	5.769E+01	1.212E+01	2.448E+01	2.080E+04	4.928E+02	-2.067E+00	5.507E-01
2.660E+00	3.413E+03	2.181E+02	5.768E+01	1.213E+01	2.448E+01	2.080E+04	4.930E+02	-2.129E+00	5.673E-01
2.670E+00	3.413E+03	2.181E+02	5.768E+01	1.213E+01	2.448E+01	2.080E+04	4.932E+02	-2.191E+00	5.839E-01

2.680E+00	3.413E+03	2.181E+02	5.768E+01	1.214E+01	2.448E+01	2.080E+04	4.934E+02	-2.253E+00	6.004E-01
2.690E+00	3.413E+03	2.181E+02	5.767E+01	1.215E+01	2.448E+01	2.080E+04	4.934E+02	-2.315E+00	6.169E-01
2.700E+00	3.413E+03	2.181E+02	5.766E+01	1.216E+01	2.448E+01	2.080E+04	4.934E+02	-2.376E+00	6.333E-01
2.710E+00	3.413E+03	2.181E+02	5.765E+01	1.216E+01	2.448E+01	2.080E+04	4.934E+02	-2.437E+00	6.496E-01
2.720E+00	3.413E+03	2.182E+02	5.764E+01	1.217E+01	2.448E+01	2.080E+04	4.934E+02	-2.498E+00	6.659E-01
2.730E+00	3.413E+03	2.182E+02	5.763E+01	1.218E+01	2.448E+01	2.080E+04	4.934E+02	-2.558E+00	6.821E-01
2.740E+00	3.413E+03	2.182E+02	5.762E+01	1.219E+01	2.448E+01	2.080E+04	4.934E+02	-2.618E+00	6.982E-01
2.750E+00	3.413E+03	2.182E+02	5.761E+01	1.219E+01	2.448E+01	2.080E+04	4.934E+02	-2.678E+00	7.143E-01
2.760E+00	3.413E+03	2.182E+02	5.760E+01	1.220E+01	2.448E+01	2.080E+04	4.934E+02	-2.738E+00	7.303E-01
2.770E+00	3.413E+03	2.182E+02	5.761E+01	1.221E+01	2.448E+01	2.080E+04	4.934E+02	-2.797E+00	7.462E-01
2.780E+00	3.413E+03	2.182E+02	5.761E+01	1.221E+01	2.448E+01	2.080E+04	4.934E+02	-2.857E+00	7.621E-01
2.790E+00	3.413E+03	2.182E+02	5.760E+01	1.222E+01	2.448E+01	2.080E+04	4.934E+02	-2.916E+00	7.779E-01
2.800E+00	3.413E+03	2.183E+02	5.759E+01	1.223E+01	2.448E+01	2.080E+04	4.934E+02	-2.974E+00	7.936E-01
2.810E+00	3.412E+03	2.183E+02	5.759E+01	1.224E+01	2.448E+01	2.080E+04	4.934E+02	-3.033E+00	8.093E-01
2.820E+00	3.412E+03	2.183E+02	5.758E+01	1.224E+01	2.448E+01	2.080E+04	4.934E+02	-3.091E+00	8.250E-01
2.830E+00	3.412E+03	2.183E+02	5.757E+01	1.225E+01	2.448E+01	2.080E+04	4.934E+02	-3.149E+00	8.405E-01
2.840E+00	3.412E+03	2.183E+02	5.757E+01	1.226E+01	2.448E+01	2.080E+04	4.934E+02	-3.206E+00	8.560E-01
2.850E+00	3.412E+03	2.183E+02	5.756E+01	1.226E+01	2.448E+01	2.080E+04	4.934E+02	-3.264E+00	8.715E-01
2.860E+00	3.412E+03	2.183E+02	5.755E+01	1.227E+01	2.448E+01	2.080E+04	4.934E+02	-3.321E+00	8.868E-01
2.870E+00	3.412E+03	2.183E+02	5.754E+01	1.227E+01	2.448E+01	2.080E+04	4.934E+02	-3.378E+00	9.021E-01
2.880E+00	3.412E+03	2.183E+02	5.754E+01	1.228E+01	2.448E+01	2.080E+04	4.934E+02	-3.435E+00	9.174E-01
2.890E+00	3.412E+03	2.184E+02	5.753E+01	1.229E+01	2.448E+01	2.080E+04	4.934E+02	-3.491E+00	9.326E-01
2.900E+00	3.412E+03	2.184E+02	5.753E+01	1.230E+01	2.448E+01	2.080E+04	4.934E+02	-3.548E+00	9.477E-01
2.910E+00	3.412E+03	2.184E+02	5.752E+01	1.231E+01	2.448E+01	2.080E+04	4.934E+02	-3.604E+00	9.628E-01
2.920E+00	3.412E+03	2.184E+02	5.751E+01	1.231E+01	2.448E+01	2.080E+04	4.934E+02	-3.660E+00	9.778E-01
2.930E+00	3.412E+03	2.184E+02	5.751E+01	1.232E+01	2.448E+01	2.080E+04	4.934E+02	-3.715E+00	9.927E-01
2.940E+00	3.412E+03	2.184E+02	5.750E+01	1.233E+01	2.448E+01	2.080E+04	4.934E+02	-3.770E+00	1.008E+00
2.950E+00	3.412E+03	2.184E+02	5.750E+01	1.233E+01	2.448E+01	2.080E+04	4.934E+02	-3.820E+00	1.022E+00
2.960E+00	3.412E+03	2.184E+02	5.749E+01	1.234E+01	2.448E+01	2.080E+04	4.934E+02	-3.881E+00	1.037E+00
2.970E+00	3.412E+03	2.184E+02	5.748E+01	1.235E+01	2.448E+01	2.080E+04	4.934E+02	-3.935E+00	1.052E+00
2.980E+00	3.412E+03	2.184E+02	5.748E+01	1.235E+01	2.448E+01	2.080E+04	4.934E+02	-3.990E+00	1.067E+00
2.990E+00	3.412E+03	2.185E+02	5.747E+01	1.236E+01	2.448E+01	2.080E+04	4.934E+02	-3.994E+00	1.081E+00
3.000E+00	3.412E+03	2.185E+02	5.746E+01	1.237E+01	2.448E+01	2.080E+04	4.934E+02	-4.049E+00	1.096E+00
3.010E+00	3.412E+03	2.185E+02	5.746E+01	1.237E+01	2.448E+01	2.080E+04	4.934E+02	-4.152E+00	1.110E+00

## BMD-05V-General Linear Hypothesis

### INTRODUCTION

BMD-05V is written in FORTRAN and operates on the CDC 6400 computer with the NCAR compiler. This program performs the calculations required for the general linear hypothesis model. The independent variables are of two general types:

1. Variables used to specify the analysis of variance classifications.
2. Variables used as covariates.

By use of these variables, the program can be used for balanced or unbalanced analysis of variance or covariance designs and missing value problems. The program is described in detail in the BMD manual.

This program is extremely powerful for several reasons.

1. It can handle missing data and unbalanced designs, both in the analysis of variance and the analysis of covariance.
2. The estimates of the coefficients of the linear model (Model I in this case) are given for any specified hypothesis, along with the residual sums of squares under those hypotheses. Thus, for example, the standard non-descript format for an analysis of covariance (assume the slopes are equal between cells and test for coincidental lines) need not be followed. The analysis may be run under any hypothesis and alternative desired.

Let  $H_0$  be the null hypothesis and  $H_a$  be the alternative. Suppose that

$N - k$  = degrees of freedom of the residual sums of squares under  $H_0$  (i.e.,  $k$  coefficients of the linear model estimated under  $H_0$ ).

$N - S$  = degrees of freedom of the residual sum of squares under

$H\omega$  (i.e. s ( $k$ ) coefficients of the linear model estimated under  $H\omega$ ).

$R\Omega$  = residual sum of squares under  $\Omega$

$R\omega$  = residual sum of squares under  $\omega$

Then we reject  $H\Omega$  at level of significance  $\alpha$  i.j.

$$\frac{(R\omega - R\Omega)/(k-s)}{R\Omega/(N-k)} > F_{1-\alpha}(k-s, N-k).$$

3. Since the sums of squares and degrees of freedom are the same for both a Model I and a Model II analysis of variance design, the analysis of variance can be performed for either Model I or Model II.

#### SAMPLE RUN

The following example is a one way analysis of covariance with unequal numbers of observations in each cell. Three groups are compared:

A		B		C	
y	x	y	x	y	x
5.9	0.8	5.2	1.6	7.8	0.6
10.7	3.1	13.4	5.8	12.4	3.4
11.4	4.4	10.0	3.6	10.9	1.5
9.6	1.6	7.5	2.0	9.9	0.7
12.6	4.6	10.1	4.3	16.8	4.5
8.0	2.6	11.9	5.8	13.9	4.1
12.8	5.5	10.7	4.8	11.4	2.3
7.5	1.1	6.8	3.3	8.9	1.3
12.5	3.9	9.0	2.6	13.7	3.1
14.2	4.9			16.0	4.6
8.4	1.4				

The tests can be divided into two categories:

1. The rate of change of  $y$  with respect to  $x$  (slope) is the same for each cell. Hence we test the following models.

$$\text{Model 1: } y_{ij} = \mu + \alpha_i + \beta x_{ij} + \epsilon_{ij}$$

$$\epsilon_{ij} \sim N(0, \sigma^2)$$

$$\sum_{i=1}^3 \alpha_i = 0$$

$$\text{Model 2: } y_{ij} = \mu + \alpha_i + \beta_i x_{ij} + \epsilon_{ij}.$$

$$\epsilon_{ij} \sim N(0, \sigma^2)$$

$$\sum_{i=1}^3 \alpha_i = 0$$

In order to test the hypothesis that the slope is the same for each cell we let:

$R\Omega$  = residual sum of squares under Model 1

= 28.96339 with 26 df.

$R\omega$  = residual sum of squares under Model 2

= 27.11248 with 24 df.

Then

$$F(2, 24) = \frac{(28.96 - 27.11)/2}{27.11/24} < 1$$

Hence we accept the hypothesis that the slopes are equal for the three cells.

2. The intercepts are the same for the three cells, and thus the regression lines are coincidental for the three cells. Thus, under Model 1 we test

$$H: \alpha_1 = \alpha_2 = \alpha_3 = 0$$

If we accept H the final linear model is

$$Y_{ij} = \mu + \beta x_{ij}$$

If we reject H the final linear model is

$$Y_{ij} = \mu + \alpha_1 + \beta x_{ij}$$

where  $(\mu + \alpha_1)$  is the intercept of the line for each cell.

All that we have to do is, under Model 1, find the residual sum of squares under H:  $\alpha_1 = \alpha_2 = \alpha_3 = 0$ . Call that RH. Then

$$RH = 121.60408 \text{ with } 29 \text{ df.}$$

We test that in the usual manner against RΩ, giving us

$$F(2,24) = \frac{(121.60 - 28.96)/(29 - 26)}{28.96/26} = 41.58$$

Hence we reject the hypothesis for  $\alpha = .01$ . Thus the regression lines are parallel but not coincidental. The final linear model is (1). The coefficients are:

$$\mu = 5.645$$

$$\alpha_1 = -0.199$$

$$\alpha_2 = -2.193$$

$$\alpha_3 = -\alpha_1 - \alpha_2 = 2.392$$

$$\beta = 1.584$$

Thus we have the following three regression lines:

$$\text{Group A: } y = 5.446 + 1.584 x$$

$$\text{Group B: } y = 3.452 + 1.584 x$$

$$\text{Group C: } y = 8.037 + 1.584 x.$$

The output of the two runs is given on the following two pages.

BMD05V - GENERAL LINEAR MODELS - VERSION OF JUNE 30, 1964  
 HEALTH SCIENCES COMPUTING FACILITY, UCLA

PROBLEM NUMBER 01

NUMBER OF DESIGN CARD SETS 3

NUMBER OF INDEPENDENT VARIABLES 4

DESIGN

1	1	1	0
2	1	0	1
3	1	-1	-1

$$MODEL 1 : Y_{ij} = \mu + \alpha_i + \beta X_{ij} + \epsilon_{ij}$$

DESIGN NO. OF MEAN SQR OF SQUARES VARIANCE STD. DEV.

DESIGN	NO. OF REPS	MEAN	SQR OF SQUARES	VARIANCE	STD. DEV.
1	11	10.3477	69.54182	6.9518	2.63708
2	9	9.4444	52.96000	6.02000	2.57294
3	10	12.17000	78.64100	8.73789	2.95599

WITHIN CELLS SUM OF SQUARES = 2.01142818E+02

HYPOTHESES AND SUMS OF SQUARES EXPLAINED BY HYPOTHESES

VARIABLE	HYPOTHESES					
	1	2	3	4	5	6
1	0.000	0.				
2	1.111	1621.68661				
3	1110	3669.50714				
4	0.000	3442.67401				
5	1001	3529.04592				
6	0.001	3251.69210				
7	1000	4611.20131				
RESIDUAL SUM SGS.	3650.65000	201.14282	207.97199	121.60408	198.95792	

ESTIMATES OF COEFFICIENTS

VARIABLE	HYPOTHESES					
	1	2	3	4	5	6
1	0.045097257	10.632424242	-0.305151515	-0.02562266	0.741391035	0.
2	-0.198557126	-1.232424242	-1.232424242	-3.185330571	0.	0.
3	-2.192660224	0.	0.	3.038397142	1.254352547	0.
4	1.56371A541	0.	0.	0.	0.	0.
RESIDUAL SUM SGS.	154.56291	160.69336	41.58109	110.71286		
DEGREES OF FREEDOM OF RESIDUAL SGS.	27	27	27	27	27	27
F TESTS						
DEGREES OF						

FREEDOM OF  
F TESTS

1 26 1 26 2 26 3 26

VARIABLES  
1 10.66333343  
2 n.  
3 n.  
4 n.

RESIDUALS  
DEGREES OF

FREEDOM OF  
RESIDUALS  
F TESTS  
62.043467

DEGREES OF  
FREEDOM OF  
F TESTS  
4 26

PROBLEM NUMBER 0?

NUMBER OF DESIGN CASES: 5

NUMBER OF INDEPENDENT VARIABLES: 3

DESIGN

1	1	1
2	1	-1
3	-1	-1

$$MODEL 2. \quad y_{ij} = \mu + \alpha_i + \beta_j x_{ij} + \epsilon_{ij}$$

$$\sum_{i=1}^3 \alpha_i = 0$$

DESIGN	NO. OF REPS	MEAN Y	SUM OF SQUARES Y	VARIANCE Y	STD. DEV. Y	MEANS OF COVARIATES
1	1	10.3277	69.54182	6.95418	2.63708	0.
2	9	9.40000	52.96000	6.00200	2.57294	0.
3	10	12.17000	78.64100	8.73789	2.95599	0.

WITHIN CELLS SUM OF SQUARES = 2.0114281E+02

HYPOTHESES AND SUMS OF SQUARES EXPLAINED BY HYPOTHESES

1	00000	0.
2	11111	3623.53752
3	11100	3449.50716
4	11111	3450.87950
5	10011	3612.44142
6	00011	3345.7754
7	10000	3411.26033

ESTIMATES OF COEFFICIENTS UNDER MODEL 2.

ESTIMATES OF COEFFICIENTS

VARIABLE	1	2	3	4	5	6
1	5.65747495	10.63262424	0.	0.060682179	0.	0.
2	0.	0.	0.	0.	0.	0.
3	0.	0.	0.	0.	0.	0.
4	0.	0.	0.	0.	0.	0.
5	0.	0.	0.	0.	0.	0.
6	0.	0.	0.	0.	0.	0.
RESIDUAL SUM SQU.	3650.64000	27.11143	20.114282	19.677050	3A.15658	254.94246
DEGREES OF FREEDOM OF RESIDUALS	39	27	25	26	26	27

F TESTS	Degrees of Freedom (F TESTS)	$\chi^2$ TESTS	Degrees of Freedom ( $\chi^2$ TESTS)	TESTS
3	24	3	24	3
51.35062	150.16144	4.88883	67.22513	

VARIABLE	RESIDUAL SUM SQU.	DEGREES OF FREEDOM OF RESIDUALS	+ TESTS	DEGREES OF FREEDOM OF TESTS
1	10.6633333333	7		5
2	7.0	6		4
3	0.0	5		3
4	0.0	4		2
5	0.0	3		1
6	0.0	2		
	23.9 = 24.344	14		24

CP SEC=000003 PP SEC=00000H PH110006 HU=000000 RU=000326 PL=00000

INPUT DECK FOR SAMPLE RUN OF BMD05V (GENERAL LINEAR HYPOTHESIS)

PROBLM01 3 3 1 4 0  
(2F5.0)

DESIGN 11 1 1 0

0.8 5.9  
3.1 10.7  
4.4 11.4  
1.6 9.6  
4.6 12.6  
2.6 8.0  
5.5 12.8  
1.1 7.5  
3.9 12.5  
4.9 14.2  
1.4 8.4

DESIGN 9 1 0 1

1.6 5.2  
5.8 13.4  
3.6 10.0  
2.0 7.5  
4.3 10.1  
5.8 11.9  
4.8 10.7  
3.3 6.8  
2.6 9.0

DESIGN 10 1 -1 -1

0.6 7.8  
3.4 12.4  
1.5 10.9  
0.7 9.9  
4.5 16.8  
4.1 13.9  
2.3 11.4  
1.3 8.9  
3.1 13.7  
4.6 16.0

HYPOTH1110

HYPOTH0111

HYPOTH1001

HYPOTH0001

PROBLM02 3 3 3 4 0  
(4F5.0)

DESIGN 11 1 1 0

0.8 0 0 5.9  
3.1 0 0 10.7  
4.4 0 0 11.4  
1.6 0 0 9.6  
4.6 0 0 12.6  
2.6 0 0 8.0  
5.5 0 0 12.8  
1.1 0 0 7.5  
3.9 0 0 12.5  
4.9 0 0 14.2  
1.4 0 0 8.4

DESIGN 9 1 0 1

0 1.6 0 5.2  
0 5.8 0 13.4

1

1

INPUT DECK FOR SAMPLE RUN OF BMD05V (GENERAL LINEAR HYPOTHESIS)

```
0 3.6 0 10.0
0 2.0 0 7.5
0 4.3 0 10.1
0 5.8 0 11.9
0 4.8 0 10.7
0 3.3 0 6.8
0 2.6 0 9.0
DESIGN 10 1 -1 -1
0 0 0.6 7.8
0 0 3.4 12.4
0 0 1.5 10.9
0 0 0.7 9.9
0 0 4.5 16.8
0 0 4.1 13.9
0 0 2.3 11.4
0 0 1.3 8.9
0 0 3.1 13.7
0 0 4.6 16.0
HYPOTH111000
HYPOTH011111
HYPOTH100111
HYPOTH000111
FINISH
```

## MATRIX MANIPULATION ROUTINES

### INTRODUCTION

The matrix manipulation routines consist of several simple and easy to use subroutines, each of which performs a specific matrix operation. Although the subroutines are very short and the coding is simple for most of them, the routines should be used, in preference to performing the operations in the main program, as they will increase the simplicity and clarity of the user's program. The operations performed by the subroutines are as follows:

1. TRNSPO calculates the transpose of a matrix and returns the results in another matrix. The transpose is obtained by interchanging the rows and columns of the matrix.
2. ADDSUB accepts two arrays and returns with two additional arrays which contain the sum and difference of the original matrices.
3. SCAMPY accepts a matrix and a scalar, multiplies each element in the matrix by the scalar and returns the result in the original matrix.
4. MATMPY calculates the product of two matrices and returns the result in a third matrix.
5. MATPWR accepts a square matrix as input, raises it to the requested power and returns with the result in a new matrix.
6. INVERT accepts a square matrix as input and uses the Gauss-Jordan Elimination method to replace that matrix with an approximation of its inverse.

7. INVERT2 Is the same as invert except that it also returns the value of the determinant of the matrix. (Since the Gauss-Jordan routine is an approximation, its accuracy decreases if the value of the determinant is close to zero) Consequently, the accuracy of the inversion can be easily checked.

#### INPUT REQUIREMENTS

All of the subroutines, excluding INVERT and INVERT2 use variable dimensioning. This requires that the dimensions for the arrays being sent are the same as the size specified in the parameter lists. For example, if the size of the matrix being sent to TRANSPO is  $3 \times 4$ , the dimension statement in the calling program must also specify the array as being  $3 \times 4$ .

The inversion routines both require that the array being sent is dimensioned  $60 \times 60$  in the calling program. This, however, may be changed if desired by changing only the dimension statements in the subroutine to agree with those in the calling program.

Variables which must be passed to the subroutines are as follows:

1. TRNSPO (A, B, M, N)

A is the M by N matrix being sent

B is an N by M array which will contain the value of the transpose of A.

2. ADDSUB (A, B, C, M, N, Y)

A & B are the matrices to be passed

C is to contain the result of  $A + B$

Y is to contain the result of  $A - B$

M is the number of rows for all four matrices

N is the number of columns for all four matrices

3. SCAMPY (A, X, M, N)

A is the matrix being sent and will contain the  
the result of the scalar product

X is the scalar to be used

M is the number of rows in A

N is the number of columns in A

4. MATMPY (A, B, C, M, N, L)

A is an M x N matrix being sent

B is an N by L matrix being sent

C is an M by L matrix to contain the result of A\*B

M,N,&L are the dimensions of the matrices as  
specified above.

5. MATPWR (A, B, DUM, N, I)

A is the N x N matrix being sent

B is the N X N matrix to contain the result of A  
to the Ith power.

DUM is an N x N dummy matrix and must also be  
dimensioned in the main program

N is the dimension and order for all three matrices

I is the power that the matrix is to be raised to

6. INVERT (A, N)

A is the 60 x 60 array which contains the matrix  
to be inverted and is to contain the result

N is the order of the matrix to be inverted  $1 \leq N \leq 60$

7. INVERT2 (A, N, D)

A is the 60 x 60 array which contains the matrix to  
be inverted. Upon completion of the routine, this

matrix will be replaced by its inverse

N is the number of rows and columns of A that are  
to be inverted (order)  $1 \leq N \leq 60$ .

D is to contain the value of the determinant of A.

Sample listing and output:

A brief, self-explanatory program is included which uses all the routines  
and displays the results.

```

PROGRAM MATRIX
C----- A 1
C-----***** A 2
C-----***** A 3
C-----***** A 4
C----- THIS PROGRAM DISPLAYS AN EXAMPLE OF THE USE OF THE MATRIX A 5
C-----MANIPULATION ROUTINES. IN THE PROGRAM THE FOLLOWING CALCULATIONS A 6
C-----ARE DISPLAYED. TRANSPOSE, ADDITION, SUBTRACTION, MULTIPLICATION, A 7
C-----BOTH BY A SCALAR AND ANOTHER MATRIX, THE INVERSE AND DETERMINANT, A 8
C-----AND THE CALCULATION OF A MATRIX RAISED TO A GIVEN POWER. A 9
C----- A 10
C-----***** A 11
C-----***** A 12
DIMENSION A(4,3), B(3,4), C(4,4), D(3,4), E(3,4), F(3,4), G(60,60) A 13
1, H(4,4), P(4,4) A 14
C----- A 15
READ (5,4) ((A(I,J),J=1,3),I=1,4) A 16
T=10HA A 17
WRITE (6,6) T,((A(I,J),J=1,3),I=1,4) A 18
C----- A 19
C-----CALCULATE THE TRANSPPOSE OF THE 4X3 MATRIX A A 20
C-----AND STORE IT IN THE 3X4 MATRIX, B A 21
C----- A 22
CALL TRNSPO (A,B,4,3) A 23
T=10HA(TRANS.) A 24
WRITE (6,7) T,((B(I,J),J=1,4),I=1,3) A 25
C----- A 26
READ (5,5) ((B(I,J),J=1,4),I=1,3) A 27
T=10HR A 28
WRITE (6,7) T,((B(I,J),J=1,4),I=1,3) A 29
C----- A 30
READ (5,5) ((D(I,J),J=1,4),I=1,3) A 31
T=10HD A 32
WRITE (6,7) T,((D(I,J),J=1,4),I=1,3) A 33
C----- A 34
C-----CALCULATE B+D AND B-D AND STORE THE RESULTS IN A 35
C-----E AND F RESPECTIVELY. ALL MATRICES ARE DIMENSIONED 3X4. A 36
C----- A 37
CALL ADDSUB (B,D,E,3,4,F) A 38
T=10HE=B+D A 39
WRITE (6,7) T,((E(I,J),J=1,4),I=1,3) A 40
T=10HF=B-D A 41
WRITE (6,7) T,((F(I,J),J=1,4),I=1,3) A 42
C----- A 43
C-----MULTIPLY THE 3X4 MATRIX, E, BY THE SCALAR 10.0 A 44
C----- A 45
CALL SCAMPY (E,10.0,3,4) A 46
T=10HE=10.0*E A 47
WRITE (6,7) T,((E(I,J),J=1,4),I=1,3) A 48
C----- A 49
C-----CALCULATE THE PRODUCT, A*B, AND STORE THE RESULT IN C. A 50
C-----A IS DIMENSIONED 4X3, B IS DIMENSIONED 3X4 AND C IS A 51
C-----DIMENSIONED 4X4. A 52
C----- A 53
CALL MATMPY (A,B,C,4,3,4) A 54
T=10HC=A*B A 55
WRITE (6,7) T,((C(I,J),J=1,4),I=1,4) A 56

```

```

C----- A 57
C-----READ IN AND PRINT A NEW C MATRIX A 58
C----- A 59
C----- T=10HC (NEW) A 60
  READ (5,5) ((C(I,J),J=1,4),I=1,4) A 61
  WRITE (6,8) T,((C(I,J),J=1,4),I=1,4) A 62
C----- A 63
C-----THE INVERT SUBROUTINE REQUIRES THAT THE MATRIX SENT IS A 64
C-----A 60X60 ARRAY. THEREFORE, THE ARRAY, C, MUST BE STORED A 65
C-----IN THE ARRAY, G, BEFORE ITS INVERSE CAN BE CALCULATED. A 66
C----- A 67
C----- DO 1 I=1,4 A 68
  DO 1 J=1,4 A 69
1   G(I,J)=C(I,J) A 70
C----- A 71
C-----CALCULATE THE INVERSE OF THE FIRST FOUR ROWS AND FOUR COLUMNS A 72
C-----OF THE MATRIX G. A 73
C----- A 74
C----- CALL INVERT (G,4) A 75
  T=10HC( INVERSE) A 76
  WRITE (6,8) T,((G(I,J),J=1,4),I=1,4) A 77
C----- A 78
C-----STORE THE INVERSE OF C INTO THE ARRAY H A 79
C----- A 80
C----- DO 2 I=1,4 A 81
  DO 2 J=1,4 A 82
2   H(I,J)=G(I,J) A 83
C----- A 84
C-----CALCULATE THE PRODUCT OF C TIMES THE INVERSE OF C A 85
C----- (THIS SHOULD GIVE THE IDENTITY MATRIX) A 86
C----- A 87
C----- CALL MATMPY (C,H,P,4,4,4) A 88
  T=10HIDENTITY A 89
  WRITE (6,7) T,((P(I,J),J=1,4),I=1,4) A 90
C----- A 91
C-----CALCULATE THE INVERSE AND DETERMINANT OF C USING INVERT2 A 92
C-----IT ALSO REQUIRES THAT THE MATRIX IS DIMENSIONED 60X60. A 93
C----- A 94
C----- DO 3 I=1,4 A 95
  DO 3 J=1,4 A 96
3   G(I,J)=C(I,J) A 97
  CALL INVERT2 (G,4,DET) A 98
  T=10HC( INVERSE) A 99
  WRITE (6,8) T,((G(I,J),J=1,4),I=1,4) A 100
  WRITE (6,9) DET A 101
C----- A 102
C-----RAISE C TO THE THIRD POWER AND STORE THE RESULT IN H. A 103
C-----P IS TO BE USED AS A DUMMY MATRIX BY THE SUBROUTINE. A 104
C-----ALL THREE MATRICES ARE DIMENSIONED 4X4. A 105
C----- A 106
C----- CALL MATPWR (C,H,P,4,3) A 107
  T=10HC**3 A 108
  WRITE (6,8) T,((H(I,J),J=1,4),I=1,4) A 109
  STOP A 110
C----- A 111
4   FORMAT (3F5.0) A 112

```

```

5      FORMAT (4F5.0)          A 113
6      FORMAT (1HO,A10,4(3F10.3,/,,11X))   A 114
7      FORMAT (1HO,A10,4(4F10.3,/,,11X))   A 115
8      FORMAT (1HO,A10,4(4E15.7,/,,11X))   A 116
9      FORMAT (*ODETERMINANT = *,E15.7)     A 117
END

```

A 113  
A 114  
A 115  
A 116  
A 117  
A 118

## SUBROUTINE MATMPY (A,B,C,M,N,L)

```

C-----
C----- SUBROUTINE MATMPY MULTIPLIES TWO MATRICES (A*B) TOGETHER    B 1
C----- AND STORES THE RESULT IN C. THE DIMENSION STATEMENT IN THE    B 2
C----- MAIN PROGRAM MUST HAVE A DIMENSIONED AS AN M BY N MATRIX.    B 3
C----- B MUST BE DIMENSIONED N BY L AND C MUST BE DIMENSIONED M BY L.    B 4
C----- B 5
C----- DIMENSION A(M,N), B(N,L), C(M,L)          B 6
DO 2 I=1,M          B 7
DO 2 J=1,L          B 8
S=0.                B 9
DO 1 K=1,N          B 10
1   S=S+A(I,K)*B(K,J)        B 11
2   C(I,J)=S          B 12
RETURN              B 13
END.                B 14
B 15
B 16

```

B 1  
B 2  
B 3  
B 4  
B 5  
B 6  
B 7  
B 8  
B 9  
B 10  
B 11  
B 12  
B 13  
B 14  
B 15  
B 16

## SUBROUTINE TRNSPO (A,B,M,N)

```

C-----
C----- THIS SUBROUTINE CALCULATES THE TRANSPOSE OF THE MXN MATRIX A    C 1
C----- AND STORES THE RESULT IN B. A MUST BE DIMENSIONED MXN IN THE    C 2
C----- MAIN PROGRAM AND B MUST BE NXM.    C 3
C----- C 4
C----- DIMENSION A(M,N), B(N,M)          C 5
DO 1 I=1,M          C 6
DO 1 J=1,N          C 7
1   B(J,I)=A(I,J)        C 8
RETURN              C 9
END.                C 10
C 11
C 12

```

C 1  
C 2  
C 3  
C 4  
C 5  
C 6  
C 7  
C 8  
C 9  
C 10  
C 11  
C 12

## SUBROUTINE SCAMPY (A,X,M,N)

```

C-----
C----- THIS SUBROUTINE REPLACES THE MATRIX A BY THE PRODUCT OF A    D 1
C----- AND THE SCALAR, X. A MUST BE DIMENSIONED MXN IN THE MAIN PROGRAM D 2
D 3
D 4

```

```

C-----
      DIMENSION A(M,N)
      MM=M*N
      DO 1 I=1,MM
L     A(I)=X*A(I)
      RETURN
      END

```

D 5  
D 6  
D 7  
D 8  
D 9  
D 10  
D 11

```

      SUBROUTINE ADDSUB (A,B,C,M,N,Y)
C-----
C----- SUBROUTINE ADDSUB STORES THE RESULT OF A+B IN C AND THE
C-----RESULT OF A-B IN Y. A, B, C, AND Y MUST ALL BE DIMENSIONED AS
C-----MXN MATRICES IN THE CALLING PROGRAM.
C-----
      DIMENSION A(M,N), B(M,N), C(M,N), Y(M,N)
      DO 1 I=1,M
      DO 1 J=1,N
      C(I,J)=A(I,J)+B(I,J)
1     Y(I,J)=A(I,J)-B(I,J)
      RETURN
      END

```

E 1  
E 2  
E 3  
E 4  
E 5  
E 6  
E 7  
E 8  
E 9  
E 10  
E 11  
E 12  
E 13

```

      SUBROUTINE INVERT (A,N)
      DIMENSION A(60,60), B(60), C(60), LZ(60)
      DO 1 J=1,N
1     LZ(J)=J
      DO 11 I=1,N
      K=I
      Y=A(I,I)
      L=I-1
      LP=I+1
      IF (N-LP) 5,2,2
2     DO 4 J=LP,N
      W=A(I,J)
      IF (ABS(W)-ABS(Y)) 4,4,3
3     K=J
      Y=W
4     CONTINUE
5     DO 6 J=1,N
      C(J)=A(J,K)
      A(J,K)=A(J,I)
      A(I,J)=-C(J)/Y
      A(I,J)=A(I,J)/Y
6     B(J)=A(I,J)
      A(I,I)=1.0/Y
      J=LZ(I)

```

F 1  
F 2  
F 3  
F 4  
F 5  
F 6  
F 7  
F 8  
F 9  
F 10  
F 11  
F 12  
F 13  
F 14  
F 15  
F 16  
F 17  
F 18  
F 19  
F 20  
F 21  
F 22  
F 23  
F 24

## MATRIX MANIPULATION ROUTINES

PAGE 5

LZ(I)=LZ(K)	F	25
LZ(K)=J	F	26
DO 10 K=1,N	F	27
IF (I-K) 7,10,7	F	28
7 DO 9 J=1,N	F	29
IF (I-J) 8,9,8	F	30
8 A(K,J)=A(K,J)-B(J)*C(K)	F	31
9 CONTINUE	F	32
10 CONTINUE	F	33
11 CONTINUE	F	34
DO 16 I=1,N	F	35
IF (I-LZ(I)) 12,16,12	F	36
12 K=I+1	F	37
DO 15 J=K,N	F	38
IF (I-LZ(J)) 15,13,15	F	39
13 M=LZ(I)	F	40
LZ(I)=LZ(J)	F	41
LZ(J)=M	F	42
DO 14 L=1,N	F	43
C(L)=A(I,L)	F	44
A(I,L)=A(J,L)	F	45
14 A(J,L)=C(L)	F	46
15 CONTINUE	F	47
16 CONTINUE	F	48
RETURN	F	49
END	F	50

## SUBROUTINE INVERT2 (COVA,N,D)

C-----	G	1
C----- SUBROUTINE INVERT USES THE GAUSS-JORDAN ELIMINATION METHOD	G	2
C-----TO REPLACE THE MATRIX, A, WITH ITS INVERSE. THE DIMENSION	G	3
C-----STATEMENT IN THE MAIN PROGRAM MUST HAVE A LISTED AS A 60X60	G	4
C-----MATRIX. HOWEVER, THE ACTUAL NUMBER OF ROWS AND COLUMNS OF A	G	5
C-----THAT ARE TO BE INVERTED IS SPECIFIED BY N (N MUST BE BETWEEN	G	6
C-----0 AND 61)	G	7
C-----	G	8
DIMENSION COVA(60,60), A(60,60), L(60), M(60)	G	9
DOUBLE PRECISION A,D,BIGA,HOLD	G	10
C-----	G	11
C-----CONVERT TO DOUBLE PRECISION	G	12
C-----	G	13
DO 1 I=1,N	G	14
DO 1 J=1,N	G	15
1 A(I,J)=COVA(I,J)	G	16
C-----SEARCH FOR LARGEST ELEMENT	G	17
D=1.0	G	18
DO 17 K=1,N	G	19
L(K)=K	G	20
M(K)=K	G	21
BIGA=A(K,K)	G	22
DO 3 I=K,N	G	23
	G	24

## MATRIX MANIPULATION ROUTINES

PAGE 6

```

DO 3 J=K,N G 25
IF (ABSF(BIGA)-ABSF(A(I,J))) 2,3,3 G 26
2 BIGA=A(I,J) G 27
L(K)=I G 28
M(K)=J G 29
3 CONTINUE G 30
C-----INTERCHANGE ROWS G 31
J=L(K) G 32
IF (L(K)=K) 6,6,4 G 33
4 DO 5 I=1,N G 34
HOLD=-A(K,I) G 35
A(K,I)=A(J,I) G 36
5 A(J,I)=HOLD G 37
C-----INTERCHANGE COLUMNS G 38
6 I=M(K) G 39
IF (M(K)=K) 9,9,7 G 40
7 DO 8 J=1,N G 41
HOLD=-A(J,K) G 42
A(J,K)=A(J,I) G 43
8 A(J,I)=HOLD G 44
C-----DIVIDE COLUMN BY MINUS PIVOT G 45
9 DO 11 I=1,N G 46
IF (I-K) 10,11,10 G 47
10 A(I,K)=A(I,K)/(-A(K,K)) G 48
11 CONTINUE G 49
C-----REDUCE MATRIX G 50
DO 14 I=1,N G 51
DO 14 J=1,N G 52
IF (I-K) 12,14,12 G 53
12 IF (J-K) 13,14,13 G 54
13 A(I,J)=A(I,K)*A(K,J)+A(I,J) G 55
14 CONTINUE G 56
C-----DIVIDE ROW BY PIVOT G 57
DO 16 J=1,N G 58
IF (J-K) 15,16,15 G 59
15 A(K,J)=A(K,J)/A(K,K) G 60
16 CONTINUE G 61
C-----CONTINUED PRODUCT OF PIVOTS G 62
D=D*A(K,K) G 63
C-----REPLACE PIVOT BY RECIPROCAL G 64
AIK,K)=1.0/A(K,K) G 65
17 CONTINUE G 66
C-----FINAL ROW AND COLUMN INTERCHANGE G 67
K=N G 68
18 K=(K-1) G 69
IF (K) 25,25,19 G 70
19 I=L(K) G 71
IF (I-K) 22,22,20 G 72
20 DO 21 J=1,N G 73
HOLD=A(J,K) G 74
A(J,K)=-A(J,I) G 75
21 A(J,I)=HOLD G 76
22 J=M(K) G 77
IF (J-K) 18,18,23 G 78
23 : DO 24 I=1,N G 79
HOLD=A(K,I) G 80

```

## MATRIX MANIPULATION ROUTINES

PAGE 7

	A(K,I)=-A(J,I)	G	81
24	A(J,I)=HOLD	G	82
	GO TO 18	G	83
C-----	CONVERT BACK TO SINGLE PRECISION	G	84
25	DO 26 I=1,N	G	85
	DO 26 J=1,N	G	86
26	COVA(I,J)=A(I,J)	G	87
	RETURN	G	88
	END	G	89

	SUBROUTINE MATPWR (A,B,DUM,N,I)	H	1
C-----	THE N BY N MATRIX A IS RAISED TO THE POWER I AND PUT BACK IN B.	H	2
C-----	DUM IS A DUMMY CALCULATION MATRIX.	H	3
	DIMENSION A(N,N), B(N,N), DUM(N,N).	H	4
	M=I-1	H	5
	DO 1 J=1,N	H	6
	DO 1 K=1,N	H	7
1	DUM(J,K)=A(J,K)	H	8
	DO 5 LL=1,M	H	9
	DO 3 II=1,N	H	10
	DO 3 JJ=1,N	H	11
	S=0.	H	12
	DO 2 KK=1,N	H	13
2	S=S+A(II,KK)*DUM(KK,JJ)	H	14
3	B(II,JJ)=S	H	15
	DO 4 J=1,N	H	16
	DO 4 K=1,N	H	17
4	DUM(J,K)=B(J,K)	H	18
5	CONTINUE	H	19
	RETURN	H	20
	END	H	21

SAMPLE DATA DECK FOR MATRIX MANIPULATION ROUTINES

-5	8	3	
6	8	-2	
-3	-6	2	
9	5	5	
-3	-2	5	4
-3	9	5	6
2	4	1	-0
6	5	3	8
8	-6	-3	2
-6	7	-5	2
1	0	2	0
0	4	0	1
2	0	3	2
0	1	2	1

A            -5.000        8.000        3.000  
               6.000        8.000        -2.000  
               -3.000      -6.000        2.000  
               9.000        5.000        5.000

A(TRANS.)    -5.000        6.000        -3.000        9.000  
               8.000        8.000        -6.000        5.000  
               3.000        -2.000        2.000        5.000

B            -3.000        -2.000        5.000        4.000  
               -3.000        9.000        5.000        6.000  
               2.000        4.000        1.000        -0.

D            6.000        5.000        3.000        8.000  
               8.000        -6.000        -3.000        2.000  
               -6.000        7.000        -5.000        2.000

E=B+D        3.000        3.000        8.000        12.000  
               5.000        3.000        2.000        8.000  
               -4.000        11.000        -4.000        2.000

F=B-D        -9.000        -7.000        2.000        -4.000  
               -11.000        15.000        8.000        4.000  
               8.000        -3.000        6.000        -2.000

E=10.0\*D     30.000        30.000        80.000        120.000  
               50.000        30.000        20.000        80.000  
               -40.000        110.000        -40.000        20.000

C=A\*B        -3.000        94.000        18.000        28.000  
               -46.000        52.000        68.000        72.000  
               31.000        -40.000        -43.000        -48.000  
               -32.000        47.000        75.000        66.000

C (NEW)    1.000000E+00    0.                2.000000E+00    0.  
          0.                4.000000E+00    0.                1.000000E+00  
          2.000000E+00    0.                3.000000E+00    2.000000E+00  
          0.                1.000000E+00    2.000000E+00    1.000000E+00

C (INVERSE)    3.6842105E-01    2.1052632E-01    3.1578947E-01    -8.4210526E-01  
          2.1052632E-01    2.6315789E-01    -1.0526316E-01    -5.2631579E-02  
          3.1578947E-01    -1.0526316E-01    -1.5789474E-01    4.2105263E-01  
          -8.4210526E-01    -5.2631579E-02    4.2105263E-01    2.1052632E-01

IDENTITY    1.000    0.    0.    0.  
          0.    1.000    0.    0.  
          -.000    .000    1.000    -.000  
          -.000    -.000    0.    1.000

C (INVERSE)    3.6842105E-01    2.1052632E-01    3.1578947E-01    -8.4210526E-01  
          2.1052632E-01    2.6315789E-01    -1.0526316E-01    -5.2631579E-02  
          3.1578947E-01    -1.0526316E-01    -1.5789474E-01    4.2105263E-01  
          -8.4210526E-01    -5.2631579E-02    4.2105263E-01    2.1052632E-01

DETERMINANT = -1.9000000E+01

C\*\*3    2.100000E+01    4.0000000E+00    4.2000000E+01    2.0000000E+01  
          4.0000000E+00    7.3000000E+01    1.6000000E+01    2.6000000E+01  
          4.2000000E+01    1.6000000E+01    8.3000000E+01    4.4000000E+01  
          2.0000000E+01    2.6000000E+01    4.4000000E+01    2.7000000E+01

## Program BMD02R

### INTRODUCTION

This program is the step-wise multiple regression of the Biomedical Computer Program series of the School of Medicine, University of California, Los Angeles. It uses a forward step-wise procedure in that it starts with one independent variable and adds another independent variable to the equation at each step.

The step-wise procedure can be valuable in screening large numbers of independent variables for their relationship with the dependent variables. Because the program operator can force individual independent variables into the equation--or conversely, delete them from consideration--the relationships and interactions among independent variables, or groups of independent variables, can be studied. Users of this program should bear in mind that the step-wise procedure does not necessarily produce the best possible regression as it does not consider all possible combinations of independent variables. It is also quite possible with this program to develop regression equations containing more independent variables than are justified by the number of observations. Considerable care should be exercised in interpreting the results. The program is written in FORTRAN and operates on the CDC 6400 computer with the NCAR compiler.

### HOW TO USE THE PROGRAM

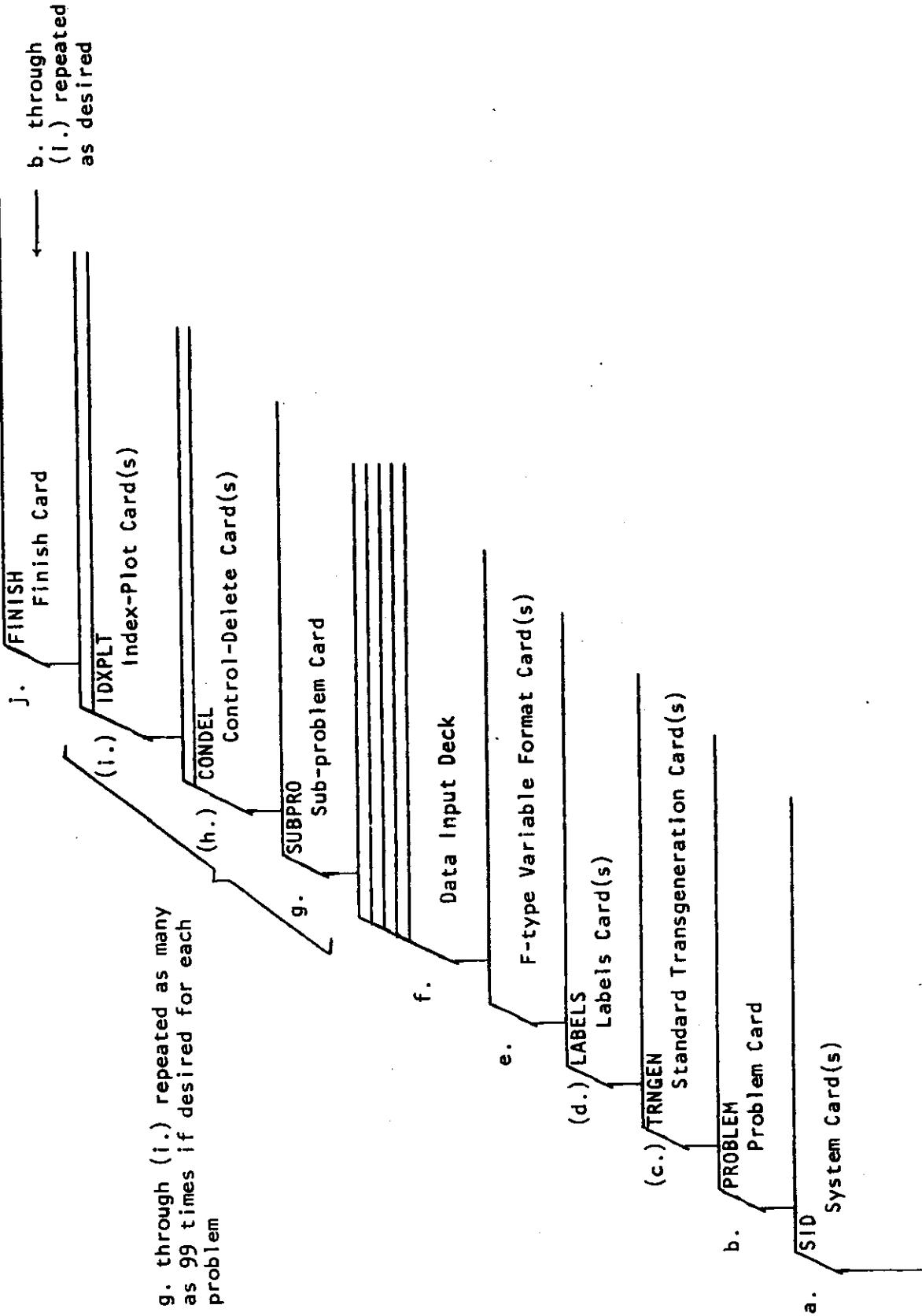
The Systems Cards are not described here except to point out that tapes 2 and 3 should be identified as scratch tapes. The sequence of input is as follows: (Cards enclosed in parentheses are optional. All other cards must be included in the order shown.)

- a. System Cards
  - b. Problem Card
  - (c.) Transgeneration Card(s)
  - (d.) Labels Card(s)
  - e. F-type Variable Format Cards
  - (f.) DATA INPUT Cards (Place data input deck here if data input is from cards.)
  - g. Sub-problem Card(s)
  - (h.) Control-Delete Card(s)
  - (i.) Index-Plot Card(s)
  - j. Finish Card
- 

Note: g. through (i.) may be repeated as many as 99 times in each problem;

b. through (i.) may be repeated as often as desired.

Example of Job Deck Set-up:



The cards are prepared as follows:

**Problem Card**

*Card preparation.*

Columns 1- 6	PROBLEM	(Mandatory)
Columns 10-15	Alphanumeric problem name	
Columns 17-20	Sample size ( $1 \leq n \leq 4000$ )	
Columns 24,25	Number of original variables ( $2 \leq p \leq 50$ )	
Columns 29,30	Number of Transgeneration Cards ( $0 \leq m \leq 99$ )	
Columns 34,35	Number of variables added by transgeneration ( $-9 \leq q \leq 48$ )	
Columns 39,40	Tape number if data is on tape (# logical 2); otherwise, leave blank.	
Columns 44,45	Number of Sub-problem Cards ( $1 \leq s \leq 99$ )	
Columns 48,49	Number of variables labeled on Labels Cards. Leave blank if Labels Cards are not used.	
Columns 51-53	YES If means and standard deviations are to be printed; otherwise, leave blank.	
Columns 55-57	YES If covariance matrix is to be printed; otherwise, leave blank.	
Columns 59-61	YES If correlation matrix is to be printed; otherwise, leave blank.	
Columns 63-65	YES If zero regression intercept is desired; otherwise, leave blank.	
Columns 68,69	NO If tape specified in Columns 39,40 is not to be rewound before this problem; leave blank if Columns 39,40 are blank, or if tape rewind is desired.	
Columns 71,72	Number of F-type Variable Format Cards ( $1 \leq k \leq 10$ )	

**Transgeneration Card(s)**

The term transgeneration is used to include transformations of input variables and creation of new variables prior to the normal computation performed by the various programs.

The transformations described below are performed on the values of the variables in each case. In these examples, the symbol  $x_i$  will denote the  $i$ th variable as well as its value.

Examples:

$$\log_{10} x_4 \rightarrow x_4 \quad \log_{10} x_4 \text{ replaces } x_4$$

$$x_5^c \rightarrow x_1 \quad x_5^c \text{ replaces } x_1$$

$$x_2 + x_3 \rightarrow x_2 \quad x_2 + x_3 \text{ replaces } x_2$$

The transgenerations available are listed below.

Notation to be used in the following transgeneration list:

$i, j, k$  are variable indices (need not be different)

$c$  is a constant

$a_1, a_2, a_3, \dots$  are constants

$n$  is the number of cases, or sample size

$$\text{The mean } \bar{x}_i = \frac{1}{n} \sum_{j=1}^n x_{ji}$$

$$\text{The standard deviation } s_i = [\frac{1}{n-1} \sum_{j=1}^n (x_{ji} - \bar{x}_i)^2]^{1/2}$$

<u>Code</u>	<u>Transgeneration</u>	<u>Restriction</u>
01	$\sqrt{x_i} \rightarrow x_k$	$x_i \geq 0$
02	$\sqrt{x_i} + \sqrt{x_i + 1} \rightarrow x_k$	$x_i \geq 0$
03	$\log_{10} x_i \rightarrow x_k$	$x_i > 0$
04	$e^{x_i} \rightarrow x_k$	--
05	$\arcsin \sqrt{x_i} \rightarrow x_k$	$0 \leq x_i \leq 1$

<u>Code</u>	<u>Transgeneration</u>	<u>Restriction</u>
06	$\arcsin \sqrt{x_i/(n+1)} + \arcsin \sqrt{(x_j+1)/(n+1)} + x_k$	$0 \leq (x_i/n) \leq 1$
07	$1/x_i \rightarrow x_k$	$x_i \neq 0$
08	$x_i + c \rightarrow x_k$	--
09	$x_i c \rightarrow x_k$	--
10	$x_i^c \rightarrow x_k$	$x_i \geq 0$
11	$x_i + x_j \rightarrow x_k$	--
12	$x_i - x_j \rightarrow x_k$	--
13	$x_i x_j \rightarrow x_k$	--
14	$x_i/x_j \rightarrow x_k$	$x_j \neq 0$
15	If $x_i \geq c$ , $1 \rightarrow x_kotherwise 0 \rightarrow x_k$	--
16	If $x_i \geq x_j$ , $1 \rightarrow x_kotherwise 0 \rightarrow x_k$	--
17	$\log_e x_i \rightarrow x_k$	$x_i > 0$
18	$x_i - \bar{x}_i \rightarrow x_k$	--
19	$x_i/s_i \rightarrow x_k$	--
20	$\sin x_i \rightarrow x_k$	--
21	$\cos x_i \rightarrow x_k$	--
22	$\arctan x_i \rightarrow x_k$	--
23	$x_i^{x_j} \rightarrow x_k$	$x_i > 0$

<u>Code</u>	<u>Transgeneration</u>	<u>Restriction</u>
24	$x_i \rightarrow x_k$	$c > 0$
25	$x_i \rightarrow x_k$	--
26	$c \rightarrow x_k$	(Leave code 1 blank)
27-39	Not defined	
40	If $x_i = a_1$ or $a_2$ or $a_3, \dots, a_7$ , then $c \rightarrow x_k$ ; otherwise $x_k$ remains unchanged.	
41	If $x_i$ is blank, then $c \rightarrow x_k$ ; otherwise $x_k$ remains unchanged.	$(x_i \neq -0)^*$
42	If $x_i = a_1$ or $a_2$ or $a_3, \dots, a_7$ , then $x_j \rightarrow x_k$ ; otherwise $x_k$ remains unchanged.	
43	If $x_i$ is blank, then $x_j \rightarrow x_k$ ; otherwise $x_k$ remains unchanged.	$(x_i \neq -0)$

When a violation of a restriction in the right-hand column occurs during transgeneration, the program will print a diagnostic message. Most programs will proceed to the next problem, if any. Some programs will delete the case where the violation occurred and continue the computation. Other programs will screen all the input data for additional restriction violations before proceeding to the next problem, if any.

*Card preparation.*

Columns 1- 6	TRNGEN	(Mandatory)
Columns 7- 9	Variable index k	
Columns 10,11	Code from transgeneration list (restricted by availability in particular program)	
Columns 12-14	Variable index i	
Columns 15-20	Variable index j or constant c	
Columns 21-25	Blank	
Column 26	Number of $a_1$ 's for transformation 40 or 42	
Columns 27-32	$a_1$ value	
Columns 33-38	$a_2$ value	
	...	
Columns 63-68	$a_7$ value	

The constants c,  $a_1$ , . . . ,  $a_7$  are punched with a decimal point if used with variables which have an F-type format and without a decimal point if used with variables which have an I-type format.

**Labels Card(s)**

Labels Cards allow the user to substitute alphanumeric names for the usual numeric indices (variable numbers or category designations) which appear on the printed output.

*Card preparation.*

Columns 1- 6	LABELS	(Mandatory)
Columns 7-10	The number of the variable (or category, or index) to be named. This number must be right-justified.	
Columns 11-16	The corresponding alphanumeric name	

Columns 17-20      The number of another variable  
Columns 21-26      The corresponding alphanumeric name  
.  
.  
.  
.  
.  
.  
.  
Columns 67-70      The number of another variable  
Columns 71-76      The corresponding alphanumeric name of that variable (up to 7 per card)

There may be from one to seven pairs of variable numbers and labels on each Labels Card. If desired, only one pair may be specified on each card. However, the total number of labels appearing on all the Labels Cards must equal the number of labels specified on the Problem or Sub-problem Card.

It is not necessary to label all the variables. Those labeled may be listed in any order.

Example:

Suppose the number of variables to be labeled as specified on the Problem Card is 9. Then the Labels Cards might be punched as:

LABELS 10HEIGHT 07WEIGHT 105AGE 003 X1 0051VAR59 0073 X+Y  
LABELS 99SEX 0100ANYNAM  
LABELS 05STATUS

Variable Format Cards

These cards prescribe the format in which the data will be read. Column one contains a left parenthesis followed by the desired format and a right parenthesis. If the entire format specification will not fit into 80 columns, it should be continued on a second card if necessary, starting in Column one. As many as 10 cards may be used for the format.

### Sup-problem Card(s)

#### *Card preparation.*

Columns 1- 6 SUBPRO (Mandatory)  
Columns 9,10 Number of the dependent variable  
Columns 13-15 Maximum number of steps. This will be 2(p+q) if left blank.  
Columns 20-25 F-level for inclusion. This will be 0.01 if left blank.  
Columns 30-35 F-level for deletion. This will be 0.005 if left blank.  
Columns 40-45 Tolerance level. This will be 0.001 if left blank.  
Columns 49,50 Number of variables on the Index-Plot Card ( $0 \leq i \leq 30$ )  
Columns 53-55 YES If Control-Delete Cards are included.  
Columns 58-60 YES If list of residuals is to be printed.  
Columns 63-65 YES If summary table is to be printed.

### Control-Delete Card(s)

#### *Card preparation.*

Columns 1- 6 CONDEL (Mandatory)  
Column 7 Control value\* for first variable  
Column 8 Control value\* for second variable  
...  
Column 72 Control value\* for 66th variable

The variable numbers above refer to variables after transgeneration.

#### \*CONTROL VALUES

- 1 Delete variable (or dependent variable)
- 2 Free variable
- 3 Low-level forced variable
- ...
- 9 High-level forced variable

If no Control-Delete Cards are included, or if a field is left blank on the Control-Delete Cards included in the deck, the value 2 will be assigned if the variable is not the dependent variable and the value 1 assigned if it is the dependent variable.

#### Index-Plot Card(s)

Variables specified on this card are plotted against the residuals.

*Card preparation.*

Columns 1- 6      IDXPLT                        (Mandatory)

Columns 7, 8      First variable to be plotted

Columns 9,10      Second variable to be plotted

... .

Columns 65,66      30th variable to be plotted.

No more than 30 variables may be plotted per sub-problem.

Variables specified refer to the original data after transgeneration.

#### PROGRAM OPERATION

This program computes a sequence of multiple linear regression equations in a step-wise manner. At each step, one variable is added to the regression equation. The variable added is the one which makes the greatest reduction in the error sum of squares. Equivalently it is the variable which has highest partial correlation with the dependent variable partialled on the variables which have already been added; and equivalently it is the variable which, if it were added, would have the highest F value. In addition, variables can be forced into the regression equation. Non-forced variables are automatically removed when their F values become too low. Regression equations with or without the regression intercept may be selected.

**Output from this program includes:**

- I. At each step:**
  - A. Multiple R
  - B. Standard error of estimate
  - C. Analysis-of-variance table
  - D. For variables in the equation:
    - 1. Regression coefficient
    - 2. Standard error
    - 3. F to remove
  - E. For variables not in the equation:
    - 1. Tolerance
    - 2. Partial correlation coefficient
    - 3. F to enter
- II. Optional output prior to performing regression:**
  - A. Means and standard deviations
  - B. Covariance matrix
  - C. Correlation matrix
- III. Optional output after performing regression:**
  - A. List of residuals
  - B. Plots of residuals vs. input variables
  - C. Summary table
- IV. Limitations per problem:**
  - A. p, number of original variables ( $2 \leq p \leq 50$ )
  - B. q, number of variables added by transgeneration ( $-9 \leq q \leq 48$ )
  - C. p+q, total number of variables ( $2 \leq p+q \leq 50$ )

- D. s, number of Sub-problem Cards ( $1 \leq s \leq 99$ )
- E. k, number of Variable Format Cards ( $1 \leq k \leq 10$ )
- F. i, number of variables to be plotted ( $0 \leq i \leq 30$ )
- G. n, number of cases ( $1 \leq n \leq 4000$ )
- H. m, number of Transgeneration Cards ( $0 \leq m \leq 99$ )

#### SAMPLE RUN

A sample run of the program was made. Three independent variables (water equivalent readings on snow courses) and the dependent variable streamflow were used. No transgenerations were made. Following are the program control cards and data cards used and the resulting output.

BMDQ2R - STEPWISE REGRESSION - VERSION OF JUNE 20, 1966  
 HEALTH SCIENCES COMPUTING FACILITY, UCLA

PROBLEM CODE	SAMPLE
NUMBER OF CASES	15
NUMBER OF ORIGINAL VARIABLES	4
NUMBER OF VARIABLES ADDED	0
TOTAL NUMBER OF VARIABLES	4
NUMBER OF SUB-PROBLEMS	1

VARIABLE	MEAN	STANDARD DEVIATION
CPA	87.20000	5.75063
CPM	28.44667	7.26677
BSA	2.34000	1.68003
POUDRE	215.93333	82.84877

INPUT DECK FOR SAMPLE RUN OF BMDQ2R (STEPWISE REGRESSION)

PROBLM	SAMPLE	15	4	0	0	1	4	YES	YES	YES	1
LABELS	ICPA	2CPM		3BSA		4POUDRE					
	(F4.1,2(F5.1),1X,F3.0)										
20.8	22.1	0.4	147								
25.1	17.6	1.6	106								
19.3	17.3	0.2	133								
30.5	38.9	2.3	202								
29.7	36.1	5.0	378								
29.4	32.9	4.0	256								
30.9	29.7	5.0	228								
29.2	26.0	2.8	199								
22.3	27.5	2.8	317								
38.9	36.5	2.1	274								
20.1	19.8	2.4	146								
35.4	32.2	1.9	176								
27.7	34.3	4.1	325								
21.1	21.9	0.0	110								
27.6	33.9	0.5	242								
SUBPRO	4										
FINISH								YES	YES		

COVARIANCE MATRIX

VARIABLE	1	2	3	4
NUMBER				
1	33.116	32.193	4.081	203.950
2		52.777	6.056	441.775
3			2.745	96.631
4				6862.924

CORRELATION MATRIX

VARIABLE	1	2	3	4
NUMBER				
1	1.000	.770	.620	.427
2		1.000	.503	.734
3			1.000	.704
4				1.000

WIDENED VEHICLE	MAXIMUM NUMBER OF STEPS	• 010000
WIDENED VEHICLE	• 000000	• 000000
WIDENED VEHICLE	• 000000	• 000000
WIDENED VEHICLE	• 000000	• 000000

STEP NUMBER		ANALYSIS OF VARIANCE		MAN SQUARE		F RATIO
VARIABLE ENTERED	METHOD	SUM OF SQUARES	D.F.	SUM OF SQUARES	D.F.	
WEIGHTS	t	117.0878	1	117.0878	1	15.0189
STJUML	t	3408.966	1	3408.966	1	

VARIABLES IN EQUATION	Coefficient STU. TEMPOR F. TO REMOVE	VARIABLE	VARIABLE	PARTIAL CORR.	VARIABLES NOT IN EQUATION	F TO ENTER
(CONSTANT) 2 -27.06 -31.06	-27.06234 ) -31.0614780	15.1689	CPA USA	1 3	.31917 .57026	1.3611 5.7629

STEP NUMBER		ANALYSIS OF VARIANCE		F RATIO	
VARIABLE ENTERED		D.F.	SUM OF SQUARES	MEAN SQUARE	
MULTIPLE N	12	66140.218	33000.109		
STUD. ERTHN OF EST.	12	23900.776	2491.726		
	49.9172	49.9172			
	49.9172	49.9172			
REGRESSION					
RESIDUAL					

VARIABLES IN EQUATION	VARIABLES NOT IN EQUATION	PARTIAL CORR.	TOLERANCE	F TO ENTER
Coefficient Std. Error F to Remove				
Variable	Variable			
CONSTANT	-1.47907	.74503		
PM	.5.79059	2.12488		
SA	.2240364	9.31665		
CA		5.7629		
				2.6529
				.4048
				-44.081

STEP NUMBER	VARIABLE ENTERED	MULTIPLE R <sup>2</sup>	STU. ERTHIN OF F(5,1)	ANALYSIS OF VARIANCE	DEGREES OF FREEDOM	SUM OF SQUARES	MEAN SQUARE	F RATIO
3	•BEGO	.0670	4.0451	INTERCEPT	1	71440.276	71440.276	10.957

LIST OF MEASUREMENTS

CASE	RESIDUAL
1	-1.45753
2	-5.34673
3	14.43924
4	-63.46194
5	64.14962
6	-27.03178
7	-91.46451
8	5.00542
9	11.86442
10	45.72756
11	-32.34115
12	-14.64649
13	17.96157
14	-25.39238
15	21.95632

SUMMARY TABLE

STEP NUMBER	VARIABLE F TO ENTER REMOVE	MULTIPLE RSU	INCREASE IN RSU	F VALUE TO ENTER OR REMOVE		NUMBER OF INDEPENDENT VARIABLES INCLUDED
				P	F	
1	CPA	7340	.5388	.5388	15.1889	1
2	BSA	.8299	.6888	.1500	5.7829	2
3	CPA	.8656	.7493	.0605	2.6529	3
RESIDUAL	1)	24090.657	2190.060			
VARIABLE	VARIABLES IN EQUATION		VARIABLES NOT IN EQUATION		VARIABLE	
VARIABLE	COEFFICIENT	STD. ERROR	F TO REMOVE	VARIABLE	PARTIAL CORR.	TOLERANCE
(CONSTANT)	54.0475					
CPA	1	-5.36391	3.41600	2.6529		
CPM	2	9.47334	2.82277	10.2809		
BSA	3	23.45324	8.75484	7.1712		

F-LEVEL INSUFFICIENT FOR FURTHER COMPUTATION

## Program NONLIN

### INTRODUCTION

NONLIN is a nonlinear programming program available for use on the FORTRAN Extended compiler of the CDC 6400 SCOPE System.

Many optimization problems cannot be dealt with using linear programming techniques because either the objective function or the restraint equations are not linear functions. Whenever the cost of a resource depends on the amount of resource used, the objective function becomes nonlinear. This is a very common occurrence in all types of problems. Programming problems also become nonlinear when risk and uncertainty are considered. For many problems the risks involved in giving up other decisions must also be considered in the objective function.

The solution of nonlinear problems does not involve one clear-cut method as does linear programming. There are several different methods of solution, and not all methods are equally well suited to a given problem. The task of the user is to discover the logical foundations of a given problem, and to find suitable formulations for the objective functions and the constraint equations. If these formulations can then be expressed as described below, this method should be used.

### PROGRAM OPERATION

The program is designed to solve the nonlinear programming problem when stated in the following form:

(A) minimize the function  $f(x)$  where  $x$  is the  $n \times 1$  vector:

$$x = (x_1, x_2, \dots, x_n)'$$

subject to the  $x$  obeying the following  $m$  (nonlinear) constraining inequalities:

$$R_j(x) \geq 0 \text{ for } j = 1, 2, \dots, m$$

The method used depends upon formulation of the problem as one of unconstrained minimization in the following way:

(B) solution of the problem stated in (A) will be the same as the limiting solution to the problem:

for  $r_k > 0, r_1 > r_2 > \dots > r_p > 0$

find the minimum with respect to  $x$  and  $r_k$  of the function

$$P(x, r_k) = f(x) + r_k \cdot \sum_{j=1}^m [R_j(x)]^{-1},$$

if the following conditions on the functions involved hold:

- C1 There exists at least one  $x$  such that the inequalities stated in (A) are true (i.e., at least one feasible solution),
- C2  $f(x)$  and  $-R_j(x)$  are convex functions and have continuously differentiable first and second derivatives,
- C3 For every finite  $k$ , the set of  $x$  such that  $f(x) \leq k$  is bounded, provided also that each  $x$  is a feasible solution,
- C4 For every  $r > 0$ ,  $P(x, r)$  is convex.

Since the function to be minimized in (B) is without constraints, the minimization can be performed by the steepest descent method starting at the known feasible solution. The method consists of starting with some arbitrary positive  $r_1$  and using the steepest descent method (or a variation) to find a vector  $x_1$  which makes  $P(x, r_1)$  a minimum. Then select an  $r_2$ , say  $1/2$  of  $r_1$ , also positive, and again minimize  $P(x, r_2)$ . In this way a series of feasible solutions,  $x_1, x_2, \dots$  will be generated. It is possible to show (prove mathematically) that under the conditions stated this sequence of feasible solutions will converge to the optimal feasible solution. (Also, under the conditions stated a single unique optimal feasible solution exists.)

The utility of the program is extended greatly by the fact that, although it finds the optimal solution when the rather stringent conditions above are met, it has also been shown empirically to provide either an optimal solution or a solution which is a great improvement over some initial feasible solution when the conditions are not met. Thus, the program is a nonlinear programming algorithm when the conditions in (B) are met and a nonlinear programming heuristic in other cases.

The program user must provide four FORTRAN coded subroutines as the manner of stating his problem. One program reads in coefficients and other necessary data; a second provides the value of the objective function and the constraining functions  $f(x)$  and  $R_j(x)$ ; a third provides the derivatives of these same functions; and a fourth provides any of  $m+1$   $n \times n$  matrices of second derivatives of the functions. In addition, a number of parameters, such as initial  $x$  vector, initial  $r$  value, decrement for  $r$ , etc. must be specified. The exact form for these subroutines and parameter cards follows.

#### INPUT REQUIREMENTS

##### User-supplied Information Cards

The user must supply a parameter card which precedes the data deck, an initial starting point or  $x$  vector following the parameter card, and an option card which follows the data deck. These cards give instructions to the computer program and are necessary for execution of the program.

1. Parameter Card

<u>Column</u>	<u>Format</u>	<u>Name</u>	<u>Use</u>
01-12	E12.0	EPSI ( $\epsilon$ )	Tolerance used to decide if an unconstrained minimum has been achieved (normally set at $10^{-5}$ ) (see option 9)
13-24	E12.0	RHOIN ( $r_1$ )	Possible initial value of $r$ (see option 1)
25-36	E12.0	THETAO ( $\theta_0$ )	Tolerance used to decide if the solution to problem (A) has been approximated (see option 5)
37-48	E12.0	RATIO (c)	Parameter (> 1) used to compute consecutive values of $r$ ; $r_1/-1 = r_1/c$
49-60	E12.0	TMMAX	Maximum amount of time for solving problem (in seconds)
61-64	I4	M	Number (integer) of non-trivial constraints (see option 2); if OPTION 2 = 1, $(M + N) \leq 200$ ; if OPTION 2 = 2, $M \leq 200$
65-68	I4	N	Number (integer) of variables, $N \leq 100$

2. Initial starting point or  $x$  vector, ( $x^0$ )

The cards designating the initial starting point immediately follow the parameter card.

There are six components per card, requiring ( $N/6$ ) cards for the vector. Each card format is 6E12.0.

3. Option Card

In general the  $i$ th option is designated by a single integer in the  $(i \times 7)$ th column. In the general situation it is recommended that all options be equal to 1. The Fortran variable name is NT1 for Option 1, NT2 for Option 2, etc.

	<u>Value</u>	<u>Meaning</u>
Option 1	= 1	$r_1$ is given by formula 25, reference 1, p. 47
	= 2	$r_1$ is given by formula 23, reference 1, p. 47
	= 3	$r_1 = \text{RHOIN}$ (see parameter card)
Option 2	= 1	The requirements (trivial constraints) that $x_i \geq 0$ for $i = 1, \dots, n$ are to be automatically included in the problem
	= 2	Only constraints on the problem are those inputed by the user
Option 3	= 1	Standard printout (This includes a call to OUTPUT at the solution of every subproblem, the estimates of the "Lagrange multipliers" and first- and second-order solution estimates.)
	= 2	For additional printout (includes standard printout, every intermediate point, gradient and mapped gradient vectors)
Option 4		Not used
Option 5		Final convergence criterion (see parameter card)
	= 1	quit when $\frac{f[x(r_k)]}{G[x(r_k), u(r_k)]} - 1 < \theta_0$
	= 2	quit when $r \sum_{j=1}^n 1/R_j [x(r_k)] < \theta_0$
	= 3	quit when $\frac{\text{first-order estimate of } v_0}{G[x(r_k), u(r_k)]} - 1 < \theta_0$
Option 6		Not used
Option 7		First move after a minimum is achieved
	= 1	No extrapolation
	= 2	Extrapolate through last two minima
	= 3	Extrapolate through last three minima
Option 8	= 1	Matrix of second partials computed every time (Recommended)
	= 2	Repeated use is made of matrix of second partials

	<u>Value</u>	<u>Meaning</u>
Option 9		Subproblem convergence criterion, or when to stop minimizing P-function for fixed value of r (see parameter card)
= 1		quit when
		$ \nabla_x P^T(x^i, r) [\frac{\partial^2 P(x, r)}{\partial x_i \partial x_j}]^{-1} \nabla_x P(x^i, r)  < \epsilon$
= 2		quit when
		$ \nabla_x P^T(x^i, r) [\frac{\partial^2 P(x, r)}{\partial x_i \partial x_j}]^{-1} \nabla_x P(x^i, r)  < \frac{P(x^{i-1}) - P(x^i)}{5}$
= 3		quit when $ \nabla_x P(x^i, r)  < \epsilon$
Option 10	= 1	At least one nonlinear constraint
	= 2	Linear constraints
	= 3	Linear constraints and linear objective function (i.e., a linear programming problem)

Note when Option 10 = 3 MATRIX - the user subroutine supplying the second partial derivatives will not be called, when Option 10 = 2 it will be called only to get the second partials of  $f(x)$ .

#### User-Supplied Subroutines

The first card in each user-supplied subroutine is necessary and connects the essential common region [called the share common region] of the main program with the user routines (see example). Of course, all the common regions may be made accessible to the user by duplication of the common and dimension cards. Blank common is left for the user's use in transferring data between his subroutines. FORTRAN II modifications require one master common card - easily made up from the separate FORTRAN IV regions.

I: Subroutine RESTNT (I,VALU)

When I = 0, this routine must set VAL =  $f(x)$ .

When I ≠ 0, routine must set VAL =  $R_1(x)$ .

$x$  is found in COMMON.

## II. Subroutine GRAD1(I)

When  $I = 0$ , GRAD1 must place  $\nabla_x f(x)$  in DEL

When  $I \neq 0$ , GRAD1 must place  $\nabla_x R_i(x)$  in DEL

$x$ , DEL in common. DEL does not have zeros upon entry to GRAD1.

## III. Subroutine MATRIX (J)

This subroutine must supply the upper triangle and diagonal portions of the matrix of second partials of  $f$  or any  $R_j$  on request.

The lower triangle (the computer variable named array is  $A( , )$ ) must not be disturbed. Note that the upper triangle and diagonal elements of  $A$  are all zero upon entry to MATRIX.

When  $J = 0$ , MATRIX must place  $\frac{\partial^2 f(x)}{\partial x_k \partial x_i}$  in  $A(k,i)$  for  $k = 1, \dots, N$   
 $i = k, \dots, N$

When  $J \neq 0$ , MATRIX must place  $\frac{\partial^2 R_j(x)}{\partial x_k \partial x_i}$  in  $A(k,i)$  for  $k = 1, \dots, N$   
 $i = k, \dots, N$

## IV. Subroutine READIN

READIN is the first of the user's subroutines to be called and is called only once for each problem. Essentially, the purpose of this routine is to have the user read in the data necessary to evaluate the objective function and constraints and all their first and second partial derivatives.

### PROGRAM LISTING AND SAMPLE OUTPUT

The following example was used by G. M. Van Dyne to predict the relationship between botanical and chemical components in fistual forage samples:

Let  $C_i$  be the chemical content by weight of a given constituent in the  $i$ th mixed sample expressed as a proportion; let  $P_j$  be the chemical

content of the jth species in the mixed sample expressed as a percent; and let  $w_{ij}$  be the percent weight of the jth species in the ith sample. Also let M be the number of species and N be the number of samples.

$$c_i = \sum_j p_j w_{ij} \quad (0 \leq c_i \leq 1)$$

$$\sum_i w_{ij} = 100 \quad (0 \leq w_{ij} \leq 100)$$

$$\text{and } 0 \leq p_j \leq 100 \quad \text{for } i = 1, 2, \dots, N \text{ and } j = 1, 2, \dots, M$$

The problem is to solve for the  $p_j$  values, given the corresponding values of  $c_i$  and  $w_{ij}$  for N samples, such that the following function, Q, is minimized:

$$Q = \sum_{i=1}^N (c_i - \sum_{j=1}^M p_j w_{ij})^2$$

The user-supplied subroutines for this were coded as follows:

I. RESTNT (IN,VAL) evaluates the constraints according to IN.

When IN = 0, VAL will be returned with the present value of the objective function Q.

When IN ≠ 0, VAL is set equal to the value specified by RH0IN on the option card.

II. GRAD1(IN) computes the gradients according to IN.

When IN = 0, the gradients stored in DEL(I) are calculated by  $\nabla_x f(x)$ . For this problem the formula is expressed as

$$\nabla_x f(x) = -2 \sum_{j=1}^M w_{ij} (c_j - p_j w_{ij})$$

When IN ≠ 0, the gradient DEL(IN) is set equal to one, and all others are set equal to zero.

III. MATRIX (IN) calculates the second partials.

When IN = 0, the  $\frac{\partial^2 f(x)}{\partial x_i \partial x_j}$  is calculated by  $A_{ij} = \sum_{k=1}^M w_{ik} w_{jk}$   
for  $i = 1, 2, \dots, N$  and  $j = i, i+1, \dots, N$ .

When IN  $\neq 0$ , the  $\frac{\partial^2 R(x)}{\partial x_i \partial x_j}$  are returned with zero values.

IV. READIN reads in all necessary data that is specified by the objective function. For this problem READIN supplied the values for M, N,  $w_{ij}$ ;  $i = 1, 2, \dots, N$  and  $j = 1, 2, \dots, M$  and  $c_j$ ,  $j = 1, 2, \dots, M$ . An identifying header card is also read and printed by READIN.

The output from this problem begins with a printout of the parameter card, and option card F is then listed as the initial value of the objective function. The initial conditions for the P variables are listed as both the current value of x and the constraint values.

For each feasible solution generated, the values of the problem variables and functions are then printed as follows:

POINT is the number of iterations necessary for convergence.

DOTT is the value of the convergence criterion for each subproblem (a subproblem consists of the calculation of a feasible solution).

RHO is the current value for r at that solution.

MAGNITUDE gives the determinant of the gradient matrix supplied by GRAD1.

$$|\nabla_x P[x(r)]|$$

F is the current value of the objective function  $f[x(r)]$ .

P is the convergence criterion used to determine if the feasible solution is also an optimal solution.

$$f[x(r)] + RSIGMA$$

G is the convergence criterion for optimality of the dual solution.

$$f[x(r)] - RSIGMA$$

RSIGMA is the amount of deviation allowed for optimality.

$$\sum_{j=1}^M r/R_j[x(r)]$$

CURRENT VALUE OF  $x$  is  $x(r)$  or the values of  $P_j$  expressed as a percent.

CONSTRAINT VALUES are  $R_1[x(r)], \dots, R_M[x(r)]$ .

For this problem, these are also the resulting values of  $P_j$ .

For each feasible solution, these values are printed and the generation of feasible solutions is continued until the solutions converge to optimality.

```

PROGRAM NONLIN(INPUT,OUTPUT,TAPE5=INPUT,TAPE6)
C-----MAIN   RAC  NON-LINEAR PROGRAMMING ROUTINE          A  2
COMMON /SHARE/ X(100),DEL(100),A(100,100),N,M,MN,NP1,NM1    A  3
COMMON /OPTNS/ NT1,NT2,NT3,NT4,NT5,NT6,NT7,NT8,NT9,NT10,NT11,NT12  A  4
COMMON /VALUE/ F,G,P0,RSIGMA,RJ(200),RHO      A  5
COMMON /CRST/ DELX(100),DELX0(100),RHOIN,RATIO,EPsi,THETA0,NTCTR,N  A  6
1UMINI,X1(100),X2(100),X3(100),XR2(100),XR1(100),PR1,PR2,P1,F1,RJ1(  A  7
2200),DOTT,PGRAD(100),DIAG(100),RJ3(200),PREV3,F3,ADELX,RSIG1,G1,G3  A  8
3,RSIG3,NVI,NPHASE,NSATTS,LRJ(200),NSOL      A  9
      REAL LRJ
C-----PARAMETER CARD          A 10
C-----INITIAL X VERCTOR CARD FORMAT      A 11
C-----OPTION CARD FORMAT          A 12
      REWIND 6
      NSOL=0
1     READ (5,5) EPsi,RHOIN,THETA0,RATIO,TMAX,M,N          A 14
      IF(N.EQ.0) GO TO 11
      CALL SIT (TMAX)
      READ (5,6) (X(I),I=1,N)          A 16
      NTCTR=0
      NP1=N+1
      NM1=N-1
C-----SUBROUTINE READIN IS UNDER PROGRAMMER CONTROL      A 20
      CALL READIN
C-----OPTION CARD FOLLOWS PROGRAMMERS DATA          A 22
      READ (5,7) NT1,NT2,NT3,NT4,NT5,NT6,NT7,NT8,NT9,NT10      A 23
      WRITE (6,8)
      WRITE (6,9) N,M,TMAX,RHOIN,RATIO,EPsi,THETA0      A 24
      A 25
C-----IF NON-NEGS INCLUDED BY LETTING NT2=1 THEN ADD M+N TO GET NO. REST      A 26
      MN=M
      GO TO (2,3), NT2          A 27
2     MN=MN+N          A 28
3     CONTINUE          A 29
      WRITE (6,10)
      WRITE (6,7) NT1,NT2,NT3,NT4,NT5,NT6,NT7,NT8,NT9,NT10      A 30
      CALL TIMEC
      NPHASE=2          A 31
      CALL EVALU
      P0=0.0          A 32
      G=0.0          A 33
      RSIGMA=0.0          A 34
      CALL OUTPUT (2)
      CALL STORE          A 35
      CALL FEAS          A 36
C-----NPHASE=5 IS USED TO INDICATE NO FEASIBLE POINT EXIST      A 37
      GO TO (4,4,4,4,1), NPHASE          A 38
4     NPHASE=2          A 39
      NTCTR=0          A 40
      CALL BODY          A 41
      GO TO 1          A 42
11    CONTINUE          A 43
      ENDFILE 6          A 44
      STOP          A 45
C-----
5     FORMAT (5E12.0,2I4)          A 46
6     FORMAT (6E12.0)          A 47
                                         A 48
                                         A 49
                                         A 50
                                         A 51

```

## NONLINEAR PROGRAMMING PROGRAM

PAGE 2

```

7   FORMAT (10I7)          A 51
8   FORMAT (37H1 NONLINEAR PROGRAMMING ROUTINE-RAC ) A 52
9   FORMAT (1H0,5X,2HN=I3,6X,2HM=I3//8X,10HMAX. TIME=1PE10.3,4X,2HR=1P A 53
10  1E14.7,4X,6HRATIO=E10.3,6X,BHEPSILON=E10.3,4X,6HTHETA=E10.3) A 54
    FORMAT (18H0 OPTIONS SELECTED) A 55
    END A 56
                                A 57

```

```

SUBROUTINE READIN          B 1
COMMON /SHARE/ X(100),DEL(100),A(100,100),N,M,MN,NP1,NM1 B 2
COMMON C,P,NN              B 3
DIMENSION C(150), P(150,20), ID(14) B 4
DATA INCASE=0               B 5
C-----VAN DYNE PROBLEM - NONNEGATIVE LEAST SQUARES ONE RHS B 5
1  NCASE=NCASE+1            B 6
  READ (5,3) (ID(I),I=1,14) B 7
  WRITE (6,4) (ID(K),K=1,14) B 8
  READ (5,5) NR,NC           B 9
  N=NC                      B 10
  M=N                      B 11
  NN=NR                     B 12
  WRITE (6,8) NR,NC,NCASE    B 13
  DO 2 I=1,NR                B 14
  READ (5,6) (P(I,J),J=1,NC),C(I) B 15
  WRITE (6,7) I,(P(I,J),J=1,NC),C(I) B 16
2  CONTINUE                  B 17
  RETURN                     B 18
C-----
3  FORMAT (13A6,1A2)          B 19
4  FORMAT (1H1,13A6,1A2)        B 20
5  FORMAT (2I3)                B 21
6  FORMAT (10F8.3)              B 22
7  FORMAT (1H ,I5,13F8.3,F15.3) B 23
8  FORMAT (1H ,2I6,5X,8HFILE NO.,I3) B 24
  END                         B 25
                                B 26
                                B 27-

```

```

SUBROUTINE RESTNT (IN,VAL)          C 1
COMMON /SHARE/ X(100),DEL(100),A(100,100),N,M,MN,NP1,NM1 C 2
COMMON C,P,NN              C 3
DIMENSION C(150), P(150,20) C 4
C-----CONSTRAINT EVALUATION VAN DYNE C 4
  IF (IN) 1,1,4               C 5
1  SUM1=0.0                   C 6
  DO 3 I=1,NN                 C 7
    SUM2=0.0                   C 8
    DO 2 J=1,N                 C 9
      SUM2=SUM2+X(J)*P(I,J)    C 10
2
3

```

## NONLINEAR PROGRAMMING PROGRAM

PAGE 3

2	CONTINUE	C 12
	SUM1=SUM1+(C(I)-SUM2)**2	
3	CONTINUE	C 13
	VAL=SUM1	C 14
	GO TO 5	C 15
4	VAL=X(IN)	C 16
5	RETURN	C 17
	END	C 18
		C 19-

```

SUBROUTINE GRAD1 (IN)
COMMON /SHARE/ X(100),DEL(100),A(100,100),N,M,MN,NP1,NM1
COMMON C,P,NN
DIMENSION C(150), P(150,20)
C----- GRADIENT COMPUTATION      VAN DYNE
IF (IN) 1,1,5
1  DO 4 I=1,N
    SUM1=0.0
    DO 3 J=1,NN
        SUM2=0.0
        DO 2 K=1,N
            SUM2=SUM2+X(K)*P(J,K)
2  CONTINUE
    PROD=C(J)-SUM2
    SUM1=SUM1+P(J,I)*PROD
3  CONTINUE
    DEL(I)=-2.0*SUM1
4  CONTINUE
    GO TO 7
5  DO 6 I=1,N
    DEL(I)=0.0
6  CONTINUE
    DEL(IN)=1.0
7  RETURN
END

```

D 1
D 2
D 3
D 4
D 5
D 6
D 7
D 8
D 9
D 10
D 11
D 12
D 13
D 14
D 15
D 16
D 17
D 18
D 19
D 20
D 21
D 22
D 23
D 24
D 25-

```

SUBROUTINE MATRIX (IN)
COMMON /SHARE/ X(100),DEL(100),A(100,100),N,M,MN,NP1,NM1
COMMON C,P,NN
DIMENSION C(150), P(150,20)
C-----MATRIX OF SECOND PARTIALS
C-----VAN DYNE PROBLEM
IF (IN) 1,1,4
1  DO 3 I=1,N
    DO 3 J=I,N
        SUM=0.0
        DO 2 K=1,NN
2

```

E 1
E 2
E 3
E 4
E 5
E 6
E 7
E 8
E 9
E 10
E 11

## NONLINEAR PROGRAMMING PROGRAM

PAGE 4

	SUM=SUM+P(K,I)*P(K,J)	E 12
2	CONTINUE	E 13
	A(I,J)=2.0*SUM	E 14
3	CONTINUE	E 15
4	RETURN	E 16
	END	E 17

	SUBROUTINE BODY	F 1
	COMMON /SHARE/ X(100),DEL(100),A(100,100),N,M,MN,NP1,NM1	F 2
	COMMON /OPTNS/ NT1,NT2,NT3,NT4,NT5,NT6,NT7,NT8,NT9,NT10,NT11,NT12	F 3
	COMMON /VALUE/ F,G,P0,RSIGMA,RJ(200),RHO	F 4
	COMMON /CRST/ DELX(100),DELX0(100),RHOIN,RATIO,EPSI,THETAO,NTCTR,N	F 5
	1UMINI,X1(100),X2(100),X3(100),XR2(100),XR1(100),PR1,PR2,P1,F1,RJ1(	F 6
	2200),DOTT,PGRAD(100),DIAG(100),RJ3(200),PREV3,F3,ADELX,RSIG1,G1,G3	F 7
	REAL LRJ	F 8
	NUMINI=0	F 9
C-----	OPTION OF GETTING INITIAL RHO	F 10
	CALL RHOCOM	F 11
1	CALL PEVALU	F 12
2	IREP=0	F 13
	ISME=1	F 14
	CALL GRAD (1)	F 15
	CALL SECORD (1)	F 16
	GO TO 8	F 17
3	IF (NT8.EQ.1) 6,4	F 18
C-----	IF NT8 IS GREATER THAN ONE THEN REPEATED USE IS MADE OF THE A MATR	F 19
4	IREP=IREP+1	F 20
	IF (IREP.LT.NT8) 7,5	F 21
5	IREP=0	F 22
6	ISME=1	F 23
	CALL SECORD (2)	F 24
	GO TO 8	F 25
7	ISME=2	F 26
8	DO 9 I=1,N	F 27
9	DELX(I)=DELX0(I)	F 28
	CALL TIME (XI)	F 29
	CALL INVERS (ISME)	F 30
	CALL TIME (YS)	F 31
	CALL STORE	F 32
	CALL TIME (ZO)	F 33
	CALL OPT	F 34
	CALL TIME (WM)	F 35
	CALL MAG	F 36
	GO TO (11,10), NT3	F 37
10	WRITE (6,32) XI,YS,ZO,WM	F 38
	CALL TIMEC	F 39
	CALL OUTPUT (1)	F 40
11	GO TO (27,12,12), NPHASE	F 41
12	CALL CONVRG (N1)	F 42
	GO TO (13,3), N1	F 43
		F 44

C-----MINIMUM ACHIEVED	F	45
13 GO TO (14,15), NT3	F	46
14 CALL TIMEC	F	47
CALL OUTPUT (1)	F	48
15 NUMINI=NUMINI+1	F	49
GO TO (31,16,16), NPHASE	F	50
16 CALL ESTIM	F	51
GO TO (28,24,17), NPHASE	F	52
17 CALL FINAL (N2)	F	53
GO TO (18,19), N2	F	54
18 RETURN	F	55
19 RHO=RHO/RATIO	F	56
C-----A VECTOR IS LEFT IN DELX(I) BY ESTIM	F	57
IF (NUMINI-2) 2,20,20	F	58
20 GO TO (2,21,21), NT7	F	59
21 CALL GRAD (2)	F	60
CALL OPT	F	61
CALL PEVALU	F	62
GO TO (23,22), NT3	F	63
22 WRITE (6,33)	F	64
CALL OUTPUT (1)	F	65
23 GO TO 5	F	66
24 GO TO (25,17), NT10	F	67
25 CONTINUE	F	68
C-----THIS IS UNCODED AT PRESENT	F	69
GO TO 17	F	70
C-----AFTER OPTIMUM MOVE GOES HERE IF IN FEASIBILITY PHASE	F	71
26 RETURN	F	72
GO TO (30,12,26), NSATIS	F	73
C-----TEST FOR NON DUAL FEASIBILITY	F	74
27 IF (RJ(NVI)) 1,1,26	F	75
28 GO TO (29,17,17), NSATIS	F	76
29 CALL STORE	F	77
IF (RJ(NVI)) 1,1,26	F	78
30 CALL STORE	F	79
GO TO 1	F	80
C-----FORTUITOUSLY SATISFIED CONSTRAINTS ACCEPTED	F	81
31 IF (G) 16,16,26	F	82
C-----	F	83
32 FORMAT(2H0 39HTHE TIME BEFORE THE CALL TO INVERSE WAS F9.3, F	84	
119H SECONDS, AFTER WAS F9.3, 8H SECONDS / 2X, 35HTHE TIME BEFF	85	
20RE THE CALL TO OPT WAS F9.3, 19H SECONDS, AFTER WAS F9.3, F	86	
3 BH SECONDS )		
33 FORMAT (6X,30HMOVED ON EXTRAPOLATION VECTOR )	F	87
END	F	88

SUBROUTINE CONVRG (N1)	G	1
COMMON /SHARE/ X(100),DEL(100),AL(100,100),N,M,MN,NPI,NM1	G	2
COMMON /OPTNS/ NT1,NT2,NT3,NT4,NT5,NT6,NT7,NT8,NT9,NT10,NT11,NT12	G	3
COMMON /VALUE/ F,G,P0,RSIGMA,RJ(200),RHO	G	4
COMMON /CRST/ DELX(100),DELX0(100),RHOIN,RATIO,EPSI,THETAO,NTCTR,N	G	5

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IUMINI,X1(100),X2(100),X3(100),XR2(100),XR1(100),PR1,PR2,P1,F1,RJ1( G 6
2200),DOTT,PGRAD(100),DIAG(100),RJ3(200),PREV3,F3,ADELX,RSIG1,G1,G3 G 7
3,RSIG3,NVI,NPHASE,NSATIS,LRJ(200) G 8
      REAL LRJ G 9
      COMMON /TSW/ NSWW G 10
C-----LEAVES A 1 IF MIN HAS BEEN FOUND, 2 IF NOT G 11
C-----DOT PRODUCT OF GRAD.AND INVERSE PRODUCT LEFT (DURING OPT) AT DOT G 12
      N1=2 G 13
      NSWW=1 G 14
      GO TO (1,2,3), NT9 G 15
1      IF (ABS(DOTT)-EPSI) 4,4,5 G 16
2      IF (ABS(DOTT)-(P1-P0)/5.) 4,4,5 G 17
3      IF (ADELX.GT.EPSI) 5,4 G 18
4      N1=1 G 19
5      GO TO (6,7), NSWW G 20
6      RETURN G 21
7      CALL EXIT G 22
     END G 23-
```

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SUBROUTINE ESTIM H 1
COMMON /SHARE/ X(100),DEL(100),A(100,100),N,M,MN,NP1,NM1 H 2
COMMON /OPTNS/ NT1,NT2,NT3,NT4,NT5,NT6,NT7,NT8,NT9,NT10,NT11,NT12 H 3
COMMON /VALUE/ F,G,P0,RSIGMA,RJ(200),RHO H 4
COMMON /CRST/ DELX(100),DELX0(100),RHOIN,RATIO,EPSI,THETA0,NTCTR,N H 5
IUMINI,X1(100),X2(100),X3(100),XR2(100),XR1(100),PR1,PR2,P1,F1,RJ1( H 6
2200),DOTT,PGRAD(100),DIAG(100),RJ3(200),PREV3,F3,ADELX,RSIG1,G1,G3 H 7
3,RSIG3,NVI,NPHASE,NSATIS,LRJ(200) H 8
      REAL LRJ H 9
C-----SIX CARDS HAVE BEEN MADE COMMENTS TO ELIMINATE 1ST AND 2ND ORDER H 10
C-----ESTIMATES AND LAGRANGE MULTIPLIER OUTPUT. ***
      CALL STORE H 12
      Z9=SQRT(RATIO) H 13
      Z1=(1./Z9+1./RATIO) H 14
      Z2=Z1+1./Z9**3 H 15
      Z3=1./Z9**3 H 16
      Z4=RATIO+Z9 H 17
      Z5=Z9**3 H 18
      Z6=1./((RATIO-1.)*(Z9-1.)) H 19
      Z7=1./Z9 H 20
      Z8=1./(Z9-1.) H 21
      IF (NUMINI-2) 5,3,1 H 22
C-----30 WRITE(6,102) H 23
1      CONTINUE H 24
      P0=(PR2-Z4*PR1+Z5*P1)*Z6 H 25
      G=(RATIO*G1-GR1)/(RATIO-1.) H 26
      DO 2 I=1,N H 27
2      X(I)=(XR2(I)-Z4*XR1(I)+Z5*X1(I))*26 H 28
      CALL EVALU H 29
C-----CALL OUTPUT(2) H 30
      CALL SPECFE H 31
      GO TO (15,3,3), NSATIS H 32

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C-----20 WRITE(6,101) H 33
3   CONTINUE H 34
    PO=(Z9*P1-PR1)*Z8 H 35
    G=(RATIO*G1-GR1)/(RATIO-1.) H 36
    DO 4 I=1,N H 37
4   X(I)=(Z9*X1(I)-XR1(I))*Z8 H 38
    CALL EVALU H 39
C-----CALL OUTPUT(2) H 40
    CALL SPECFE H 41
    GO TO (15,5,5), NSATIS H 42
C-----105 WRIRE(6,103) H 43
5   CONTINUE H 44
    DO 6 J=1,MN H 45
6   RJ(J)=RJ1(J)**2 H 46
    GO TO (7,9), NT2 H 47
7   DO 8 I=1,N H 48
8   X(I)=RJ(I) H 49
C-----46 CALL OUTPUT (2) H 50
9   CONTINUE H 51
    CALL REJECT H 52
    CALL PEVALU H 53
    CALL GRAD (2) H 54
    IF (NUMINI-2) 13,16,10 H 55
10  GO TO (13,17,11), NT7 H 56
C-----SECOND ORDER MOVE FOR NEXT MINIMUM H 57
11  DO 12 I=1,N H 58
12  DELX(I)=Z1*X1(I)-Z2*XR1(I)+Z3*XR2(I) H 59
13  PR2=PR1 H 60
    GR2=GR1 H 61
    PR1=P1 H 62
    GR1=G1 H 63
    DO 14 I=1,N H 64
    XR2(I)=XR1(I) H 65
14  XR1(I)=X1(I) H 66
15  RETURN H 67
16  GO TO (13,17,17), NT7 H 68
17  DO 18 I=1,N H 69
18  DELX(I)=(X1(I)-XR1(I))*Z7 H 70
    GO TO 13 H 71
C----- H 72
    END H 73

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```

SUBROUTINE EVALU I 1
COMMON /SHARE/ X(100),DEL(100),A(100,100),N,M,MN,NP1,NM1 I 2
COMMON /VALUE/ F,G,PO,RSIGMA,RJ(200),RHO I 3
COMMON /OPTNS/ NT1,NT2,NT3,NT4,NT5,NT6,NT7,NT8,NT9,NT10,NT11,NT12 I 4
COMMON /CRST/ DELX(100),DELX0(100),RHOIN,RATIO,EPSI,THETA0,NTCTR,N I 5
1UMINI,X1(100),X2(100),X3(100),XR2(100),XR1(100),PR1,PR2,P1,F1,RJ1( I 6
2200),DOTT,PGRAD(100),DIAG(100),RJ3(200),PREV3,F3,ADELX,RSIG1,G1,G3 I 7
3,RSIG3,NVI,NPHASE,NSATIS,LRJ(200) I 8
REAL LRJ I 9

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## NONLINEAR PROGRAMMING PROGRAM

PAGE 8

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C-----DIFFERENT FOR PHASE3
      GO TO (1,1,9), NPHASE
1      GO TO (2,4), NT2
2      DO 3 I=1,N
3      RJ(I)=X(I)
      IPN=N
      GO TO 5
4      IPN=0
5      DO 6 I=1,M
      J=IPN+I
      CALL RESTNT (I,RJ(J))
6      CONTINUE
      GO TO (7,8), NPHASE
7      F=-RJ(NVI)
      GO TO 9
8      CALL RESTNT (0,F)
9      RETURN
      END

```

```

SUBROUTINE FEAS
COMMON /SHARE/ X(100),DEL(100),A(100,100),N,M,MN,NPI,NM1
COMMON /VALUE/ F,G,P0,RSIGMA,RJ(200),RHO
COMMON /OPTNS/ NT1,NT2,NT3,NT4,NT5,NT6,NT7,NT8,NT9,NT10,NT11,NT12
COMMON /CRST/ DELX(100),DELX0(100),RH0IN,RATIO,EPSI,THETAO,NTCTR,N
1 LUMINI,X1(100),X2(100),X3(100),XR2(100),XR1(100),PR1,PR2,P1,F1,RJ1(
2 2200),DOTT,PGRAD(100),DIAG(100),RJ3(200),PREV3,F3,ADELX,RSIG1,G1,G3
3,RSIG3,NVI,NPHASE,NSATIS,LRJ(200)
REAL LRJ
NPHASE=1
NSW=1
GO TO (1,5), NT2
NFIIX=1
DO 3 I=1,N
IF (X(I)) 2,2,3
NFIIX=2
X(I)=1.E-05
CONTINUE
GO TO (5,4), NFIIX
NPHASE=2
CALL EVALU
NPHASE=1
WRITE (6,11)
CALL OUTPUT (2)
DO 6 I=1,MN
IF (RJ(I)) 9,9,6
CONTINUE
GO TO (8,7), NSW
CALL TIMEC
WRITE (6,12)
G=0.0
P0=0.0

```

	CALL OUTPUT (2)	J 33
8	RETURN	J 34
9	NVI=I	J 35
	F==RJ(NVI)	J 36
	CALL BODY	J 37
	NSW=2	J 38
	NVI=0	J 39
	IF (F) 5,5,10	J 40
10	WRITE (6,13)	J 41
C-----	TO INDICATE TO MAIN TO START ON NEXT PROBLEM.	J 42
	NPHASE=5	J 43
	GO TO 8	J 44
C-----		J 45
11	FORMAT (1H0,2X,48HMADE VIOLATED NON-NEGATIVITIES SLIGHTLY POSITIVE	J 46
1)		J 47
12	FORMAT (51H0*****THE FEASIBLE STARTING POINT TO BE USED IS ...)	J 48
13	FORMAT (3X,89HTHIS PROBLEM POSSESSES NO FEASIBLE STARTING POINT, W	J 49
	1ILL LOOK FOR DATA FOR NEXT PROBLEM. )	J 50
	END	J 51

	SUBROUTINE FINAL (N2)	K 1
	COMMON /SHARE/ X(100),DEL(100),A(100,100),N,M,MN,NP1,NM1	K 2
	COMMON /OPTNS/ NT1,NT2,NT3,NT4,NT5,NT6,NT7,NT8,NT9,NT10,NT11,NT12	K 3
	COMMON /VALUE/ F,G,P0,RSIGMA,RJ(200),RHO	K 4
	COMMON /CRST/ DELX(100),DELX0(100),RHOIN,RATIO,EPSI,THETA0,NTCTR,N	K 5
	LUMINI,X1(100),X2(100),X3(100),XR2(100),XR1(100),PR1,PR2,P1,F1,RJ1(	K 6
	2200),DDTT,PGRAD(100),DIAG(100),RJ3(200),PREV3,F3,ADELX,RSIG1,G1,G3	K 7
	3,RSIG3,NVI,NPHASE,NSATIS,LRJ(200)	K 8
	REAL LRJ	K 9
C-----	FINAL CONVERGENCE CRITERION	K 10
C-----	1 LEFT IF CONVERGENCE MET 2 IF NOT	K 11
	GO TO (1,2,3), NT5	K 12
1	EPSIL=ABS(F/G-1.)	K 13
	IF (EPSIL-THETA0) 5,5,6	K 14
2	IF (RSIGMA-THETA0) 5,5,6	K 15
3	IF (NUMINI-1) 5,4,4	K 16
4	PEST=PR1-(PR1-P0)/(1.-1./SQRT(RATIO))	K 17
	EPSIL=ABS(PEST/G-1.)	K 18
	IF (EPSIL-THETA0) 5,5,6	K 19
5	N2=1	K 20
	GO TO 7	K 21
6	N2=2	K 22
7	RETURN	K 23
	END	K 24

```

COMMON /SHARE/ X(100),DEL(100),A(100,100),N,M,MN,NP1,NM1      L
COMMON /OPTNS/ NT1,NT2,NT3,NT4,NT5,NT6,NT7,NT8,NT9,NT10,NT11,NT12   L
COMMON /VALUE/ F,G,P0,RSIGMA,RJ(200),RHO                         L
COMMON /CRST/ DELX(100),DELX0(100),RHOIN,RATIO,EPSI,THETAO,NTCTR,N  L
1UMINI,X1(100),X2(100),X3(100),XR2(100),XR1(100),PR1,PR2,P1,F1,RJ1( L
2200),DOTT,PGRAD(100),DIAG(100),RJ3(200),PREV3,F3,ADELX,RSIG1,G1,G3  L
3,RSIG3,NVI,NPHASE,NSATIS,LRJ(200)                                L
      REAL LRJ
C-----IF (IS=1) ACCUM. MATRIX OF 2ND PARTIALS IF(IS=2) DONT      L
      GO TO (1,3), IS
1      DO 2 I=1,N
2      DO 2 J=1,I
3      A(I,J)=0.
4      DO 4 I=1,N
5      DELX0(I)=0.
C-----THIS SECTION WORKS CORRECTLY IN FEASIBILITY PHASE AS WELL AS NORMA  L
IPN=0
      GO TO (5,9), NT2
5      DO 8 I=1,N
6      IF (X1(I)) 8,8,6
7      DELX0(I)=-RHO/X(I)**2
      GO TO (7,8), IS
8      A(I,I)=-2.*DELX0(I)/X(I)
8      CONTINUE
IPN=N
9      DO 16 J=1,M
K=IPN+J
      IF (RJ1(K)) 16,16,10
10     CALL GRADI (J)
TT=RHO/RJ(K)**2
      DO 15 I=1,N
      IF (DEL(I)) 11,15,11
C-----IF DEL(I)=0 SKIP ALL THE FOLLOWING COMPUTATION INVOLVING * BY DEL( L
11     T=TT*DEL(I)
      DELX0(I)=DELX0(I)-T
      GO TO (12,15), IS
12     T=2.*T/RJ(K)
      DO 14 JJ=1,I
      IF (DEL(JJ)) 13,14,13
13     A(I,JJ)=A(I,JJ)+T*DEL(JJ)
14     CONTINUE
15     CONTINUE
16     CONTINUE
      GO TO (17,19), IS
17     DO 18 I=1,N
18     DIAG(I)=A(I,I)
19     GO TO (20,27,29), NPHASE
20     NJ=NVI
      GO TO (21,25), NT2
21     IF (NVI.GT.N) 24,22
22     DO 23 I=1,N
23     DELX0(I)=-DELX0(I)
      DELX0(NVI)=DELX0(NVI)+1.0
      GO TO 29
24     NJ=NVI-N
25     CALL GRADI (NJ)

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      DO 26 I=1,N          L 58
26    DELX0(I)=-DELX0(I)+DEL(I)   L 59
      GO TO 29             L 60
27    CALL GRAD1 (0)        L 61
      DO 28 I=1,N          L 62
28    DELX0(I)=-DELX0(I)-DEL(I)   L 63
C-----LEAVES THE NEG. GRAD OF P IN DELX0
29    RETURN              L 64
      END                 L 65
                                         L 66

```

```

SUBROUTINE INVERS (NSME)          M 1
COMMON /SHARE/ X(100),DEL(100),A(100,100),N,M,MN,NP1,NM1   M 2
COMMON /OPTNS/ NT1,NT2,NT3,NT4,NT5,NT6,NT7,NT8,NT9,NT10,NT11,NT12 M 3
COMMON /CRST/  DELX(100),DELX0(100),RHOIN,RATIO,EPSI,THETAO,NTCTR,N M 4
1UMINI,X1(100),X2(100),X3(100),XR2(100),XR1(100),PR1,PR2,P1,F1,RJ1( M 5
2200),DOTT,PGRAD(100),DIAG(100),RJ3(200),PREV3,F3,ADELX,RSIG1,G1,G3 M 6
3,RSIG3,NVI,NPHASE,NSATIS,LRJ(200)   M 7
      REAL LRJ            M 8
      EQUIVALENCE (B,DELX)   M 9
      DIMENSION B(100)       M 10
C-----GETTING THE PRODUCT INVERSE USING THE CROUT METHOD AND TAKING ADVA M 11
C-----AGE OF THE SYMMETRY OF THE A MATRIX           M 12
C-----IF A DIVISOR OF ZERO IS GENERATED, THEN DELX IS SET EQUAL TO DELX0 M 13
C-----IF NSME=1 HAVE NEW A MATRIX IF NSME=2 COMPUTE INVERSE PRODUCT US M 14
C-----A AS LEFT FROM LAST TIME.                      M 15
      GO TO (2,1), NSME      M 16
1     GO TO (12,19), KSW        M 17
2     KSW=1                  M 18
3     IF (A(1,1)) 23,23,3    M 19
4     A(1,1)=1./A(1,1)       M 20
      DO 4 I=2,N              M 21
5     A(1,I)=A(1,I)*A(1,1)   M 22
6     DO 11 J=2,N             M 23
7     JM1=J-1                M 24
8     T=0.                   M 25
9     DO 6 I=1,JM1            M 26
10    IF (A(I,J)) 5,6,5       M 27
11    T=T+A(J,I)*A(I,J)      M 28
12    CONTINUE                 M 29
13    A(J,J)=A(J,J)-T        M 30
14    IF (A(J,J)) 24,24,7      M 31
15    A(J,J)=1./A(J,J)        M 32
16    IF (J.EQ.N) GO TO 12      M 33
17    JP1=J+1                  M 34
18    DO 10 L=JP1,N            M 35
19    T=0.                     M 36
20    DO 9 I=1,JM1            M 37
21    IF (A(I,J)) 8,9,8       M 38
22    T=T+A(L,I)*A(I,J)      M 39
23    CONTINUE                 M 40
24    A(L,J)=A(L,J)-T        M 41

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      A(J,L)=A(L,J)*A(J,J)          M   4
10    CONTINUE                      M   4
11    CONTINUE                      M   4
12    B(1)=B(1)*A(1,1)              M   4
      DO 15 J=2,N                  M   4
      T=0.                          M   4
      JM1=J-1                      M   4
      DO 14 I=1,JM1                M   4
      IF (A(J,I)) 13,14,13        M   4
      T=T+A(J,I)*B(I)             M   4
13    CONTINUE                      M   5
14    B(J)=(B(J)-T)*A(J,J)        M   5
15    CONTINUE                      M   5
      DO 16 I=1,NM1                M   5
      NMK=N-I                      M   5
      DO 17 J=1,I                  M   5
      L=NP1-J                      M   5
      IF (A(NMK,L)) 16,17,16      M   5
16    B(NMK)=B(NMK)-A(NMK,L)*B(L) M   6
17    CONTINUE                      M   6
18    CONTINUE                      M   6
19    GO TO 122,201, NT3          M   6
20    WRITE (6,27)                 M   6
      WRITE (6,261) (DELX0(I),I=1,N) M   6
      GO TO 121,22), KSW           M   6
21    WRITE (6,28)                 M   6
      WRITE (6,26) (DELX(I),I=1,N) M   6
22    RETURN                       M   6
23    J=1                          M   7
24    WRITE (6,29) J,A(J,J)        M   7
      KSW=2                         M   7
      DO 25 I=1,N                  M   7
25    DELX(2)=DELX0(I)            M   7
      GO TO 19                      M   7
C-----
26    FORMAT (7E17.8)              M   7
27    FORMAT (1HO,6X,12HDEL P VECTOR) M   7
28    FORMAT (1HO,6X,24HSECOND ORDER MOVE VECTOR) M   7
29    FORMAT(2HO 51HTHIS MIGHT NOT BE A CONVEX PROGRAMMING PROBLEM, THE M   8
1 13, 16HTHE DISCRIMINANT= ,E15.7 ) M   8
      END                           M   8

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## SUBROUTINE MAG

```

COMMON /SHARE/ X(100),DEL(100),A(100,100),N,M,MN,NP1,NM1 N
COMMON /CRST/ DELX(100),DELX0(100),RHOIN,RATIO,EPSI,THETAO,NTCTR,N N
1UMINI,X1(100),X2(100),X3(100),XR2(100),XR1(100),PR1,PR2,P1,F1,RJ1( N
200),DOTT,PGRAD(100),DIAG(100),RJ3(200),PREV3,F3,ADELX,RSIG1,G1,G3 N
3,RSIG3,NVI,NPHASE,NSATIS,LRJ(200) N
      REAL LRJ N
      ADELX=0. N
      DO 1 I=1,N N

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1 ADELX=ADELX+DELX0(I)**2 N 10
ADELX=SQRT(ADELX) N 11
RETURN N 12
END N 13

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SUBROUTINE OPT SUM 1
COMMON /SHARE/ X(100),DEL(100),A(100,100),N,M,MN,NP1,NM1 SUM 2
COMMON /OPTNS/ NT1,NT2,NT3,NT4,NT5,NT6,NT7,NT8,NT9,NT10,NT11,NT12 SUM 3
COMMON /VALUE/ F,G,P0,RSIGMA,RJ(200),RHO SUM 4
COMMON /CRST/ DELX(100),DELX0(100),RHOTIN,RATIO,EPSI,THETAO,NTCTR,NSUM 5
1UMINI,X1(100),X2(100),X3(100),XR2(100),XR1(100),PR1,PR2,P1,F1,RJ1(SUM 6
2200),DOTT,PGRAD(100),DIAG(100),RJ3(200),PREV3,F3,ADELX,RSIG1,G1,G3SUM 7
3,RSIG3,NSATIS,LRJ(200) SUM 8
REAL LRJ
KSW=1 SUM 9
DOTT=0. SUM 10
DO 1 J=1,N SUM 11
1 DOTT=DOTT+DELX(J)*DELX0(J) SUM 12
IF (DOTT) 2,2,4 SUM 13
2 DO 3 I=1,N SUM 14
3 DELX(I)=DELX0(I) SUM 15
4 CONTINUE SUM 16
NTCTR=NTCTR+1 SUM 17
DO 5 I=1,N SUM 18
5 X2(I)=X(I) SUM 19
PX1=P0 SUM 20
N401=0 SUM 21
6 N401=N401+1 SUM 22
DO 7 I=1,N SUM 23
7 X(I)=X2(I)+DELX(I) SUM 24
CALL EVALU SUM 25
CALL SPECFE SUM 26
C-----1 MEANS SATIS.OF CONSTRAINT NT.PREV. 2MEANS NOCHANGE 3MEANS VIOLATSUM 27
C-----IF POINT IS NOT FEASIBLE GIVE IT AN ARBITRARILY HIGH VALUE SUM 28
GO TO (46,9,8), NSATIS SUM 29
8 PX2=10.E35 SUM 30
P0=10.E35 SUM 31
GO TO 10 SUM 32
9 CALL PEVALU SUM 33
PX2=P0 SUM 34
IF (PX1-PX2) 10,10,15 SUM 35
10 IF (N401-2) 13,11,11 SUM 36
11 DO 12 I=1,N SUM 37
12 X1(I)=X(I) SUM 38
P1=PX2 SUM 39
GO TO 37 SUM 40
C-----
C-----ONLY ONE POINT SO FAR COMPUTED SUM 41
13 DO 14 I=1,N SUM 42
14 X3(I)=X2(I) SUM 43
PREV3=PX1 SUM 44
SUM 45
SUM 46

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      GO TO 18          SUM  47
15   DO 16 I=1,N     SUM  48
      X3(I)=X2(I)     SUM  49
      X2(I)=X(I)      SUM  50
16   DELX(I)=1.61803399*DELX(I)  SUM  51
      PREV3=PX1        SUM  52
      PX1=PX2        SUM  53
      GO TO 6         SUM  54
C-----FIBONACCI METHOD
C-----B VECTOR GOES TO X1(I)
17   P0=1.E36        SUM  55
18   DO 19 I=1,N     SUM  56
19   X1(I)=X(I)      SUM  57
      P1=P0          SUM  58
      DO 20 I=1,N     SUM  59
      X(I)=.38196601*(X1(I)-X3(I))+X3(I)  SUM  60
20   X2(I)=X(I)      SUM  61
      CALL EVALU      SUM  62
      CALL SPECFE     SUM  63
      GO TO (46,21,17), NSATIS  SUM  64
21   CALL PEVALU     SUM  65
      PX1=P0          SUM  66
      DO 22 I=1,N     SUM  67
22   X(I)=0.38196601*(X1(I)-X2(I))+X2(I)  SUM  68
      CALL EVALU      SUM  69
      CALL SPECFE     SUM  70
      GO TO (46,23,17), NSATIS  SUM  71
23   CALL PEVALU     SUM  72
      PX2=P0          SUM  73
      N401=1          SUM  74
24   N401=N401+1    SUM  75
      IF (N401-25) 28,25,25  SUM  76
25   KSW=2          SUM  77
      IF (N401-40) 26,40,40  SUM  78
26   DO 27 I=1,N    SUM  79
      IF (ABS(X2(I)/X(I)-1.0).GE.1.E-7) 28,27  SUM  80
27   CONTINUE        SUM  81
      GO TO 40        SUM  82
28   IF (ABS(PX1/PX2-1.).LE.1.E-7) 40,29  SUM  83
29   IF (PX1-PX2) 30,40,35  SUM  84
C-----FROM LEFTORIGHT X3(I)(PREV3)X2(I)(PX1)X(I)PX2 X1(I)P1
30   DO 31 I=1,N    SUM  85
31   X1(I)=X(I)      SUM  86
C-----THROW AWAY RIGHT PART
      P1=PX2          SUM  87
      DO 32 I=1,N    SUM  88
C-----POINTXP1 BECOMES XP2
32   X(I)=.38196601*(X1(I)-X3(I))+X3(I)  SUM  89
C-----TEMPORARILY IN X STORAGE
      CALL EVALU      SUM  90
      CALL SPECFE     SUM  91
      GO TO (46,33,17), NSATIS  SUM  92
33   CALL PEVALU     SUM  93
      PX2=PX1          SUM  94
C-----SWITCH VECTORS TO PROPER POSITION
      PX1=P0          SUM  95
                                         SUM  96
                                         SUM  97
                                         SUM  98
                                         SUM  99
                                         SUM 100
                                         SUM 101
                                         SUM 102

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      DO 34 I=1,N                      SUM 103
      XX=X2(I)                         SUM 104
      X2(I)=X(I)                         SUM 105
34   X(I)=XX                          SUM 106
      GO TO 24                          SUM 107
C-----LEFT SIDE TOSSED AWAY          SUM 108
35   DO 36 I=1,N                      SUM 109
      X3(I)=X2(I)                         SUM 110
36   X2(I)=X(I)                         SUM 111
      PREV3=PX1                          SUM 112
      PX1=PX2                          SUM 113
37   DO 38 I=1,N                      SUM 114
38   X(I)=0.38196601*(X1(I)-X2(I))+X2(I)    SUM 115
      CALL EVALU                         SUM 116
      CALL SPECFE                        SUM 117
      GO TO (46,39,17), NSATIS           SUM 118
39   CONTINUE                           SUM 119
      CALL PEVALU                        SUM 120
      PX2=PO                            SUM 121
      GO TO 24                          SUM 122
C-----FIBONNACCI POINTS HAVE EQUAL VALUE NOW COMPUTE MIDPOINT  SUM 123
40   DO 41 I=1,N                      SUM 124
      DELX0(I)=X(I)                         SUM 125
41   X(I)=(DELX0(I)+X2(I))*0.5        SUM 126
      PPI=PX2                          SUM 127
      CALL EVALU                         SUM 128
      CALL PEVALU                        SUM 129
      GO TO (42,43), KSW                SUM 130
42   IF (ABS(PO/PX1-1.).GT.1.E-7) 44,43    SUM 131
C-----NOTE POSSIBLE ACCUM SECOND PARTIALS HERE ALSO          SUM 132
43   CALL GRAD (2)                     SUM 133
      RETURN                            SUM 134
44   DO 45 I=1,N                      SUM 135
45   X(I)=DELX0(I)                     SUM 136
      GO TO 30                          SUM 137
46   RETURN                            SUM 138
C-----NOT YET CODED FOR PHASE=3          SUM 139
      END                               SUM 140

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SUBROUTINE OUTPUT (K)                      SUM 1
COMMON /SHARE/ X(100),DEL(100),A(100,100),N,M,MN,NP1,NM1    SUM 2
COMMON /OPTNS/ NT1,NT2,NT3,NT4,NT5,NT6,NT7,NT8,NT9,NT10,NT11,NT12 SUM 3
COMMON /VALUE/ F,G,PO,RSIGMA,RJ(200),RHO                      SUM 4
COMMON /CRST/ DELX(100),DELX0(100),RHOIN,RATIO,EPSI,THETA0,NTCTR,NSUM 5
1UMINI,X1(100),X2(100),X3(100),XR2(100),XR1(100),PR1,PR2,P1,F1,RJ1(SUM 6
2200),DOTT,PGRAD(100),DIAG(100),RJ3(200),PREV3,F3,ADELX,RSIG1,G1,G3SUM 7
3,RSIG3,NVI,NPHASE,NSATIS,LRJ(200),NSOL
      REAL LRJ                           SUM 9
      GO TO (1,5), K                      SUM 10
1     WRITE (6,9)                         SUM 11
      WRITE (6,10) NTCTR,DOTT,RHO,ADELX,NPHASE                  SUM 12

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## NONLINEAR PROGRAMMING PROGRAM

PAGE 16

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1 IF (NPHASE.NE.1) 5,2          SUM 11
2 NVII=NVI                      SUM 12
3 GO TO (3,4), NT2              SUM 13
4 NVII=NVI-N                    SUM 14
5 WRITE (6,14) NVII              SUM 15
6 WRITE (6,11) F,P0,G,RSIGMA    SUM 16
7 WRITE (6,12) (X(I),I=1,MN)    SUM 17
8 WRITE (6,15)                  SUM 18
9 GO TO (6,7), NT2              SUM 19
10 WRITE (6,16)                  SUM 20
11 WRITE (6,13) (RJ(I),I=NPI,MN) SUM 21
12 GO TO 8                       SUM 22
13 WRITE (6,13) (RJ(I),I=1,MN)    SUM 23
14 NSOL=NSOL+1                   SUM 24
15 IF(NSOL.LT.5) RETURN          SUM 25
16 NSOL=0                         SUM 26
17 WRITE(6,17)
18 RETURN                         SUM 27
C-----
19 FORMAT (50H0*****)             SUM 28
20 FORMAT (10X,6HPOINT=I4,6X,6H DOTT=1PE15.7,6X,4HRHO=E15.7,6X,10HMAGSUM 29
21 INITUDE=E15.7,6X,6HPHASE=I2)  SUM 30
22 FORMAT (10X,2HF=1PE15.7,6X,2HP=E15.7,6X,2HG=E15.7,6X,7HRSIGMA=E15.SUM 31
23 17)                           SUM 32
24 FORMAT (6X,25HTHE CURRENT VALUE OF X IS/(1P6F20.7))  SUM 33
25 FORMAT (1P6E20.7)              SUM 34
26 FORMAT (1H ,117X,6X,4HNVI=I3)  SUM 35
27 FORMAT (6X,21HTHE CONSTRAINT VALUES)  SUM 36
28 FORMAT (1H ,27X,34HNNOT INCLUDING THE NON-NEGATIVITIES)  SUM 37
29 FORMAT(*1NONLINEAR PROGRAMMING ROUTINE-RAC*///)
30 END                            SUM 38

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SUBROUTINE PEVALU
COMMON /SHARE/ X(100),DEL(100),A(100,100),N,M,MN,NPI,NM1      SUM 1
COMMON /OPTNS/ NT1,NT2,NT3,NT4,NT5,NT6,NT7,NT8,NT9,NT10,NT11,NT12 SUM 2
COMMON /VALUE/ F,G,P0,RSIGMA,RJ(200),RHO                         SUM 3
COMMON /CRST/ DELX(100),DELX0(100),RHOIN,RATIO,EPSI,THETA0,NTCTR,NSUM 4
1 UMINI,X1(100),X2(100),X3(100),XR2(100),XR1(100),PR1,PR2,P1,F1,RJ1(SUM 5
2 2200),DOTT,PGRAD(100),DIAG(100),RJ3(200),PREV3,F3,ADELX,RSIG1,G1,G3SUM 6
3,RSIG3,NVI,NPHASE,NSATIS,LRJ(200)                                SUM 7
4 REAL LRJ
5 GO TO (5,1,4), NPHASE                                         SUM 8
1 RSIGMA=0.                                                       SUM 9
2 DO 2 I=1,MN
3   RSIGMA=RSIGMA+RHO/RJ(I)                                     SUM 10
4   P0=RSIGMA+F
5   G=F-RSIGMA
6   RETURN
7   RSIGMA=0.
8   DO 7 I=1,MN
9   IF (RJ1(I)) 7,7,6                                         SUM 17
10

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6	RSIGMA=RSIGMA+RHO/RJ(I)	SUM	20
7	CONTINUE	SUM	21
	GO TO 3	SUM	22
	END	SUM	23

SUBROUTINE REJECT		SUM	1
COMMON /SHARE/ X(100),DEL(100),A(100,100),N,M,MN,NP1,NM1		SUM	2
COMMON /OPTNS/ NT1,NT2,NT3,NT4,NT5,NT6,NT7,NT8,NT9,NT10,NT11,NT12		SUM	3
COMMON /VALUE/ F,G,P0,RSIGMA,RJ(200),RHO		SUM	4
COMMON /CRST/ DELX(100),DELX0(100),RH0IN,RATIO,EPSI,THETA0,NTCTR,NSUM		SUM	5
1UMINI,X1(100),X2(100),X3(100),XR2(100),XR1(100),PRI,PR2,P1,F1,RJ1(SUM		SUM	6
2200),DOTT,PGRAD(100),DIAG(100),RJ3(200),PREV3,F3,ADELX,RSIG1,G1,G3SUM		SUM	7
3,RSIG3,NVI,NPHASE,NSATIS,LRJ(200)		SUM	8
REAL LRJ		SUM	9
1	DO 2 I=1,N	SUM	10
2	X(I)=X1(I)	SUM	11
	DO 3 J=1,MN	SUM	12
3	RJ(J)=RJ1(J)	SUM	13
	P0=P1	SUM	14
	RSIGMA=RSIG1	SUM	15
	G=G1	SUM	16
	F=F1	SUM	17
	RETURN	SUM	18
	END	SUM	19

SUBROUTINE REJCT1		1
COMMON /SHARE/ X(100),DEL(100),A(100,100),N,M,MN,NP1,NM1		2
COMMON /OPTNS/ NT1,NT2,NT3,NT4,NT5,NT6,NT7,NT8,NT9,NT10,NT11,NT12		3
COMMON /VALUE/ F,G,P0,RSIGMA,RJ(200),RHO		4
COMMON /CRST/ DELX(100),DELX0(100),RH0IN,RATIO,EPSI,THETA0,NTCTR,N		5
1UMINI,X1(100),X2(100),X3(100),XR2(100),XR1(100),PRI,PR2,P1,F1,RJ1(		6
2200),DOTT,PGRAD(100),DIAG(100),RJ3(200),PREV3,F3,ADELX,RSIG1,G1,G3		7
3,RSIG3,NVI,NPHASE,NSATIS,LRJ(200)		8
REAL LRJ		9
1	DO 1 I=1,N	10
	X(I)=X3(I)	11
2	DO 2 J=1,MN	12
	RJ(J)=RJ3(J)	13
	P0=PREV3	14
	G=G3	15
	RSIGMA=RSIG3	16
	F=F3	17
	RETURN	18
	END	19

```

SUBROUTINE SPECFE          SUM
COMMON /SHARE/ X(100),DEL(100),A(100,100),N,M,MN,NPI,NM1   SUM
COMMON /VALUE/ F,G,P0,RSIGMA,RJ(200),RHO                   SUM
COMMON /CRST/ DELX(100),DELX0(100),RHOIN,RATIO,EPSI,THETA0,NTCTR,NSUM
1UMINI,X1(100),X2(100),X3(100),XR2(100),XR1(100),PR1,PR2,P1,F1,RJ1(SUM
2200),DOTT,PGRAD(100),DIAG(100),RJ3(200),PREV3,F3,ADELX,RSIG1,G1+G3SUM
3,RSIG3,NVI,NPHASE,NSATIS,LRJ(200)                         SUM
      REAL LRJ
C-----3 IF NOT 'FEAS' . 2 IF NO CHANGE IN VIOLS+SATIS.  1 SATIS  IORMSUM
      NSATIS=2
      DO 4 J=1,MN
        IF (RJ1(J)) 2,2,1
1       IF (RJ1(J)) 5,5,4
2       IF (RJ1(J)) 4,4,3
3       NSATIS=1
4       CONTINUE
      RETURN
5      NSATIS=3
      RETURN
      END

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SURROUTINE RHOCOM          SUM
COMMON /SHARE/ X(100),DEL(100),A(100,100),N,M,MN,NPI,NM1   SUM
COMMON /OPTNS/ NT1,NT2,NT3,NT4,NT5,NT6,NT7,NT8,NT9,NT10,NT11,NT12 SUM
COMMON /VALUE/ F,G,P0,RSIGMA,RJ(200),RHO                   SUM
COMMON /CRST/ DELX(100),DELX0(100),RHOIN,RATIO,EPSI,THETA0,NTCTR,NSUM
1UMINI,X1(100),X2(100),X3(100),XR2(100),XR1(100),PR1,PR2,P1,F1,RJ1(SUM
2200),DOTT,PGRAD(100),DIAG(100),RJ3(200),PREV3,F3,ADELX,RSIG1,G1+G3SUM
3,RSIG3,NVI,NPHASE,NSATIS,LRJ(200)                         SUM
      REAL LRJ
C-----SUBROUTINE TO COMPUTE INITIAL RHO VALUE           SUM
C----- CONTROLLED BY COL. 7 ON OTION CARD             SUM
      CALL STORE
      GO TO (11,5,1,19), NT1
1      RHO=RHOIN
2      IF (RHO) 3,3,4
3      RHO=1.
4      RETURN
5      NPAR1=1
6      RHO=1.
C-----2 MEANS RHO WHICH MINIMIZES GRADIENT MAG.     SUM
      CALL GRAD (2)
      CALL GRADI (0)
C-----TO GET -DEL F                               SUM
      DO 7 I=1,N
7      PGRAD(I)=-DEL(I)
      DO 8 I=1,N
8      DELX0(I)=DELX0(I)-PGRAD(I)
C-----THIS LEAVES DEL SIGMA IN DELX0            SUM
      CONTINUE
      GO TO (9,13), NPAR1

```

```

9     DOT1=0.                      SUM  31
      DOT2=0.                      SUM  32
      DO 10 I=1,N                  SUM  33
      DOT1=DOT1+DELX0(I)*PGRAD(I)
10    DOT2=DOT2+DELX0(I)**2        SUM  34
      RHO=ABS(DOT1/DOT2)           SUM  35
      GO TO 2                      SUM  36
C-----3 MEANS COMPUTE RHO SO AS TO MINIMIZE DEL P(/DDP/1.)DEL P
11    NPAR2=1                      SUM  38
12    NPAR1=2                      SUM  39
C-----USE DF AND DR SUBROUTINE
      GO TO 6                      SUM  40
13    RHO=1.                        SUM  41
C-----ASSUME SIGMA TERM IS CONST. GRTER THAN F TERM
      CALL SECORD (2)              SUM  42
      DO 14 I=1,N                  SUM  43
14    DELX(I)=PGRAD(I)            SUM  44
      CALL INVERS (1)              SUM  45
      DO 15 I=1,N                  SUM  46
15    X3(I)=DELX(I)               SUM  47
      DELX(I)=DELX0(I)             SUM  48
      CALL INVERS (2)              SUM  49
      DO 16 I=1,N                  SUM  50
16    XR2(I)=DELX(I)              SUM  51
      GO TO (17,20), NPAR2         SUM  52
17    DOT1=0.                      SUM  53
      DOT2=0.                      SUM  54
      DO 18 I=1,N                  SUM  55
      DOT1=DOT1+PGRAD(I)*X3(I)
18    DOT2=DOT2+DELX0(I)*XR2(I)   SUM  56
      RHO=SQRT(ABS(DOT1/DOT2))    SUM  57
      GO TO 2                      SUM  58
19    NPAR2=2                      SUM  59
C-----RHO MINIMIZES 2ND ORDER MOVE
      GO TO 12                     SUM  60
C-----USES INTERNAL SUB. TO COM /DDP/-1 DF AND /DDP/- DR
20    DOT1=0.                      SUM  61
      DOT2=0.                      SUM  62
      DO 21 I=1,N                  SUM  63
      DOT1=X3(I)**2+DOT1           SUM  64
21    DOT2=X3(I)*XR2(I)+DOT2    SUM  65
      RHO=ABS(DOT1/DOT2)           SUM  66
      GO TO 2                      SUM  67
      END                         SUM  68
                                         SUM  69
                                         SUM  70
                                         SUM  71
                                         SUM  72
                                         SUM  73
                                         SUM  74

```

```

SUBROUTINE SECORD (IS)
COMMON /SHARE/ X(100),DEL(100),A(100,100),N,M,MN,NP1,NM1    SUM  1
COMMON /OPTNS/ NT1,NT2,NT3,NT4,NT5,NT6,NT7,NT8,NT9,NT10,NT11,NT12 SUM  2
COMMON /VALUE/ F,G,PO,RSIGMA,RJ(200),RHO                      SUM  3
COMMON /CRST/ DELX(100),DELX0(100),RHOIN,RATIO,EPSI,THETAQ,NTCTR,NSUM  4
1UMINI,X1(100),X2(100),X3(100),XR2(100),XR1(100),PRI,PR2,P1,F1,RJ1(SUM  5
                                         SUM  6

```

```

2200),DOTT,PGRAD(100),DIAG(100),RJ3(200),PREV3,F3,ADELX,RSIG1,G1,G3SUM    7
3,RSIG3,NVI,NPHASE,NSATIS,LRJ(200)                                         SUM  8
REAL LRJ
IPN=0
GO TO (1,2), NT2
1 IPN=N
2 GO TO (3,5), IS
3 DO 4 I=1,N
4 DO 4 J=1,N
A(I,J)=0.
GO TO 18
5 DO 6 I=1,N
6 DO 6 J=1,N
A(I,J)=0.
C-----GRAD. TERM NOT PREV. COMPUTED
GO TO (7,10), NT2
7 DO 9 I=1,N
IF (X1(I)) 9,9,8
8 A(I,I)=2.*RHO/RJ(I)**3
9 CONTINUE
10 DO 16 KK=1,M
K=IPN+KK
IF (RJ1(K)) 16,16,11
11 CALL GRADI (KK)
DO 15 I=1,N
IF (DEL(I)) 12,15,12
12 T=(2.*RHO/RJ(K)**3)*DEL(I)
DO 14 J=1,I
IF (DEL(J)) 13,14,13
13 A(I,J)=A(I,J)+T*DEL(J)
14 CONTINUE
15 CONTINUE
16 CONTINUE
DO 17 I=1,N
DIAG(I)=A(I,I)
17 A(I,I)=0.
C-----READY NOW FOR MATRIX OF 2ND PARTIALS OF RESTRAINTS
18 GO TO (23,19,20), NT10
C-----BY PASS COMPUTING SECOND PARITALS WHEN THEY ARE KNOWN TO BE ZERO
19 GO TO (20,38,38), NPHASE
20 DO 21 I=2,N
IM1=I-1
DO 21 J=1,IM1
A(J,I)=A(I,J)
21 A(I,I)=DIAG(I)
DO 22 I=1,N
22 A(I,I)=DIAG(I)
GO TO 44
23 DO 28 KK=1,M
K=IPN+KK
CALL MATRIX (KK)
T=-RHO/RJ(K)**2
DO 25 I=2,N
IM1=I-1
DO 25 J=1,IM1
IF (A(J,I)) 24,25,24
24 A(I,J)=A(I,J)+T*A(J,I)
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```

A(J,I)=0.          SUM 63
25  CONTINUE        SUM 64
    DO 27 I=1,N     SUM 65
    IF (A(I,I)) 26,27,26
    A(I,I)=0.        SUM 66
26  DIAG(I)=DIAG(I)+T*A(I,I)  SUM 67
27  CONTINUE        SUM 68
28  CONTINUE        SUM 69
    GO TO (29,38,38), NPHASE  SUM 70
C-----FOR NPHASE=3 ADDITIONS WILL BE ADDED LATER
29  NJ=NVI          SUM 71
    GO TO (30,32), NT2        SUM 72
30  IF (NVI-N) 44,44,31      SUM 73
31  NJ=NVI-N         SUM 74
32  CALL MATRIX (NJ)        SUM 75
    DO 34 I=2,N           SUM 76
    IM1=I-1              SUM 77
    DO 34 J=1,IM1         SUM 78
    IF (A(J,I)) 33,34,33  SUM 79
33  A(I,J)=A(I,J)-A(J,I)  SUM 80
34  A(J,I)=A(I,J)        SUM 81
    DO 37 I=1,N           SUM 82
    IF (A(I,I)) 35,36,35  SUM 83
35  A(I,I)=DIAG(I)-A(I,I)  SUM 84
    GO TO 37             SUM 85
36  A(I,I)=DIAG(I)        SUM 86
37  CONTINUE            SUM 87
    GO TO 44             SUM 88
C-----GET MATRIX OF 2ND PARTIALS OF OBJECTIVE FUNCTION
38  CALL MATRIX (0)        SUM 89
    DO 40 I=2,N           SUM 90
    IM1=I-1              SUM 91
    DO 40 J=1,IM1         SUM 92
    IF (A(J,I)) 39,40,39  SUM 93
39  A(I,J)=A(I,J)+A(J,I)  SUM 94
40  A(J,I)=A(I,J)        SUM 95
    DO 43 I=1,N           SUM 96
    IF (A(I,I)) 41,42,41  SUM 97
41  A(I,I)=DIAG(I)+A(I,I)  SUM 98
    GO TO 43             SUM 99
42  A(I,I)=DIAG(I)        SUM 100
43  CONTINUE            SUM 101
44  RETURN              SUM 102
END                SUM 103
                                SUM 104
                                SUM 105
                                SUM 106

```

```

SUBROUTINE STORE          SUM 1
COMMON /SHARE/ X(100),DEL(100),A(100,100),N,M,MN,NP1,N#1   SUM 2
COMMON /VALUE/ F,G,P0,RSIGMA,RJ(200),RHO                      SUM 3
COMMON /CRST/ DELX(100),DELX0(100),RHOIN,RATIO,EPSI,THETAO,NTCTR,NSUM 4
1UMINI,X1(100),X2(100),X3(100),XR2(100),XRI(100),PR1,PR2,P1,F1,RJ1:SUM 5
2200),SOTT,PGRAD(100),DIAG(100),RJ3(200),PREV3,F3,ADELX-RSIG1,G1,G3SUM 6

```

```

3,RSIG3,NVI,NPHASE,NSATIS,LRJ(200)          SUM   7
REAL LRJ                                     SUM   8
1 DO 2 I=1,N                                  SUM   9
2 X1(I)=X(I)                                 SUM  10
DO 3 J=1,MN                                  SUM  11
3 RJ1(J)=RJ(J)                               SUM  12
P1=P0                                       SUM  13
F1=F                                         SUM  14
G1=G                                         SUM  15
RSIG1=RSIGMA                                SUM  16
RETURN                                      SUM  17
END                                         SUM  18

```

```

SUBROUTINE STORE1                           SUM   1
COMMON /SHARE/ X(100),DEL(100),A(100,100),N,M,MN,NP1,NM1  SUM   2
COMMON /VALUE/ F,G,P0,RSIGMA,RJ(200),RHO               SUM   3
COMMON /CRST/ DELX(100),DELX0(100),RHOIN,RATIO,EPSI,THETA0,NTCTR,NSUM 4
1 UMINI,X1(100),X2(100),X3(100),XR2(100),XR1(100),PR1,PR2,P1,F1,RJ1(SUM 5
2200),DOTT,PGRAD(100),DIAG(100),RJ3(200),PREV3,F3,ADELX,RSIG1,G1,G3SUM 6
3,RSIG3,NVI,NPHASE,NSATIS,LRJ(200)          SUM   7
REAL LRJ                                     SUM   8
DO 1 I=1,N                                  SUM   9
1 X3(I)=X(I)                                 SUM  10
DO 2 J=1,MN                                 SUM  11
2 RJ3(J)=RJ(J)                               SUM  12
PREV3=P0                                    SUM  13
F3=F                                         SUM  14
RSIG3=RSIGMA                                SUM  15
G3=G                                         SUM  16
RETURN                                      SUM  17
END                                         SUM  18

```

```

SUBROUTINE TIMEC                           1
C-----CALLS SUBROUTINE TIME AND WRITES OUT ELAPSED TIME IN SECONDS. 2
RETURN                                     3
END                                         4

```

```

SUBROUTINE TIME (X)                         1
C-----THE ELAPSED TIME SINCE CALLING SET IS CONVERTED TO THE NUMBER 2
C-----OF SECONDS IN FLOATING POINT FORM AND STORED IN LOCATION X. 3
C-----TERMINATES PRESENT PROBLEM WHEN TMAX IS EXCEEDED. 4

```

ROUTINE FOR PROGRAMMING PRINTS

PAGE 23

RETURN  
END

SUBROUTINE SIT (TMAX)  
C-----WHERE TMAX IS THE ADDRESS OF A FLOATING POINT NUMBER GIVING THE  
C-----MAXIMUM NUMBER OF SECONDS THE PROGRAM IS TO BE ALLOWED TO RUN  
C-----UNTIL TERMINATION OR ANOTHER CALL TO SET.  
RETURN  
END

## SAMPLE DATA SHEET FOR VINTAGE

PAGE 24

STYLIN' RIFTAPY BOTANICAL COMPONENTS AND CRUSS ENERGY		PFRIND 2 STYLIS ?.	
1.0E-05	2.0E+02	1.0E-C6	3.2E+01
3.0E+01	3.0E+01	3.0E+01	2.4E+00
3.0E+01	3.0E+01	3.0E+01	7.7
1H	7		
46.50	6.00	23.50	5.00
46.00	8.50	9.50	0.50
64.50	13.00	3.50	0.50
67.50	11.00	7.00	2.50
71.50	9.00	5.50	2.50
68.50	12.00	3.00	0.50
53.00	8.50	14.50	8.50
48.00	5.50	6.50	9.00
72.50	8.50	1.50	8.00
58.40	6.50	7.50	10.50
45.00	11.50	16.00	0.50
55.00	10.00	0.50	1.50
74.00	10.00	6.50	10.50
65.50	12.50	5.00	6.50
58.00	8.50	14.50	7.50
56.00	10.00	15.50	7.50
42.70	5.70	12.40	10.50
65.50	7.00	12.50	7.50
3	1	1	2
			1
			2
			1
			1

SEVEN DILATORY TACTICAL COMPONENTS AND GROSS ENERGY PERIOD 2 SERIES 2.

		FILE #0. 1			
1	58.000	6.000	23.500	5.000	*500
2	68.001	8.500	9.500	6.000	*500
3	69.000	13.000	3.500	5.500	*500
4	67.500	11.000	7.000	5.500	1.000
5	71.501	9.000	5.500	2.500	*500
6	68.500	12.000	3.000	8.000	1.000
7	53.000	8.500	14.500	8.500	*500
8	48.000	5.500	6.500	9.000	*500
9	72.000	8.500	1.500	8.000	*500
10	58.300	5.500	7.500	10.500	*500
11	45.000	11.500	16.000	9.500	1.500
12	55.000	10.000	6.500	10.500	*500
13	74.000	7.000	5.000	6.500	*500
14	65.500	12.500	5.500	5.000	1.000
15	54.001	9.500	14.500	7.500	*500
16	56.000	10.000	15.500	7.500	*500
17	45.700	5.000	12.400	10.500	1.000
18	65.500	7.000	12.500	7.500	*500

```

N= / M= 7
MAX. T(U)= 7.400E+00 R= 2.0000000E+02 RATIO= 3.2000E+01 EPSILON= 1.000E-05 THETA= 1.000E-06

OPTIONS SPACES=0
3   1   1   2   1   1   1   G= 0.   2   RSIGMA= 0.
F= 2.4085479E+07 P= 0.   THE CURRENT VALUE OF X IS
3.0000000E+01 3.0000000E+01 3.0000000E+01 3.0000000E+01 3.0000000E+01 3.0000000E+01
THE CONSTRAINT VALUES NOT INCLUDING THE NON-NEGATIVITIES
3.0000000E+01 3.0000000E+01 3.0000000E+01 3.0000000E+01 3.0000000E+01 3.0000000E+01
***** POINT= 5 DJTT= 4.1286320E-06 RHO= 2.0000000E+02 MAGNITUDE= 1.0354811E-02 PHASE= 2
F= 1.5265721E+04 P= 1.5341382E+04 G= 1.5190060E+04 RSIGMA= 7.5661042E+01
THE CURRENT VALUE OF X IS
4.7520417E+01 5.1611689E+01 4.5633755E+01 3.6065173E+01 1.6139895E+01 5.5718522E+01
5.2119245E+01
THE CONSTRAINT VALUES NOT INCLUDING THE NON-NEGATIVITIES
4.7520417E+01 5.1611689E+01 4.5633755E+01 3.6065173E+01 1.6139895E+01 5.5718522E+01
5.2119245E+01
***** POINT= 6 DJTT= 3.7880640E-06 RHO= 6.2500000E+00 MAGNITUDE= 8.0414981E-04 PHASE= 2
F= 1.5265702E+04 P= 1.5267412E+04 G= 1.5262531E+04 RSIGMA= 2.4104558E+00
THE CURRENT VALUE OF X IS
4.7515238E+01 5.1695085E+01 4.5642378E+01 3.6056356E+01 1.5224950E+01 5.5763905E+01
5.2126731E+01
THE CONSTRAINT VALUES NOT INCLUDING THE NON-NEGATIVITIES
4.7515238E+01 5.1695085E+01 4.5642378E+01 3.6056356E+01 1.5224950E+01 5.5763905E+01
5.2126731E+01
***** POINT= 7 DJTT= 1.4993889E-06 RHO= 1.9531250E-01 MAGNITUDE= 5.3124655E-04 PHASE= 2
F= 1.5265001E+04 P= 1.5265076E+04 G= 1.5264925E+04 RSIGMA= 7.5381102E-02
THE CURRENT VALUE OF X IS
4.7515034E+01 5.1698050E+01 4.5642684E+01 3.6056050E+01 1.5192447E+01 5.5752053E+01
5.2126937E+01
THE CONSTRAINT VALUES NOT INCLUDING THE NON-NEGATIVITIES
4.7515034E+01 5.1698050E+01 4.5642684E+01 3.6056050E+01 1.5192447E+01 5.5752053E+01
5.2126937E+01
***** POINT= 8 DJTT= 2.7621047E-06 RHO= 6.1035156E-03 MAGNITUDE= 6.8005849E-04 PHASE= 2
F= 1.5265001E+04 P= 1.5265003E+04 G= 1.5264998E+04 RSIGMA= 2.3557495E-03
THE CURRENT VALUE OF X IS
4.7515034E+01 5.1698207E+01 4.5642700E+01 3.6056034E+01 1.5190727E+01 5.5752114E+01
5.2127001E+01
THE CONSTRAINT VALUES NOT INCLUDING THE NON-NEGATIVITIES
4.7515034E+01 5.1698207E+01 4.5642700E+01 3.6056034E+01 1.5190727E+01 5.5752114E+01
5.2127001E+01

```

NONLINEAR PHASE AMPLITUDE ROUTINE-RAC

```
*****
POINT= 15  DFT= 2.2415907E-07  RHO= 1.9073486E-04  MAGNITUDE= 1.9371209E-04
F= 1.5265001E+04  P= 1.5265001E+04  G= 1.5265001E+04  RSIGMA= 7.3616310E-05  PHASE= 2
THE CURRENT VALUE OF X IS
4.7515767E+01  5.1698162E+01  4.5642695E+01  3.6056039E+01  1.5191217E+01  5.5752097E+01
5.2127305E+01
THE CONSTRAINT VALUES
4.7515767E+01  5.1698162E+01  4.5642695E+01  3.6056039E+01  1.5191217E+01  5.5752097E+01
5.2127305E+01
*****
POINT= 16  DFT= 2.1773704E-08  RHO= 5.9606545E-06  MAGNITUDE= 6.0381074E-05
F= 1.5265001E+04  P= 1.5265001E+04  G= 1.5265001E+04  RSIGMA= 2.3005134E-06  PHASE= 2
THE CURRENT VALUE OF X IS
4.7515767E+01  5.1698176E+01  4.5642697E+01  3.6056037E+01  1.5191064E+01  5.5752102E+01
5.2127305E+01
THE CONSTRAINT VALUES
4.7515767E+01  5.1698176E+01  4.5642697E+01  3.6056037E+01  1.5191064E+01  5.5752102E+01
5.2127305E+01
*****
POINT= 17  DFT= 2.0756337E-09  RHO= 1.8626451E-07  MAGNITUDE= 1.8631889E-05
F= 1.5265001E+04  P= 1.5265001E+04  G= 1.5265001E+04  RSIGMA= 7.1891155E-08  PHASE= 2
THE CURRENT VALUE OF X IS
4.7515767E+01  5.1698172E+01  4.5642697E+01  3.6056038E+01  1.5191112E+01  5.5752100E+01
5.2127305E+01
THE CONSTRAINT VALUES
4.7515767E+01  5.1698172E+01  4.5642697E+01  3.6056038E+01  1.5191112E+01  5.5752100E+01
5.2127305E+01
```

and careful thought of each application of the program is necessary if correct results are to be obtained. For an in depth discussion of this program, its development and methods of computation, refer to *Evaluation of a digital computer method for analysis of compartmental models of ecological systems*, L. J. Bledsoe and G. M. Van Dyne, Oak Ridge National Laboratory, Oak Ridge, Tennessee, ORNL-TM-2414, February 1969. This abstract describes a sample problem and illustrates its solution along with a description of the control cards required and the input format of the data.

## Program COMSYS2

A FORTRAN program developed at Colorado State University using a CDC 6400 computer using the SCOPE version 2.0 FORTRAN extended compiler.

This program was developed to find the coefficients of a set of linear homogeneous differential equations. The compartment model, characterized by these differential equations, is one of the more general mathematical models available to the systems biologist attempting to explain multivariable data taken from a complex system. A compartment model for a biological system consists of an abstraction in which the system is viewed as a series of discrete compartments between which flow energy or material. Flow between compartments is characterized by first-order differential equations. The net flow associated with each compartment is given as a function of time and as a function of the contents of the other compartments. At least as a first approximation, it is useful to think of these differential equations as being linear and homogeneous. This linear differential equation system is,

$$v_j' = \sum_{i=1}^n v_i \cdot f_{ij},$$

where n is the number of compartments in the system,

$v_i$  is a function of time and represents the contents of compartment i,

$v_j'$  is the derivative of the contents of the jth compartment,

$f_{ij}$  is the ith row and jth column entry in a matrix f, representing the constant of proportionality associated with the flow from compartment i to compartment j.

It is the purpose of this program, given some observed values for  $v_i$  through time to determine the  $f_{ij}$ . The program will handle up to five compartments and as many data points through time as desired. The use of the program is complex

## INTRODUCTION

Program LINDIFF is a FORTRAN program developed at Colorado State University using a CDC 6400 computer with the SCOPE version 2.0 FORTRAN extended compiler. The program is also operational using the NCAR compiler on the CDC 6400.

Program LINDIFF solves a set of linear differential equations with constant coefficients of the form:

$$y_i' = \sum_{j=1}^n a_{ij} \cdot y_j.$$

The solution of the above set of equations amounts to determining  $y_i$  ( $i=1, \dots, n$ ) for an interval of interest along the independent variable. The integration scheme is of the Runge-Kutta type and requires initial values of the dependent variable to start the solution. The matrix  $[a_{ij}]$  is read in and are the constants in the equations. Although the program is designed for solution of the above type equations, the Runge-Kutta integration routine is somewhat more general and may be easily adapted to other problems. By changing subroutine EQUA which evaluates the derivatives and changing the input scheme appropriately all equations of the form,

$$y' = f(x, y)$$

may be solved. Also since each ordinary differential equation of the second or higher order is equivalent to a system of first order equations, these also admit to solution by Runge-Kutta methods.

The program will solve up to 20 equations in 20 unknowns although this is easily modified to handle longer systems by changing the appropriate dimensions and is subject only to computer memory requirements.

## PROGRAM OPERATION

The main program reads in the control cards, and the data, and produces the output. It also sets up and increments the independent variable (usually time) by the amounts to be outputed. For each increment subroutine KUTTA is called which integrates along the independent variable to the new increment point. Subroutine KUTTA in turn calls subroutine EQ1 which evaluates the derivatives for current values of the independent variable by means of matrix multiplication. The coefficients of the differential equations are passed to EQ1 in common, and EQ1 is external in the main program and called by the name EQUA in subroutine KUTTA. In the absence of round-off errors, truncation errors due to a stepwise approximation of continuous integration can become significant. The Runge-Kutta routine will alter the increment size read into the program such that the accuracy which is also input to the program is maintained. Since the Runge-Kutta method employed is of the 4th order, the local truncation errors are of the order of the increment size (within KUTTA) raised to the 4th power. A rough measure of local truncation errors (variable E(I) in KUTTA) is used to adjust if necessary the step size. Also, the starting solution should be computed more accurately than the required solution by at least a factor of ten. Since the program outputs the integrated values of the dependent variables over a range of the independent variable at fixed intervals some care should be taken to insure that the desired information is output but that the interval size is not so small that the program takes an excessively long time. A specified accuracy of more than one part in 10 to the 12th is futile (unless conversion to double precision is made) due to round off errors in the intermediate calculations, and especially in excessively long intervals when error propagation becomes significant.

### Input-Control Card Requirements

Columns	Format	Variable	
<b>I. First Control Card</b>			
1-5	I5	NCOM	No. of equations
6-10	I5	NT	No. of independent variable points.
11-20	F10.3	T1	Initial indirect variable value
21-30	F10.3	TDEL	Indirect variable step value for output
31-40	A4	NSTOP	Flag for halting problem (if "STOP" - no more problems to follow)
<b>II. Second Control Card</b>			
1-10	F10.3	ACC	Desired accuracy of solution
11-20	F10.3	DEL	Estimate of time step required for integration
21-25	I5	ITER	Maximum no. of iterations to be allowed in integration
<b>III. I/O Format Card</b>			
1-80	8A10	FMT	Format statement by which the initial conditions and matrix of coefficient values are read in and outputed.
<b>IV. Data Cards</b>			
--	--	V(I)	Vector of initial conditions (NCOM in number)
--	--	F(I,J)	Matrix of coefficient values (NCOM x NCOM in number)

As many sets of control cards with data may be input to the program in sequence, i.e., I through IV may be repeated as many times as desired as long as a card with the letters STOP in columns 31-34 follows the last set

of data. Since  $V(I)$  and  $F(I,J)$  are read with the same format, allowances must be made such that both variables are read properly.  $V(I)$  and  $F(I,J)$  are read by two different read statements using the same variable format.

```

PROGRAM LINDIFF
*(INPUT,OUTPUT,TAPE5=INPUT,TAPE6=OUTPUT)
C SOLVES A SET OF LINEAR DIFFERENTIAL EQUATIONS
C NCOM NO OF EQUATIONS
C NT NO OF TIME POINTS
C T1 INITIAL TIME VALUE
C TDEL TIME STEP FOR PRINTOUT
C ACC DESIRED ACCURACY IN SOLUTION
C DEL ESTIMATE OF TIME STEP TO BE USED FOR INTEGRATION
C ITER NO OF ITERATIONS, MAXIMUM, TO BE ALLOWED IN INTEGRATION
C FMT FORMAT STATEMENT TO BE USED TO READ INITIAL CONDITIONS
C AND MATRIX OF COEFFICIENT VALUES
C V VECTOR OF INITIAL CONDITION VALUES
C F MATRIX OF COEFFICIENT VALUES
DIMENSION FMT(8),V(20)
COMMON/L1/F(20,20),NCOM
EXTERNAL EQ1
C READ AND PRINT INPUT DATA
1 READ(5,100) NCOM,NT,T1,TDEL,NSTOP,ACC,DEL,ITER
IF(NSTOP.EQ.4)STOP; GO TO 20
WRITE(6,200) T1,TDEL,NT,NCOM,ACC,DEL,ITER
READ(5,300)FMT
READ(5,FMT) (V(I),I=1,NCOM)
READ(5,FMT) ((F(I,J),J=1,NCOM),I=1,NCOM)
WRITE(6,FMT) (V(I),I=1,NCOM)
WRITE(6,400)
WRITE(6,FMT) ((F(I,J),J=1,NCOM),I=1,NCOM)
C SET UP OUTPUT FORMAT
N=NCOM+1
ENCODE(15,400,FMT) N
400 FORMAT(*(F20.4,*I2*F12.4)*)
WRITE(6,500)
C ITERATE THROUGH TIME AND FIND EQUATION SOLUTION
T=T1-TDEL
DO 10 J=1,NT
T=T+TDEL
T2=T+TDEL
WRITE(6,FMT) T,(V(J),J=1,NCOM)
CALL KUTTA(T,T2,V,NCOM,DEL,ACC,ITER,EQ1)
10 CONTINUE
GO TO 1
20 STOP
100 FORMAT(2I5,2F10.3,A4/2F10.3,I5)
200 FORMAT(*1LINEAR DIFFERENTIAL EQUATION SOLUTION// TIME STARTS AT
1#F10.3#, INCREMENTS BY #F10.3#, FOR #I6# ITERATIONS// */
216# CCOMPARTMENT SYSTEM// ACCURACY OF SOLUTION#E15.4// TIME STEP
3SIZE#E15.4// MAXIMUM ITERATIONS/STEP#I6// INITIAL VALUES AND MATR
4IX#/)
300 FORMAT(BALU)
500 FORMAT(*1#/ TIME, COMPARTMENT VALUES, IN ORDER//)
600 FORMAT(//)
END

```

UTINE E41

FORTRAN EXTENDED VERSION 2.0

03/14/70

\*00.41.14.

SUBROUTINE EQ1(X,Z,ZP)

C FINDS DERIVATIVES FOR A SET OF LINEAR DIFF. EQU.

C X -- CURRENT TIME, Z -- CURRENT UEP VAR VALUE, ZP -- CURRENT  
C DERIVATIVE VALUES TO BE FOUND BY MATRIX MULTIPLICATION

COMMON/L1/LAMBDA(20,20),N

REAL LAMBDA

DIMENSION Z(1),ZP()

DO 10 I=1,N

ZP(I)=0.

DO 10 J=1:N

10 ZP(I)=ZP(I)+LAMBDA(I,J)\*Z(J)

RETURN

END

```

SUBROUTINE KUTTA(XL,XU,Y,NE,DEL,ACCURC,IMAX,EQUA)
C PROGRAM AUTHOR F.D.HAMMERLING, CENTRAL DATA PROCESSING, ORGDP.
DIMENSION Y(1),YI(25),YN(25),K1(25),K2(25),K3(25),
1          K4(25),K5(25),F(25),E(25),F1(25)
REAL K1,K2,K3,K4,K5
LOGICAL QUIT
ITTER=0
N=NE
XN=XL
H=DEL
QUIT=.FALSE.
DO 1 I=1,N
1  YN(I)=Y(I)
2 IF(XN+H.LT.XU)GO TO 3
DEL=H
H=XU-XN
QUIT=.TRUE.
3 CALL EQUA(XN,YN,F1)
4 DO 5 I=1,N
   K1(I)=H*F1(I)/3.
5  YI(I)=YN(I)+K1(I)
   CALL EQUA(XN+H/3.,YT,F)
   DO 6 I=1,N
      K2(I)=H*F(I)/3.
6  YT(I)=YN(I)+K1(I)/2.+K2(I)/2.
   CALL EQUA(XN+H/3.,YT,F)
   DO 7 I=1,N
      K3(I)=H*F(I)/3.
7  YT(I)=YN(I)+3.*K1(I)/8.+9.*K3(I)/8.
   CALL EQUA(XN+H/2.,YT,F)
   DO 8 I=1,N
      K4(I)=H*F(I)/3.
8  YT(I)=YN(I)+3.*K1(I)/2.-9.*K3(I)/2.+6.*K4(I)
   CALL EQUA(XN+H,YI,F)
TEST=0.0
DO 9 I=1,N
   K5(I)=H*F(I)/3.
   E(I)=(K1(I)-9.*K3(I)/2.+4.*K4(I)-K5(I)/2.)/5.
TEST=AMAX1(TEST,ABS(E(I)))
9  CONTINUE
IF(TEST.LT.ACCURC)GO TO 10
ITTER=ITTER+1
IF(ITTER.GE.IMAX)GO TO 13
H=H/2.
QUIT=.FALSE.
GO TO 4
10 DO 11 I=1,N
11  YN(I)=YN(I)+(K1(I)+4.*K4(I)+K5(I))/2.
   XN=XN+H
   IF(TEST.LT.ACCURC/32.)H=2.*H
   IF(.NOT.QUIT)GO TO 2
   DO 12 I=1,N
12  YT(I)=YN(I)
   IMAA=0.
   GO TO 14
13  DEL=H $ IMAX=ITTER
14  RETURN
END

```

INPUT DECK FOR SAMPLE RUN OF LINCDIFF

4 201 40. 1  
.00001 .025 50  
(4F10.4)  
7.0568 4.3436 7.6290 80.972  
-.1 .03333333 .03333333 .03333333  
0. -.1 .05 .05  
.05 0. -.1 .05  
0. 0. 0. .  
STOP

LINEAR DIFFERENTIAL EQUATION SOLUTION

TIME STARTS AT 40.000, INCREMENTS BY .100, FOR 201 ITERATIONS

4 COMPARTMENT SYSTEM

ACCURACY OF SOLUTION .1000E-04

TIME STEP SIZE .2500E-01

MAXIMUM ITERATIONS/STEP 50

INITIAL VALUES AND MATRIX

7.0568 4.3436 7.6290 80.9720

-.1000	.0333	.0333	.0333
0.0000	-.1000	.0500	.0500
.0500	0.0000	-.1000	.0500
0.0000	0.0000	0.0000	0.0000

TIME, COMPARTMENT VALUES, IN ORDER

40.0000	.7057E+01	.4344E+01	.7529E+01	.8097E+02
40.1000	.7024E+01	.4324E+01	.7598E+01	.8106E+02
40.2000	.6992E+01	.4304E+01	.7567E+01	.8114E+02
40.3000	.6960E+01	.4284E+01	.7536E+01	.8122E+02
40.4000	.6928E+01	.4265E+01	.7506E+01	.8130E+02
40.5000	.6897E+01	.4245E+01	.7475E+01	.8138E+02
40.6000	.6865E+01	.4226E+01	.7445E+01	.8147E+02
40.7000	.6834E+01	.4206E+01	.7414E+01	.8155E+02
40.8000	.6803E+01	.4187E+01	.7384E+01	.8163E+02
40.9000	.6772E+01	.4168E+01	.7354E+01	.8171E+02
41.0000	.6741E+01	.4149E+01	.7324E+01	.8179E+02
41.1000	.6710E+01	.4130E+01	.7294E+01	.8187E+02
41.2000	.6680E+01	.4111E+01	.7264E+01	.8195E+02
41.3000	.6649E+01	.4092E+01	.7234E+01	.8203E+02
41.4000	.6619E+01	.4074E+01	.7204E+01	.8210E+02
41.5000	.6589E+01	.4055E+01	.7175E+01	.8218E+02
41.6000	.6559E+01	.4036E+01	.7145E+01	.8226E+02
41.7000	.6529E+01	.4018E+01	.7116E+01	.8234E+02
41.8000	.6499E+01	.4000E+01	.7087E+01	.8242E+02
41.9000	.6470E+01	.3981E+01	.7058E+01	.8249E+02
42.0000	.6441E+01	.3963E+01	.7029E+01	.8257E+02
42.1000	.6411E+01	.3945E+01	.7000E+01	.8265E+02
42.2000	.6382E+01	.3927E+01	.6971E+01	.8272E+02
42.3000	.6354E+01	.3909E+01	.6942E+01	.8280E+02
42.4000	.6325E+01	.3891E+01	.6913E+01	.8287E+02
42.5000	.6296E+01	.3873E+01	.6885E+01	.8295E+02
42.6000	.6268E+01	.3856E+01	.6856E+01	.8302E+02
42.7000	.6239E+01	.3838E+01	.6828E+01	.8310E+02
42.8000	.6211E+01	.3820E+01	.6800E+01	.8317E+02
42.9000	.6183E+01	.3803E+01	.6772E+01	.8324E+02
43.0000	.6155E+01	.3786E+01	.6744E+01	.8332E+02
43.1000	.6127E+01	.3768E+01	.6716E+01	.8339E+02
43.2000	.6100E+01	.3751E+01	.6688E+01	.8346E+02
43.3000	.6072E+01	.3734E+01	.6660E+01	.8354E+02
43.4000	.6045E+01	.3717E+01	.6632E+01	.8361E+02
43.5000	.6018E+01	.3700E+01	.6605E+01	.8368E+02
43.6000	.5991E+01	.3683E+01	.6577E+01	.8375E+02
43.7000	.5964E+01	.3666E+01	.6550E+01	.8382E+02
43.8000	.5937E+01	.3649E+01	.6523E+01	.8389E+02
43.9000	.5910E+01	.3633E+01	.6496E+01	.8396E+02
44.0000	.5884E+01	.3616E+01	.6469E+01	.8403E+02
44.1000	.5857E+01	.3600E+01	.6442E+01	.8410E+02
44.2000	.5831E+01	.3583E+01	.6415E+01	.8417E+02
44.3000	.5805E+01	.3567E+01	.6388E+01	.8424E+02
44.4000	.5779E+01	.3551E+01	.6361E+01	.8431E+02
44.5000	.5753E+01	.3534E+01	.6335E+01	.8438E+02
44.6000	.5727E+01	.3518E+01	.6308E+01	.8445E+02
44.7000	.5701E+01	.3502E+01	.6282E+01	.8452E+02
44.8000	.5676E+01	.3485E+01	.6256E+01	.8458E+02
44.9000	.5650E+01	.3470E+01	.6230E+01	.8465E+02
45.0000	.5625E+01	.3454E+01	.6204E+01	.8472E+02
45.1000	.5600E+01	.3439E+01	.6178E+01	.8479E+02
45.2000	.5575E+01	.3423E+01	.6152E+01	.8485E+02
45.3000	.5550E+01	.3407E+01	.6126E+01	.8492E+02
45.4000	.5525E+01	.3392E+01	.6100E+01	.8498E+02
45.5000	.5500E+01	.3376E+01	.6075E+01	.8505E+02
45.6000	.5476E+01	.3361E+01	.6049E+01	.8512E+02
45.7000	.5451E+01	.3346E+01	.6024E+01	.8518E+02
45.8000	.5427E+01	.3330E+01	.5999E+01	.8525E+02
45.9000	.5403E+01	.3315E+01	.5973E+01	.8531E+02

46.0000	.5379E+01	.3300E+01	.5948E+01	.8537E+02
46.1000	.5355E+01	.3285E+01	.5923E+01	.8544E+02
46.2000	.5331E+01	.3270E+01	.5898E+01	.8550E+02
46.3000	.5307E+01	.3255E+01	.5874E+01	.8557E+02
46.4000	.5283E+01	.3240E+01	.5849E+01	.8563E+02
46.5000	.5260E+01	.3226E+01	.5824E+01	.8569E+02
46.6000	.5237E+01	.3211E+01	.5800E+01	.8575E+02
46.7000	.5213E+01	.3196E+01	.5775E+01	.8582E+02
46.8000	.5190E+01	.3182E+01	.5751E+01	.8588E+02
46.9000	.5167E+01	.3167E+01	.5727E+01	.8594E+02
47.0000	.5144E+01	.3153E+01	.5703E+01	.8600E+02
47.1000	.5121E+01	.3139E+01	.5678E+01	.8606E+02
47.2000	.5098E+01	.3124E+01	.5654E+01	.8612E+02
47.3000	.5076E+01	.3110E+01	.5631E+01	.8619E+02
47.4000	.5053E+01	.3096E+01	.5607E+01	.8625E+02
47.5000	.5031E+01	.3082E+01	.5583E+01	.8631E+02
47.6000	.5008E+01	.3068E+01	.5559E+01	.8637E+02
47.7000	.4986E+01	.3054E+01	.5536E+01	.8643E+02
47.8000	.4964E+01	.3040E+01	.5513E+01	.8648E+02
47.9000	.4942E+01	.3026E+01	.5489E+01	.8654E+02
48.0000	.4920E+01	.3012E+01	.5466E+01	.8660E+02
48.1000	.4898E+01	.2999E+01	.5443E+01	.8666E+02
48.2000	.4876E+01	.2985E+01	.5420E+01	.8672E+02
48.3000	.4855E+01	.2972E+01	.5397E+01	.8678E+02
48.4000	.4833E+01	.2958E+01	.5374E+01	.8684E+02
48.5000	.4812E+01	.2945E+01	.5351E+01	.8689E+02
48.6000	.4791E+01	.2931E+01	.5328E+01	.8695E+02
48.7000	.4769E+01	.2918E+01	.5306E+01	.8701E+02
48.8000	.4748E+01	.2905E+01	.5283E+01	.8707E+02
48.9000	.4727E+01	.2891E+01	.5261E+01	.8712E+02
49.0000	.4706E+01	.2878E+01	.5238E+01	.8718E+02
49.1000	.4686E+01	.2865E+01	.5216E+01	.8723E+02
49.2000	.4665E+01	.2852E+01	.5194E+01	.8729E+02
49.3000	.4644E+01	.2839E+01	.5172E+01	.8735E+02
49.4000	.4624E+01	.2826E+01	.5150E+01	.8740E+02
49.5000	.4603E+01	.2814E+01	.5128E+01	.8746E+02
49.6000	.4583E+01	.2801E+01	.5106E+01	.8751E+02
49.7000	.4563E+01	.2788E+01	.5084E+01	.8757E+02
49.8000	.4542E+01	.2776E+01	.5063E+01	.8762E+02
49.9000	.4522E+01	.2763E+01	.5041E+01	.8767E+02
50.0000	.4502E+01	.2750E+01	.5020E+01	.8773E+02
50.1000	.4483E+01	.2738E+01	.4998E+01	.8778E+02
50.2000	.4463E+01	.2726E+01	.4977E+01	.8784E+02
50.3000	.4443E+01	.2713E+01	.4956E+01	.8789E+02
50.4000	.4423E+01	.2701E+01	.4935E+01	.8794E+02
50.5000	.4404E+01	.2689E+01	.4914E+01	.8800E+02
50.6000	.4385E+01	.2676E+01	.4893E+01	.8805E+02
50.7000	.4365E+01	.2664E+01	.4872E+01	.8810E+02
50.8000	.4346E+01	.2652E+01	.4851E+01	.8815E+02
50.9000	.4327E+01	.2640E+01	.4830E+01	.8820E+02
51.0000	.4308E+01	.2628E+01	.4810E+01	.8826E+02
51.1000	.4289E+01	.2616E+01	.4789E+01	.8831E+02
51.2000	.4270E+01	.2605E+01	.4769E+01	.8836E+02
51.3000	.4251E+01	.2593E+01	.4748E+01	.8841E+02
51.4000	.4232E+01	.2581E+01	.4728E+01	.8846E+02
51.5000	.4214E+01	.2569E+01	.4708E+01	.8851E+02
51.6000	.4195E+01	.2558E+01	.4688E+01	.8856E+02
51.7000	.4177E+01	.2546E+01	.4667E+01	.8861E+02
51.8000	.4158E+01	.2535E+01	.4646E+01	.8866E+02
51.9000	.4140E+01	.2523E+01	.4628E+01	.8871E+02
52.0000	.4122E+01	.2512E+01	.4608E+01	.8876E+02
52.1000	.4104E+01	.2500E+01	.4588E+01	.8881E+02
52.2000	.4086E+01	.2489E+01	.4568E+01	.8886E+02
52.3000	.4068E+01	.2478E+01	.4549E+01	.8891E+02
52.4000	.4050E+01	.2467E+01	.4529E+01	.8896E+02
52.5000	.4032E+01	.2456E+01	.4510E+01	.8900E+02

52,500	.4614E+01	.2445E+01	.4491E+01	.8905E+02
52,600	.2956E+01	.2433E+01	.4471E+01	.8910E+02
52,800	.2379E+01	.2422E+01	.4452E+01	.8915E+02
53,000	.3461E+01	.2412E+01	.4433E+01	.8920E+02
53,000	.3444E+01	.2401E+01	.4414E+01	.8924E+02
53,100	.3927E+01	.2390E+01	.4395E+01	.8929E+02
53,200	.3809E+01	.2379E+01	.4376E+01	.8934E+02
53,300	.3842E+01	.2368E+01	.4357E+01	.8938E+02
53,400	.3775E+01	.2358E+01	.4339E+01	.8943E+02
53,500	.3858E+01	.2347E+01	.4320E+01	.8948E+02
53,600	.2847E+01	.2336E+01	.4301E+01	.8952E+02
53,700	.7824E+01	.2326E+01	.4283E+01	.8957E+02
53,P610	.3308E+01	.2315E+01	.4265E+01	.8961E+02
53,800	.7791E+01	.2305E+01	.4246E+01	.8966E+02
54,000	.3774E+01	.2295E+01	.4228E+01	.8970E+02
54,100	.3754E+01	.2284E+01	.4210E+01	.8975E+02
54,200	.3741E+01	.2274E+01	.4192E+01	.8979E+02
54,300	.3725E+01	.2264E+01	.4174E+01	.8984E+02
54,400	.3708E+01	.2253E+01	.4156E+01	.8988E+02
54,500	.3692E+01	.2243E+01	.4138E+01	.8993E+02
54,600	.3676E+01	.2233E+01	.4120E+01	.8997E+02
54,700	.3660E+01	.2223E+01	.4102E+01	.9002E+02
54,800	.3544E+01	.2213E+01	.4084E+01	.9006E+02
54,900	.3628E+01	.2203E+01	.4067E+01	.9010E+02
55,000	.3612E+01	.2193E+01	.4049E+01	.9015E+02
55,100	.1576E+01	.2183E+01	.4032E+01	.9019E+02
55,200	.2580E+01	.2174E+01	.4015E+01	.9023E+02
55,300	.2565E+01	.2164E+01	.3997E+01	.9028E+02
55,400	.2544E+01	.2154E+01	.3980E+01	.9032E+02
55,500	.2533E+01	.2144E+01	.3963E+01	.9036E+02
55,600	.3519E+01	.2135E+01	.3946E+01	.9040E+02
55,700	.3502E+01	.2125E+01	.3929E+01	.9045E+02
55,800	.2587E+01	.2116E+01	.3912E+01	.9049E+02
55,900	.2572E+01	.2106E+01	.3895E+01	.9053E+02
56,000	.3457E+01	.2095E+01	.3878E+01	.9057E+02
56,100	.3441E+01	.2085E+01	.3861E+01	.9061E+02
56,200	.3425E+01	.2078E+01	.3845E+01	.9065E+02
56,300	.3415E+01	.2058E+01	.3828E+01	.9069E+02
56,400	.3346E+01	.2059E+01	.3812E+01	.9073E+02
56,500	.3362E+01	.2050E+01	.3795E+01	.9077E+02
56,600	.3357E+01	.2041E+01	.3779E+01	.9082E+02
56,700	.3352E+01	.2032E+01	.3762E+01	.9086E+02
56,800	.3437E+01	.2023E+01	.3746E+01	.9090E+02
56,900	.3323E+01	.2013E+01	.3730E+01	.9094E+02
57,000	.3308E+01	.2004E+01	.3714E+01	.9098E+02
57,100	.3294E+01	.1945E+01	.3698E+01	.9101E+02
57,200	.3279E+01	.1965E+01	.3682E+01	.9105E+02
57,300	.3265E+01	.1977E+01	.3666E+01	.9109E+02
57,400	.3251E+01	.1969E+01	.3650E+01	.9113E+02
57,500	.3236E+01	.1960E+01	.3634E+01	.9117E+02
57,600	.3222E+01	.1951E+01	.3618E+01	.9121E+02
57,700	.3208E+01	.1942E+01	.3603E+01	.9125E+02
57,800	.3194E+01	.1934E+01	.3587E+01	.9129E+02
57,900	.3180E+01	.1925E+01	.3572E+01	.9132E+02
58,000	.3166E+01	.1916E+01	.3556E+01	.9136E+02
58,100	.3152E+01	.1908E+01	.3541E+01	.9140E+02
58,200	.3139E+01	.1899E+01	.3525E+01	.9144E+02
58,300	.3125E+01	.1891E+01	.3510E+01	.9148E+02
58,400	.3111E+01	.1882E+01	.3495E+01	.9151E+02
58,500	.3094E+01	.1874E+01	.3480E+01	.9155E+02
58,600	.3084E+01	.1865E+01	.3465E+01	.9159E+02
58,700	.3071E+01	.1857E+01	.3450E+01	.9162E+02
58,800	.3057E+01	.1849E+01	.3435E+01	.9166E+02
58,900	.3044E+01	.1840E+01	.3420E+01	.9170E+02
59,000	.3030E+01	.1831E+01	.3405E+01	.9173E+02
59,100	.3017E+01	.1824E+01	.3390E+01	.9177E+02

59.2000	.3004E+01	.1816E+01	.3376E+01	.9181E+02
59.3000	.2991E+01	.1808E+01	.3361E+01	.9184E+02
59.4000	.2978E+01	.1800E+01	.3346E+01	.9188E+02
59.5000	.2965E+01	.1791E+01	.3332E+01	.9191E+02
59.6000	.2952E+01	.1783E+01	.3318E+01	.9195E+02
59.7000	.2939E+01	.1775E+01	.3303E+01	.9198E+02
59.8000	.2926E+01	.1768E+01	.3299E+01	.9202E+02
59.9000	.2913E+01	.1760E+01	.3275E+01	.9205E+02
60.0000	.2901E+01	.1752E+01	.3260E+01	.9209E+02

## Program SNOOP

### INTRODUCTION

Program SNOOP allows examination of interactions by extending two-dimensional (2D) graphing procedures to three-dimensional (3D) plotting. A variable hereafter referred to as a plotting character (PC) denotes the third dimension. The PC can assume values from 0 to 9 and is designated by the content of a selected card column in the observation data. The numeric characters that appear on the completed graph are the actual PC values that appear on the cards (a blank results in a PC value of 0).

For example, if volume, diameter, and height are measured on a group of felled trees, the 2D relationship of volume and diameter can be plotted on the same graph and up to 10 values (or classes) of the plotting character (height) can be distinguished. Examination of the graph may then result in selections of appropriate transformations, interaction terms, and/or weights to be applied in regression analysis. This procedure is not necessary for so simple a problem as postulated here, but extension of the possible uses of 3D plotting should be obvious. However, because of its simplicity, a volume-estimation problem is used as an example later.

Two-dimensional plotting is also available to the user of SNOOP. In this case the numeric characters that appear on the completed graph are frequencies of occurrence. The resulting character at any set of coordinates may then be blank (no occurrence), 1 to 9, or C (10 or more).

If overplots are attempted, messages (containing the coordinates and, in the case of 3D plotting, the PC values) are printed after the appropriate graph. An attempted overplot would occur when 2 or more observations have identical coordinates for 3D plotting, or if 10 or more observations for 2D plotting.

When several dependent (Y) and independent (X) variables are included in one job, a set of fully labeled graphs is made, including each Y-X combination. And, for 3D, a separate set of graphs is made for each PC specified. The program automatically scales the graphs for each variable used. Other flexibility available to the user, barring certain properties given in the section *Program Limitations*, can be summarized as follows:

2D and 3D jobs can be included in the same run in any order.

As many jobs as desired may be included in a single run. Observation values can be negative, zero, and positive. Order of the variables on the observation cards is completely flexible.

PC's can be located anywhere on the observation cards. Multiple cards per observation can be used.

The major use of program SNOOP is in the model-building stage of an estimation problem. A segment of data can be plotted in various ways, and the graphs can be examined for logical trends in dependent-variable values as responses to changes in the values of independent variables. Models can then be formed for regression analyses with the remaining data.

Consequently the value of the program is easily recognized when the researcher is attempting to explain previously unfamiliar functional relationships between many variables. With only a few variables, many observations and expectations that limit the possibilities of functional-relationship alternatives, the researcher can go directly to the use of one of the canned regression routines--for example, Furnival--available at any large computer center.

Program SNOOP was thoroughly tested and is operational on the CDC 6400 computer. The program is written in FORTRAN IV and should run with little or no modification on other computers that accept FORTRAN IV, have a 32K core,

and have three tape drives or equivalent input/output devices. The logical tape assignments are:

<u>Unit</u>	<u>Use</u>
5	Control-deck input
6	Program output
9	Intermediate operations (scratch tape)

A special subroutine was necessary for backspacing logical unit 5 at the computer installation where this program was developed. A simple BACKSPACE 5 command or its equivalent is all that is necessary at other installations. The two places in the program where this must be done are marked with comments.

At CSU, the program has been checked out on the NCAR compiler only.

#### HOW TO USE THE PROGRAM

The program is activated by a control deck supplied by the user. The control deck consists of cards containing the observations and information designating a specific manner in which the observations are to be handled by the program. The following instructions describe the complete control-deck setup (all underlined characters *must* be punched exactly as they appear in the instructions):

Card Group	Number of Cards	Title	Card Columns	Content
1	1	Job description	1- 2	<u>2D</u> --For two-dimensional plotting. <u>3D</u> --For three-dimensional plotting.
			3- 4	Number of Y's (NYS), right adjusted.
			5- 6	Number of X's (NXS), right adjusted (does not include PC variables).

<u>Card Group</u>	<u>Number of Cards</u>	<u>Title</u>	<u>Card Columns</u>	<u>Content</u>
	1 (Continued)			
			7- 8	Number of plotting characters (NPC), right adjusted. Use <u>00</u> (or blanks) for 2D.
			9-11	Number of observations (NOBS), right adjusted.
			12	Number of cards per observation (NCARDS). The use of <u>0</u> (or blank) will be interpreted as <u>1</u> .
			13-72	Alphabetic job title to be printed above each graph.
2	1	Format	1	<u>1</u> --There is no format continuation card. <u>2</u> --The format specification is continued on the format continuation card.
			2	(--Left parenthesis.
			3-72	Up to 70 alphabetic characters, ending with a right parenthesis, and containing a FORTRAN BCD format (F-specifications), which describes the format of the Y's and X's on the observation cards. The right parenthesis is put on the format continuation card if column 1 of the format card = 2.
3	0 or 1	Format continuation	1-72	Continuation of the format specification described for columns 3-72 of the format card.
4	NYS + NXS	Variable labels	1	<u>Y</u> --If the variable is a dependent variable. <u>X</u> --If the variable is an independent variable.

Card Group	Number of Cards	Title	Card Columns	Content
4	(Continued)			
			2	Blank.
			3-52	Alphabetic label (identifying information) associated with the variable. This group of cards must be arranged in the order that the variables appear on the observation cards.
5	0 if 2D, NPC if 3D	3D plotting characters	1-18	<u>PLOTTING CHARACTER</u>
			19	Blank.
			20	Number of the card (of the observation set) on which the PC value is found. The use of <u>0</u> (or blank) will be interpreted as <u>1</u> .
			21-22	Column number (right adjusted) in which the PC value is found.
			23	Blank.
			24-31	Alphabetic label (identifying information) associated with the PC.
6	NOBS xNCARDS	Observations	1-80	One or more cards for each observation as designated by the format cards.
7	1	Job control	1- 8	<u>CONTINUE</u> --If more than one job is included in the run. Card groups 1-7 are repeated after the job control card. <u>DONE</u> (left adjusted)--Designates the end of the last job in the run.

## PROGRAM LIMITATIONS

Job restrictions applying both to 2D and 3D plotting are:

$$NYS + NXS \leq 50$$

$$NYS \geq 1$$

$$NXS \geq 1$$

$$2 \leq NOBS \leq 500$$

$$1 \leq NCARDS \leq 9$$

Job restrictions pertaining to 3D plotting only are:

$$(NYS + NXS + NPC) \times NOBS \leq 10,000$$

$$1 \leq NPC \leq 10$$

A job restriction pertaining to 2D plotting only is:

$$(NYS + NXS) \times NOBS \leq 10,000$$

## SAMPLE RUN OF PROGRAM

For the researcher who is developing a regression model, the graphs produced by the program can be a valuable aid in selecting transformations, interaction terms, and variance-stabilizing weights, and in ordering of variables.

As an example, let us examine the sample control deck and the output which is attached.

The first page of output consists of summary information pertaining to the entire job. Card groups 1 to 5 of the control deck are printed as well as the values of all the variables in the first observation (the Y's precede the X's in the printout). Because the first job in this example specifies 3D plotting, the values of the plotting characters for the first observation are also included in the summary information.

Now, assume for the moment that expectations of functional relationships involving cubic-foot volume, diameter, and height are vague. The trees plotted in this example could be an initial sample of trees to be measured in the construction of a standard volume table; that is, we want to express cubic volume as a function of both diameter and height, if possible. Consequently, the control deck has been set up to plot a 3D graph of cubic-foot volume as a function of diameter, using 10-ft height class as a plotting character.

The resultant graph shows that volume increases with an increase in diameter, and there is an increase in the slope of the relationship as diameter increases.

The second job is simply a demonstration of 2D graphing. The same observations were used as in the first job. Two graphs were specified by designating volume as a dependent variable.

#### ACKNOWLEDGMENTS

A FORTRAN listing of SNOOP is contained in U. S. Forest Service Research Paper NE-91, by Warren E. Frayer. It is available from the Northeast Forest Experiment Station, Upper Darby, Pennsylvania. The present information on this program was liberally extracted from that source with the author's kind permission.

```

PROGRAM SNOOP
1(INPUT,OUTPUT,TAPE5=INPUT,TAPE6=OUTPUT,TAPE1,TAPE2,TAPE3) SNOOP
  DIMENSION FMT(36),LABEL(50,50),ILABEL(50,50),CONLAB(10,2),TITLE(15 SNOOP
  1),IVAR(50),CHECK(5),IPC(10),XMAT(10120),PC(10),V(50),VV(50),KPC(72 SNOOP
  20),R(20),IGRAPH(50,100),XABS(5),IG(12) SNOOP
C SNOOP
C SNOOP
C REAU THE CONTROL DECK AND CHECK FOR ERRORS SNOOP
C SNOOP
C SNOOP
DATA THREEED/2H3D/
DATA TWOUD/2H2D/
DATA YY/1HY/
DATA XX/1HA/
DATA T1,T2,T3,T4,T5/2HPL,4HOTTI,4HNG C,4HHARA,4HCTER/
DATA IG/1H ,1H1,1H2,1H3,1H4,1H5,1H6,1H7,1H8,1H9,1H0,1H,/
DATA EE,CC/4HDONE,4HCUNT/
REWIND 1 SNOOP
REWIND 3 SNOOP
580n READ(5,B9Z)(R(I),I=1,20) SNOOP
  WRITE(1,B9Z)(R(I),I=1,20) SNOOP
  WRITE(3,B9Z)(R(I),I=1,20) SNOOP
  IF(R(1).NE.EE)GO TO 5800 SNOOP
  END FILE 1 SNOOP
  END FILE 3 SNOOP
  REWIND 1 SNOOP
  REWIND 3 SNOOP
C REAU THE JOB DESCRIPTION CARD SNOOP
  IJOB=0 SNOOP
799  IJDB=IJUH+1 SNOOP
  READ(1,700)DEM,NYS,NXS,NPC,NOBS,NCARDS,(TITLE(I),I=1,15) SNOOP
700  FORMAT(A2,3I2,13,I1,15A4) SNOOP
  NC=NCARDS SNOOP
  IF(NCARDS.EQ.0)NC=1 SNOOP
  IF(NCARDS.EQ.0)NCARDS=0 SNOOP
  WRITE(6,7501)IJOB SNOOP
  WRITE(6,7511)(TITLE(J),J=1,15) SNOOP
  WRITE(6,752)DEM SNOOP
  WRITE(6,753)NYS SNOOP
  WRITE(6,754)NXS SNOOP
  WRITE(6,755)NOBS SNOOP
  WRITE(A,10001)NC SNOOP
10001 FORMAT(34H NUMBER OF CARDS PER OBSERVATION =I1) SNOOP
  WRITE(6,756)NPC SNOOP
  WRITE(6,757) SNOOP
7501 FORMAT(11H1JOB NUMAFRI3) SNOOP
7511 FORMAT(12H JOB TITLE =15A4) SNOOP
752  FORMAT(1H A2,9H PLOTTING) SNOOP
753  FORMAT(35HNUMBER OF DEPENDENT(Y) VARIABLES =I2) SNOOP
754  FORMAT(37H NUMBER OF INDEPENDENT(X) VARIABLES =I2) SNOOP
755  FORMAT(25H NUMBER OF OBSERVATIONS =I3) SNOOP
756  FORMAT(32H NUMBER OF PLOTTING CHARACTERS =I2) SNOOP
757  FORMAT(43H THE CONTROL DECK FOR THIS JOB IS.....) SNOOP
  IF(DEM.NE.THREED.AND.DEM.NE.TWOD)GO TO 999 SNOOP
  IF(NYS.LE.0.OR.NYS.GE.50)GO TO 800 SNOOP
  IF(NXS.LE.0.OR.NXS.GE.50)GO TO 801 SNOOP
  IF(NOBS.LT.2.0.RT.1000.GT.500)GO TO 810 SNOOP
  IF(DEM.EQ.THREED GO TO 702 SNOOP
  IF(NPC.NE.0)GO TO R,2 SNOOP
  IF((NYS+NXS)*NOBS)=10000)703,703,860 SNOOP

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702 IF(NPC.LE.0.OR.NPC.GT.10)GO TO 803
    IF(((NYS+NXS+NPC)*NOBS)-10000)703,703,861
703 WRITE(6,704)DEM,NYS,NXS,NPC,NOBS,NCARDS,(TITLE(I),I=1,15)
704 FORMAT(1H0A2,3I2,I3,I1,15A4)
C READ THE FORMAT CARDS
    READ(1,780)IFORM,(FMT(I),I=1,18)
780 FORMAT(1I,17A4,A3)
    READ(3,12321)ISPACE
12321 FORMAT(A1)
    IF(IFORM.LT.1.OR.IFORM.GT.2)GO TO 999
    WRITE(6,781)IFORM,(FMT(I),I=1,18)
781 FORMAT(1H I1,17A4,A3)
    IF(IFORM.EQ.1)GO TO 706
    READ(1,705)(FMT(I),I=19,36)
705 FORMAT(18A4)
    READ(3,12321)ISPACE
    WRITE(6,782)(FMT(I),I=19,36)
782 FORMAT(1H 18A4)
C READ THE VARIABLE LABELS
706 NVAR=NYS+NXS
    IXX=0
    IYY=0
    DO 790 I=1,50
790 IVAR(I)=0
    DO 707 I=1,NVAR
    READ(1,708)VAR,(LABEL(I,K),K=1,50)
708 FORMAT(A1,1X,50A1)
    READ(3,12321)ISPACE
    IF(VAR.NE.YY.AND.VAR.NE.XX)GO TO 999
    IF(VAR.EQ.XX)GO TO 709
    IYY=IYY+1
    IVAR(I)=IYY
    GO TO 710
709 IXX=IXX+1
    IVAR(I)=IXX+NYS
710 WRITE(6,791)VAR,(LABEL(I,K),K=1,50)
C ORDER THE VARIABLE LABELS
    KKK=IVAR(I)
    DO 711 K=1,50
711 ILABEL(KKK,K)=LABEL(I,K)
707 CONTINUE
C READ THE PLOTTING CHARACTERS LABELS
    IF(UEM.EQ.TWOD)GO TO 751
    DO 750 I=1,NPC
    READ(1,712)(CHECK(IJ),IJ=1,5),ICARD,IPC(I),(CONLAB(I,K),K=1,2)
712 FORMAT(A2,4A4,1X,I1,I2,1X,2A4)
    READ(3,12321)ISPACE
    IF(CHECK(1).EQ.YY.OR.CHECK(1).EQ.XX)GO TO 830
    IF(CHECK(1).NE.T1.OR.CHECK(2).NE.T2.OR.CHECK(3).NE.T3.OR.CHECK(4).NE.T4.OR.CHECK(5).NE.T5)GO TO 999
    IF(IPC(I).LE.0.OR IPC(I).GT.80)GO TO 999
    WRITE(6,742)(CHECK(IJ),IJ=1,5),ICARD,IPC(I),(CONLAB(I,K),K=1,2)
792 FORMAT(1H A2,4A4,2I2,1X,2A4)
    IC=ICARD
    IF(IC.EQ.0)IC=1
    IPC(I)=((IC-1)*80)+IPC(I)
750 CONTINUE
751 CONTINUE
    READ(3,12321)ISPACE
C

```

```

C
C THE OBSERVATIONS ARE NOW PLACED IN A VECTOR CALLED XMAT
C
C
  WRITE(6,797)
797  FORMAT(45H0....OBSERVATION CARDS ARE LOCATED HERE... )
    DO 100 K=1,50
      V(K)=0.0
100   VV(K)=0.0
      DO 110 K=1,10120
110   XMAT(K)=0.0
      ICOUNT=0
C READ THE VARIABLES
103  READ(1,FMT)(V(K),K=1,NVAR)
      ICOUNT=ICOUNT+1
C READ THE PLOTTING CHARACTERS
      KSTART=1
      KEND=80
      DO 9692 IJKL=1,NC
        READ(3,112)(KPC(K),K=KSTART,KEND)
        KSTART=KSTART+80
9692  KEND=KEND+80
      IF(DEM.NE.THREED)GO TO 13
112  FORMAT(8U1)
      DO 113 I=1,NPC
        KRPC=IPC(I)
        IRKPC=KPC(KRPC)
        DO 960 LL=1,11
          IF(IRKPC.NE.IG(LL))GO TO 960
          PC(1)=LL-1
          IF(LL.EQ.1)PC(1)=0.
          GO TO 113
960   CONTINUE
          GO TO 835
113   CONTINUE
          GO TO 13
10013 WRITE(6,970)
970  FORMAT(54H0THE PLOTTING CHARACTERS FOR THIS OBSERVATION ARE... )
    DO 972 I=1,NPC
      L=PC(1)
972  WRITE(6,971)I,L
971  FORMAT(4H PC(I2,2H)=I1)
    GO TO 795
C ORDER THE VARIABLES
13   DO 200 ISKIP=1,NVAR
      IP=IVAR(ISKIP)
200   VV(IP)=V(ISKIP)
      IF(ICOUNT.NE.1)GO TO 795
      WRITE(6,7999)
7999 FORMAT(48H0THE VARTABLES IN THE FIRST OBSERVATION ARE... )
    DO 650 I=1,NYS
650   WRITE(6,651)I,VV(I)
651   FORMAT(3H Y(I2,2H)=,E14.8)
    DO 652 I=1,NXS
      IXS=I+NYS
652   WRITE(6,653)I,VV(IXS)
653   FORMAT(3H X(I2,2H)=,E14.8)
      IF(DEM.EQ.THREED)GO TO 10013
C STORE THE VARIABLES
795   KK=0

```

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## SNOOP FORTRAN EXTENDED VERSION 2.0

03/14/70

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DO 410 K=1,NVAR
KSUB=((K-1)*NOBS)+KK+1COUNT
KMIN=KSUB+NOBS-1COUNT+1
KMAX=KMIN+1
XMAT(KSUB)=VV(K)
KK=KK+2
C STORE THE MAXIMUM AND MINIMUM VALUES
IF(ICOUNT.EQ.1)GO TO 107
AMAX=XMAT(KMAX)
AMIN=XMAT(KMIN)
120 IF((AMAX-VV(K))*(VV(K)-AMIN))106,106,410
106 IF(VV(K)-AMAX)108,107,107
107 AMAX=VV(K)
XMAT(KMAX)=AMAX
IF(ICOUNT.NE.1)GO TO 410
108 AMIN=VV(K)
XMAT(KMIN)=AMIN
410 CONTINUE
C STORE THE PLOTTING CHARACTERS
IF(DEM.NE.THREED)GO TO 500
DO 401 L=1,NPC
KSLOT=(NOBS+2)*(NVAR+L-1)+1COUNT
401 XMAT(KSLOT)=PC(L)
500 IF(ICOUNT.NE.NOBS)GO TO 103
C
C THE VALUES IN XMAT ARE CHANGED TO ROW AND COLUMN NUMBERS FOR THE
C OUTPUT MATRIX(TGRAPH)
C
KA=1
DO 1050 K=1,NVAR
NL=(K-1)*NOBS+KK
ML=(NOBS*K)+KK-1
KK=KK+2
DO 1050 LK=NL,ML
IF(K.GT.NYS)GO TO 1010
DIV=50.
GO TO 1011
1010 DIV=100.
1011 XINC=(XMAT(ML+2)-XMAT(ML+1))/DIV
IF(XINC.EQ.0.)XINC=1.0
A=XMAT(ML+1)
XMAT=0.
1007 IF(A.GT.XMAT(LK))GO TO 1006
A=A+XE(C
RXMAT=RXMAT+1.
GO TO 1007
1006 XMAT(LK)=RXMAT
IF(K.GT.NYS)GO TO 1020
IF(XMAT(LK).LE.50.)GO TO 1050
XMAT(LK)=50.
GO TO 1050
1020 IF(XMAT(LK).LE.100.)GO TO 1050
XMAT(LK)=100.
1050 CONTINUE
GO TO 3145
800 WRITE(6,990)NYS
GO TO 1000
801 WRITE(6,991)NXS

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AM SNOOP FORTRAN EXTENDED VERSION 2.0

03/14/70

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GO TO 1000
402 WRITE(6,942)NPC
GO TO 1000
803 WRITE(6,943)NPC
GO TO 1000
A10 WRITE(6,944)NORS
GO TO 1000
H30 WRITE(6,995)
GO TO 1000
A35 WRITE(6,996)ICOUNT,T
GO TO 12322
A60 NOVER=((NYS+NXS)*NORS)
WRITE(6,997)NOVER
GO TO 1000
861 NOVER=((NYS+NXS+NPC)*NOBS)
WRITE(6,998)NOVER
GO TO 1000
990 READ(3,892)(R(I),I=1,20)
WRITE(6,891)
WRITE(6,893)(R(I),I=1,20)
GO TO 12322
990 FORMAT(5H0NYS=I2,/44H NYS MUST BE GREATER THAN 0 AND LESS THAN 50) SNOOP
991 FORMAT(5H0NXS=I2,/44H NXS MUST BE GREATER THAN 0 AND LESS THAN 50) SNOOP
992 FORMAT(5H0NPC=I2,/44H NPC MUST BE BLANK OR 0 ) SNOOP
993 FORMAT(5H0NPC=I2,/44H NPC MUST BE GREATER THAN 0 AND LESS THAN 11) SNOOP
994 FORMAT(6H0NOBS=I3,/46H NOBS MUST BE GREATER THAN 1 AND LESS THAN 5 SNOOP
101)
995 FORMAT(63M0THERE IS A VARIABLE LABEL WITH THE 3D PLOTTING CHARACTE SNOOP
1R GMDUH)
996 FORMAT(49M0THERE IS A NON-NUMERIC CHARACTER IN OBSERVATION I3,24H SNOOP
1FOR PLOTTING CHARACTER I2)
997 FORMAT(18H0(NYS+NXS) X NOBS=I6,/42H THIS MUST BE EQUAL TO OR LESS SNOOP
1THAN 10,000) SNOOP
998 FORMAT(22H0(NYS+NXS+NPC) X NOBS=I6,/42H THIS MUST BE EQUAL TO OR L SNOOP
1ESS THAN 10,000) SNOOP
891 FORMAT(60M0THE FOLLOWING CONTROL CARD IS MISPUNCHED OR OUT OF ORDER SNOOP
1R...)
492 FORMAT(20A4)
893 FORMAT(1H 20A4)
1000 READ(3,12321)ISPACE
12322 WRITE(6,1001)
1001 FORMAT(27H0UNABLE TO PROCESS THIS JOB/55H THE PROGRAM IS NOW SEARC SNOOP
1HING FOR THE NEXT JOB(IF ANY) )
1002 READ(1,1003)TAL
READ(3,12321)ISPACE
1003 FORMAT(A4)
IF(TAL.EQ.FE)GO TO 2000
IF(TAL.EQ.CC)GO TO 799
GO TO 1002

C
C
C CONSTRUCT THE GRAPHS (IGRAPH)
C
C
3145 IF(DEN.EQ.1)NPC=1
DO 2010 J=1,NPC
DO 2010 K=1,NYS
NX=(2*(K-1))+1
KY=(2*(JYS)+1
LNYS=NY*S+1

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AM SNOOP FORTRAN EXTENDED VERSION 2.0 03/14/70 #00.55.10

```

DO 2010 L=LNYS,NVAR
REWIND 2
DO 2030 I=1,50
DO 2030 M=1,100
2030 IGRAPH(I,M)=100
MT=(K-1)*NORS+KX
NK=(L-1)*NORS+KY
MK=NK+NORS-1
KY=KY+2
ICNT=0
ID=0
DO 2011 LK=NK,MK
IY=XMAT(MT)+.001
IX=XMAT(LK)+.001
IF (DEM.EQ.THREED) GO TO 2015
IF (IGRAPH(IY,IX).EQ.110) GO TO 3000
IGRAPH(IY,IX)=IGRAPH(IY,IX)+1
GO TO 2011
3000 WRITE(2,3002) IY,IX
791 FORMAT(1H A1+1X,50A1)
3002 FORMAT(2I3)
ID=ID+1
GO TO 2011
2015 ICNT=ICNT+1
KSLUT=(NORS+2)*(NVAR+J-1)+ICNT
KPLUT=XMAT(KSLUT)+.001
IF (IGRAPH(IY,IX).NE.100) GO TO 3001
IGRAPH(IY,IX)=KPLUT
GO TO 2011
3001 WRITE(2,3003) IY,IX,KPLOT
3003 FORMAT(3I3)
ID=ID+1
2011 MT=MT+1
END FILE 2
REWIND 2
C PRINT A GRAPH
WRITE(6,3041) IJOB
3041 FORMAT(1H115X,11HJOR NUMBER 13)
WRITE(6,3040)(TITLE(I),I=1,15)
3040 FORMAT(1H 15X,15A4)
IF (DEM.EQ.THREED) GO TO 3042
WRITE(6,3043)
3043 FORMAT(1H 15X,23HTwo-DIMENSIONAL GRAPH )
GO TO 3044
3042 WRITE(6,3045) J,(CONLAB(J,JC),JC=1,2)
3045 FORMAT(1H 15X,27HTHREE-DIMENSIONAL GRAPH,PC(I2,16M) IS DEFINED AS
12A4)
3044 CONTINUE
DO 3050 IY=1,50
DO 3050 IX=1,100
IF (IGRAPH(IY,IX).NE.100) GO TO 3051
IGRAPH(IY,IX)=IG(1)
GO TO 3050
3051 IF (IGRAPH(IY,IX).GT.100) IGRAPH(IY,IX)=IGRAPH(IY,IX)-100
DO 3053 I=1,10
IF (IGRAPH(IY,IX).NE.I) GO TO 3053
IGRAPH(IY,IX)=IG(I+1)
GO TO 3050
3053 CONTINUE
IGRAPH(IY,IX)=IG(1)

```

4M SNOOP FORTRAN EXTENDED VERSION 2.0

03/14/70

\*00.55.10.

```

3050 CONTINUE
    YINC=AMAT(MT+1)-XMAT(MT)
    YINC=YINC/50.
    BEGIN=XMAT(MT+1)-(5*YINC)
    DO 3055 IJK=1,50
        I=50-IJK+1
        IF(I.EQ.50,OR,I.EQ.40,OR,I.EQ.30,OR,I.EQ.20,OR,I.EQ.10)GO TO 3060
        WRITE(6,3061)ILABEL(K,IJK),(IGRAPH(I,II),II=1,100)
3061 FORMAT(1H A1,14X,1H,100A1)
        GO TO 3055
3060 WRITE(6,3063)ILABEL(K,IJK),BEGIN,(IGRAPH(I,II),II=1,100)
3063 FORMAT(1H A1,2X,E11.5,2H..100A1)
3055 BEGIN=BEGIN-YINC
3071 WRITE(6,3070)BEGIN
3070 FORMAT(*H E11.5,102H.....)
        I.....)
        WRITE(6,3060)
3080 FORMAT(1H 15X,1H.19X,1H.19X,1H.19X,1H.19X,1H.19X,1H.)
        XINC=(XMAT(MK+2)-XMAT(MK+1))/100.
        XBEGIN=XMAT(MK+1)-(5*XINC)
        DO 6070 IIJK=20,100,20
            IIIJK=IIJK/20
            XIK=IIJK
            XABS(IIIJK)=XBEGIN+(XIK*XINC)
            WRITE(6,6071)XBEGIN,(XABS(I),I=1,5)
6071 FORMAT(1H 10X,E11.5,5(9X,E11.5))
            WRITE(6,3081)(ILABFL(L,II),II=1,50)
3081 FORMAT(1H015X,50A1)
            WRITE(6,3082)ID
3082 FORMAT(31H NUMBER OF ATTEMPTED OVERPLOTS=I3)
            IF(ID.EQ.0)GO TO 2010
            WRITE(6,3083)
3083 FORMAT(37H COORDINATES OF ATTEMPTED OVERPLOTS      )
C PRINT THE OVERPLOTS
        DO 3085 I=1,10
            IF(I.EQ.1,THREE)GO TO 3090
            READ(2,4040)IY,IX
4040 FORMAT(2I3)
            YI=IY
            YI=(BEGIN+(YI*YINC))
            XI=IX
            XI=(XBEGIN+(XI*XINC))
            WRITE(6,3091)YI,XI
3091 FORMAT(3H Y=E11.5,3X,2HX=E11.5)
            GO TO 3085
3090 READ(2,4041)IY,IX,KPLOT
4041 FORMAT(3I3)
            YI=IY
            YI=(BEGIN+(YI*YINC))
            XI=IX
            XI=(XBEGIN+(XI*XINC))
            WRITE(6,3092)YI,XI,KPLOT
3092 FORMAT(3H Y=E11.5,3X,2HX=E11.5,3X,3HPC=I2)
3085 CONTINUE
2010 CONTINUE
            READ(1,3020)TAIL,TAIM
            IF(TAIL.NE.EE,AND.TAIL.NE.CC)GO TO 999
            READ(3,12321)ISPACF
3020 FORMAT(2A4)
            WRITE(6,3021)TAIL,TAIM

```

SNOOP FORTRAN EXTENDED VERSION 2.0

03/14/70

\*00.55.10

3021 FORMAT(1H12A4)  
IF(TAIL,EW,CC)GO TO 799  
2000 CONTINUE  
STOP  
END

SNOOP  
SNOOP  
SNOOP  
SNOOP  
SNOOP

INPUT DECK FOR SAMPLE RUN OF SNOOP

3D0101010951RED PINE VOLUME TABLE CONSTRUCTION (PRELIMINARY PLOTTING)

1(5X,F3.1,5X,F4.1)

X            DIAMETER AT BREAST HEIGHT

Y            CUBIC-FOOT VOLUME

PLOTTING CHARACTER 111 HT CLASS

143	62	432
145	72	513
148	80	597
150	46	351
152	45	356
153	40	317
154	52	418
156	68	561
157	56	470
159	75	640
160	60	521
163	73	657
165	85	780
168	80	770
170	50	480
173	60	609
175	56	570
177	58	617
178	64	694
179	72	790
180	58	630
181	69	766
183	62	704
184	74	840
186	76	900
188	64	788
131	44	250
132	56	335
134	48	292
136	47	290
137	53	338
139	56	369
140	59	390
50	20	17
51	22	19
52	26	25
54	28	23
56	24	26
59	36	42
60	30	36
62	33	43
63	24	33
65	26	38
65	36	52
70	40	66
72	39	69
74	42	79
77	42	82
79	45	94
80	46	100
83	45	102

INPUT DECK FOR SAMPLE RUN OF SNOOP

86	50	123
90	30	84
92	35	101
94	36	111
97	44	140
111	58	242
100	51	175
101	40	138
103	52	187
104	48	174
106	55	209
189	84	1030
193	70	880
198	90	1222
109	58	234
110	39	160
199	86	1141
200	60	801
99	38	123
119	45	216
219	82	1330
220	95	1502
221	98	1634
223	74	1263
225	86	1530
119	65	315
120	54	260
126	70	377
230	60	1036
233	95	1750
130	40	235
130	42	241
240	97	1894
261	60	1360
263	100	2371
266	87	2104
268	101	2453
280	102	2763
113	40	170
155	64	283
202	72	1002
210	74	983
218	75	1223
116	43	199

CONTINUE

2D0102000951RED PINE DATA - EXAMPLES OF TWO-DIMENSIONAL PLOTTING)  
1(5X,F3.1,1X,F3.0,1X,F4.1)

X           DIAMETER AT BREAST HEIGHT

X           TOTAL HEIGHT

Y           CUBIC-FOOT VOLUME

143	62	432
145	72	513
148	80	597
150	46	351
152	45	356
153	40	317

INPUT DECK FOR SAMPLE RUN OF SNOOP

154	52	418
156	68	561
157	56	470
159	75	640
160	60	521
163	73	657
165	85	780
168	80	770
170	50	480
173	60	609
175	56	570
177	58	617
178	64	694
179	72	790
180	58	630
181	69	766
183	62	704
184	74	840
186	76	900
188	64	788
131	44	250
132	56	335
134	48	292
136	47	290
137	53	338
139	56	369
140	59	390
50	20	17
51	22	19
52	26	25
54	28	23
56	24	26
59	36	42
60	30	36
62	33	43
63	24	33
65	26	38
65	36	52
70	40	66
72	39	69
74	42	79
77	42	82
79	45	94
80	46	100
83	45	102
86	50	123
90	30	84
92	35	101
94	36	111
97	44	140
111	58	242
100	51	175
101	40	138
103	52	187
104	48	174
106	55	209

INPUT DECK FOR SAMPLE RUN OF SNOOP

189	84	1030
193	70	880
198	90	1222
109	58	234
110	39	160
199	86	1141
200	60	801
99	38	123
119	45	216
219	82	1330
220	95	1502
221	98	1634
223	74	1263
225	86	1530
119	65	315
120	54	260
126	70	377
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233	95	1750
130	40	235
130	42	241
240	97	1894
261	60	1360
263	100	2371
266	87	2104
268	101	2453
280	102	2763
113	40	170
155	64	283
202	72	1002
210	74	983
218	75	1223
116	43	199

DONE

JOB NUMBER 1  
JOB TITLE = RED PINE VOLUME TABLE CONSTRUCTION (PRELIMINARY PLOTTING)  
3D PLOTTING

NUMBER OF DEPENDENT(Y) VARIABLES = 1  
NUMBER OF INDEPENDENT(X) VARIABLES = 1  
NUMBER OF OBSERVATIONS = 95  
NUMBER OF CARDS PER OBSERVATION = 1  
NUMBER OF PLOTTING CHARACTERS = 1

THE CONTROL DECK FOR THIS JOB IS.....

3D 1 1 1 951RED PINE VOLUME TABLE CONSTRUCTION (PRELIMINARY PLOTTING)  
1(5X,F3.1,5X,F4.1)

X DIAMETER AT BREAST HEIGHT

Y CUBIC-FOOT VOLUME

PLOTTING CHARACTER 111 HT CLASS

....OBSERVATION CARDS ARE LOCATED HERE....

THE VARIABLES IN THE FIRST OBSERVATION ARE...

Y( 1)= .43200000E+02

X( 1)= .14300000E+02

THE PLOTTING CHARACTERS FOR THIS OBSERVATION ARE....

PC( 1)=6

COORDINATES OF ATTEMPTED OVERPLOTS

Y= .44460E+01 X= .51140E+01 PC= 2

Y= .44460E+01 X= .51150E+01 PC= 2

Y= .44460E+01 X= .626E+01 PC= 2

Y= .44460E+01 X= .64950E+01 PC= 3



JOB NUMBER 2

JOB TITLE \*RED PINE DATA - EXAMPLES OF TWO-DIMENSIONAL PLOTTING)  
2D PLOTTING

NUMBER OF DEPENDENT (Y) VARIABLES = 1

NUMBER OF INDEPENDENT (X) VARIABLES = 2

NUMBER OF OBSERVATIONS = 95

NUMBER OF CARDS PER OBSERVATION = 1

NUMBER OF PLOTTING CHARACTERS = 4

THE CONTROL DECK FOR THIS JOB IS.....

2D 1 2 0 951RED PINE DATA - EXAMPLES OF TWO-DIMENSIONAL PLOTTING)

1(Sx,F3.1,1x,F3.0,1x,F4.1)

X DIAMETER AT BREAST HEIGHT

X TOTAL HEIGHT

Y CUBIC-FOOT VOLUME

....OBSERVATION CARDS ARE LOCATED HERE....

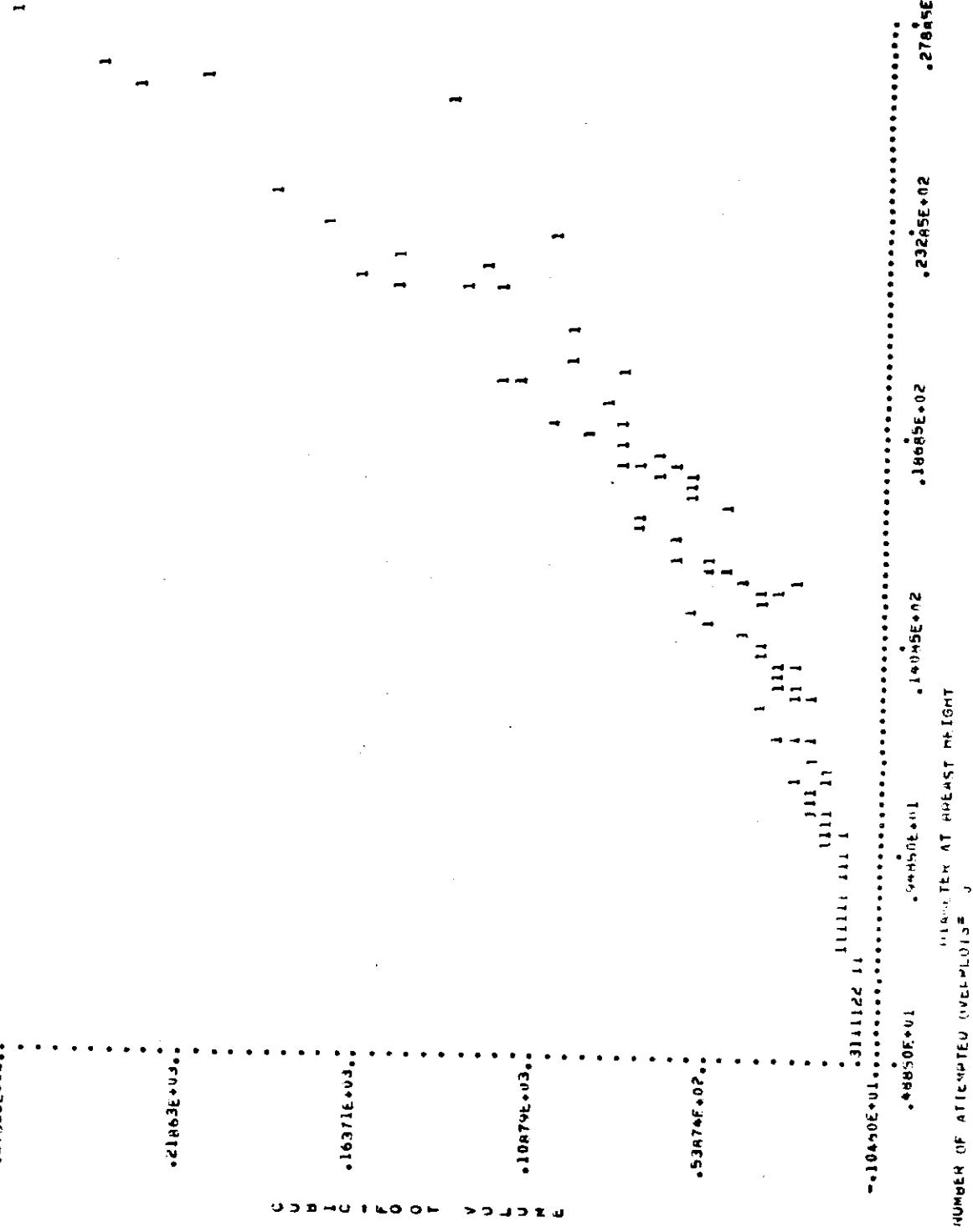
THE VARIABLES IN THE FIRST OBSERVATION ARE...

Y( 1)= .43200000E+02

X( 1)= .14300000E+02

X( 2)= .62000000E+02

(E) PLOT OF NUMBER OF ATTACHMENT POINTS VS. TIME (INTERSTICIAL PLUTTING)  
•27355E+02



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יְהוָה יְהוָה יְהוָה

ՀԱՅԱՍՏԱՆԻ ՀԱՆՐԱՊԵՏՈՒԹՅԱՆ ԿԱռավարության կողմէ

## LINPROG

### INTRODUCTION

LINPROG is a linear programming program originally written by R. J. Classen and converted for use on the FORTRAN Extended compiler of the CDC 6400 SCOPE system.

Linear programming deals with the problem of allocating limited resources among competing activities in an optimal manner. This problem of allocation can arise whenever one must select the level of certain activities which must compete for certain scarce resources necessary to perform those activities. The applications of linear programming extend to a wide variety of situations. For the ecologist the applications extend from the determination of the maximum profit in resource management to the achievement of the greatest cost-effectiveness of one's research procedures. For the systems ecologist, the application of optimization techniques such as linear programming reduces the likelihood of suboptimization. Suboptimization can result from too much concentration on one of the subsystems at the expense of a more important subsystem. Whatever the application, all linear programming problems involve the planning of activities in order to obtain the result, among all the feasible alternatives, which reaches the specified goal best.

### PROGRAM OPERATION

The mathematical statement of a general form of the linear programming problem is the following. Find  $z_1, z_2, \dots, z_n$  which maximizes the linear objective function,

$$X = \sum_{j=1}^n c_j z_j$$

subject to the r constraints

$$\sum_{j=1}^n A_{ij} z_j = B_i \text{ for } i = 1, 2, \dots, r$$

and  $z_j \geq 0$  for all  $j$ .

Where the  $A_{ij}$ ,  $B_i$ , and  $C_j$  are given constants and the  $z_j$  are the unknown decision variables.

The method used by the program is a variation of the explicit inverse form of the simplex method. All computations are in single precision arithmetic. The limitations of the program allow up to 100 decision variables and as many as 82 constraints. The simplex algorithm used by the program is a subroutine written by R. J. Classen in September, 1961. The subroutine is very versatile and complex and allows for the solution of many different types of linear programming problems. LINPROG was written to make this subroutine easy to use for the basic type of problem. It can easily be altered if a special case is to be solved.

#### INPUT REQUIREMENTS

Input to the problem is as follows:

Card 1 (Problem identification)

Col. 1-78 XID--alphanumeric title for problem

79-80 NTYPE--< zero to stop program

= zero to read in a new problem

> zero to read in a new resource constraint

for the right hand side and rework the last  
problem.

Card 2 (if NTYPE > 0)

Col. 1-5 row number of the new constraint

6-15 value of the new constraint

(this is the only card required if NTYPE > 0)

**Card 2 (if NTYPE = 0)**

Col. 1-5      NR--number of constraint equations  
6-10      NC--number of variables including artificial  
                and slack variables  
11-15      INVOFF ≠ 0 to print inverse matrix  
                = 0 to skip printing

**Card 3 (variable format card of the type "FORMAT I NN(...)"")**

Col. 1-6      "FORMAT"  
8-10      I--"ROW" if the A matrix is to be read in by rows  
                "COL" if it is to be read by columns  
12-13      NN--number of coefficients per card  
15-80      (...)--format specification, this specification  
                must allow for two leading index numbers on each  
                card which indicate the matrix position of the  
                first coefficient on the card

**Card 4 - number required (constraint matrix)**

The "A" matrix is input as specified by variable format card  
or card 3 and is followed by a blank card.

**"B" card - (right hand sides of constraint equations)**

the  $B_j$  are input in an 8E10.0 format

ID card to start a new problem or else stop the program as explained above.

To allow for inequalities and free variables the "A" matrix should be  
set up as follows:

1. Inequalities - to change equation  $l1$  from an equality to  
 $\leq$ , add a column,  $J1$ , in which all entries are zero except that

$A(11, J1) = 1$ . Variable  $J1$  is then a positive slack variable. To change the equation to a  $\geq$ , do the same as above except  $A(11, J1) = -1$ .

2. free variables - to remove the restriction on variable  $J1$ , that  $B(J1) \geq 0$  add a column  $J2$  in which all entries  $A(I, J2) = -A(I, J1)$ .

#### LISTING AND SAMPLE OUTPUT

The output shown is the solution of the following problem:

$$\text{Minimize } 4z_1 + 7z_2 + 8z_3 + 6z_4$$

while satisfying

$$150z_1 + 140z_2 + 170z_3 + 160z_4 = 150$$

$$0.1z_1 + 0.1z_2 + 0.3z_3 + 0.3z_4 \leq 0.2$$

$$2z_1 + 4z_2 + 5z_3 + 3z_4 \geq 3$$

$$\text{and } z_1 \geq 0, z_2 \geq 0, z_3 \geq 0, z_4 \geq 0$$

The first output grouping shows the initial tableau or the "A" matrix as it was read in. Row 1 shows the  $C_j$  coefficients of the objective function and the remaining rows are the  $a_{ij}$  coefficients of the constraint equations. This page also shows the value of the objective function at each iteration.

The second output grouping shows the characteristics of the problem. The seven output constants are:

KOUT (1) = K, output condition:

3 - feasible and optimal

4 - no feasible solution

5 - no pivot, infinite solution

6 - iteration limit exceeded

7 - illegal input quantity

KOUT(2) = ITER, number of iterations taken.

KOUT(3) = INVC, number of iterations since last inversion (ignoring final inversions, if done).

KOUT(4) = NUMVR, number of inversions done (including final and initial inversions).

KOUT(5) = NUMPV, number of pivots done

KOUT(6) = INF5, infeasibility flag, 1 = infeasible, 0 = feasible

KOUT(7) = JT, final pivot column selected. (Conditions 5 and 6 only.)

The eight quantities in ERROR are:

ERR(1) Sum of the feasibility errors (AZ-B).

ERR(2) Maximum feasibility error.

ERR(3) Sum of the reduced costs in basis.

ERR(4) Maximum reduced cost (in absolute value) in basis.

In a final inversion is performed, the above errors will be the errors before inversion and ERR (5, 6, 7,8) will be the corresponding errors after inversion.

The eight quantities in INFIX are as follows:

INFIX (1) = INFLAG, the input condition, usually "4"; other values are explained below.

INFIX (2) = N, the number of columns in "A" matrix.

INFIX (3) = ME, the length of one column in "A" matrix, i.e., the first dimension of "A" matrix.

INFIX (4) = M, the row number of the final constraint in the "A" matrix; MF < ME.

INFIX (5) = MF, the row number of the first constraint in the "A" matrix; MF < M.

INFIX (6) = MC, the row number of the objective form (costs) in the "A" matrix; MF < MC < 0.

INFIX (7) = NCUT, the maximum number of iterations that will be allowed to solve the problem.

INFIX (8) = NVER, the reinversion frequency; NVER = 0 means don't reinvert.

The four tolerances are:

TOL (1) = TPIV, pivot tolerance

TOL (2) = TZERO, tolerance for setting "X" to zero.

TOL (3) = TCOST  $\leq$  0, reduced cost is considered to be negative only if it is below this quantity.

TOL (4) = TECOL, quantities in the pivot row of the inverse are assumed zero if magnitude below this quantity (used only in inversion 2 of the subroutine).

The third output grouping shows the solution of the problem. The column JJH shows the decision variables which are in the solution at the point of optimality. z(0) is the objective function. BBAR shows the final value of the objective function for z(0) and the final values for the other z variables in solution. PI shows the negatives of the solution of the dual problem. YTEMP(1) shows the negative value of the objective function and the remaining values show the truncation error when the z values are substituted into the constraint equations.

The fourth output grouping shows the inverse matrix if it is requested.

The fifth grouping shows, for each  $z_j$ , the amount that the cost  $c_j$  would have to be reduced in order to include that variable in the solution. This amount is zero for the variables that are already in the optimal solution.

## LINEAR PROGRAMMING PROGRAM

PAGE 1

PROGRAM LINPROG

```

C----- A
C-----***** A
C----- A
C-----LINEAR PROGRAMMING SETUP ROUTINE A
C-----CARD 1 A
C----- COL. 1-78 ALPHANUMERIC PROBLEM IDENTIFICATION A
C----- COL. 79-80 LESS THAN ZERO TO STOP PROGRAM A
C----- EQUAL TO ZERO TO READ IN A NEW PROBLEM A
C----- GREATER THAN ZERO TO READ IN A NEW RESOURCE A
C----- CONSTRAINT FOR THE RIGHT HAND SIDE AND REWORK A
C----- THE LAST PROBLEM. A
C-----CARD 2 A
C----- COL 1- 5 NUMBER OF CONSTRAINT EQUATIONS A
C----- 6-10 NUMBER OF VARIABLES INCLUDING ARTIFICIAL AND A
C----- SLACK VARIABLES A
C----- 11-15 NOT EQUAL TO ZERO TO PRINT INVERSE MATRIX. A
C-----CARD 3 A
C----- COL 1- 6 FORMAT A
C----- 8-10 ROW IF CONSTRAINT MATRIX IS TO BE INPUT BY ROWS A
C----- COL IF IT IS INPUT BY COLUMNS. A
C----- 12-13 NUMBER OF COEFFICIENTS PER CARD. A
C----- 15-80 VARIABLE FORMAT TO READ IN TWO INDEX NUMBERS, A
C----- INDICATING THE MATRIX POSITION OF THE FIRST COEF- A
C----- FICIENT ON THAT CARD, AND THE NUMBER OF COEFFICIENT A
C----- SPECIFIED IN COLUMNS 12 AND 13 A
C-----CARDS 4 THROUGH N A
C----- THE CONSTRAINT MATRIX IS INPUT AS SPECIFIED BY THE A
C----- VARIABLE FORMAT IN CARD 3 A
C-----CARD N+1 A
C----- THE RIGHT HAND SIDE OF THE TABLEAU IS INPUT IN AN BF10.0 FORMAT A
C-----CARD N+2 A
C----- THE SAME AS CARD 1 A
C----- A
C-----***** A
C----- DIMENSION TAB(82,100), E(82,82), RHS(82), JJH(82), BBAR(82), PI(82) A
1, YTEMP(82), KB(100), RC(100), KOUT(8), ERR(8), INFIX(8), TOL(8), A
2 XID(14) A
NRT=82 A
REWIND 6 A
1 READ (5,9) (XID(I),I=1,13),NTYPE A
WRITE (6,10) (XID(I),I=1,13) A
IF (NTYPE) 8,2,3 A
2 READ (5,11) NR,NC,INVOFF A
C-----PLACE CONSTRAINTS IN TABLEAU A
IMAX=NR+1 A
JMAX=NC A
CALL MATIN (TAB,NRT,IMAX,NC) A
C-----WRITE TABLEAU A
WRITE (6,14) A
CALL FPRINT (TAB,NRT,IMAX,JMAX,3,1,1) A
C-----SET UP RIGHT HAND SIDE A
RHS(1)=0.0 A
READ (5,12) (RHS(I),I=2,IMAX) A
INFIX(I)=0 A

```

```

INFIX(2)=JMAX A 56
INFIX(3)=NRT A 57
INFIX(4)=IMAX A 58
INFIX(5)=2 A 59
INFIX(6)=1 A 60
INFIX(7)=200 A 61
INFIX(8)=2*IMAX A 62
TOL(1)=1.0E-06 A 63
TOL(2)=1.0E-05 A 64
TOL(3)=-1.0E-03 A 65
TOL(4)=1.0E-10 A 66
TOL(5)=0.0 A 67
TOL(6)=0.0 A 68
TOL(7)=0.0 A 69
TOL(8)=0.0 A 70
KOUT(8)=0 A 71
PRM=0.0 A 72
GO TO 4 A 73
3 INFIX(1)=5 A 74
READ (5,13) I,RHS(I)
4 CALL SIMPLX (INFIX,TAB,RHS,TOL,PRM,KOUT,ERR,JJH,RRBAR,PI,YTEMP,KB,F A 75
1)
    WRITE (6,10) (XID(I),I=1,13) A 76
    WRITE (6,15) A 77
    WRITE (6,16) (I,KOUT(I),ERR(I),INFIX(I),TOL(I),I=1,8) A 78
    WRITE (6,10) (XID(I),I=1,13) A 79
    WRITE (6,17) A 80
    WRITE (6,18) (I,JJH(I),BBAR(I),PI(I),RHS(I),YTEMP(I),I=1,IMAX) A 81
    IF (INVOFF) 5,6,5 A 82
5     WRITE (6,10) (XID(I),I=1,13) A 83
      WRITE (6,19) A 84
      CALL EPRINT (E,IMAX,IMAX,IMAX,3,1,1) A 85
6      DO 7 J=1,JMAX A 86
      CALL DEL (J,RC(J),INFIX(4),TAB,PI,INFIX(3)) A 87
7      CONTINUE A 88
      WRITE (6,10) (XID(I),I=1,13) A 89
      WRITE (6,20) A 90
      WRITE (6,21) (I,KF(I),RC(I),I=1,JMAX) A 91
      GO TO 1 A 92
8      CONTINUE A 93
      ENDFILE 6 A 94
      STOP
C-----
9      FORMAT (13A6,I2) A 95
10     FORMAT (1H-,8X,13A6) A 96
11     FORMAT (5I5) A 97
12     FORMAT (8F10.4) A 99
13     FORMAT (15,F10.4) A 100
14     FORMAT (1HO,4X,7HTABLEAU) A 101
15     FORMAT (1HO,14X,4HKOUT,7X,5HERROR,9X,5HINFIX,7X,3HTOL) A 102
16     FORMAT (1HO,I5,I12,5X,E14.7,17,5X,E12.5) A 103
17     FORMAT (1HO,14X,3HJJH,9X,4HBBAR,12X,2HPI,14X,3HRHS,13X,5HYTEMP) A 104
18     FORMAT (1HO,I8,4X,2HX,(I3,3H) =,4F16.7) A 105
19     FORMAT (1HO,4X,14HINVERSE MATRIX) A 106
20     FORMAT (1HO,13X,2H(B,7X,10HREDUCED C.) A 107
21     FORMAT (1H ,I8,I7,2X,E16.7) A 108
                                A 109

```

## LINEAR PROGRAMMING PROGRAM

PAGE 3

END

A 11

```

SUBROUTINE FPRINT (A,MR,NR,NC,K,L,N)
C-----OUTPUT ROUTINE FOR 1 OR 2 DIMENSIONAL ARRAYS      (FORTRAN IV)
C-----
C-----MR = FIRST DIMENSION NUMBER OF THE A ARRAY
C-----NR = NO. OF ROWS IN THE ARRAY TO BE PRINTED
C-----NC = NO. OF COLUMNS IN THE ARRAY TO BE PRINTED
C-----K AND L ARE NOT PRESENTLY UTILIZED
C-----FOR RETURN WITHOUT ACTION, SET N = 0
C-----
C----- DIMENSION A(MR,888)
      IF (N) 1,11,1
1      NFULLB=NC/10
      NCLEFT=NC-10*NFULLB
      IF (NCLEFT) 2,3,2
2      NFULLB=NFULLB+1
3      NSKIP=MAX0(1,60/(NR+4))
      DO 10 M=1,NFULLB
      NC1=10*M-9
      IF (M-NFULLB) 5,4,4
4      NC2=NC
      GO TO 6
5      NC2=10*M
6      WRITE (6,12)
      WRITE (6,13) (J,J=NC1,NC2)
      WRITE (6,12)
      DO 7 I=1, NR
      WRITE (6,14) I,(A(I,J),J=NC1,NC2)
7      CONTINUE
      IF (NC2-NC) 8,11,11
8      IF (M-NSKIP*(M/NSKIP)) 10,9,10
9      WRITE (6,15)
10     CONTINUE
11     RETURN
C-----
C-----
12    FORMAT (1X)
13    FORMAT (1H ,IX,10I10)
14    FORMAT (1H ,I5,2X,10E11.3)
15    FORMAT (1H1)
END

```

SUBROUTINE MATIN (A,MR,NR,NC)  
C-----THIS PROGRAM READS DATA INTO AN ARRAY.  
C-----A FORMAT CARD MUST PRECEDE THE DATA.

123

```

C----- I.E.,FORMAT I NN (...)

C----- WITH 'FORMAT' IN COL. 1-6, C 4
C----- I = 'ROW' FOR ROW FORMAT, I = 'COL' FOR COLUMN FORMAT C 5
C----- NN = NO. DATA WORDS PER CARD, C 6
C----- (...) = FORMAT SPECIFICATION. C 7
C----- EACH DATA CARD MUST HAVE TWO INDEX NUMBERS C 8
C----- INDICATING THE MATRIX POSITION OF THE FIRST DATA WORD. C 9
C----- THE READING OF CARDS IS COMPLETED BY ONE BLANK CARD. C 10
C----- THIS ROUTINE HAS A PROVISION FOR CHANGING FORMATS IN MIDSTREAM. C 11
C----- A CARD WITH BOTH INDICES NEGATIVE IMPLIES THAT A FORMAT CARD FOLLO C 12
C----- C 13
C----- DIMENSION A(MR,NC), FMT(17), XLIST(78) C 14
C----- CALL EQUIV (CHECK1,4HFCRM) C 15
C----- CALL EQUIV (CHECK2,4HAT ) C 16
C----- CALL EQUIV (ROW,3HROW) C 17
C----- DO 1 I=1,MR C 18
C----- DO 1 J=1,NC C 19
C----- 1 A(I,J)=0.0 C 20
C----- READ FORMAT CARD C 21
C----- 2 READ (5,28) WORD1,WORD2,ROC,NN,(FMT(I),I=1,17) C 22
C----- IF (WORD1-CHECK1) 4,3,4 C 23
C----- 3 IF (WORD2-CHECK2) 4,5,4 C 24
C----- 4 WRITE (6,32) C 25
C----- GO TO 27 C 26
C----- READ DATA CARD C 27
C----- 5 READ (5,FMT) I,J,(XLIST(K),K=1,NN) C 28
C----- CHECK FOR NEW FORMAT CARD C 29
C----- IF (I) 6,7,7 C 30
C----- 6 IF (J) 2,19,10 C 31
C----- CHECK FOR BLANK CARD TO END LIST C 32
C----- 7 IF (I+J) 8,27,8 C 33
C----- 8 IF (ROC-ROW) 18,9,18 C 34
C----- ROW FORMAT *** C 35
C----- 9 IF (I-NR) 11,11,10 C 36
C----- 10 WRITE (6,29) I,J,MR,NR,NC C 37
C----- GO TO 5 C 38
C----- 11 DO 17 JJ=1,NN C 39
C----- JJJ=J+JJ-1 C 40
C----- IF (XLIST(JJ)) 12,17,12 C 41
C----- 12 IF (JJJ-NC) 14,14,13 C 42
C----- 13 WRITE (6,30) I,JJJ,MR,NR,NC C 43
C----- GO TO 5 C 44
C----- 14 IF (A(I,JJJ)) 15,16,15 C 45
C----- 15 WRITE (6,31) I,JJJ,MR,NR,NC C 46
C----- GO TO 17 C 47
C----- 16 A(I,JJJ)=XLIST(JJ) C 48
C----- 17 CONTINUE C 49
C----- GO TO 5 C 50
C----- COLUMN FORMAT *** C 51
C----- 18 IF (J-NC) 20,20,19 C 52
C----- 19 WRITE (6,30) I,J,MR,NR,NC C 53
C----- GO TO 5 C 54
C----- 20 DO 26 II=1,NN C 55
C----- III=I+II-1 C 56
C----- IF (XLIST(III)) 21,26,21 C 57
C----- 21 IF (III-NR) 23,23,22 C 58
C----- C 59

```

## LINEAR PROGRAMMING PROGRAM

PAGE 5

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22   WRITE (6,29) III,J,MR,NR,NC          C 6
      GO TO 5                               C 6
23   IF (A(III,J)) 24,25,24              C 6
24   WRITE (6,31) III,J,MR,NR,NC          C 6
      GO TO 26                             C 6
25   A(III,J)=XLIST(II)                  C 6
26   CONTINUE                            C 6
      GO TO 5                               C 6
27   RETURN                               C 6
C-----
28   FORMAT (1A4,1A2,1X,1A3,1X,I2,1X,16A4,1A2)    C 6
29   FORMAT (22H0ILLEGAL 1ST INDEX, I=,I3,2X,2HJ=,I3,2X,3HMR=,I3,2X,3HN  C 7
      1R=,I3,2X,3HNC=,I3)                   C 7
30   FORMAT (22H0ILLEGAL 2ND INDEX, I=,I3,2X,2HJ=,I3,2X,3HMR=,I3,2X,3HN  C 7
      1R=,I3,2X,3HNC=,I3)                   C 7
31   FORMAT (22H0DUPLICATION ERROR, I=,I3,2X,2HJ=,I3,2X,3HMR=,I3,2X,3HN  C 7
      1R=,I3,2X,3HNC=,I3)                   C 7
32   FORMAT (1H0,51H*** PROGRAM EXPECTS FORMAT CARD AT THIS POINT ***  C 7
      1)
      END                                C 7

```

## SUBROUTINE EQUIV (A,B)

```

A=B
RETURN
END

```

D 1  
D 2  
D 3  
D 4

```

SUBROUTINE SIMPLX (INFIX,A,B,TOL,PRM,KOUT,ERS,JH,X,P,Y,KB,E)          E 1
C-----BOSS      MASTER SUBROUTINE OF RS MSUB, VERSION 2.                  E 2
C-----
DIMENSION INFLAG,IOFIX(1),N,IOFIX(2),ME,IOFIX(3),M,IOF
1IX(4),MF,IOFIX(5),MC,IOFIX(6),NCUT,IOFIX(7),NVER,IOFIX
2(8),K,IOFIX(9),ITER,IOFIX(10),INV,IOFIX(11),NUMVR,IOF
3IX(12),NUMPV,IOFIX(13),INFS,IOFIX(14),JT,IOFIX(15),LA,
4IOFIX(16),ZZ(1),TPIV,ZZ(2),TZERO,ZZ(3),TCOST,ZZ(4),TEC
5OL
C-----
C-----MOVE INPUTS ... ZERO OUTPUTS
DO 1 I=1,8
TERR(I)=0.0
IOFIX(I+8)=0
1   IOFIX(I)=INFLAG(I)

```

E 14

E 15

E 16

E 17

E 18

E 19

E 20

```

2      DO 2 I=1,4          E 21
2      ZZ(I)=TOL(I)        E 22
2      PMIX=PRM            E 23
2      TCOST=-ABS(TCOST)   E 24
2      M2=M**2              E 25
2      INFS=1               E 26
2      LA=0                 E 27
C-----      CHECK FOR ILLEGAL INPUT          E 28
3      IF (N) 7,7,3          E 29
3      IF (M-MF) 7,7,4       E 30
4      IF (MF-MC) 7,7,5      E 31
5      IF (MC) 7,7,6         E 32
6      IF (ME-M) 7,8,8       E 33
7      K=7                  E 34
7      GO TO 28             E 35
8      IF (MOD(INFLAG,4)-1) 9,10,11          E 36
9      CALL NEW (M,N,JH(1),KB(1),A(1),B(1),MF,ME) E 37
10     CALL VER (A(1),B(1),JH(1),X(1),E(1),KB(1),Y(1),N,ME,M,MF,INVc,NUMV
10      1R,NUMPV,INFS,LA,TPIV,TECOL,M2)          E 38
10      E 39
C-----      PERFORM ONE ITERATION          E 40
11     CALL XCK (M,MF,JH(1),X(1),TZFR0,JIN)       E 41
C-----          E 42
C-----      CHECK CHANGE OF PHASE.. GO BACK TO INVERT IF GONE INFEAS. E 43
12     IF (INFS-JIN) 10,14,12          E 44
C-----      BECOME FEASIBLE          E 45
12     INFS=0                E 46
13     PMIX=0.0              E 47
14     CALL GET (M,MC,MF,JH(1),X(1),P(1),E(1),INFS,PMIX)          E 48
14     CALL MIN (JT,N,M,A(1),P(1),KB(1),ME,TCOST)          E 49
14     JM=JT                E 50
14     J=JM                E 51
14     IF (JM) 15,15,16          E 52
C-----      ALL COSTS NON-NEGATIVE... K = 3 OR 4          E 53
15     K=3+INFS            E 54
15     GO TO 18             E 55
C-----      NORMAL CYCLE          E 56
16     CALL JMY (J,A(1),E(1),M,Y(1),ME)          E 57
16     CALL ROW (IR,M,MF,JH(1),X(1),Y(1),TPIV)          E 58
C-----      TEST PIVOT          E 59
17     IF (IR) 17,17,19          E 60
C-----      NO PIVOT          E 61
17     K=5                  E 62
18     IF (PMIX) 13,24,13          E 63
C-----      ITERATION LIMIT FOR CUT OFF          E 64
19     IF (ITER-NCUT) 20,23,23          E 65
C-----      PIVOT FOUND          E 66
20     CALL PIV (IR,Y(1),M,E(1),X(1),NUMPV,TECOL)          E 67
20     JOLD=JH(IR)            E 68
20     IF (JOLD) 22,22,21          E 69
21     KB(JOLD)=0            E 70
22     KB(JM)=IR             E 71
22     JH(IR)=JM             E 72
22     LA=0                 E 73
22     ITER=ITER+1           E 74
22     WRITE (5,31) ITER,X(1)          E 75
22     INVc=INVc+1           E 76

```

## LINEAR PROGRAMMING PROGRAM

PAGE

```

C-----          INVERSION FREQUENCY
  IF (INVC-NVER) 11,10,11
C-----          CUT OFF ... TOO MANY ITERATIONS
23   K=6
24   CALL ERR (M,A(1),B(1),TERR(1),JH(1),X(1),P(1),Y(1),ME,LA)
     IF (LA) 26,25,26
25   LA=4
     IF (INFLAG-4) 10,26,26
26   IF (K-5) 28,27,28
27   CALL JMY (J,A(1),E(1),M,Y(1),ME)
C-----          SET EXIT VALUES
28   DO 29 I=1,8
29   ERS(I)=TERR(I)
     DO 30 I=1,7
30   KOUT(I)=IOFIX(I+8)
     RFTURN
C-----          .
C-----          .
31   FORMAT (1H ,6HITER =,I6,8H X(1) =,E15.5)
END

```

```

SUBROUTINE DEL (JM,DT,M,A,P,ME)
C-----DELS          DELTA-JAY.  PRICES OUT ONE MATRIX COLUMN
  DIMENSION A(1), P(1)
C-----DIMENSION A(1), P(1)
C-----          .
1    DT=0.0
     KDEL=(JM-1)*ME
C-----          .
     DO 4 IDEL=1,M
     KDEL=KDEL+1
     IF (A(KDEL)) 2,4,2
2    IF (P(IDEL)) 3,4,3
3    DT=DT+P(IDEL)*A(KDEL)
4    CONTINUE
C-----          .
     RETURN
END

```

```

C-----ERRS          ERROR CHECK.  COMPARES AX WITH B, PA WITH ZERO
  SUBROUTINE ERR (M,A,B,TERR,JH,X,P,Y,ME,LA)
  DIMENSION JH(1), A(1), B(1), X(1), P(1), Y(1), TERR(8)
C-----DIMENSION JH(1), A(1), B(1), X(1), P(1), Y(1), TERR(8)
C-----          STORE AX-B AT Y
     DO 1 I=1,M
1    Y(I)=-B(I)

```

```

DO 5 I=1,M          G  8
JA=JH(I)           G  9
IF (JA) 2,5,2       G 10
2 IA=ME*(JA-1)     G 11
DO 4 IT=1,M         G 12
IA=IA+1            G 13
IF (A(IA)) 3,4,3   G 14
3 Y(IT)=Y(IT)+X(I)*A(IA) G 15
4 CONTINUE          G 16
5 CONTINUE          G 17
C-----          FIND SUM AND MAXIMUM OF ERRORS G 18
DO 9 I=1,M          G 19
YI=Y(I)             G 20
IF (JH(I)) 7,6,7   G 21
6 YI=YI+X(I)        G 22
7 TERR(LA+1)=TERR(LA+1)+ABS(YI) G 23
IF (ABS(TERR(LA+2))-ARS(YI)) 8,9,9 G 24
8 TERR(LA+2)=YI    G 25
9 CONTINUE          G 26
C-----          STORE P TIMES BASIS AT DT G 27
DO 12 I=1,M         G 28
JM=JH(I)            G 29
IF (JM) 10,12,10    G 30
10 CALL DEL (JM,DT,M,A(1),P(1),ME) G 31
TERR(LA+3)=TERR(LA+3)+ABS(DT) G 32
IF (ABS(TERR(LA+4))-ABS(DT)) 11,12,12 G 33
11 TERR(LA+4)=DT    G 34
12 CONTINUE          G 35
RETURN              G 36
END                G 37

```

```

SUBROUTINE GET (M,MC,MF,JH,X,P,E,INFS,PMIX) H 1
C----- LABEL H 2
C-----GETS      GET PRICES H 3
DIMENSION JH(1), X(1), P(1), E(1) H 4
C-----DIMENSION JH(1), X(1), P(1), E(1) H 5
C-----
1     MMM=MC          H 6
C-----          PRIMAL PRICES H 7
DO 2 J=1,M          H 8
P(J)=E(MMM)         H 9
2     MMM=MMM+M        H 10
IF (INFS) 3,11,3     H 11
C-----          COMPOSITE PRICES H 12
3     DO 4 J=1,M        H 13
4     P(J)=P(J)*PMIX   H 14
DO 10 I=MF,M          H 15
MMM=I                H 16
IF (X(I)) 5,7,7       H 17
5     DO 6 J=1,M        H 18
P(J)=P(J)+E(MMM)     H 19
6     H 20

```

## LINEAR PROGRAMMING PROGRAM

PAGE

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6      MMM=MMM+M          H
      GO TO 10            H
7      IF (JH(I)) 10,8,10 H
8      DO 9 J=1,M         H
9      P(J)=P(J)-E(MMM)  H
9      MMM=MMM+M         H
10     CONTINUE           H
C-----
11     RETURN             H
      END                 H

```

```

C-----JMYS      J MULTIPLY. BASIS INVERSE * COLUMN J
      SUBROUTINE JMYS (JT,A,E,M,Y,ME)
      DIMENSION A(1), E(1), Y(1)
C-----DIMENSION A(1), E(1), Y(1)
C-----
1      DO 2 I=1,M
2      Y(I)=0.0
      LP=JT*ME-ME
      LL=0
      DO 6 I=1,M
      LP=LP+1
      IF (A(LP)) 3,5,3
3      DO 4 J=1,M
      LL=LL+1
4      Y(J)=Y(J)+A(LP)*E(LL)
      GO TO 6
5      LL=LL+M
6      CONTINUE
      RETURN
      END

```

```

C-----MINS      MIN D-J. SELECTS COLUMN TO ENTER BASIS
      SUBROUTINE MINS (JT,N,M,A,P,KB,ME,TCOST)
      DIMENSION A(1), P(1), KB(1)
C-----DIMENSION A(1), P(1), KB(1)
C-----
1      JT=0
      DA=TCOST
C-----
C-----      DO 4 JM=1,N
C-----      IF (KB(JM)) 4,2,4
2      CALL DEL (JM,DT,M,A(1),P(1),ME)
      IF (DT-DA) 3,4,4
3      DA=DT

```

	JT=JM	J 15
4	CONTINUE	J 16
	RETURN	J 17
	END	J 18-

C-----NEWS	STARTS PHASE ONE	K 1
	SUBROUTINE NEW (M,N,JH,KB,A,B,ME,MF)	K 2
	DIMENSION JH(1), KB(1), A(1), B(1)	K 3
C-----	DIMENSION JH(1), KB(1), A(1), B(1)	K 4
C-----	INITIATE	K 5
1	DO 2 I=1,M	K 6
2	JH(I)=0	K 7
C-----	INSTALL SINGLETONS	K 8
	KT=0	K 9
	DO 8 J=1,N	K 10
	KB(J)=0	K 11
	KTA=KT+MF	K 12
	KTB=KT+M	K 13
C-----	TALLY ENTRIES IN CONSTRAINTS	K 14
	KQ=0	K 15
	DO 4 L=KTA,KTB	K 16
	IF (A(L)) 3,4,3	K 17
3	KQ=KQ+1	K 18
	LQ=L	K 19
4	CONTINUE	K 20
C-----	CHECK WHETHER J IS CANDIDATE	K 21
	IF (KQ-1) 8,5,8	K 22
5	IQ=LQ-KT	K 23
	IF (JH(IQ)) 8,6,8	K 24
6	IF (A(LQ)*B(IQ)) 8,7,7	K 25
C-----	J IS CANDIDATE. INSTALL	K 26
7	JH(IQ)=J	K 27
	KB(J)=IQ	K 28
8	KT=KT+ME	K 29
	RETURN	K 30
	END	K 31

C-----PIVS	PIVOT. PIVOTS ON GIVEN ROW	L 1
	SUBROUTINE PIV (IR,Y,M,E,X,NUMPV,TECOL)	L 2
	DIMENSION Y(1), E(1), X(1)	L 3
C-----	DIMENSION Y(1), E(1), X(1)	L 4
C-----	LEAVE TRANSFORMED COLUMN IN Y(1)	L 5
C-----		L 6
1	NUMPV=NUMPV+1	L 7
C-----		L 8
	T2=-Y(IR)	L 9

## LINEAR PROGRAMMING PROGRAM

PAGE 1

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Y(IR)=-1.0
LL=0
C----- TRANSFORM INVERSE
    DO 5 JP=1,M
    L=LL+IR
    IF (ABS(E(L))-TECOL) 2,2,3
2     LL=LL+M
    GO TO 5
3     T3=E(L)/T2
    E(L)=0.0
    DO 4 I=1,M
    LL=LL+1
4     E(LL)=E(LL)+T3*Y(I)
5     CONTINUE
C----- TRANSFORM X
    T3=X(IR)/T2
    X(IR)=0.0
    DO 6 I=1,M
6     X(I)=X(I)+T3*Y(I)
C----- RESTORE Y(IR)
    Y(IR)=-T2
C----- RETURN
    END

```

```

C-----ROWS      ROW SELECTION--COMPOSITE
    SUBROUTINE ROW (IR,M,MF,JH,X,Y,TPIV)
    DIMENSION JH(1), X(1), Y(1)
C-----DIMENSION JH(1), X(1), Y(1)
C-----
C-----AMONG EQS. WITH X=0, FIND MAX ABS(Y) AMONG ARTIFICIALS, OR, IF NON
C-----GET MAX POSITIVE Y(I) AMONG REALS.
1     IR=0
    AA=0.0
    IA=0
    DO 10 I=MF,M
    IF (X(I)) 10,2,10
2     YI=ABS(Y(I))
    IF (YI-TPIV) 10,10,3
3     IF (JH(I)) 4,6,4
4     IF (IA) 10,5,10
5     IF (Y(I)) 10,10,7
6     IF (IA) 7,8,7
7     IF (YI-AA) 10,10,9
8     IA=1
9     AA=YI
    IR=I
10    CONTINUE
    IF (IR) 21,11,21
11    AA=1.0E+20
C----- FIND MIN. PIVOT AMONG POSITIVE EQUATIONS

```

```

DO 16 IT=MF,M M 27
IF (Y(IT)-TPIV) 16,16,12 M 28
12 IF (X(IT)) 16,16,13 M 29
13 XY=X(IT)/Y(IT) M 30
14 IF (XY-AA) 15,14,16 M 31
15 IF (JH(IT)) 16,15,16 M 32
AA=XY M 33
IR=IT M 34
16 . CONTINUE M 35
C----FIND PIVOT AMONG NEGATIVE EQUATIONS, IN WHICH X/Y IS LESS THAN THE M 36
C----MINIMUM X/Y IN THE POSITIVE EQUATIONS, THAT HAS THE LARGEST ABSFLY M 37
BB=-TPIV M 38
DO 20 I=MF,M M 39
IF (X(I)) 17,20,20 M 40
17 IF (Y(I)-BB) 18,20,20 M 41
18 IF (Y(I)*AA-X(I)) 19,19,20 M 42
19 BB=Y(I) M 43
IR=I M 44
20 CONTINUE M 45
21 RETURN M 46
END M 47

```

```

C----VERS FORMS INVERSE FROM KB N 1
SUBROUTINE VER (A,B,JH,X,E,KB,Y,N,ME,M,MMF,INVC,NUMVR,NUMPV,INFS,L N 2
1A,TPIV,TECOL,M2) N 3
DIMENSION A(1), B(1), JH(1), X(1), E(1), KB(1), Y(1) N 4
C----DIMENSION A(1), B(1), JH(1), X(1), E(1), KB(1), Y(1) N 5
MF=MMF N 6
C---- INITIATE N 7
IF (LA) 1,1,2 N 8
1 INV=0 N 9
2 NUMVR=NUMVR+1 N 10
DO 3 I=1,M2 N 11
3 E(I)=0.0 N 12
MM=1 N 13
DO 4 I=1,M N 14
E(MM)=1.0 N 15
X(I)=B(I) N 16
4 MM=MM+M+1 N 17
DO 6 I=MF,M N 18
IF (JH(I)) 5,6,5 N 19
5 JH(I)=12345 N 20
6 CONTINUE N 21
INFS=1 N 22
C---- FORM INVERSE N 23
DO 13 J=1,N N 24
IF (KB(J)) 7,13,7 N 25
7 CALL JMY (J,A(1),E(1),M,Y(1),ME) N 26
C---- CHOOSE PIVOT N 27
TY=0.0 N 28
DO 10 I=MF,M N 29

```

## LINEAR PROGRAMMING PROGRAM

PAGE 13

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      IF (JH(I)-12345) 10,8,10          N 30
8       IF (ABS(Y(I))-TY) 10,10,9      N 31
9       IR=I                           N 32
10      TY=ABS(Y(I))                  N 33
10      CONTINUE
C-----           TEST PIVOT        N 34
11      IF (TY-TPIV) 11,12,12         N 35
C-----           BAD PIVOT, ROW IR, COLUMN J   N 36
11      KB(J)=0                      N 37
11      GO TO 13                     N 38
C-----           PIVOT             N 39
12      JH(IR)=J                     N 40
12      KB(J)=IR                    N 41
12      CALL PIV (IR,Y(1),M,E(1),X(1),NUMPV,TECOL) N 42
13      CONTINUE
C-----           RESET ARTIFICIALS    N 43
14      DO 15 I=1,M                 N 44
14      IF (JH(I)-12345) 15,14,15      N 45
14      JH(I)=0                      N 46
15      CONTINUE
15      RETURN
15      END

```

```

C-----XCKS      X CHECKER
SUBROUTINE XCK (M,MF,JH,X,TZERO,JIN)          0  1
DIMENSION JH(1), X(1)                         0  2
C-----DIMENSION JH(1), X(1)                      0  3
C-----                                     0  4
C-----           RESET X AND CHECK FOR INFEASIBILITIES 0  5
1      JIN=0                         0  6
1      DO 6 I=MF,M                   0  7
1      IF (ABS(X(I))-TZERO) 2,3,3      0  8
2      X(I)=0.0                      0  9
2      GO TO 6                      0 10
3      IF (X(I)) 5,6,4               0 11
4      IF (JH(I)) 6,5,6               0 12
5      JIN=1                         0 13
6      CONTINUE
6      RETURN
6      END

```

SAMPLE DATA DECK FOR LINPROG

PAGE 14

PROGRAM LINPROGO TEST PROBLEM FROM WRITE-UP

3 6 1  
FORMAT ROW 6 (2I5,6F10.0)

1	1	4	7	8	6	0	0
2	1	150	140	170	160	0	0
3	1	0.1	0.1	0.3	0.3	1	0
4	1	2	4	5	3	0	-1

150 0.2 3

PROGRAM LINPROG TEST PROBLEM FROM WRITE-UP

TABLEAU

	1	2	3	4	5	6
1	4.000E+00	7.000E+00	8.000E+00	6.000E+00	0.	0.
2	1.500E+02	1.400E+02	1.700E+02	1.600E+02	0.	0.
3	1.000E-01	1.000E-01	3.000E-01	3.000E-01	1.000E+00	0.
4	2.000E+00	4.000E+00	5.000E+00	3.000E+00	0.	-1.000E+00
ITER = 1	X(1) = -4.8000E-04					
ITER = 2	X(1) = -5.26829E-04					

PROGRAM LINPROG TEST PROBLEM FROM WRITE-UP

KJUT	ERROR	INFIX	TOL
1	3	1.1666015E-16	0
2	2	-6.1149003E-17	6
3	2	4.2632564E-14	82
4	2	2.8421709E-14	4
5	6	1.1850330E-16	2
6	0	-6.1257423E-17	1
7	0	0.	200
8	0	0.	8
		0.	0.

PROGRAM LINPROG TEST PROBLEM FROM WRITE-UP

JJH	BBAR	P1	RHS	YTEMP
1	X( 0) = -5.2682927E-04	1.0000000E+00	0.	5.2682927E-04
2	X( 1) = 5.8536585E-05	-9.7560976E-03	1.5000000E-02	-5.5511151E-17
3	X( 5) = 1.9998317E-01	0.	2.0000000E-01	-6.1257423E-17
4	X( 3) = 3.6585366E-05	-1.2682927E+00	3.0000000E-04	-1.7347235E-18

PROGRAM LINPROG TEST PROBLEM FROM WRITE-UP

INVERSE MATRIX

	1	2	3	4
1	1.000E+00	-9.756E-03	0.	-1.268E+00
2	0.	1.220E-02	0.	-4.146E-01
3	0.	2.439E-04	1.000E+00	-6.829E-02
4	0.	-4.878E-03	0.	3.659E-01

PROGRAM LINPROG TEST PROBLEM FROM WRITE-UP

KB	REDUCED C.
1	0.
2	5.6097561E-01
3	0.
4	6.3414634E-01
5	0.
6	1.2682927E+00

## Subroutine KUTTA

### GENERAL PURPOSE

To numerically solve a set of Ordinary Differential Equations (ODE) of the form

$$\dot{Y}_i = f_i(t, Y, C_1(t), C_2(t), \dots, C_m(t)), \quad i = 1, \dots, n$$

Where  $Y_i$  is the  $i$ th dependent variable

$Y$  is a vector whose  $n$  components are the  $Y_i$ 's

$t$  is time

$C_j(t)$ ,  $j = 1, \dots, m$  is a set of extrinsic functions of time, some of which might be constants.

### METHOD OF OPERATION

KUTTA has arguments (XL, XU, Y, NE, DEL, ACC, IMAX, EQUA).  $Y$  is dimensioned 25, other variables are scalars. When KUTTA is called by a main program,  $Y$  should contain the NE values ( $NE = n$ ) which represent the state of the system at time XL. KUTTA will provide an estimate of  $Y$  at time XU. The estimating method is a 5th order Runge-Kutta technique with an error estimation procedure designed to ensure that the error in the estimation of the components of  $Y$  will be less than  $ACC*Y(I)$  for the  $I$ th component. DEL is a number, less than or equal to  $(XU - XL)$ , which is the users' estimate of the proper time step to use for obtaining the desired accuracy (as set by ACC) with a 5th order R-K procedure.

KUTTA will use a time step either greater or smaller than DEL, depending upon its error estimation procedure. The step size will start as DEL and be successively halved (or doubled) until the necessary accuracy is reached. If more than IMAX halvings (or doublings) are required for the requested accuracy, KUTTA will return to the main program with the values of  $Y$  unmodified. On our return to the main program IMAX will be set to the number of iterations (halvings or doublings of DEL) which were required. An error check in the main program can be made by comparing the actual number of iterations with the initial

value of IMAX. If these are the same, it is likely that the numerical method has failed. This is most likely due to discontinuous functions for the derivatives, or functions which change very erratically between XL and XU (assuming that all difficulties due strictly to coding have been solved).

The independent variable, of course, need not be time. KUTTA can be used to solve partial differential equations and integro-differential equations by reformulating these equations as ODE's.

EQUA is the name of a subroutine which must be declared EXTERNAL in the main program. EQUA has arguments (T, Y, YP) where YP and Y is dimensioned 25. EQUA must use T, Y, and the  $C_j(t)$  functions, transmitted either through COMMON or as additional subprograms, to evaluate  $Y_i$ ,  $i = 1, NE$  in array YP.

The device whereby a subroutine name is transmitted through an argument list and declared EXTERNAL in the main program is little used in FORTRAN IV but very convenient in this application. The sample program outline below illustrates the technique whereby the name of the subroutine used by KUTTA to evaluate the derivatives is declared to be EQI when KUTTA is called:

PROGRAM ODE

COMMON/LI/NT, NE, LAMBDA (25, 25)

EXTERNAL EQI

.....

T = 0.

DO 10 I = 1, NT

T = T + DT

.....

CALL KUTTA (T - DT, T, Y, NE, DT\*.1, .01, 50, EQI)

.....

10 PRINT 100, T, Y

```
END
```

```
SUBROUTINE KUTTA (XL, XU, Y, NE, DEL, ACC, IMAX, EQUA)
```

```
.....
```

```
CALL EQUA (T, Y, YP)
```

```
.....
```

```
END
```

```
SUBROUTINE EQI (T, Y, YP)
```

```
COMMON/LI/NT, NE, LAMBDA (25, 25)
```

```
.....
```

```
DO 10 I = 1, NE
```

```
YP(I) = 0.
```

```
DO 10 J = 1, NE
```

```
10 YP(I) = YP(I) + Y(J) * LAMBDA(I, J)
```

```
RETURN
```

```
END
```

```
.....
```

Though KUTTA calls EQUA, transfer is actually made to EQI.

The accompanying FORTRAN IV program (ODE) illustrates the use of KUTTA to solve a set of *linear*, homogeneous, ordinary differential equations. KUTTA can be used to solve other (*nonlinear*) ODE's by replacing EQI with an appropriate routine. We have tested KUTTA with a variety of nonlinear equations, both partial and ordinary, and with integro-differential equations of the Volterra and Fredholm types and found it to be reliably accurate and rapid. Its speed is dependent upon the complexity of the equation to be solved and thus avoids much of the need for multiple integration techniques. The only restriction is that the derivatives must be continuous functions of time, though the routine works in some cases when this restriction is violated.

KUTTA was written by F. D. Hammerling, ORGDP, Oak Ridge National Laboratory.

## PROGRAM LINDIFF

```

C SOLVES A SET OF LINEAR DIFFERENTIAL EQUATIONS
C NCOM NO OF EQUATIONS
C NT NO OF TIME POINTS
C T1 INITIAL TIME VALUE
C TDEL TIME STEP FOR PRINTOUT
C ACC DESIRED ACCURACY IN SOLUTION
C DFL ESTIMATE OF TIME STEP TO BE USED FOR INTEGRATION
C ITER NO OF ITERATIONS, MAXIMUM, TO BE ALLOWED IN INTEGRATION
C FMT FORMAT STATEMENT TO BE USED TO READ INITIAL CONDITIONS
C AND MATRIX OF COEFFICIENT VALUES
C V VECTOR OF INITIAL CONDITION VALUES
C F MATRIX OF COEFFICIENT VALUES
DIMENSION FMT(8),V(20)
COMMON/L1/F(20,20),NCOM
EXTERNAL EQ1
C READ AND PRINT INPUT DATA
1 READ 100,NCOM,NT,T1,TDEL,ACC,DEL,ITER
PRINT 200,T1,TDEL,NT,NCOM,ACC,DEL,ITER
READ 300,FMT
READ FMT,(V(I),I=1,NCOM)
READ FMT,((F(I,J),J=1,NCOM),I=1,NCOM)
PRINT FMT,(V(I),I=1,NCOM)
PRINT 600
PRINT FMT,((F(I,J),J=1,NCOM),I=1,NCOM)
C SET UP OUTPUT FORMAT
N=NCM+1
ENCODE(15,400,FMT) N
400 FORMAT(*E20.4,*12E12.4)*
PRINT 500
C ITERATE THROUGH TIME AND FIND EQUATION SOLUTION
T=T1-TDEL
10 T0 10 J=1,NT
T=T+TDEL
T2=T+TDEL
PRINT FMT,T,(V(I),I=1,NCOM)
CALL KUTTA(T,T2,V,NCOM,DEL,ACC,ITER,EQ1)
10 CONTINUE
GO TO 1

100 FORMAT(2I5,2F10.3/2F10.3,15)
200 FORMAT(*1LINEAR DIFFERENTIAL EQUATION SOLUTION**// TIME STARTS AT
1*F10.3*, INCREMENTS BY *F10.3*, FOR *16* ITERATIONS**/*
216* COMPARTMENT SYSTEM**// ACCURACY OF SOLUTION=E15.4/* TIME STEP
3SIZE*E15.4/* MAXIMUM ITERATIONS/STEP*16// INITIAL VALUES AND MATR
4TX**/
500 FORMAT(8A10)
500 FORMAT(*1**// TIME, COMPARTMENT VALUES, IN ORDER**/)
500 FORMAT(//)
END

```

```
SUBROUTINE EU1(X,Z,ZP)
C   FINDS DERIVATIVES FOR A SET OF LINEAR DIFF. Eqs.
C   X -- CURRENT TIME, Z -- CURRENT DEP VAR VALUE, ZP -- CURRENT
C   DERIVATIVE VALUES TO BE FOUND BY MATRIX MULTIPLICATION
COMMON/L1/LAMHDA(20,20),N
REAL LAMHDA
DIMENSION Z(1),ZP(1)
DO 10 I=1,N
ZP(I)=0.
10 ZP(I)=ZP(I)+LAMHDA(I+1)*Z(I)
RETURN
END
```

```

SUBROUTINE KUTTA(XL,XU,Y,NF,DEL,ACCURC,IMAX,EQUA)
C PROGRAM AUTHOR F.D.HAMMERLING, CENTRAL DATA PROCESSING, ORGUP.
DIMENSION Y(1),YI(25),YN(25),K1(25),K2(25),K3(25),
      K4(25),KS(25),F(25),E(25),FI(25)
REAL K1,K2,K3,K4,K5
LOGICAL QUIT
ITTER=0
N=NE
XN=XL
H=DEL
QUIT=.FALSE.
DO 1 I=1,N
1 YN(I)=Y(I)
2 IF(XN+H.LT.XU)GO TO 3
DEL=H
HEXU=YN
QUIT=.TRUE.
3 CALL FQUA(XN,YN,F)
4 DO 5 I=1,N
      K1(I)=H*FI(I)/3.
5 YI(I)=YN(I)+K1(I)
      CALL FQUA(XN+H/3.,YI,F)
DO 6 I=1,N
      K2(I)=H*FI(I)/3.
6 YI(I)=YN(I)+K1(I)/2.+K2(I)/2.
      CALL FQUA(XN+H/3.,YI,F)
DO 7 I=1,N
      K3(I)=H*FI(I)/3.
7 YI(I)=YN(I)+3.*K1(I)/8.+9.*K3(I)/8.
      CALL FQUA(XN+H/2.,YI,F)
DO 8 I=1,N
      K4(I)=H*FI(I)/3.
8 YI(I)=YN(I)+3.*K1(I)/2.-9.*K3(I)/2.+6.*K4(I)
      CALL FQUA(XN+H,YI,F)
TEST=0.0
DO 9 I=1,N
      KS(I)=H*FI(I)/3.
      E(I)=(K)(T)-9.*K3(I)/2.+4.*K4(I)-KS(I)/2./5.
      TEST=AMAX1(TEST,ABS(E(I)))
9 CONTINUE
IF(TEST.LT.ACCURC)GO TO 10
ITTER=ITTER+1
IF(ITTER.GE.IMAX)GO TO 13
H=H/2.
QUIT=.FALSE.
GO TO 4
10 DO 11 I=1,N
11 YN(I)=YN(I)+(K)(T)+4.*K4(I)+K5(I))/2.
XN=XN+H
IF(TEST.LT.ACCURC/32.)H=2.*H
IF(.NOT.QUIT)GO TO 2
DO 12 I=1,N
12 Y(I)=YN(I)
IMAX=0.
GO TO 14
13 DEL=H $ IMAX=ITTER
14 RETURN
END

```

4 201 40.

•00001 •025 50  
(4E10-4)

7.0568	4.3434	7.6290	40.972
- .1	.03333333	.03333333	.03333333
0.	- .1	.05	.05
.05	0.	- .1	.05
0.	0.	0.	0.

CP SEC=000003 PP SEC=000013 PR=000008 PU=000000 RD=000176 PL=000000

119250 119250 119250 119250

## APPENDIX I

### OTHER USEFUL PROGRAMS

#### I. STAT03C - Factorial Analysis of Covariance

This program computes a full factorial analysis of covariance.

Output includes:

1. The total covariance matrix and a breakdown into its full factorial design components.
2. The components in 1 adjusted by residuals.
3. Inverses of the covariate parts of the adjusted components.
4. Regression coefficients
5. t-values, an F-statistic, and the residual mean square.
6. An analysis-of-variance table for the factorial components of the design.

Limitations in the program are:

1. v, number of AOV classifications ( $1 \leq v \leq 6$ )
2. p, number of covariates ( $1 \leq p \leq 8$ )
3. r, number of replicates ( $r \leq 999$ )
4.  $L_i$ , number of categories or levels of any one classification ( $L_i \leq 999$ ) and ( $L_1 \times L_2 \times L_3 \times \dots \times L_v \leq 1200$ )
5. q, number of covariates generated. ( $-7 \leq q \leq 7$ ) and [ $0 < (p+q) \leq 8$ ]

#### II. BMD07D Description of Strata with Histograms

This program groups the data into a specified number of groups based on the order of entry of the data or into groups whose values for a base variable are w/in intervals established by specified cut points. For these groups, histograms are printed for each variable. The number of classes or categories of the histograms may be specified or they may be computed

by the program. Means, standard deviations and correlation coefficients are computed for each group; means and standard deviations are computed also for the combined groups of a variable. Special values may be specified for all variables, except the base variable, to exclude certain values to codes from computations.

Output includes:

1. Input data after transgeneration
2. Input data after ordering from high to low on the specified base variable
3. Histograms for each variable showing the frequencies of distribution of C classes over the g groups.
4. Correlation matrices for each group
5. Means and standard deviations
6. Tabulations of special values.

Limitations in the program are:

1. p, number of variables ( $1 \leq p \leq 100$ )
2. n, number of observations ( $1 \leq n \leq 9999$ )
3. g, number of groups ( $0 \leq g \leq 10$ )
4. c, number of classes ( $5 \leq c \leq 30$ )
5.  $m_i$ , number of special values for variable i ( $0 \leq m_i \leq 5$ )
6. q, number of variables added in transgeneration ( $0 \leq q \leq 99$ )
7. T, number of group cut points ( $1 \leq T \leq 9$ )
8.  $n(p+q)$ , [ $n(p+q) \leq 19,000$ ]

### III. BMD10D Data Patterns for Dichotomies

This program finds frequencies and patterns of any one particular specified code in the input data. Frequent use will be for a code representing missing

values. The program prints 0's to designate the specified code, or missing values, and 1's to designate and other values. A data matrix of 0's and 1's is printed. Frequencies of the specified code, or missing values are computed; and the cases having the specified code are identified by item numbers which correspond to the order in which the cards appear in the data input deck. If desired, patterns of data may be obtained also after eliminating each variable in turn. Thus, patterns are available for the  $p + 1$  different choices of  $p$  variables.

Output includes.

1. Patterns of data (0's for the specified code or missing values; 1's for all other values). Tabulated by numbers of missing values, and item numbers to identify cases.
2. Data matrix of 0's and 1's

Limitations in the program are:

1.  $p$ , number of variable ( $1 \leq p \leq 30$ )
2.  $n$ , number of cases or items ( $1 \leq n \leq 700$ )

#### IV. STAT31S Chi Square Analysis

This program computes the Chi Square test for independence in two way contingency tables. In addition, tests for goodness of fit are calculated for one way classifications.

Output includes:

1. Listing of original table with observed and theoretical frequency as well as the contributions to the test statistic.
2. Calculated  $\chi^2$  value and degrees of freedom
3. Tabled values of  $\chi^2_\alpha$  for comparison
4. Marginal tests of row and column totals.

The limitation in the program is that it is for two way tables no larger than  $10 \times 10$ .

## V. STAT02V ANOVA for Balanced Factorial Design

This program computes an analysis of variance for a balanced factorial design.

Output includes:

1. Analysis of variance table and the grand mean.
2. A breakdown of the sums of squares into orthogonal polynomial components for as many as four main effects and all of their first order interactions.
3. Main effects and first order interactions for the variables specified in 2.
4. Cell means and variances, main effect means and plots.
5. Two factor and three factor interaction means if there are more than two factors.

Limitations in the program are:

1. F, number of factors (independent variables) or ways ( $F \leq 8$ )
2. D, number of observations per cell ( $R \leq 999$ )
3.  $L_i$ , Number of categories or levels of any one factor ( $L_i \leq 999$ ) and ( $L_1 \times L_2 \times L_3 \times \dots \times L_F \leq 4000$ ).

## VI. STAT31V ANOVA for Unequal Subclass Frequencies

This program performs an analysis of variance for data from an unbalanced (unequal subclass frequencies) three (or two) way classification. The method used is one in *Topics in Intermediate Statistical Methods* by T. A. Bancroft (1958). The analysis consists of two steps, the preliminary ANOVA and the final ANOVA.

If interactions are known not to exist in the population or at least one subclass is empty, the method of fitting constants is used to test main effects in the final ANOVA.

If interactions are known to be present in the population, the method of weighted square of means is used to investigate main effects in the final ANOVA.

If it is not known whether interactions are present or not, a test for it is included in the preliminary ANOVA. The method of fitting constants or the method of weighted square of means is used on the outcome of the test of whether interactions are absent or present. In this situation, the tests on main effects will not exactly be at a level because the test for interaction is a preliminary test which precedes the test for main effects. Test for significance of interaction should, in general, be made at .25 significance level to insure the main effect subsequent tests to be made at the .05 level.

Output includes the preliminary and final ANOVA. Subclass means and variances and marginal totals are optional.

Limitations in the program are that a problem may have a maximum of:

1. three factors
2. 20 levels for each factor
3. 100 observations in each subclass.