GROWTH, STRUCTURE, AND PROPERTIES OF SELECTED TWO-DIMENSIONAL MATERIALS FROM DENSITY FUNCTIONAL THEORY INVESTIGATIONS

by

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ABSTRACT

After an initial decade of excitement brought by the successful isolation of graphene and discovery of its exotic properties, the attention of the scientific community turned to other 2-D materials that could provide diversity in terms of useful properties without relying on increasingly complex engineering of graphene-based 2-D layers or nanostructures. In this arena, a range of materials have been either experimentally synthesized or theoretically hypothesized, the most important currently being hexagonal boron nitride (hBN), molybdenum disulphide, silicene, phosphorene, and maxenes—among others. Some of the key issues of current importance in 2-D research are synthesis of specific 2-D materials, effects of the substrates on the morphology and properties of 2-D layers, and control of the properties through synthesizing different 2-D polymorphs: this thesis addresses particular problems falling under these three distinct themes. Specifically, parts of the thesis focus on phosphorene and hBN growth, morphology of hBN on palladium, and range of mechanical and electronic properties obtained from different 2-D silica polymorphs. For the phosphorene growth, the thesis advances the idea that the phosphorene can in fact grow by chemical vapor deposition on metals, provided that they are covered with hBN or graphene so as to prevent the formation of metal phosphides. For the multilayer hBN growth, results in this thesis support a recently proposed notion that adsorption of one precursor activates the adsorption and dehydrogenation of ammonia (the second precursor), which leads to the formation of second hBN layer and beyond when the metal substrate is already passivated by the first hBN layer. Another chapter of this thesis shows a phenomenological model and density functional theory calculations explaining experimentally-observed novel morphologies of hBN on palladium. Lastly, this thesis shows examples of how polymorphs of 2-D silica can lead to diverse electronic properties ranging from insulating to metallic.
# TABLE OF CONTENTS

ABSTRACT ................................................................. iii

LIST OF FIGURES ..................................................... vii

LIST OF TABLES ....................................................... xii

LIST OF ABBREVIATIONS ........................................... xiii

ACKNOWLEDGMENTS .................................................. xiv

DEDICATION ............................................................ xv

CHAPTER 1 INTRODUCTION ........................................... 1

1.1 Brief overview .................................................. 1

1.1.1 Hexagonal boron nitride (hBN) ............................ 3

1.1.2 Molybdenum disulfide (MoS$_2$) .......................... 4

1.1.3 Silicene (Si) .................................................. 4

1.1.4 Germanene (Ge) .............................................. 5

1.1.5 Phosphorene (P) ............................................. 5

1.2 Key issues in 2-D materials and role of theoretical investigations .................... 5

1.3 Research work in this thesis and specific contributions of the candidate ............ 7

1.3.1 Ch. 2: Necessary conditions for phosphorene growth on graphene- or boron-nitride-covered metals .......................................................... 7

1.3.2 Ch. 3: Growth of a bilayer hexagonal Boron-Nitride on Copper substrate ...................... 8

1.3.3 Ch. 4: Corrugation of hexagonal Boron-Nitride monolayer on Palladium ....................... 8
4.5 Results from complete hBN monolayers on Pd ........................................ 49
4.6 Results from adsorption of molecular probes ........................................ 53
4.7 Model for the energetic competition between blistered and flat structures ... 56
4.8 Conclusions ......................................................................................... 59

CHAPTER 5 MECHANICAL AND ELECTRONIC PROPERTIES OF 2-D SILICA . 61

5.1 Introduction ......................................................................................... 61
5.2 Description of the simulation protocol ............................................... 65
5.3 Proposed structures of 2D silica ....................................................... 67
5.4 Mechanical properties of the 2D silica structures ............................... 72
5.5 Band structures and Density of states (DOS) ....................................... 75
5.6 Summary ............................................................................................ 81

APPENDIX PERMISSIONS FOR CONTENT REUSED ................................. 82
REFERENCES CITED .............................................................................. 105
LIST OF FIGURES

Figure 2.1  Dependence of the electronic bandgap on the number of layers in phosphorene. Reproduced from Ref. , with permission of the American Physical Society. .................................................. 10

Figure 2.2  (a) Typical metal-P phase diagram, showing the formation of various phosphides. At intermediate P concentrations (i.e. not corresponding the phosphide stoichiometry), there is decomposition into Cu and Cu₃P, or between Cu₃P and CuP₂, but there is never segregation of P at the surface as encountered for example in the Cu-C phase diagram (b). Reproduced from with permission from Springer, and from National Physical Laboratory (open access) ........................................... 11

Figure 2.3  Molecules making up the gaseous precursors that can be used for the synthesis of phosphorene: (a) P₂, (b) P₄, and (c) PH₃. .......................... 13

Figure 2.4  Adsorption locations for PHₓ (x = 0,1,2,3), vertical P₂, vertical P₄ (C, hex, bridge), and the horizontal P₂ molecules (a-c). ....................... 14

Figure 2.5  Adsorption locations for PHₓ (x = 0,1,2,3), vertical P₂, vertical P₄ (C, hex, bridge), and the horizontal P₂ molecules (a-c). ....................... 14

Figure 2.6  Adsorption locations for PHₓ (x = 0,1,2,3), vertical P₂, vertical P₄ (N, B, hex, bridge), and the horizontal P₂ molecules (a-d). ....................... 15

Figure 2.7  Adsorption locations for PHₓ (x = 0,1,2,3), vertical P₂, vertical P₄ (N, B, hex, bridge), and the horizontal P₂ molecules (a-d). ....................... 15

Figure 2.8  Adsorption energies for the P₂ molecule on graphene- or hBN-covered Ni and Cu substrates, for several selected positions. The symbols ⊥ and || stand for the vertical and horizontal orientations of the molecule, respectively; C is a top site, bb bridge site, and the other symbols are shown in Figure 2.4 to Figure 2.7 .................................................. 16

Figure 2.9  Adsorption energies for PHₓ (x = 0,1,2,3) on graphene- or hBN-covered Ni and Cu substrates. .................................................. 18

Figure 2.10 reaction pathway for the dehydrogenation step PH₃ → PH₂ + H on gr/Cu and gr/Ni surfaces ....................... 20
Figure 2.11 reaction pathway for the dehydrogenation step $PH_3 \rightarrow PH_2 + H$ on hBN/Cu and hBN/Ni surfaces .......................... 20

Figure 2.12 reaction pathway for the dehydrogenation step $PH_2 \rightarrow PH + H$ on gr/Cu and gr/Ni surfaces .................................................. 21

Figure 2.13 reaction pathway for the dehydrogenation step $PH_2 \rightarrow PH + H$ on hBN/Cu and hBN/Ni surfaces .................................................. 21

Figure 3.1 TEB ($C_6H_{15}B$) and its radicals $C_4H_{10}B$ and $C_2H_5B$. ................................. 29

Figure 3.2 Borane and its radicals, $BH_x$ ($x = 1,2,3$). ................................. 30

Figure 3.3 Ammonia and its radicals, $NH_x$ ($x = 1,2,3$) molecule ................................. 30

Figure 3.4 Adsorption locations for molecules on Cu(111) surface ................................. 31

Figure 3.5 Adsorption locations for molecules on hBN/Cu surface ................................. 31

Figure 3.6 Adsorption locations for molecules on hBN surface ................................. 32

Figure 3.7 Adsorption energies at the strongest binding sites for $C_6H_{15}B$, $C_4H_{10}B$ and $C_2H_5B$ on Cu(111), hBN/Cu, and hBN substrates. ................................. 33

Figure 3.8 Adsorption energies for $BH_x$ ($x = 0,1,2,3$) on hBN, Cu(111), and hBN/Cu substrates. ................................. 34

Figure 3.9 Adsorption energies for $NH_x$ ($x = 0,1,2,3$) on hBN, Cu(111), and hBN/Cu substrates. ................................. 35

Figure 4.1 The dependence of spatial periodicity $\lambda$ of orientation $\theta$, Equation (4.1). ................................. 44

Figure 4.2 Atomic structures for the moiré patterns associated with the experimentally observed periodicities $\lambda = 0.6$, 1.8, 2.7 and 2.8 nm: these periodicities correspond to $\theta$ values of 24.6, 6.3, 1.1, and 0.0°, respectively. ................................. 45

Figure 4.3 Schematic diagram showing the operation of STM. The tunneling current depends on the distance between the tip and the sample, as well as on the density of states of the tip and the sample ................................. 45
Figure 4.4  Plots of the apparent corrugation $\Delta z$ as a function of the bias voltage $V$ for a tunelling current $I=7.0$ nA, for multiple domains: $\lambda=1.8$ nm (green squares), 2.7 nm (blue circles), and 2.8 nm (orange triangles). Courtesy of Pedro Arias and Prof. Suneel Kodambaka.

Figure 4.5  Molecular probes used for assessing the local interaction strength via density functional theory (DFT) calculations. The molecules are in two orientations, zigzag (a, b, e, f) and armchair (c, d, g, h). The larger molecule, $B_{12}N_{12}H_{12}$, has two configurations $\alpha$ and $\beta$, depending on the succession of the B and N atoms in the central six-atom ring. The center of the molecule is placed above the Pd surface, in a top site, fcc site, hcp site, and bridge bond. These configurations are relaxed, and adsorption energies and the minimum and maximum distance from any atom of the probe molecule to the top Pd layer are reported Tables Table 4.1 and Table 4.2.

Figure 4.6  Adsorption locations for center of BN-molecules on Pd(111) surface, top, face-centered cubic (fcc), hexagonal close-packed (hcp), and bridge.

Figure 4.7  Small hBN/Pd unit cell for calculations of electronic properties, (a) top view, (b) side view.

Figure 4.8  (a) Band structure of free-standing hBN. (b) Bandstructure of hBN/Pd for the surface unit cell shown in Figure 4.7. (c) Local density of states at the surface.

Figure 4.9  Simulated STM image for a supercell with $11\times11$ hBN on $10\times10$ Pd substrate. The top view shows the simulated STM image (sharp white dots are the N atoms beneath) with obvious large scale moiré pattern (color gradient) and the side image shows the relaxed atomic structure without any noticeable geometric corrugation of the hBN monolayer.

Figure 4.10  (a) Structure of the hBN/Pd(111) with maximal periodicity, obtained from flat layers with lattice constants $a_{hBN} = 0.250$ nm and $a_{Pd(111)} = 0.275$ nm. Small flakes (b) $B_7N_6H_9$ (top) and $B_6N_7H_9$ (bottom) and (c) $B_{12}N_{12}H_{12}$ employed to determine the adsorption tendencies for different portions (highlighted) of the moir structure. The circular region is van der Waals (vdW) bonded to the substrate, while the triangular region represents the strongest bonded core of the remaining chemically-bonded area in the unit cell.

Figure 4.11  Schematic of a surface unit cell of hBN/Pd with a blistered configuration. The blister is approximated as a spherical calotte of height $h$ and base radius $R$. 
Figure 4.12 Schematic of a surface unit cell of hBN/Pd with a blistered configuration. The blister is approximated as a spherical calotte of height $h$ and base radius $R$. ................................. 60

Figure 5.1 Common 3D crystalline phases of silica. From , with permission of Royal Society of Chemistry. ................................. 63

Figure 5.2 3D amorphous phase of silica. From , with permission of Royal Society of Chemistry. ................................. 64

Figure 5.3 Theoretical 2D phases of silica proposed in the literature and their formation energy. Reproduced with permission from American Chemical Society. ................................. 64

Figure 5.4 Silica 2D layer epitaxially grown on Molybdenum from Ref. Reproduced with permission from the Institute of Physics. ................................. 65

Figure 5.5 Atomic structure of 2D silica where the tetrahedra share corners, forming triangular holes, with all tetrahedra on one side of the surface: (a) perspective view showing the Si-centered tetrahedra, and (b) top view, with atoms shows as red (O) or blue (Si) spheres. ................................. 67

Figure 5.6 Atomic structure of 2D silica where tetrahedra share corners, forming triangular holes with half of tetrahedra on each side of the surface: (a) perspective view showing the Si-centered tetrahedra, and (b) top view, with atoms shows as red (O) or blue (Si) spheres. ................................. 68

Figure 5.7 Atomic structure of 2D silica where the tetrahedra share corners, forming hexagonal holes with all tetrahedra on one side of the surface: (a) perspective view showing the Si-centered tetrahedra, and (b) top view, with atoms shows as red (O) or blue (Si) spheres. ................................. 69

Figure 5.8 Atomic structure of 2D silica where the tetrahedra share corners, forming hexagonal holes with half of tetrahedra on each side of the surface: (a) perspective view showing the Si-centered tetrahedra, and (b) top view, with atoms shows as red (O) or blue (Si) spheres. ................................. 70

Figure 5.9 Atomic structure of 2D silica where the tetrahedra share edges, all the tetrahedra on one side of the surface: (a) perspective view showing the Si-centered tetrahedra, and (b) top view, with atoms shows as red (O) or blue (Si) spheres. ................................. 70
Figure 5.10  Atomic structure of 2D silica where the tetrahedra share edges, half the tetrahedra on each side: (a) perspective view showing the Si-centered tetrahedra, and (b) top view, with atoms shows as red (O) or blue (Si) spheres.

Figure 5.11  Band structure and DOS for structure 1

Figure 5.12  Band structure and DOS for structure 2

Figure 5.13  Band structure and DOS for Structure 3

Figure 5.14  Band structure and DOS for Structure 4

Figure 5.15  Band structure and DOS for 2D silica, Structure 6
LIST OF TABLES

Table 2.1 Calculated reaction barriers for the dehydrogenation steps on hBN or graphene covered Ni or Cu substrates. ........................................ 19

Table 2.2 Adsorption Energy of PH(0,1,2,3), P$_2$ and P$_4$ Molecules on gr/Cu ........ 23

Table 2.3 Adsorption Energy of PH(0,1,2,3), P$_2$ and P$_4$ Molecules on gr/Ni ........ 24

Table 2.4 Adsorption Energy of PH(0,1,2,3), P$_2$ and P$_4$ Molecules on hBN/Cu ...... 25

Table 2.5 Adsorption Energy of PH(0,1,2,3), P$_2$ and P$_4$ Molecules on hBN/Ni ...... 26

Table 3.1 Adsorption energy for TEB (3-Ethyl) and its radicals with 2- and 1-Ethyl groups. ................................................................. 37

Table 3.2 Adsorption energy of boron-containing molecules and radicals .......... 38

Table 3.3 Adsorption energy of nitrogen-containing molecules and radicals ....... 39

Table 4.1 Adsorption energy ($E_{ads}$) and the minimum ($z_{min}$) and maximum ($z_{max}$) distance between atoms in the small molecular probes B$_7$N$_6$H$_9$ and B$_6$N$_7$H$_9$ on Pd(111). .............................................................. 55

Table 4.2 Adsorption energy ($E_{ads}$) and the minimum ($z_{min}$) and maximum ($z_{max}$) distance between atoms in the large molecular probes B$_{12}$N$_{12}$H$_{12}$ on Pd(111). .............................................................. 56

Table 5.1 Lattice parameters of the proposed 2D silica structures ......................... 72

Table 5.2 Converting the stiffness tensor to Voigt notation .................................. 72

Table 5.3 The stiffness constant $c_{11}^{2D}$ of graphene. ....................................... 74

Table 5.4 Stiffness constants ................................................................................. 74

Table 5.5 Summary of Band gap .......................................................................... 81
LIST OF ABBREVIATIONS

Density functional theory .............................................. DFT
Scanning tunneling microscopy ....................................... STM
Two-dimensional ......................................................... 2-D
van der Waals .......................................................... vdW
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THIS THESIS IS DEDICATED TO MY BELOVED PARENTS.
CHAPTER 1
INTRODUCTION

Two-dimensional (2-D) materials have a thickness of a few Angstroms or less. They show unusual and novel properties, due to the rich and novel physical phenomena that occur when electronic and thermal conduction are limited to a plane. More than eighty years ago, Landau and Peierls showed theoretically that perfect 2D crystals could not exist [1–3]. Because of this rather general and fundamental result, numerous investigations of 2-D materials have been delayed until recently. In 2004, flakes of graphene (single layer of carbon atoms that makes graphite) have been successfully isolated by exfoliation from graphite. The key in reconciling Landau’s theory with the recent isolation of graphene is understanding that the excitations required to bend a graphene layer out of its plane are infinitesimally small—hence, the graphene crystal is not strictly in 2-D but contains measurable ripples at any finite temperature. After this realization, 2-D materials became some of the most intensively investigated category of materials in recent years [4–7].

1.1 Brief overview

As mentioned, the starting point was the isolation of single-atomic layer of graphite, freely suspended in vacuum or air [8]. Graphene has several outstanding properties, such as very high thermal conductivity (3000 $W m^{-1} K^{-1}$) and a very high mechanical stiffness (1060 GPa) [9–12]. Furthermore, the monolayer of graphene showed a remarkable electronic transport properties [11, 13, 14]. From the point of view of electronic conduction, graphene is termed a semimetal with a zero bandgap. This is due to the contact of the valence and conduction band at a single point, the same point through which the Fermi level passes. Due to this small contact of the conduction and valence bands, the electronic structure and behavior of graphene displays high sensitivity to external electric fields, deformation, doping, and adsorbates, making the graphene an interesting candidate material for producing
sensors [15]. Furthermore, a very high thermal conductivity of a suspended single-layer graphene has been calculated, which makes graphene a candidate for thermal management of electronic devices [16]. These properties have not only theoretically and numerically have been predicted, but also experimentally confirmed [14, 17], thus starting a new field—that of 2-D materials.

Materials scientists and organic chemists are designing new synthetic methods to synthesize high-quality single layers, while engineers are fabricating innovative devices to utilize graphenes extraordinary properties. Due to high, dissipationless conduction, graphene has been hypothesized initially as promising material for nanoelectronic applications. However, any electronic application would require graphene to be isolated from, e.g., metallic substrate onto which it grows. Furthermore, to use graphene as an active element in devices requires the presence of a bandgap—otherwise graphene could only be used lead connecting active elements and not as active element itself. Even if graphene is engineered as a smallbandgap semiconductor, it would have to be grown or transferred on an insulating substrate because if used on the metal substrate on which it has grown, then that metal substrate would significantly alter its properties.

Because of the need for engineered band gap and insulating substrate, soon after the initial excitement of synthesizing graphene and discovering its unusual properties [1], scientific efforts have turned towards other materials that could be used by themselves in various applications, or in conjunctions with graphene layers. For example, instead of trying to engineer the electronic properties of graphene, finding another 2-D material which already has a desired bandgap appears as good alternative especially if some of these materials are easier to obtain or to synthesize. For example, layered materials known as transition metal dichalcogenides (e.g., MoS$_2$) already have a semiconducting bandgap of 1.8 eV (Section 1.2 below). Several currently pursued 2-D materials are briefly described below.
1.1.1 Hexagonal boron nitride (hBN)

Growth of a large-area, single or bilayer graphene with a low cost, limited only by the size of the champer, and via ambient pressure CVD on Ni films had been reported [18]. The growth of graphene monolayers on metals substrates such as Ru, [19, 20], Pt [21, 22], Ni [23, 24] and Ir [25, 26] is well known. Hydrocarbon methane CH$_4$ is more stable than acetylene (C$_2$H$_2$) at high temperature (e.g. 800-1000$^\circ$C) as precursors for graphene growth [27]. More than one layer of graphene can form on Ni substrate, while usually only one layer forms on Cu substrates [28]. Using similar substrates, hBN can also be grown using CVD on the entire Ni surface may be limited by the size of the Ni single crystal grains [29]. At low pressure and using CVD on the Cu substrate, and using Ammonia borane as BN precursor one can synthesize thin layers of hBN [30]. Boron nitride films were deposited on (001) silicon substrates using plasma CVD and using a HeN$_2$BF$_3$H$_2$ gas system as BN precursor [31].

Large area of h-BN films consisting of two to five atomic layers have been synthesised using CVD, using Cu substrates and ammonia borane precursors [32]. Hexagonal Boron nitride (BN) is structurally analog to graphene; one of the two C atoms in the primitive cell is replaced by B, and the other by N. An experimental study showed it is possible to segregate one or more layers of hexagonal h-BN [33]. The elastic modulus of BN is in the range of 200 - 500 N/m. hBN has high a optical band gap of 5.5 eV [32].

A high degree of control over the electronic properties of thin films is the key piece of know-how that allows the production of modern integrated circuitry [34]. By using the technique heterostructures of graphene and h-BN, we should be able to control the electrical properties, which could lead to novel thought-provoking electronic applications. Graphene and hBN have similar crystal structures with a nearly the same lattice constant. Nevertheless, pristine graphene is a zero-bandgap semimetal with curiously high carrier mobility at room temperature [1, 35, 36]. Research on combinations of 2-D layers can produce devices that have potential for high-frequency operation and large-scale integration [37].
1.1.2 Molybdenum disulfide (MoS$_2$)

A single layer of Molybdenum disulfide MoS$_2$ has been inspected by optical spectroscopy and found to have an intrinsic bandgap of 1.8 eV [38]. It has been mechanically exfoliated forming a nano-sheet, and used for making novel phototransistors with better photoresponsivity as compared with the graphene-based devices [39]. Large-area single crystalline monolayer sheets of MoS$_2$ have been manufactured on SiO$_2$, electrical [40]. The Youngs modulus for MoS$_2$ of a few (5 to 25) layers thick, freely suspended, has been measured to be 0.33 TPa, very high comparing to graphene oxide [41]. The electronic properties of MoS$_2$-graphene bilayer heterostructures have also been inspected and depend on the interlayer orientation of graphene with respect to MoS$_2$ [42]. The monolayer molybdenum disulfide (MoS$_2$) can be grown in a scalable manner, with the ability to control the atomic layer thickness on SiO$_2$ substrates [43]. Large-area MoS$_2$ atomic layers had been synthesized on SiO$_2$ substrates by chemical vapor deposition using MoO$_3$ as a precursor. [40]. The MoS$_2$ grows on few-layer h-BN films by using CVD, confirming that there is strong interaction between the MoS$_2$ and underlying h-BN [44]. A large area with layer controlled (monolayer, bilayer, and trilayer) of MoS$_2$ films on SiO$_2$/Si substrates, using low pressure CVD can obtained [45].

1.1.3 Silicene (Si)

2-D silicon has been obtained by the synthesis of epitaxial silicene sheets on a silver (111) substrate [46, 47]. The elastic stiffness of silicene for the zigzag and armchair directions have been calculated from molecular dynamics simulations, and their values were 50.44 N/m and 62.31 N/m, respectively [48]. The electronic properties of silicene have been examined using the first principles simulations, and it was found that silicene is zero bandgap semimetal [49]. After the analysis of the chemical, magnetic and electronic properties of silicene were seen to display some of the same trends as graphene, which may allow silicen to become a viable candidate for 2-D materials-based electronic devices [50]. It has been reported that under increasing perpendicular electric field, the monolayer of silicene can drastically change its
electronic properties [51].

1.1.4 Germanene (Ge)

Germanene has been obtained by growth an atom-thin germanium layer on the gold (111) surface [52]. Also another growth of Germanene has been done on platinum (111) [53]. It has been reported that the germanane had much smaller in-plane stiffness than both graphene and boron nitride nanoribbons, which make germanene easier to stretch [54]. Its electronic properties have been inspected: germanene is a direct-gap material, with average gap of about 3.2 eV, so it is also material that has tremendous potential for novel optoelectronic applications [55, 56].

1.1.5 Phosphorene (P)

Phosphorene is a single or few layers of black phosphorus and is obtained by mechanical exfoliation only [57, 58]. Experimentally, the Young’s modulus of few-layer black phosphorus have been measured for both zigzag and armchair directions and found 58.6 ± 11.7 and 27.2 ± 4.1 GPa, respectively [59]. First-principles calculations show a significant band gap of 1-4 layers of phosphorene, with a direct band gap [60]. The effect number of layers on the band gap has been calculated, and observed that the band gap changes dramatically with the number of layers [61].

1.2 Key issues in 2-D materials and role of theoretical investigations

*Synthesis and its mechanism.* There are several key issues that generally appear when pursuing the investigation of 2-D materials beyond graphene. The first key issue is the synthesis of any new 2-D material, which would require either small changes to older methods, or new methods of growth altogether. In the examples given above, silicene as a single layer of Si atoms is highly reactive and cannot exist by itself: the metallic substrate is not only necessary for synthesis of Si from a precursor gas (usually silane) but also imparts stability to silicene: as such, silicene cannot be removed from the metallic substrate (with the purpose
of transferring it elsewhere) because it would be destroyed in the process. In other cases, for example the case of hBN, multiple layers can be grown on a metallic substrate and some of them can be removed and transferred on inert substrates. While sometimes synthesis techniques can be “borrowed” from other 2D materials, most of the times different 2D materials require different chemistry and/or thermodynamics to enable their growth. For example, it is rather straightforward to grow graphene on copper, but virtually impossible to grow phosphorene on copper. Chapter 2 and Chapter 3 deal with synthesis issues for different 2-D materials, phosphorene and multilayer hBN, respectively. A more subtle but important aspect of synthesis is also understanding how to control what particular polymorph would grow: for graphene and hBN, this is a non-issue since there is only one crystal structure in each case. However, for phosphorene or silica –both of which displaying several polymorphs, it is important to grow the polymorph with desired properties.

*Effect of the substrate of structure and properties* 2-D materials for high quality are usually grown on substrates, which are often metallic so as to enable their formation via catalyzed processes from precursor gases. Once grown, the 2-D materials certainly interact with the substrates, sometimes strongly (chemically) sometimes weakly (van der Waals, vdW) [62, 63]. The interaction with the substrate can give rise to significant large scale periodic patterns called moiré structures, can affect (usually deleteriously) the electronic properties of the 2D material grown on them (hBN, graphene), but can also impart chemical and mechanical stability to an otherwise unstable layer (silicene, germanene, 2-D silica). In all cases, there is significant interest surrounding the effect of the substrate on the structure, properties, and stability of the 2-D materials. Representative of the issue of how substrates can affect structure and properties, Chapter 4 deals with the effect of the substrate on the morphology and electronic properties of an hBN monolayer.

*Control of properties via synthesis of different polymorphs* Graphene and boron nitride as 2-D materials have one single structure, the honeycomb lattice. However, it is conceivable that other materials (such as silica, phosphorene) can form in several different polymorphs
due to their richer phase diagram. Even though these phase diagrams are constructed and tabulated for 3-D phases, the presence of a multitude of 3-D phases often suggests that there could be multiple polymorphs for the 2-D phases as well. An important approach under the theme of controlling the properties via different polymorph structures (or designing the 2D material to have desired properties) is a high-throughput computation framework in which a large number of structures is created, optimized according to some protocol (usually global optimization methods), and then subject to computation of various properties (electronic, mechanical, piezoelectric, dielectric, magnetic, etc). Similar protocols have been pursued successfully for 3-D materials, but seem in infancy for 2-D materials. More commonly, heuristic structures are proposed and investigated with respect to desired properties, and we will show an example of this heuristic approach in Chapter 5.

The work in this thesis contains portions that fall under each of key issues mentioned above. In the very dynamic field of 2-D materials, the work here cannot be, and does not aim to be comprehensive, but rather addresses a few outstanding issues.

1.3 Research work in this thesis and specific contributions of the candidate

As mentioned, Chapter 2 and Chapter 3 deal with two current synthesis issues, Chapter 4 addresses one example of the effect of the metallic substrate on the structure and properties of the 2D hBN grown on it, and Chapter 5 shows examples of how different polymorphs of the same 2-D material determine vastly different properties.

1.3.1 Ch. 2: Necessary conditions for phosphorene growth on graphene- or boron-nitride-covered metals

In this chapter, it is hypothesized that phosphorene can be grown on hBN- or graphene-covered metallic substrates. It is shown that these substrate can still bind the main molecular precursors that can lead to growth of phosphorene. Abdulfattah Abdulslam (AA) is the sole computational student or postdoc on this project. As such, he performed all the adsorption and reaction barrier calculations on the project. Chapter 2 is expected to become a theory-
lead publication soon, with the other authors contributing experimental insight or theoretical guidance.

1.3.2 Ch. 3: Growth of a bilayer hexagonal Boron-Nitride on Copper substrate

This chapter uses literature insight to initiate investigations of the hypothesis that B-containing precursors can adsorb first on the substrate, pyrolyze, and activate the adsorption and dehydrogenation of the second precursor (ammonia). It is expected that this work could lead to a theory-only publication, provided that sufficient insight can be gained in regard to interaction of the different radicals on the substrate. AA is the sole computational student on this project, performing the adsorption calculations for precursors and their radicals, and comparing with recent literature.

1.3.3 Ch. 4: Corrugation of hexagonal Boron-Nitride monolayer on Palladium

This work was motivated by recent experimental work from collaborators at University of California Los Angeles dealing with scanning tunneling microscopy of hBN/Pd. The chapter shows a theoretical model for explaining the possibility well-oriented hBN layers on palladium can have both flat and corrugated structures due to the propensity of the layers to bend. AA was the only computational student or postdoc on the project, which resulted in an experimentally-led manuscript submitted to Nano Letters.

1.3.4 Ch. 5: Mechanical and electronic properties of 2D silica configurations

This chapter investigates several 2-D silica configurations and determined their mechanical and electronic properties. It is an example of how much the polymorphs can affect the electronic properties, going in this case from metallic to insulating behaviour depending on the 2-D polymorph. AA is the sole computational student on this theory-only project, which is expected to lead to a publication within the calendar year.
NECESSARY CONDITIONS FOR PHOSPHORENE GROWTH ON METALLIC SUBSTRATES

Synopsis: Phosphorene has emerged as a highly sought-after new 2-D material, but its synthesis via chemical vapor deposition (CVD) on metals remains a major challenge. Although successful for the growth of graphene of high quality over large areas, the CVD synthesis route fails because all metals have a tendency to form stable phosphides, preventing the growth of phosphorene from gaseous precursors deposited on metal substrates. In this chapter, the possibility of using metal surfaces (covered with graphene or boron nitride) as substrates is explored: the passivation with boron nitride or graphene monolayers is proposed as a way to prevent the formation of phosphides. With these substrates, the phosphorene growth from three common precursors, $\text{P}_2$, $\text{P}_4$, and $\text{PH}_3$, is analyzed. Attachment of the precursors to the substrate is the first condition for a monolayer to form. Using DFT calculations, we find that these precursors and the radicals derived from them still attach to Cu(111) and Ni(111) when passivated with graphene or hBN, thereby suggesting potentially viable new substrates for growing phosphorene via CVD. Another condition is that the precursors decompose into radicals, which we show for the case of $\text{PH}_3$. Therefore, our computational results provide evidence that two necessary not sufficient-conditions for growth of phosphorene can be met, which should provide useful guidance for future experimental endeavors.

2.1 Introduction

Phosphorene—single or few layers of the black phosphorus (BP) allotrope, is an intriguing 2-D material exhibiting numerous exciting properties, similar to graphene [64, 65]. Unlike graphene, however, phosphorene is a semiconductor with a direct bandgap Figure 2.1 that varies strongly with the number of layers from 0.3 eV to about 2 eV [66, 67].
This range covers bandgap values between graphene (semimetal) and transition metal dichalcogenides (TMDs, bandgaps of 1.8 eV). The bandgap and its layer dependence, along with the high carrier mobility large on/off ratio at room temperature, make phosphorene well suited for electronic, optoelectronic, and photovoltaic applications. In order to access these and many other technological possibilities that could be open by using phosphorene in devices, it is necessary to synthesize high quality, large area phosphorene sheets, ideally with a controlled number of layers. Phosphorene sheets were first obtained by mechanical exfoliation of BP similar to graphene, solution methods for BP exfoliation have also been developed.

Bottom-up approaches (e.g. chemical vapor deposition, CVD) while immensely successful for graphene on many metallic substrates, are only now emerging for phosphorene and involve formation of an intermediate phase (white or red phosphorus) that can subsequently be converted to BP in the presence of mineralizing agents and pressure. Because of the intermediate phase, the CVD procedures for BP growth do not yield high-quality phosphorene sheets with controllable number of layers. Analysis of the phase diagrams for metal-C and metal-P show a key difference with respect to graphene.
Figure 2.2. For graphene, C is incorporated in the metal lattice as interstitials during the CVD of hydrocarbons at high temperature: upon cooling, C atoms from the lattice segregate at the surface and form graphene because of the large stable graphite + fcc region in the phase diagram (Figure 2.2(a)). The phase separated region(s) in the metal-P phase diagram (Figure 2.2(b)) involve either pure Cu and a phosphide (Cu$_3$P), or two phosphides (Cu$_3$P and CuP$_2$): in either case, phosphorus is bound into the phosphide it is not thermodynamically feasible for it to segregate at the metal surface. As a result, the mechanism of CVD growth of phosphorene on metal using gaseous precursors is vastly different than that for graphene, and in fact unknown. This work proposes such a mechanism in which phosphorene could grow on passive Ni or Cu substrates, from gaseous precursors, by heterogeneous catalysis similar to hBN on these substrates.

Figure 2.2: (a) Typical metal-P phase diagram, showing the formation of various phosphides. At intermediate P concentrations (i.e. not corresponding the phosphide stoichiometry), there is decomposition into Cu and Cu$_3$P, or between Cu$_3$P and CuP$_2$, but there is never segregation of P at the surface as encountered for example in the Cu-C phase diagram (b). Reproduced from [86] with permission from Springer, and from National Physical Laboratory (open access).

Hence there is a need to seek CVD growth paradigms for phosphorene, which should necessarily involve arresting the formation of phosphides. This can be achieved by prior growth of a monolayer of graphene or hexagonal boron nitride (hBN) on common metal
substrates. The phosphorus precursors, i.e., P$_2$, P$_4$, or PH$_3$, are large enough and inert enough that they cannot penetrate the monolayer graphene [87] or hBN (similar lattice constant) to reach the metal hence the phosphide formation is avoided. There still remains the issue of whether there is sufficient adsorption of these precursors on graphene- or hBN-covered metals. In this work, we use two common substrates, Ni(111) and Cu(111), based on their range of interaction with monolayer hBN or graphene: Ni is strongly interacting, while Cu is weakly interacting. Using density DFT calculations, we determine the adsorption energies of all three precursors and their radicals on the four model substrates (i.e., graphene- or hBN-covered Ni and Cu). Subsequently, we focus on one of these precursors, PH$_3$, and analyze the dehydrogenation reactions on the surface: the formation of these radicals on the surface will likely enable the formation of phosphorene by polymerization of P chains on the surface.

2.2 Details of the DFT calculations

To analyze the adsorption of precursor molecules and radicals on the hBN-covered Ni and Cu surfaces, we have used the plane-wave based DFT package Vienna Ab initio Simulation Package VASP [88, 89] to perform calculations (DFT) in the framework of the generalized gradient approximation (GGA) with the Perdew-Burke-Ernzerhof (PBE) functional [90]. The weak van der Waals (vdW) interactions between monolayer and the metal surface, and between the adsorbed molecules and the graphene- or hBN-covered metal substrates, were included using the DFT-D2 vdW functional of Grimme [91]. We have carried out spin-independent DFT calculations (geometry relaxations) calculations for P$_2$, P$_4$, and PH$_3$ (Figure 2.3) and their intermediates reaction intermediates P, PH, PH$_2$. The reactivity of surfaces is assessed through the adsorption of these reaction intermediates, and in the case of phosphine (PH$_3$) also by calculating the barriers for various steps of dehydrogenation. We have studied the adsorption of radicals on different sites on graphene/Cu, hBN/Cu, graphene/Ni, and hBN/Ni, using a three layer thick, 4 × 4 Ni(111) or Cu(111) slab with either graphene or hBN monolayer on it, with an 18 Å vacuum spacing. The hBN sheet in our computational
supercell has the registry with the substrate proposed by Bokdam et al., with the N atom above a top layer Cu or Ni atom, and the B atom above a hollow site [92]. Keeping fixed the bottom two layers of Cu and Ni, the geometries were relaxed via conjugate-gradient in the presence of dipole corrections using a plane-wave cutoff of 500 eV, a Monkhorst-Pack k-point grid of $3 \times 3 \times 1$, and a force tolerance criterion of 0.02 eV/Å.

For the phosphine precursor, PH$_3$, we have also analyzed the dehydrogenation processes by calculating the associated energy barriers using the nudged elastic band (NEB) method [93–95]. In this method, the initial (reactants) and final (products) are known and intermediate configurations between them are generated by a python script. For determining the barriers, we have used NEB with 9 intermediate configurations between the initial and final. During the NEB, these configurations are optimized so as to yield the minimum energy pathway between the initial and final configurations. From the final optimized configurations and their energies, we determine the reaction pathway and the corresponding energy barrier.

Figure 2.3: Molecules making up the gaseous precursors that can be used for the synthesis of phosphorene: (a) P$_2$, (b) P$_4$, and (c) PH$_3$.

2.3 Results on adsorption of precursors and their radicals

Figure 2.4, Figure 2.5, Figure 2.6, and Figure 2.7 show the adsorption sites considered for the precursors and (some of) their radicals. For PH$_3$, PH$_2$, PH, P and P$_4$, we considered four high symmetry sites above which they could be placed: N (or top, for graphene-covered
Figure 2.4: Adsorption locations for $\text{PH}_x$ ($x = 0,1,2,3$), vertical $P_2$, vertical $P_4$ (C, hex, bridge), and the horizontal $P_2$ molecules (a-c).

Figure 2.5: Adsorption locations for $\text{PH}_x$ ($x = 0,1,2,3$), vertical $P_2$, vertical $P_4$ (C, hex, bridge), and the horizontal $P_2$ molecules (a-c).
Figure 2.6: Adsorption locations for PH_x (x = 0,1,2,3), vertical P_2, vertical P_4 (N, B, hex, bridge), and the horizontal P_2 molecules (a-d).

Figure 2.7: Adsorption locations for PH_x (x = 0,1,2,3), vertical P_2, vertical P_4 (N, B, hex, bridge), and the horizontal P_2 molecules (a-d).
metals), B (or hollow), bridge bond, and the center of the hexagon, hex (Figure 2.4 to Figure 2.7). PH$_x$ are placed with the P atom above the site, while P$_4$ are placed with one corner of the tetrahedron above the site and the opposite plane away from the surface. For simplicity, this is the only orientation in which we placed the P$_4$ molecule, even though there are other high-symmetry orientations in which this molecule can face the substrate, e.g. with an edge down or with a facet down. The P$_2$ molecules are placed vertically (sites N (top), B (hollow), bridge and hex) or horizontally (locations (a) through (e) in Figure 2.4 to Figure 2.7. All the adsorption energies calculations are listed in Tables Table 2.2, Table 2.3, Table 2.4, and Table 2.5.

![Figure 2.8: Adsorption energies for the P$_2$ molecule on graphene- or hBN-covered Ni and Cu substrates, for several selected positions. The symbols $\perp$ and $\parallel$ stand for the vertical and horizontal orientations of the molecule, respectively; C is a top site, bb bridge site, and the other symbols are shown in Figure 2.4 to Figure 2.7](image)

First, we analyze the P$_2$ molecule on the four substrates. This precursor adsorbs somewhat strongly on the hBN- or graphene-covered Ni, and more weakly when the metal is Cu (Figure 2.8). This is expected, given the proximity of the Ni substrate to the graphene
or hBN (chemical binding [62]), as opposed to the Cu metal which is vdW bonded to the monolayer [63, 85]. This proximity is expected to have a catalyzing effect on the dissociation of the P$_2$ molecule or other precursors. By itself, the P$_2$ molecule has a bond energy of 9 eV, with an adsorption energy of the order 0.65 eV (Figure 2.8). For two P atoms adsorbed on separate sites, the adsorption energy is approximately $2 \times 3.25 \text{ eV} = 6.5 \text{ eV}$ (Figure 2.8, adsorption of P on hBN/Ni). Therefore, we expect a barrier of at least $9.656.5 = 3.25 \text{ eV}$. This barrier is rather high, and it could be overcome for large fluxes and/or exposure time, or, presumably, in the presence of other radicals on the surface. For example, atomic hydrogen and other radicals have been shown to influence the films structure and morphology in other cases [96–98]. The reason for this expectation is that in separate studies, there was significant evidence that hBN can grow from borazine on graphene-covered nickel [99–101]. The barriers are significant in this case also (a computed N-H bond energy of 6.5 eV), as they involve the dehydrogenation of borazine nevertheless, they were overcome by using a well-chosen interplay between flux, exposure time, and temperature, to the final result that a monolayer hBN grows on a very weakly catalytic substrate (graphene/Ni) [99]. Similar to these previous studies [99–101], it is reasonable to envision that flux, exposure time, and temperature can be tuned to lead to the nucleation and growth of a phosphorene layer from the P$_2$ precursor. The analysis of P$_4$ adsorption on the four selected substrates suggests that this molecule adsorbs somewhat more strongly on the hBN/Cu substrate as opposed to any other one. The dissociation of this molecule is more facile, since our calculations reveal that the energy per bond in P$_4$ is 1 eV smaller than that in P$_2$. The adsorption energy calculations suggest no particular impediment against growing from P$_4$. However, this molecule is larger than P$_2$ or PH$_3$ and non-planar, hence it diffusion could be slower: this means that a large flux is more conducive to the growth on amorphous structures, as P$_4$ can accumulate without significant dissociation or diffusion on the substrate: once such nucleation of amorphous P islands proceeds, there is no factor to drive the formation of 2-D phosphorene.
Figure 2.9: Adsorption energies for PH$_x$ (x = 0,1,2,3) on graphene- or hBN-covered Ni and Cu substrates.
2.4 Results on energy barriers for dehydrogenation on the surface

We now discuss the adsorption and dehydrogenation of PH$_3$ on the substrates. The lowest adsorption energies across the adsorption locations considered are shown in Figure 2.9. The first important conclusion is the PH$_3$ sticks to all substrates, for example more strongly than ammonia [85]. The barrier for the first dehydrogenation step (PH$_3$ → PH$_2$) can be assessed comparatively by adsorption energy of PH$_2$, by virtue of the Evans-Polanyi principle [102–105]. The stronger the adsorption of PH$_2$, the lower the barrier for the first dehydrogenation step. In this respect, the dehydrogenation process should be the most facile on the hBN/Ni and graphene/Ni substrates. This may also have been inferred by virtue of the fact that the Ni substrate is closer (2.1 Å) to the monolayer (graphene or hBN) compared to Cu, which is van der Waals bonded (~3 Å): this proximity facilitates a better transmission of the catalytic activity of the metal [106]. through the monolayer covering it. For a better assessment of the initial stages of phosphine deposition, we also compute the energy barriers and reaction pathways for the two dehydrogenation steps PH$_3$ → PH$_2$ and PH$_2$ → PH where in radicals and atomic H remain on the substrate, i.e., prior to atomic H migration and its molecular desorption from the surface. In other words, we are computing the reaction barrier for the bottleneck part of the dehydrogenation reactions, in which an H atom splits from PH$_3$ or PH$_2$ by virtue of the catalytic activity of the substrate, or by interactions with other radicals. The reaction barriers are listed in Table 2.1 for each stage and each substrate.

Table 2.1: Calculated reaction barriers for the dehydrogenation steps on hBN or graphene covered Ni or Cu substrates.

<table>
<thead>
<tr>
<th>Substrate</th>
<th>$P$H$_3$ → $P$H$_2$ + $H$</th>
<th>$P$H$_2$ → PH+$+$ $H$</th>
</tr>
</thead>
<tbody>
<tr>
<td>hBN/Ni</td>
<td>1.937</td>
<td>2.487</td>
</tr>
<tr>
<td>hBN/Cu</td>
<td>3.339</td>
<td>2.928</td>
</tr>
<tr>
<td>gr/Ni</td>
<td>1.627</td>
<td>1.145</td>
</tr>
<tr>
<td>gr/Cu</td>
<td>2.320</td>
<td>1.623</td>
</tr>
</tbody>
</table>

The NEB for the reaction pathways and the associated energy barriers are shown in Figure 2.10, Figure 2.11, Figure 2.12 and Figure 2.13.
Figure 2.10: reaction pathway for the dehydrogenation step $\text{PH}_3 \rightarrow \text{PH}_2 + H$ on gr/Cu and gr/Ni surfaces

Figure 2.11: reaction pathway for the dehydrogenation step $\text{PH}_3 \rightarrow \text{PH}_2 + H$ on hBN/Cu and hBN/Ni surfaces
Figure 2.12: reaction pathway for the dehydrogenation step $PH_2 \rightarrow PH + H$ on gr/Cu and gr/Ni surfaces

Figure 2.13: reaction pathway for the dehydrogenation step $PH_2 \rightarrow PH + H$ on hBN/Cu and hBN/Ni surfaces
In experimental conditions, the substrate by itself may not be sufficient to lead to dehydrogenation, but temperature, flux, and diffusion of atomic or molecular hydrogen or radicals on the surface can potentially make these reactions feasible. It is instructive to notice that some of the barriers listed in Table 2.1 are similar to those encountered in the dehydrogenation of ammonia directly on the catalytic substrate Cu(111), 1.84 eV and 1.59 eV ([85] and references therein). While this may come as a surprise, we note that phosphine is in general more reactive than ammonia, hence it can dehydrogenate reasonably easily when the metallic substrate is covered, e.g., with graphene.

Based on these adsorption calculations, the growth of very thin layers of phosphorus should proceed on either of these two substrates (i.e. hBN/Ni and gr/Ni) from the PH$_3$ precursor. Two necessary conditions for growth of phosphorus are met, namely avoiding the formation of a phosphide and catalyzing the dehydrogenation of the precursor. It is not a priori clear that the growth would yield a phosphorene layer, since these necessary conditions are not automatically sufficient, i.e., they do not address the later stages of growth during which different competing allotropes of phosphorus may compete to form on the substrate. We surmise, however, that a control of the temperature and flux of the precursors to the substrate can yield the desired low energy allotrope.

2.5 Conclusions

Therefore, we summarize the guidance for future experiments that is offered by these calculations as follows. In order to enable the growth of 2-D crystalline phosphorene, is is feasible to first grow graphene or boron nitride on them so as to prevent the formation of phosphides. Secondly, the best precursors are PH$_3$ and P$_2$, or a combination thereof. Thirdly, the best substrates are hBN- or graphene-covered Ni, since it these two substrate have the highest ”activity” as assessed by the strength of adsorption of the precursors and their radicals. To expand on this results and narrow the search field for suitable substrates, we specify that the metal simply has to be Ni, rather than any other strongly interacting metal. The reason for this prescription is that other metals with strong interactions (e.g., Ru
do not have surface lattices that match that of graphene or hBN that cover the substrate. This lattice mismatch is accommodated by the formation of large, corrugated moire patterns in which there are regions strongly bonded to the substrate (which will contain adsorption sites for the precursors) and regions that are away from the substrate (an example shown in Chapter 4) and vdW bonded to it: for the vdW region, the adsorption is weak which is likely to prevent the formation of continuous 2-D phosphorene layers.

Table 2.2: Adsorption Energy of PH(0,1,2,3), P$_2$ and P$_4$ Molecules on gr/Cu

<table>
<thead>
<tr>
<th>Substrate</th>
<th>Molecules</th>
<th>Positions</th>
<th>Adsorption Energy (eV)</th>
</tr>
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<tbody>
<tr>
<td>gr/Cu</td>
<td>PH$_3$</td>
<td>C</td>
<td>-0.2668</td>
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Table 2.3: Adsorption Energy of PH(0,1,2,3), P$_2$, and P$_4$ Molecules on gr/Ni

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<th>Substrate</th>
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<th>Positions</th>
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Table 2.4: Adsorption Energy of PH(0,1,2,3), P₂ and P₄ Molecules on hBN/Cu

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<th>Positions</th>
<th>Adsorption Energy (eV)</th>
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Table 2.5: Adsorption Energy of PH(0,1,2,3), P$_2$ and P$_4$ Molecules on hBN/Ni

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CHAPTER 3
GROWTH OF BILAYER HEXAGONAL BORON NITRIDE ON COPPER SUBSTRATES

Synopsis: Hexagonal boron nitride (hBN) is an important insulator with nearly the same lattice constant as graphene. With its insulating properties and similar lattice constant, hBN has become an important support for graphene, and in general as an ultrathin 2D dielectric material: hence, synthesizing hBN has become important in its own right. Recent CVD growth have shown that hBN can be synthesized on metallic surfaces, since the metal substrate acts as a catalyst on the precursor molecules and enables their reactions on the substrate and the formation of the first layer of hBN. However, after the growth of the first hBN layer, the catalytic effect of the metal ceases for the next precursors that come to the surface, because they only meet the (passive) hBN layer. It is therefore intriguing why additional layers of hBN can be grown \[109\]. Most often the growth of additional hBN layers is observed for the case when there are two precursors, i.e., one source of boron (borane, diborane, triethylborane (TEB), etc) and one source of nitrogen (e.g., ammonia). Since the catalytic activity of the substrate is virtually voided after the growth of the first hBN layer, recent work \[85\] suggested that in the case of growth from two precursors molecules one of the precursors decompose thermally at the surface (pyrolizes), and the surface bound radicals resulting from it activate the reaction with ammonia that ultimately leads to the formation of a new hBN layer. Since this recently proposed mechanism has focused mostly on the adsorption and dehydrogenation of ammonia on hBN-covered Cu, in this chapter we look at the other precursor as well, i.e. the source of boron. We study the adsorption of borane and TEB, as well as ammonia, on Cu, hBN/Cu and hBN –with the pure hBN layer meant to simulate the adsorption on multiple hBN layers covering the substrate and therefore fully passivating it. We find that, indeed the boron precursors, and the radicals resulted
from them adsorb on the hBN-passivated surfaces and could thereafter act as catalytic sites themselves for the adsorption and dehydrogenation of ammonia.

3.1 Motivation

Hexagonal boron nitride (h-BN) is a layered material similar to graphite. In its 2-D version, hBN is a promising dielectric substrate for growing graphene and other 2-D materials [32]. hBN shows many unique physical and electronic properties such as high thermal conductivity, low density, high melting point, high-temperature stability [110], and high mechanical strength [29, 30]; also, it is an isolator with band gap 5.7 eV [111]. hBN can be used for graphene-based nanoelectronic devices as a chemically inactive substrate [112, 113], and for atomically thin capacitors [114].

3.2 Current state of the art

hBN in atomic monolayers is largely grown from single precursors, either borazine or ammonia borane, via chemical vapor deposition (CVD) on various metallic substrates [110, 115, 116]. Flat hBN monolayers can be grown on metals with small lattice mismatch (Cu) [63, 117]. However, for various application control over the quality, uniformity, and the number of layers is necessary [29, 30, 32, 118, 119]. The mechanism of growing multiple hBN layers on metallic substrate has not been well understood; recently, it was proposed [85] that when using two precursor gases (one source of boron, and one source of nitrogen) then one of the precursors pyrolizes at the surface and helps activating the other one (ammonia, the source of nitrogen). Siegel et al. [85], however, focused mostly on the adsorption and dehydrogenation of ammonia; guided by their work, here we study the adsorption of the source of boron and their radicals as well.

3.3 Adsorption geometries and computational details

In order for any reaction to proceed at the surface, the precursor molecular have to be able to adsorb (bind) to the surface. We therefore focus in this study on adsorption of
precursors and their radicals. As substrates, we use bare Cu, hBN/Cu (one layer of hBN on Cu), and single layer hBN. The single layer hBN is used as an approximation of the limiting case in which many hBN layers already cover the copper substrate, and therefore none of its catalytic effect reaches the surface.

We have performed the DFT calculations using the Vienna Ab-initio Simulation Package (VASP) [88], with the generalized gradient approximation (GGA) with the Perdew-Burke-Ernzerhof functional [90]. The interactions between hBN layer and a Cu(111) substrate are modeled in the calculations using the DFT-D2 method of Grimme. We have studied the adsorption of molecules and their radicals on different sites on Cu(111) Figure 3.4, hBN Figure 3.6, hBN/Cu Figure 3.5, using a three layer of Cu, 4 × 4 Cu(111) slab , with an 18 Å vacuum spacing. Keeping fixed the bottom two layers of Cu, the geometries were relaxed via conjugate-gradient in the presence of dipole corrections using a plane-wave cutoff of 500 eV, a Monkhorst-Pack k-point grid of 3 × 3 × 1, and a force tolerance criterion of 0.02 eV/Å for relaxations.

The molecules studied (along with their radicals) are TEB (Figure 3.1), borane (Figure 3.2), and ammonia (Figure 3.3). As such, these calculations in this chapter are relevant for two synthesis procedures, one based on TEB and ammonia, and the other based on borane and ammonia.

![Figure 3.1: TEB (C₆H₁₅B) and its radicals C₄H₁₀B and C₂H₅B.](image-url)
Figure 3.2: Borane and its radicals, BH\textsubscript{x} (x = 1,2,3).

Figure 3.3: Ammonia and its radicals, NH\textsubscript{x} (x = 1,2,3) molecule
The adsorption energy usually depends on specific adsorption sites, so he have considered several high-symmetry adsorption sites on each of the substrates (Cu, hBN/Cu, hBN). These sites are shown in Figure 3.4, Figure 3.5 and Figure 3.6.

Figure 3.4: Adsorption locations for molecules on Cu(111) surface

Figure 3.5: Adsorption locations for molecules on hBN/Cu surface

3.4 Results

The adsorption results are discussed below for each precursor molecule.
3.4.1 Adsorption of TEB and its radicals

First, we analyze the tri-ethyl borane and its radicals: referring to Figure 3.7 for tri-ethyl borane, we note that the adsorption energy values for all three substrates are close to one another. The two-ethyl borane has stronger adsorption energy than one-ethyl borane. The most strongly bound radical is two-ethyl borane, and the difference between first layer and second layers adsorption energy is $\approx 2$ eV. The adsorption energies for TEB and its radicals on the high-symmetry sites on each substrate are shown in Table 3.1. For TEB, we note that adsorption depends mostly on the substrate, with the bare copper being the one interacting the strongest. Within any one given substrate, however, the adsorption of TEB depends only weakly on the exact sites. This observation, coupled with calculations of the molecule-substrate distances, indicates that TEB is weakly adsorbed on the metal (physisorbed). Its radicals, however, bind strongly since for these radicals the central boron atom has one or two dangling bonds. For the radical with two ethyl arms, the adsorption is chemical and depends strongly both on the substrate and on the exact site on the substrate (Table 3.1 and Figure 3.7). The radical with one ethyl displays similar trends as that with two ethyls, but the adsorption is very weak and somewhat independent on site for the hBN-covered substrates (hBN/Cu and hBN) (Table 3.1 and Figure 3.7).
Figure 3.7: Adsorption energies at the strongest binding sites for C\textsubscript{6}H\textsubscript{15}B, C\textsubscript{4}H\textsubscript{10}B and C\textsubscript{2}H\textsubscript{5}B on Cu(111), hBN/Cu, and hBN substrates.
3.4.2 Adsorption of borane and its radicals

Now we discuss the adsorption energy of borane and its radicals. According to the Figure 3.8 is clear that the values of adsorption energy for BH$_3$, BH$_2$, BH on hBN/Cu are almost the same values on hBN. Furthermore, the most adsorption precursor is BH, and the difference between first layer and second layers adsorption energy is $\approx 3$ eV. The adsorption energy for three substrate is given in Table Table 3.2.

![Figure 3.8: Adsorption energies for BH$_x$ (x = 0,1,2,3) on hBN, Cu(111), and hBN/Cu substrates.](image)

Figure 3.8: Adsorption energies for BH$_x$ (x = 0,1,2,3) on hBN, Cu(111), and hBN/Cu substrates.

3.4.3 Adsorption of ammonia and its radicals

Finally, we discuss the adsorption energy of ammonia and its radicals. As shown in Figure 3.9, the ammonia molecule NH$_3$ has almost the same adsorption energy on all three substrates. NH is the most adsorption radical. The adsorption energy on Cu pure metallic substrate and hBN/Cu metallic covered with hBN for NH are $\approx 5.6$ eV and $4.3$ eV $\approx$
respectively, therefore the difference between first layer and second layers adsorption energy is \( \approx 1.3 \) eV. Our results for a both ammonia and its radical on Cu(111) and hBN/Cu substrates are consistent with [85, 120]. The adsorption energy values for each substrate are reported in Table 3.3.

![Figure 3.9: Adsorption energies for NH\(_x\) \((x = 0,1,2,3)\) on hBN, Cu(111), and hBN/Cu substrates.](image)

3.5 Summary

Growth procedures with possibility to control the layer number of one or a few layers of hBN has been recently reported [29, 109, 121–123]. There is a clear evidence of a mechanism which relies on catalyst to crack the precursor and adsorption into substrate then forming hBN layer during cooling [123, 124]. The heterogeneous pyrolysis mechanism [85] is different, in that one precursors thermally cracks and then activates the other. The adsorption of ammonia on the second layer was less effective than tri-ethyl borane and borane. In summary, the DFT calculations calculations show that the second layer growth requires significant
adsorption energies, and the growth always encounter high kinetic barriers. Yet, these barriers are comparable with other systems for which it had been shown that nucleation and growth are possible. For boron sources, the tri-ethyl borane are more efficient than borane based on adsorption energy.
Table 3.1: Adsorption energy for TEB (3-Ethyl) and its radicals with 2- and 1-Ethyl groups.

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<th>Substrates</th>
<th>Position</th>
<th>Adsorption Energy (eV)</th>
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### Table 3.2: Adsorption energy of boron-containing molecules and radicals

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Table 3.3: Adsorption energy of nitrogen-containing molecules and radicals.

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CHAPTER 4
CORRUGATION OF HEXAGONAL BORON NITRIDE ON PALLADIUM
Part of φ Orientation-Dependent Corrugation of Two-Dimensional Hexagonal Boron Nitride Domains on Pd(111) submitted to The Journal of Nano Letters
Pedro Arias\textsuperscript{1}, Abdulfattah Abdulsalam \textsuperscript{2}, Abbas Ebnonnasir\textsuperscript{1}, Cristian V. Ciobanu\textsuperscript{2}, and Suneel Kodambaka\textsuperscript{1}

Synopsis: This work is part of a manuscript in preparation, recently submitted to Nano Letters. The work in the manuscript is joint experimental (performed at University of California Los Angeles) and computational: the latter was performed by the candidate at Colorado School of Mines, and is described in the sections below, with only a small section on experimental motivation. There is a recurring problem in the analysis of STM images obtained with a metallic tip when scanning geometrically corrugated surfaces. These corrugations occur at the atomic scale, but in addition to geometric corrugation there are electronic effects that change the (apparent) height measured by STM. Therefore, the STM data cannot directly be used to infer actual geometrical height variations (corrugations) on the surface, and has to be analyzed via, e.g., atomic scale computations and modeling wherein geometric corrugation are explicit. In this work, the corrugations measured for hBN on palladium have been analyzed using DFT calculations and interface energy modeling. The STM measurements suggest a bifurcation behaviour of the hBN monolayer on Pd in which both flat monolayers and "blistered" (having a morphology akin to that of bubble wrap) could exist together on the same hBN sheet. The phenomenological model presented here rationalize this behavior in terms of an energetic competition between chemical bonding (lower regions), vdW bonding (upper regions of the blisters), and bending energy of the sheet. At the same time, our DFT show that the hBN/Pd system can have domains with multiple

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orientations, some of which having the blistered morphology. These results are applicable for interactions between hBN sheet and other substrates in the intermediate range.

4.1 Introduction

As described in the previous chapter, hBN is an important substrate for nanoelectronics since it is insulating (at least in its free-standing state) and can serve as passivating agent for metal substrates. hBN can grow on a variety of transition metal surfaces such as such as Ni(111) [125], Pd(111) [125, 126] and Pd(110) [127], Pt(111) [125], Rh(111) [128], Ru(0001) [129], Ir(111) [130], and Cu(111) [131]. Graphene or other 2-D materials can be synthesized onto hBN-covered substrates. In addition, hBN is often investigated as a material for ultra-thin capacitors. As such, the morphology of hBN on different substrates becomes important, as the subsequent 2-D layers that could be grown on it would be bonded by weak vdW forces, and hence would be conformal to the hBN layer. Depending on the lattice mismatch with the substrate (defined as the difference in lattice constants between hBN and the substrate, divided by the lattice constant of the substrate), and on the strength of the interaction, hBN can acquire a variety of morphologies on the metallic substrate: (a) it is commensurate on Ni(111) due to the very low lattice mismatch, with the N atoms atop Ni atoms and the B atoms in the hollow site between them, (b) incommensurate and forming moire patterns on domains at vdW distance (∼3Å) from the substrate (e.g., on Cu(111)[63] or Ir(111) [130], and (c) incommensurate and strongly bonded to the substrate such as on Ru(0001)[129].

Previous studies [42, 62, 80, 117, 131–135] indicated that the properties of hBN can depend on the underlying substrate, in particular on the surface orientation and the interaction strength for the binding with hBN. For example, hBN/Ni(111) shows metallic or insulating behavior depending on the registry of B and N atoms on the nickel top layer [62]. hBN on weakly interacting Cu(111) [63, 131] and Pt(111) [125] surface, the properties of hBN are insulating, and multiple domains (regions with different orientation with regard to the substrate) have been observed. Certainly, the substrates referred to above fall into two clear categories [92]: strongly interacting (Co, Ni, Ti) and weakly interacting (Cu, Ir, Pt, Au etc).
There is an additional category, however, with a few metallic representatives (perhaps only one, Pd [92]) but potentially many metal oxides: qualitatively speaking, this is the category of intermediate interactions – neither too strong to be considered strictly chemical bonds, nor too weak so as to be considered pure vdW interactions. In this category, we expect lower bandgap for hBN (likely becoming semiconductor, or close to it), and fewer orientational domains on the substrate, than, for example of the vdW interacting Cu(111) substrate. Given that the intermediate value of the interactions and the fact that the lattice mismatch is large on Pd(111), it is not a priori clear if the hBN monolayer is always flat or can support actual geometric corrugations. These corrugations, as mentioned, can be important as they can serve as templates for the self-organizations of the large organic molecules or metallic clusters. In what follows, we described briefly experimental evidence (unpublished as of the date of the thesis defense) from collaborators at University of California Los Angeles that the Pd substrate can sustain several orientational domains of hBN and that some have geometric corrugations, while most are actually flat despite displaying apparent hill and valley patterns in STM.

4.2 Moiré Patterns on Metallic Substrates

Regardless of the interaction strength, the atomic layers of hBN on nominally flat metal substrates often form so-called moiré patterns. These patterns are periodic or quasi-periodic structures that form because the lattice constants of hBN ($a_{\text{hBN}}$) and the substrate ($a_{\text{Pd}}$) are different and the crystalline vectors of the layer and substrates are not aligned. Depending on the alignment on the periodic vectors of hBN and the substrate, there can be multiple spatial periodicities. To briefly explain the concept of moiré periodicity, in a theoretical one-dimensional situation in which the layer has the lattice constant of 2Å and the substrate a lattice constant of 5Å then the moiré periodicity would be the smallest common multiple of the lattice constants of the substrate and the layer, i.e. 10Å. This situation remains true in principle when turning to two dimensions; however, there are several complexities that arise:
(a) the lattice constants do not have a small common multiple, and both are rational numbers rather than integers
(b) the spatial periodicity is not only a function of the lattice constants of the hBN and the substrate, but also of the in-plane rotation of the hBN layer on top of the substrate, and
(c) the substrate and the lattice interact with each other, which often results in modifications of the ideal spatial periodicity of the moiré structures (by ideal periodicity we mean the periodicity that is obtained mathematically from overlapping the hBN and the metal top layer lattices) [136].

The spatial (quasi-)periodicity $\lambda$ of the moiré patterns of hBN on the Pd(111) surface is a function of the angle $\theta$ between two given crystalline directions, one on the hBN sheet (the so-called zigzag direction, [1-120]) and the other on the top Pd (111) layer (the [1-10] direction), described by [136]:

$$\lambda = \frac{a_{\text{Pd}}a_{\text{hBN}}}{\sqrt{a_{\text{Pd}}^2 + a_{\text{hBN}}^2 - 2a_{\text{Pd}}a_{\text{hBN}} \cos \theta}}. \quad (4.1)$$

This dependence is important as it constitutes a direct way to assess the crystalline orientation of the hBN layer on the substrate simply by measuring its spatial periodicity in STM images.

The function $\lambda(\theta)$, Equation (4.1), is plotted in Figure 4.1, which shows that the maximum spatial periodicity is achieved for $\theta = 0^\circ$, while the lowest periodicity is achieved for $\theta = 30^\circ$. As an illustrative example, atomic structure models corresponding to the moiré structures of hBN on Pd(111) observed in experiments are shown in Figure 4.2.

While the (horizontal) spatial periodicity $\lambda$ measured from STM scan has no intrinsic ambiguity other than usual uncertainties associated with the measurements, this is not the case for the height information obtained from STM. The way STM operates [137–141] is based on the tunneling of electrons between a sharp conductive tip and the “sample” (Figure 4.3), which in this case is the hBN-covered palladium. There is a potential difference maintained between tip and sample, and usually the STM is operated in a constant-current mode [138].
In this mode, the current between the tip and the sample is kept constant during the raster scanning of the sample by automatically (feedback loop) changing the distance between the tip and the substrate. If the tip encounters a geometric protuberance, then effectively the tip would be approaching the sample thus increasing the tunneling current: through the feedback loop, the tip is subsequently moved upward/away in order to maintain the current at the constant prescribed value. However, another reason why a tip height changes is that there could be regions on the substrate where there exists a larger density of states, and that tends to increase the tunneling current (Figure 4.3): to balance the increase in the current stemming from variable density of states across the sample, the tip height again has to change. Therefore the height profile $z = z(x, y)$ traced by the tip is not always reflecting actual height variations, but very often encumbers both geometric and electronic effects. For this reason, STM height profiles are called apparent height profiles. In the case of 2-D monolayers on metallic substrates, it is already known that there are situations in which the

Figure 4.1: The dependence of spatial periodicity $\lambda$ of orientation $\theta$, Equation (4.1).
Figure 4.2: Atomic structures for the moiré patterns associated with the experimentally observed periodicities $\lambda = 0.6, 1.8, 2.7$ and $2.8$ nm: these periodicities correspond to $\theta$ values of $24.6, 6.3, 1.1$, and $0.0$ °, respectively.

Figure 4.3: Schematic diagram showing the operation of STM. The tunneling current depends on the distance between the tip and the sample, as well as on the density of states of the tip and the sample.
apparent height variations or corrugations are mainly electronic in nature (case of graphene or hBN on Cu(111) [142, 143] or mainly geometric in nature (for example, graphene or hBN on Ru(0001) [108, 135, 143]. As we shall see below, in the case of hBN on Pd we can encounter both of these situation, which makes this system unique among other epitaxial monolayers on metallic substrates.

4.3 Experimental Motivation

Figure 4.4 shows the variation of the apparent corrugation (i.e., hill-to-valley height difference) as given by the STM measurements.

![Figure 4.4: Plots of the apparent corrugation $\Delta z$ as a function of the bias voltage $V$ for a tunelling current $I=7.0$ nA, for multiple domains: $\lambda=1.8$ nm (green squares), 2.7 nm (blue circles), and 2.8 nm (orange triangles). Courtesy of Pedro Arias and Prof. Suneel Kodambaka.](image)

In Figure 4.4, several trends suggests insights into the nature of the apparent corrugation $\Delta z$ measured in STM. First, there is a significant dependence on the bias voltage for all the curves, which means that the electronic effects are an important part of the apparent height
profiles measured in STM. However, for the spatial periodicities of 0.6, 1.8, and 2.7 nm the values of corrugation at each bias voltage are very similar to each other, practically exhibiting no significant dependence on the periodicity \( \lambda \). This suggests that the nature of the corrugation is merely electronic in nature, at least for moiré patterns with that have less than maximal periodicity. For the structure with the largest periodicity (corresponding the orientation angle \( \theta = 0 \)) there is a clear jump in the corrugation value \( \Delta z \) in the vicinity of zero bias: since this occurs at very low bias, it is likely that the largest corrugation observed (for \( \lambda = 2.8 \) nm) is geometric in nature, with a hill-to-valley distance of approximately 150 pm. This geometric corrugation value is assessed as the difference between the \( \Delta z \approx 200 \) pm maximum (at \( V = \pm 50 \) mV for the 2.8 nm moiré pattern) and the \( \approx 50 \) pm value of the corrugation for all the other moiré patterns at \( V = \pm 50 \) mV. This estimate effectively amounts to subtracting the mainly electronic corrugation, which we ascribed to all the domains with non-zero orientation angle \( \theta \), from the total apparent corrugation observed for the domain with maximal periodicity (\( \theta = 0 \)). In order to rationalize the physical origin of the trends in the STM observations in Figure 4.4, we turn to atomic scale calculations at the level of DFT, and to modeling the interfacial energy of hBN on Pd.

4.4 Details of the DFT calculations.

We have performed the DFT calculations using the Vienna Ab-initio Simulation Package (VASP) [88], with the generalized gradient approximation (GGA) with the Perdew-Burke-Ernzerhof functional [90]. The interactions between hBN monolayer and a Pd(111) substrate are weak [63, 131, 144], and we have incorporated them using the DFT-D2 method of Grimme [112]. There are two types of calculations carried out:

(i) relaxation and electronic structure of the complete hBN monolayer with periodic boundary conditions corresponding to the smallest and largest spatial periodicities observed in experiments;

(ii) hBN flakes (\( \text{B}_7\text{N}_6\text{H}_9 \), \( \text{B}_6\text{N}_7\text{H}_9 \), and \( \text{B}_{12}\text{N}_{12}\text{H}_{12} \)) adsorbed on Pd(111) with different registries and angular orientations, in order to assess the physisorption or chemisorption for
these flakes in the absence of the continuous monolayer.

Figure 4.5 shows the small flakes that we use as molecular probes to investigate the strength of the interactions at the local level, in the absence of possible artifacts that can be induced by using periodic boundary conditions in our computations. In each case, the center of the molecule is placed at one of the four adsorption locations shown in Figure 4.6, namely the top, face-centered cubic (fcc), hexagonal close-packed (hcp), and bridge configurations.

![Molecular probes used for assessing the local interaction strength via density functional theory (DFT) calculations. The molecules are in two orientations, zigzag (a, b, e, f) and armchair (c, d, g, h). The larger molecule, B₁₂N₁₂H₁₂, has two configurations α and β, depending on the succession of the B and N atoms in the central six-atom ring. The center of the molecule is placed above the Pd surface, in a top site, fcc site, hcp site, and bridge bond. These configurations are relaxed, and adsorption energies and the minimum and maximum distance from any atom of the probe molecule to the top Pd layer are reported Tables Table 4.1 and Table 4.2.

For these adsorption calculations, we have employed 5 × 5 surface unit cells of Pd (four layers, fixed) so as to ensure that the flakes do not overlap with themselves through the use of periodic boundary conditions. The computational cell included an 18 Å vacuum spacing. The flake structures were relaxed via conjugate-gradient in the presence of dipole corrections.
Figure 4.6: Adsorption locations for center of BN-molecules on Pd(111) surface, top, face-centered cubic (fcc), hexagonal close-packed (hcp), and bridge.

using a plane-wave cutoff of 500 eV, a Monkhorst-Pack k-point grid of $3 \times 3 \times 1$, and a force tolerance criterion of 0.02 eV/Å.

4.5 Results from complete hBN monolayers on Pd

There are several possibilities for the interplay between the electronic and geometric corrugation:

(i) the corrugation is mainly electronic in nature and the hBN monolayer is (nearly) flat, similar to hBN/Cu(111) [145];

(ii) the corrugation is short-ranged, and no moiré patterns arise, akin to that of commensurate $1 \times 1$ hBN/Ni(111) [146];

(iii) the corrugation is mainly geometric, similar to the moiré patterns formed by hBN or graphene on Ru(0001) [143, 147]; and, finally,

(iv) one in which there is a moiré pattern with meaningful contributions from both electronic and geometric effects.

Based on binding energy assessments previously published [92], we rule out the commensurate $1 \times 1$ structures, (ii). As mentioned, Figure 4.4 shows significant dependence of $\Delta z$ on the bias $V$, which rules out case (iii) for the structures with $\lambda = 1.8$ nm and 2.7 nm, which
exhibit similar variations of the corrugation with bias voltage despite the fact that they have very different orientations. The structure with $\lambda = 0.6$ nm periodicity also does not have any significant geometric corrugation ($\approx 3\text{pm}$, from our DFT calculations) because its periodicity is too short to accommodate vertical oscillations. For this structure (Figure 4.7), we have also performed calculations of the electronic structure and density of states at the surface. The results of these calculations are shown in Figure 4.8. Due to the presence of the metallic substrate, the bandgap of hBN [shown for free-standing sheets in Figure 4.8(a)] decreases to about 3.2 eV [Figure 4.8(b)]. This is consistent with our calculations of local density of states at the surface [Figure 4.8(c)], which shows the same bandgap.

Figure 4.7: Small hBN/Pd unit cell for calculations of electronic properties, (a) top view, (b) side view.

Returning to the discussion of corrugation, the structures with $\lambda = 0.6$, 1.8, and 2.7 nm display a corrugation which is mainly electronic in nature, although we cannot fully rule out a small geometric component. For $\lambda = 2.8$ nm, we notice a sharp increase in the corrugation close to zero bias, which is not present for any of the other cases at any bias voltage.
Figure 4.8: (a) Band structure of free-standing hBN. (b) Bandstructure of hBN/Pd for the surface unit cell shown in Figure 4.7. (c) Local density of states at the surface.
Figure 4.9: Simulated STM image for a supercell with $11 \times 11$ hBN on $10 \times 10$ Pd substrate. The top view shows the simulated STM image (sharp white dots are the N atoms beneath) with obvious large scale moiré pattern (color gradient) and the side image shows the relaxed atomic structure without any noticeable geometric corrugation of the hBN monolayer.
We performed further DFT in order to understand the different contributions (geometric vs. electronic) to the measured STM corrugation. The $2.7 \pm 0.20$ nm and $2.8 \pm 0.14$ nm moiré structures have significantly different corrugations (Figure 4.4), despite the fact that their periodicities are the same within the experimental uncertainties: this prompted us to investigate more closely the possibility that the both geometrically flat and geometrically corrugated structures could be encountered in domains with very similar orientations around $\theta = 0$. We note that an atomically flat layer can occur under conditions of commensurability: for example, at $\theta = 0$, a $10\times10$ Pd substrate with the lattice constant of $a_{\text{Pd}} = 0.275$ nm is perfectly commensurate with an $11\times11$ hBN monolayer with $a_{\text{hBN}} = 0.250$ nm. This is a very likely configuration for the structure with the largest spatial periodicity. Due to commensurability, a geometrically corrugated structure with this precise in-plane unit cell would involve straining the B-N bonds to create hills and valleys, which would in turn require high energetic penalties and hence does not occur. We have tested this assertion using DFT calculations for this orientation and periodicity ($11\times11$ hBN on $10\times10$ Pd): the perfectly commensurate hBN layer with $\theta = 0$ and $\lambda = 2.75$ nm remains flat and settles a distance of 280 pm from the substrate. The bonding character with the substrate is necessarily mixed: it cannot be purely vdW, since that would require about 320 pm separation from the substrate. The DFT calculations for the 2.75 nm structure shows that the layer remains nearly flat, with no noticeable geometric corrugation (6). However, the STM simulated image for the 2.75 nm moiré structure displays a large scale corrugation pattern (Figure 4.9). This is consistent with the STM measurements that show similar corrugations for structures with periodicities of 0.6, 1.8, 2.7 nm, and support the earlier assertion that the corrugation for these structures is mainly electronic in nature.

4.6 Results from adsorption of molecular probes

We have also tested the possibility that a significant geometric corrugation may develop for the maximal moiré periodicity $\lambda = 2.8$ nm, which is strongly suggested by the measurements in Figure 4.4 showing an additional 150 pm corrugation difference between the moiré
pattern at $\theta = 0$ and the other hBN domains. In order to do this and avoid computational artifacts stemming from the use of fixed periodic boundary condition in the surface plane, we have decided to locally test the hBN/Pd bonding by using small 2-D molecular flakes ($B_7N_6H_9$, $B_6N_7H_9$, and $B_{12}N_{12}H_{12}$) placed at different locations around the Pd substrate and studying the distance at which they settle with respect to the substrate. At certain orientations (0 and 30°) and registries above the substrate, these molecular flakes simulate various portions of a complete hBN/Pd layer (Figure 4.10).

![Figure 4.10: (a) Structure of the hBN/Pd(111) with maximal periodicity, obtained from flat layers with lattice constants $a_{hBN} = 0.250$ nm and $a_{Pd(111)} = 0.275$ nm. Small flakes (b) $B_7N_6H_9$ (top) and $B_6N_7H_9$ (bottom) and (c) $B_{12}N_{12}H_{12}$ employed to determine the adsorption tendencies for different portions (highlighted) of the moir structure. The circular region is van der Waals (vdW) bonded to the substrate, while the triangular region represents the strongest bonded core of the remaining chemically-bonded area in the unit cell.]

We have used the flakes to effectively probe the strength of the interaction and the height of the flake with respect to the substrate. Depending on the location on the substrate, the $B_7N_6H_9$ and $B_6N_7H_9$ flakes experience mostly localized geometric corrugations ranging from 8 pm to 56 pm and can settle such that the minimum distance to the substrate ranges from 54
214 pm to 257 pm (Table 4.1). There is no doubt that the distance of 214 pm is indicative of strong chemical bonding similar to that one encountered for hBN on Ni [125, 125, 131]. On the other hand, the larger flakes (B_{12}N_{12}H_{12}) experience bowing even though they are only about 1 nm wide (Table 4.2). The bowing corresponds to a geometric corrugation of 90 pm achieved between its center (295 pm away from the substrate) and periphery (205 pm away): this value can be viewed as a crude estimate of the actual geometric corrugation of the \( \lambda = 2.8 \) nm structure, in which most of the local interfacial configurations probed using our small flakes are present. An inspection of Figure 4.10 suggests that better estimate of the geometric corrugation can be glean from the molecular probe results as the height difference between the \( z_{\text{max}} \) value from the large bowed molecule B_{12}N_{12}H_{12} from the substrate, and the \( z_{\text{min}} \) value corresponding to a small strongly bounded flake, i.e. \( \approx 83 \) pm (Table 4.1, Table 4.2). This is still only about 55% of the value estimated from STM (Figure 4.4: this is likely to occur because of our method of using unconnected flakes to probe the interaction, so the order of magnitude agreement suffices.

Table 4.1: Adsorption energy \( (E_{\text{ads}}) \) and the minimum \( (z_{\text{min}}) \) and maximum \( (z_{\text{max}}) \) distance between atoms in the small molecular probes B_{7}N_{6}H_{9} and B_{6}N_{7}H_{9} on Pd(111).

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</tr>
</tbody>
</table>
Table 4.2: Adsorption energy ($E_{\text{ads}}$) and the minimum ($z_{\text{min}}$) and maximum ($z_{\text{max}}$) distance between atoms in the large molecular probes $B_{12}N_{12}H_{12}$ on Pd(111).

<table>
<thead>
<tr>
<th>Edge shape</th>
<th>Molecules</th>
<th>Positions</th>
<th>$E_{\text{ads}}$(eV)</th>
<th>$z_{\text{min}}$(nm)</th>
<th>$z_{\text{max}}$(nm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Zigzag</td>
<td>$B_{12}N_{12}H_{12}$-α</td>
<td>top</td>
<td>-4.948</td>
<td>0.248</td>
<td>0.297</td>
</tr>
<tr>
<td></td>
<td></td>
<td>fcc</td>
<td>-5.6716</td>
<td>0.227</td>
<td>0.268</td>
</tr>
<tr>
<td></td>
<td></td>
<td>hcp</td>
<td>-5.1902</td>
<td>0.257</td>
<td>0.276</td>
</tr>
<tr>
<td></td>
<td></td>
<td>bridge</td>
<td>-5.6580</td>
<td>0.210</td>
<td>0.262</td>
</tr>
<tr>
<td>Armchair</td>
<td>$B_{12}N_{12}H_{12}$-β</td>
<td>top</td>
<td>-5.0444</td>
<td>0.246</td>
<td>0.294</td>
</tr>
<tr>
<td></td>
<td></td>
<td>fcc</td>
<td>-5.1994</td>
<td>0.259</td>
<td>0.273</td>
</tr>
<tr>
<td></td>
<td></td>
<td>hcp</td>
<td>-5.4870</td>
<td>0.219</td>
<td>0.276</td>
</tr>
<tr>
<td></td>
<td></td>
<td>bridge</td>
<td>-5.5431</td>
<td>0.209</td>
<td>0.266</td>
</tr>
<tr>
<td></td>
<td>$B_{12}N_{12}H_{12}$-α</td>
<td>top</td>
<td>-5.1724</td>
<td>0.239</td>
<td>0.270</td>
</tr>
<tr>
<td></td>
<td></td>
<td>fcc</td>
<td>-5.2846</td>
<td>0.211</td>
<td>0.290</td>
</tr>
<tr>
<td></td>
<td></td>
<td>hcp</td>
<td>-5.2988</td>
<td>0.208</td>
<td>0.290</td>
</tr>
<tr>
<td></td>
<td></td>
<td>bridge</td>
<td>-5.1856</td>
<td>0.226</td>
<td>0.282</td>
</tr>
<tr>
<td></td>
<td>$B_{12}N_{12}H_{12}$-β</td>
<td>top</td>
<td>-5.1715</td>
<td>0.240</td>
<td>0.270</td>
</tr>
<tr>
<td></td>
<td></td>
<td>fcc</td>
<td>-5.2855</td>
<td>0.210</td>
<td>0.283</td>
</tr>
<tr>
<td></td>
<td></td>
<td>hcp</td>
<td>-5.2996</td>
<td>0.205</td>
<td>0.294</td>
</tr>
<tr>
<td></td>
<td></td>
<td>bridge</td>
<td>-5.1850</td>
<td>0.225</td>
<td>0.282</td>
</tr>
</tbody>
</table>

4.7 Model for the energetic competition between blistered and flat structures

The strength of the chemical bond between hBN and Pd may be influenced by the orientation $\theta$ between BN clusters and the Pd surface similar to the case of graphene/Pd(111) [132]. Given the above DFT results from the molecular probes, we hypothesize that axial strain in the bonds can be avoided for (incommensurate) hBN layers that have in excess of $11 \times 11$ hBN unit cells within the (average) maximal moiré structure of 2.8 nm. In this case, axial strain is traded for bending strains, which are significantly lower and can lead to the formation of "blisters", i.e. geometric corrugations. These blisters can be supported (or pinned to the substrate at their periphery) if the binding energy for the regions closest to the substrate is sufficiently strong. We now describe a simple model of the energetic competition between the flat and blistered configurations of the hBN monolayer on the substrate, with the goal of assessing the possibility of blister formation on a moiré pattern with (average) maximal periodicity. Within a moiré period, we calculate the interface energy per area starting from
three (positive) binding energies:

(i) $E_{ch}$, an average (per area) corresponding to regions of the moiré structure that are chemically bonded to the substrate (interlayer distance 230 pm) [148],

(ii) $E_{vdW}$, corresponding to regions that are vdW bonded (interlayer distance $\sim 320$ pm),

and

(iii) $E_f$, corresponding to an atomically flat monolayer situated at an intermediate distance, e.g., 280 pm.

While $E_{ch}$ and $E_{vdW}$ are local averages for their corresponding regions (close or far from the substrate, respectively), $E_f$ is a function of $\theta$ whose value is averaged over the entire (periodic) area, which is an increasing function of the misorientation angle $\theta$, based on graphene on Pd results [149].

We first derive the interfacial energy of the monolayer with periodic geometric corrugation in the form of blisters, and subsequently compare it to that of a flat monolayer. The blistered monolayer has the schematic profile in Figure 4.11, wherein the lower regions are approximated as flat and strongly bonded to the substrate (binding energy per area $E_{ch}$), and the upper regions are approximated as spherical segments that are vdW bonded to the substrate ($E_{vdW}$). The model is qualitative and meant to capture the main features of the interface energy of the blistered layer; as such, it neglects in the first approximation the transition region between the flat portions and the spherical segments. The geometric parameters are the height of the spherical calotte, $h$, the radius of the sphere, $\rho$, and the radius of the circular projection of the blister $R$.

The total interfacial energy $\gamma_b$ per unit area of the blistered periodic structure can be written as:

$$
\gamma_b(R, \lambda) = \frac{2}{\lambda^2 \sqrt{3}} [-E_{ch}(\frac{\lambda^2 \sqrt{3}}{2} - \pi R^2) - E_{vdW} \pi R^2 + M \kappa^2 \pi R^2]
$$

(4.2)

where $\lambda^2 \sqrt{3}/2$ is the area of the moiré surface cell with the periodicity $\lambda$, $M$ is the bending modulus of the hBN monolayer and $\kappa$ is the curvature of the spherical segment. Equation
Figure 4.11: Schematic of a surface unit cell of hBN/Pd with a blistered configuration. The blister is approximated as a spherical calotte of height \( h \) and base radius \( R \).

(4.2) combines the energies of the two regions shown in Figure 4.11 (both negative because of the positive binding), with the elastic energy of the (bent) spherical portion (positive), and to obtain the interface energy (per area) \( \gamma_b \), which is a function of the radius \( R \) and the periodicity \( \lambda \). The curvature \( \kappa \) of the blister can be estimated as:

\[
\kappa = \frac{1}{\rho} = \frac{2h}{R^2 + h^2} \approx \frac{2h}{R^2} \tag{4.3}
\]

where the height \( h \) is neglected in comparison to \( R \) in the denominator. Substituting (4.3) in (4.2), we obtain the interface energy as a function of \( R \) and \( \lambda \):

\[
\gamma_b(R, \lambda) = 2\lambda \sqrt{\frac{\pi}{3}} \left[ \left( \frac{\lambda^2 \sqrt{3}}{2} - \pi R^2 \right) - E_{vdw} \pi R^2 + \frac{4\pi h^2}{R^2} \right] \tag{4.4}
\]

At a fixed periodicity \( \lambda \), the radius \( R \) should be optimal, i.e., it should assume the value \( R^* \) that minimizes the interface energy Eq. (4.4). Setting to zero the derivative \( d\gamma_b/dR \), we obtain:

\[
R^* = \left( \frac{4Mh^2}{E_{ch} - E_{vdw}} \right)^{1/4} \tag{4.5}
\]

The minimum energy is then obtained by substituting (4.5) into (4.4), so that the minimum interface energy of the blistered configuration becomes a function only of \( \lambda \):

\[
\gamma_b = -E_{ch} + \frac{8\pi h \sqrt{M(E_{ch} - E_{vdw})}}{\lambda^2 \sqrt{3}} \tag{4.6}
\]
Given that the periodicity is related to the misorientation angle [136] via:

\[
\lambda(\theta) = \frac{a_{pd}a_{hBN}}{\sqrt{a_{pd}^2 + a_{hBN}^2 - 2a_{pd}a_{hBN} \cos \theta}} \quad (4.7)
\]

the interface energy \( \gamma_b \) can be expressed as a function of the misorientation \( \theta \) as:

\[
\gamma_b = -E_{ch} + \frac{8\pi h \sqrt{M(E_{ch} - E_{vdW})}}{\sqrt{3}} \left( \frac{1}{a_{pd}^2 + 1} \frac{1}{a_{hBN}^2} - \frac{2 \cos \theta}{a_{pd}a_{hBN}} \right) \quad (4.8)
\]

This energy is to be compared with the interfacial energy \( \gamma_f \) of a flat hBN monolayer (no significant geometric corrugation), which is a monotonically decreasing function of \( \theta \) based on results derived for graphene on Pd(111) [149]. The comparison of interfacial energies for the flat and blistered configurations is illustrated in Figure 4.12. The relationship between the binding energies is necessarily \( E_{ch} > E_f(\theta = 0) > E_{vdW} \), based on the corresponding distances with respect to the substrate. This inequality is not changed by the addition of the constant terms proportional to \( \sqrt{M} \) in Eq. (4.8), and thus leads to the interface energy curves \( \gamma_b \) and \( \gamma_f \) with the relative positions shown in Figure 4.12. At \( \theta = 0 \), \( E_{ch} > E_f \) requires that \( \gamma_b < \gamma_f \), which shows that the blistered configuration is favorable at least at \( \theta = 0 \). However, given that \( \gamma_b \) decreases with \( \theta \) while \( \gamma_f \) increases, the two curves necessarily intersect (Figure 4.12), and the flat configuration becomes more stable at a nonzero angle \( \theta_c \). Based on experiments which show both blistered and flat configurations at similar periodicities (2.7-2.8 nm), the intersection must occur at a small angle \( \theta_c \sim 1^\circ \). The fact that the critical angle is small amounts to a bifurcation behaviour in which for angles that are slightly below \( \theta_c \) it is energetically favorable for the surface to develop blisters, and for angles above \( \theta_c \) a flat monolayer settling at a distance closer to the vdW separation (rather than to the interlayer spacing corresponding to strong bonding) is preferred.

4.8 Conclusions

In conclusion, we used DFT to understand the geometric and electronic contributions to the apparent surface corrugation measured by STM on multiple hBN domains on Pd(111). We have found that for most hBN domains on Pd, the apparent corrugation is mostly
Figure 4.12: Schematic of a surface unit cell of hBN/Pd with a blistered configuration. The blister is approximated as a spherical calotte of height $h$ and base radius $R$.

electronic in nature. For domains of maximal or near maximal periodicity, we found that geometric blisters could form on hBN via the interplay of chemical binding, vdW binding, and bending within the moiré period: this was inferred by a general (yet qualitative) model for this behavior and for the associated interface energy of the blistered configuration. The existence of both flat and blistered domains on supported 2-D hBN is atypical, and in the case of hBN/Pd it is enabled by the intermediate binding energy per unit area, i.e. between strong (akin to Ni [131] or Ru [150]) and weak (akin to Cu [131] or Pt [117]). We expect similar bifurcation behavior to occur on hBN when supported by other substrates with intermediate interactions, not necessarily metallic ones (for example, metal oxides). This behavior can potentially be used to control of the templated self-organization of molecules or nanocrystals on hBN/Pd(111), as they could form either sparse patterns or compact agglomerations on the same hBN monolayer depending on whether its structure is blistered or flat.
Synopsis: With the quest for newer and more inexpensive 2-D materials well underway, there have recently been proposals for layers phases of silica, SiO$_2$. The material itself is certainly inexpensive, but at the present is not well understood what the best conditions to grow it are or what is the range of structure and properties that can be attained from this 2-D material. In order to gain insight into the properties that can be derived from 2-D phases of silica, in this chapter we propose several 2-D silica configurations and calculate their electronic and mechanical properties. Using DFT calculations, a wide variety of properties are predicted. These properties could serve to guide future growth efforts, as well as serve as a starting point for future simulation efforts aimed at understanding how the presence of substrates (metallic or semiconducting) may alter the properties of 2-D silica grown on them.

5.1 Introduction

Three dimensional silica (SiO$_2$, sometimes with deviations from this composition, SiO$_x$) has a very rich phase diagram [151], with a large number of phases present. At ambient pressures, the local environment of the Si atoms is a tetrahedron with oxygen corners, while at high pressure the Si atom is the center of octahedra [152]. Silica is a ceramic with large bandgap for both crystalline and amorphous phases. These structures are all made of tetrahedra centered on Si atoms and having O atoms as corners. The tetrahedra usually share the O-atom corners and thus they make up the structure in three dimensions: $\alpha$—quartz, $\beta$—quartz, cristobalite, other crystalline phases Figure 5.1), or amorphous (Figure 5.2). Interestingly, in the amorphous structure the tetrahedra are sharing corners in the same way as in the crystals, only they do not have long range order. Silicon wafers spontaneously “cover” themselves with amorphous layer(s) of silica when they are in contact with ambient
atmosphere, and this insulating layer contributes to their passivation. This passivating layer is usually hundreds of nanometers thick (amounts to what is called a thin film), and has found uses in electronics industry as dielectric layer [153], as well as in catalysis [154]. In light of these technological applications, it would be interesting to attempt to create periodic arrays or crystalline 2-D silica layers instead of the naturally occurring amorphous ones, since the properties of crystalline layers are more reproducible and display less variation –which could be important at least for catalytic applications that require a large number of active catalytic sites per unit area.

In general, lowering dimensionality of a material may or may not lead to new structural configurations being formed. For example, in the case of graphene there is no difference between the layers in graphite and those in graphene. However, other materials may adopt new structures with lowering the dimensionality. In general, there are fully developed global optimization methods for surface reconstructions and supported 2-D materials [155–162], as well as for 1-D nanostructures [162–166]. In recent years, a number of 2-D silica structures were proposed using DFT calculations [167–172]. Some of these structures are shown in Figure 5.3, and they can be single layers or bilayers. Experimentally, these 2-D structures (Figure 5.3) have not yet been realized, but recent efforts have been successful at growing 2-D phases of silica and germania on metals [173–177]. The metallic substrate stabilizes these 2-D phases, offering them both support and stability against decay or wrinkling: the layers are made of Si-centered tetrahedra in which an O plane made of three corners is exposed at the surface, while the fourth oxygen is strongly bonded to the metallic substrate (Figure 5.4).

In this chapter, we describe DFT calculations that show how much the properties of 2D silica layers vary with the specific configuration. These efforts are important in that they show very wide electronic behaviour, from metallic, to semiconductor, to insulator. The results could serve as guide for future experiments aimed at producing inexpensive 2D materials with a specifically desired electronic bandgap.
Figure 5.1: Common 3D crystalline phases of silica. From [178], with permission of Royal Society of Chemistry.
Figure 5.2: 3D amorphous phase of silica. From [179], with permission of Royal Society of Chemistry.

Figure 5.3: Theoretical 2D phases of silica proposed in the literature [172] and their formation energy. Reproduced with permission from American Chemical Society.
5.2 Description of the simulation protocol

One of the methods to control the properties of materials is to change their atomic structure and their chemical composition. We have examined six different structures of 2D Silica. We performed DFT calculations within the framework of the generalized gradient approximation (GGA) [90], using the projector-augmented wave (PAW) potentials [181]. Each 2D SiO$_2$ structure is subjected to the same simulation protocol, described below.

- Obtaining relaxed structure

While the atomic structure (stored in the POSCAR file, which is the geometry input to the DFT package called VASP) are easy to construct using Matlab programming, they do not necessarily have the precise lattice parameter and interatomic bond lengths. Because of that, the first step in the protocol is to carry out atomic relaxations. In these relaxations, atoms are moved slightly in the direction of force gradients until the total energy has come to a local minimum. In this process, not only the atoms are
allowed to relax, but the lattice parameters of the 2D crystal as well.

- Calculating mechanical properties

Mechanical properties, in particular the stiffness matrix $C_{ijkl}$, can be computed after relaxation by setting appropriate commands in the VASP command file called INCAR. These stiffness’s are calculated by taking the numerical derivatives of the total energy with respect to strain components in different directions [182]:

$$C_{ijkl} = \frac{\partial^2 (E/V)}{\partial \varepsilon_{ij} \partial \varepsilon_{kl}}, \quad (5.1)$$

where $E$ is the elastic energy stored in the domain of volume $V$ of the crystal subjected to the appropriate deformations.

- Density of state (DOS) calculation

The density of states (DOS) is essentially the number of states (per unit volume) that fall within an interval $(E, E + \Delta E)$ of energies. As such, DOS is a function of the energy $E$, and can give us information on the electronic nature of the material. Moreover, various partitions of the DOS (e.g., per atom, per type of angular momentum, spin etc) give even more detailed information about bonding and about the available states for, e.g., interactions with the environment.

The calculations of DOS is triggered by specific commands in the input files, commands that results also in the storage of electron density at every point in space (CHGCAR file) and the complex wavefunctions of occupied and unoccupied states of the electrons (stored in the binary WAVECAR file). These files are used for the calculations of band structures, which are dispersion relations of the type $E_n(k)$, where $n$ is the band index and $k$ is the wave vector of the electrons in the material; the wave vector is the momentum of electron up to the multiplicative Plank’s constant.
• Band structure calculation

Calculations of the band gap of materials are important in order to classify the materials as semiconductors, insulators, or metals. For band structure calculations, we need to use two output files, WAVECAR and CHGCAR from density of state DOS calculation as input files for the computation of the dispersion relationship $E_n(k)$. The band structure and DOS is extracted from the VASP output file called vasprun.xml.

5.3 Proposed structures of 2D silica

Six different geometrical configurations have been examined. These configurations differ in terms of:

(i) how the tetrahedra are connected in 2D (sharing corners or sharing edges),
(ii) what type of interstices are developing in the 2D lattice (triangular holes or hexagonal holes), and
(iii) whether all tetrahedra are on the same side of the base plane or not.

The six structures, labelled 1 through 6, fall into two categories: structures with corner-sharing tetrahedra (1 through 4), and those with edge-sharing tetrahedra (5,6).

Structure 1

![Structure 1](image)

Figure 5.5: Atomic structure of 2D silica where the tetrahedra share corners, forming triangular holes, with all tetrahedra on one side of the surface: (a) perspective view showing the Si-centered tetrahedra, and (b) top view, with atoms shown as red (O) or blue (Si) spheres.
Figure 5.5 shows the suggested atomic structure of 2D silica where the tetrahedra share corners forming triangular holes with all tetrahedra on one side of the surface. The lattice vectors of the primitive cell and their unit in angstrom (Å) are:

\[ \mathbf{a} = a \mathbf{i} \]
\[ \mathbf{b} = \frac{1}{2} b \mathbf{i} + \frac{\sqrt{3}}{2} b \mathbf{j} \]
\[ \mathbf{c} = c \mathbf{k} \]

where: \( a = b = 2.678 \, \text{Å} \), and \( c = 20 \, \text{Å} \).

**Structure 2**

![Image](image1)

Figure 5.6: Atomic structure of 2D silica where tetrahedra share corners, forming triangular holes with half of tetrahedra on each side of the surface: (a) perspective view showing the Si-centered tetrahedra, and (b) top view, with atoms shows as red (O) or blue (Si) spheres.

Figure 5.6 demonstrates the way to distribute the tetrahedra equally in two existing sides of the surface. The lattice vectors of the primitive cell and their unit in angstrom (Å) are:

\[ \mathbf{a} = 2a \mathbf{i} \]
\[ \mathbf{b} = -\frac{1}{2} b \mathbf{i} + \frac{\sqrt{3}}{2} b \mathbf{j} \]
\[ \mathbf{c} = c \mathbf{k} \]

where: \( a = 2.678 \, \text{Å} \), \( b = 5.356 \, \text{Å} \) and \( c = 20 \, \text{Å} \).
Structure 3

Figure 5.7: Atomic structure of 2D silica where the tetrahedra share corners, forming hexagonal holes with all tetrahedra on one side of the surface: (a) perspective view showing the Si-centered tetrahedra, and (b) top view, with atoms shown as red (O) or blue (Si) spheres.

The Figure 5.7 shows the atomic structure of 2D silica where the tetrahedra share corners, forming hexagonal holes with all tetrahedra on one side of the surface. Lattice vectors in angstrom (Å) are:

\[ \mathbf{a} = a \hat{i} - \frac{1}{2} b \hat{i} \]  
\[ \mathbf{b} = -\frac{1}{2} b \hat{i} + \frac{\sqrt{3}}{2} b \hat{j} \]  
\[ \mathbf{c} = c \hat{k} \]

where: \( a = b = 5.356 \) Å and \( c = 20 \) Å

Structure 4

From the Figure 5.8 the atomic structure of 2D silica where the tetrahedra share corners, forming hexagonal holes with half of tetrahedrons on each side of the surface. The lattice vectors in angstrom (Å) are:

\[ \mathbf{a} = a \hat{i} - \frac{1}{2} b \hat{i} \]  
\[ \mathbf{b} = -\frac{1}{2} b \hat{i} + \frac{\sqrt{3}}{2} b \hat{j} \]  
\[ \mathbf{c} = c \hat{k} \]
Figure 5.8: Atomic structure of 2D silica where the tetrahedra share corners, forming hexagonal holes with half of tetrahedra on each side of the surface: (a) perspective view showing the Si-centered tetrahedra, and (b) top view, with atoms shows as red (O) or blue (Si) spheres.

where: \( a = b = 5.356 \text{ Å} \) and \( c = 20 \text{ Å} \)

**Structure 5**

Figure 5.9: Atomic structure of 2D silica where the tetrahedra share edges, all the tetrahedra on one side of the surface: (a) perspective view showing the Si-centered tetrahedra, and (b) top view, with atoms shows as red (O) or blue (Si) spheres.

From the Figure 5.9, the atomic structure of 2D silica where the tetrahedra share edges, all the tetrahedra on one side of the surface. The lattice vectors in angstrom (Å) are:

\[
\begin{align*}
\mathbf{a} &= a \mathbf{i} \\
\mathbf{b} &= -\frac{1}{2}b \mathbf{i} + \frac{\sqrt{3}}{2}b \mathbf{j} \\
\mathbf{c} &= c \mathbf{k}
\end{align*}
\]

where: \( a = b = 3.593 \text{ Å} \) and \( c = 20 \text{ Å} \)
Structure 6

Figure 5.10: Atomic structure of 2D silica where the tetrahedra share edges, half the tetrahedra on each side: (a) perspective view showing the Si-centered tetrahedra, and (b) top view, with atoms shown as red (O) or blue (Si) spheres.

From the Figure 5.10, the atomic structure of 2D silica where the tetrahedra share edges, half of the tetrahedra on each side of the surface. The lattice vectors in angstrom (Å) are:

\[
\mathbf{a} = a \hat{\mathbf{i}} \\
\mathbf{b} = -\frac{1}{2} b \hat{\mathbf{i}} + \frac{\sqrt{3}}{2} b \hat{\mathbf{j}} \\
\mathbf{c} = c \hat{\mathbf{k}}
\]

where: \(a = b = 2.678\ \text{Å}\) and \(c = 20\ \text{Å}\)

Table 5.1 shows the summary of lattice vectors of all six structures, five of them have been relaxed. The relaxed structures have a low formation energy which indicate they are would be quite easy to synthesize. Only one structure has not been relaxed / converged: this is structure 5, with shared edges and no holes in the structures. In this structures, the oxygen ions too close to each other which leads to large electrostatic repulsion and failure to converge.
Table 5.1: Lattice parameters of the proposed 2D silica structures

<table>
<thead>
<tr>
<th>Sharing type</th>
<th>Structure No.</th>
<th>Lattice parameters</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
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</tr>
<tr>
<td>Corners</td>
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</tr>
<tr>
<td></td>
<td>2</td>
<td>2.678</td>
</tr>
<tr>
<td></td>
<td>3</td>
<td>5.356</td>
</tr>
<tr>
<td></td>
<td>4</td>
<td></td>
</tr>
<tr>
<td>Edges</td>
<td>5</td>
<td>3.593</td>
</tr>
<tr>
<td></td>
<td>6</td>
<td>2.678</td>
</tr>
</tbody>
</table>

5.4 Mechanical properties of the 2D silica structures

The generalized form of Hooke’s Law expresses the stress components in terms of the strain components via [183]:

\[
\sigma_{ij} = c_{ijkl} \epsilon_{kl},
\]

where \(c_{ijkl}\) are the 81 components of the stiffness tensor. For convenience, a matrix notation based on Voigt’s convention will be used. This can be done after extracting all the components of the four rank tensor \(c_{ijkl}\), and converting them to Voigt’s notation as shown in Table 5.2.

Table 5.2: Converting the stiffness tensor to Voigt notation

<table>
<thead>
<tr>
<th>Regular indices</th>
<th>11</th>
<th>22</th>
<th>33</th>
<th>23,32</th>
<th>31,13</th>
<th>12,21</th>
</tr>
</thead>
<tbody>
<tr>
<td>Voigt notation</td>
<td>1</td>
<td>2</td>
<td>3</td>
<td>4</td>
<td>5</td>
<td>6</td>
</tr>
</tbody>
</table>

In this notation, the stiffness matrix becomes:
where: $c_{12} = c_{21}, c_{13} = c_{31}, c_{14} = c_{41}, c_{15} = c_{51}, c_{16} = c_{61}, c_{23} = c_{32}, c_{24} = c_{42}, c_{25} = c_{52}, c_{26} = c_{62}, c_{34} = c_{43}, c_{35} = c_{53}, c_{36} = c_{63}, c_{45} = c_{54}, c_{46} = c_{64}$, and $c_{56} = c_{65}$

So the general stiffness matrix has 21 independent stiffness constants. Furthermore, the crystals symmetry will reduce the number of these stiffness components. For bulk materials with hexagonal geometry, the stiffness matrix has only five independent stiffness constants:

$$
c = \begin{bmatrix}
  c_{11} & c_{12} & c_{13} & 0 & 0 & 0 \\
  c_{21} & c_{22} & c_{23} & 0 & 0 & 0 \\
  c_{31} & c_{32} & c_{33} & 0 & 0 & 0 \\
  0 & 0 & 0 & c_{44} & 0 & 0 \\
  0 & 0 & 0 & c_{55} & 0 & 0 \\
  0 & 0 & 0 & 0 & 0 & c_{66}
\end{bmatrix}
$$

where $c_{11} = c_{22}, c_{13} = c_{23}, c_{44} = c_{55}, c_{12} = c_{21}, c_{13} = c_{31}$ and $c_{66} = \frac{1}{2}(c_{11} - c_{12})$.

To convert the 3D system to 2D, we assume ($\epsilon_{ij} = 0$, $\sigma_{ij} = 0$ for $i = 3$ or $j = 3$), which leads to an elastic tensor with only two independent constants. The elastic tensor for 2D materials thus becomes:
\[
c = \begin{bmatrix}
c_{11}^{2D} & c_{12}^{2D} & 0 \\
c_{21}^{2D} & c_{22}^{2D} & 0 \\
0 & 0 & c_{66}^{2D}
\end{bmatrix}
\]

where \( c_{11}^{2D} = c_{22}^{2D}, c_{12}^{2D} = c_{21}^{2D} \), and \( c_{66}^{2D} = \frac{1}{2}(c_{11}^{2D} - c_{12}^{2D}) \).

The VASP package software always calculates these coefficients using periodic boundary conditions in three dimensions; because of this, the 2D coefficients \( c_{ij}^{2D} \) must be normalized by the \( c \) lattice parameter [171, 184].

We validate our results by computing the stiffness matrix for a well known 2D material (graphene) and comparing the results to other published work as shown in Table 5.3.

### Table 5.3: The stiffness constant \( c_{11}^{2D} \) of graphene.

<table>
<thead>
<tr>
<th>stiffness constant ( c_{11} ) in TPa</th>
<th>present work</th>
<th>Ref. [185]</th>
<th>Ref. [186]</th>
<th>Ref. [187]</th>
</tr>
</thead>
<tbody>
<tr>
<td>1.057</td>
<td>0.992</td>
<td>1.029</td>
<td>1.025</td>
<td></td>
</tr>
</tbody>
</table>

After ensuring that the computed stiffness components are indeed close to those reported in the literature [185–187] (with the differences coming from the details of the specific methodologies used in various articles), we turn to calculating the stiffness constants for our 2D silica structures described above. These elastic constants are summarized in Table 5.4.

### Table 5.4: Stiffness constants

<table>
<thead>
<tr>
<th>Stiffness constants for 2D Silica in GPa</th>
<th>Chemical formula</th>
<th>Structure No.</th>
<th>( c_{11} )</th>
<th>( c_{12} )</th>
</tr>
</thead>
<tbody>
<tr>
<td>SiO\textsubscript{2}</td>
<td>1</td>
<td>356</td>
<td>362</td>
<td></td>
</tr>
<tr>
<td>SiO\textsubscript{2}</td>
<td>2</td>
<td>449</td>
<td>242</td>
<td></td>
</tr>
<tr>
<td>Si\textsubscript{2}O\textsubscript{5}</td>
<td>3</td>
<td>281</td>
<td>116</td>
<td></td>
</tr>
<tr>
<td>Si\textsubscript{2}O\textsubscript{5}</td>
<td>4</td>
<td>160</td>
<td>73</td>
<td></td>
</tr>
<tr>
<td>Si\textsubscript{2}O\textsubscript{3}</td>
<td>6</td>
<td>90</td>
<td>423</td>
<td></td>
</tr>
</tbody>
</table>
Structure 5 has one of the computed stiffness constants negative, which indicates that it is mechanically unstable. For this reason, it has been dropped from Table 5.4 and from the electronic structure calculations.

5.5 Band structures and Density of states (DOS)

The band structure plot represents the available energies for electrons in the materials. When represented as functions of the wave number, these energies form bands, which fill up with electrons starting at the lowest energy and continuing towards the higher energies. The last filled band is called the valence band, and the first unoccupied band is called the conduction band. If there is a gap between valence and conduction bands, this means that electrons in the valence would have to be supplied a minimum energy in order for them to cross the gap and become conduction electrons. This is called bandgap, and its exact value determines the electronic behavior of the materials (metal, semiconductor, or insulator.) It is often useful to plot DOS next to the band structure, which we do in the next figures

- Band structure and DOS of Structure 1

From the DOS and band structure graphs, Figure 5.11 it is shown that the valence and conduction band are contact at Γ point only, meaning that Structure 1 is metallic. The precise nomenclature is “semimetallic” to indicate that the valence and conduction bands cross only at one point: this is an electronic behavior similar to graphene, which is also a semimetal.

- Band structure and DOS of Structure 2

The atomic structure of 2D silica with share corners forming triangular holes with half of tetrahedra on each side of the plane show the DOS and band structure graph Figure 5.12, a band gap of 1.8 eV, that allow the structure as a candidate of semiconductor material. The precise value of 1.8 eV can make this material suitable for photovoltaic application; this is a proposal which can be tested experimentally in the future.
Figure 5.11: Band structure and DOS for structure 1
Figure 5.12: Band structure and DOS for structure 2
• Band structure and DOS of Structure 3

From the Figure 5.13, it is clear that the atomic structure with share corners forming hexagonal holes with all tetrahedrons on one side of the surface has the band gap of 6.5 eV, which makes this structure an insulator.

• Band structure and DOS of Structure 4

Referring to the Figure 5.14, the atomic structure of 2D silica with shared corners forming hexagonal holes with half of the tetrahedra on each side of the surface has a large band gap, 6 eV. This structure is therefore an insulator.
Figure 5.14: Band structure and DOS for Structure 4
• Band structure and DOS of Structure 6

From Figure 5.15, the 2D silica sharing edges half the tetrahedrons on each side of the surface behaves as a semiconductor with band gap of 1 eV at M point.

![Figure 5.15: Band structure and DOS for 2D silica, Structure 6](image)

Table 5.5 summarizes the calculated band gaps for the stable structures.

Electronic behaviors similar to those in Table 5.5 have been reported for graphene (semimetal), MoS$_2$ (semiconductor with bandgap of 1.8 eV), and hBN (insulator with bandgap of 5 eV). 2D silica is able to realize all electronic behaviors, with the precise structure determining the electronic properties.
Table 5.5: Summary of Band gap

<table>
<thead>
<tr>
<th>Structure number</th>
<th>Band gap (eV)</th>
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<tbody>
<tr>
<td>1</td>
<td>0, contact only at Γ point</td>
</tr>
<tr>
<td>2</td>
<td>1.8</td>
</tr>
<tr>
<td>3</td>
<td>6.5</td>
</tr>
<tr>
<td>4</td>
<td>6.0</td>
</tr>
<tr>
<td>6</td>
<td>1.0</td>
</tr>
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5.6 Summary

With the noted exception of Structure 5 (which is mechanically unstable), it is very likely that all the remaining structures can be synthesized in the future as they are mechanically stable. The 2D silica display as wide range of possible electronic behaviours, depending on the exact structure. Future efforts should be aimed at understanding what parameters during growth can be tuned to determined one particular structure or another. These efforts are not particularly facile, given that currently the silica structure are formed on metallic substrates, and they are strongly bonded to these substrate. The strong bonding with the substrates alters the electronic properties of 2D silica, practically ”short-circuiting” them from an electronic point of view. Thus, in the future growth efforts should also proceed using insulating substrate which will only provide support (against wrinkling) and not alter the electronic properties.
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Publication: The Journal of Physical Chemistry C

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