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WIND-TUNNEL RESEARCH ON THE MECHANICS OF PLUMES IN THE ATMOSPHERIC SURFACE LAYER

PART III

by

M. Poreh¹ and J. E. Cermak²



FLUID MECHANICS AND WIND ENGINEERING PROGRAM

COLLEGE OF ENGINEERING

COLORADO STATE UNIVERSITY

FORT COLLINS, COLORADO

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M. Poreh¹ and J. E. Cermak²

WIND-TUNNEL STUDY OF DIFFUSION AND DEPOSITION OF PARTICLES WITH APPRECIABLE SETTLING VELOCITIES

-ANNUAL REPORT-

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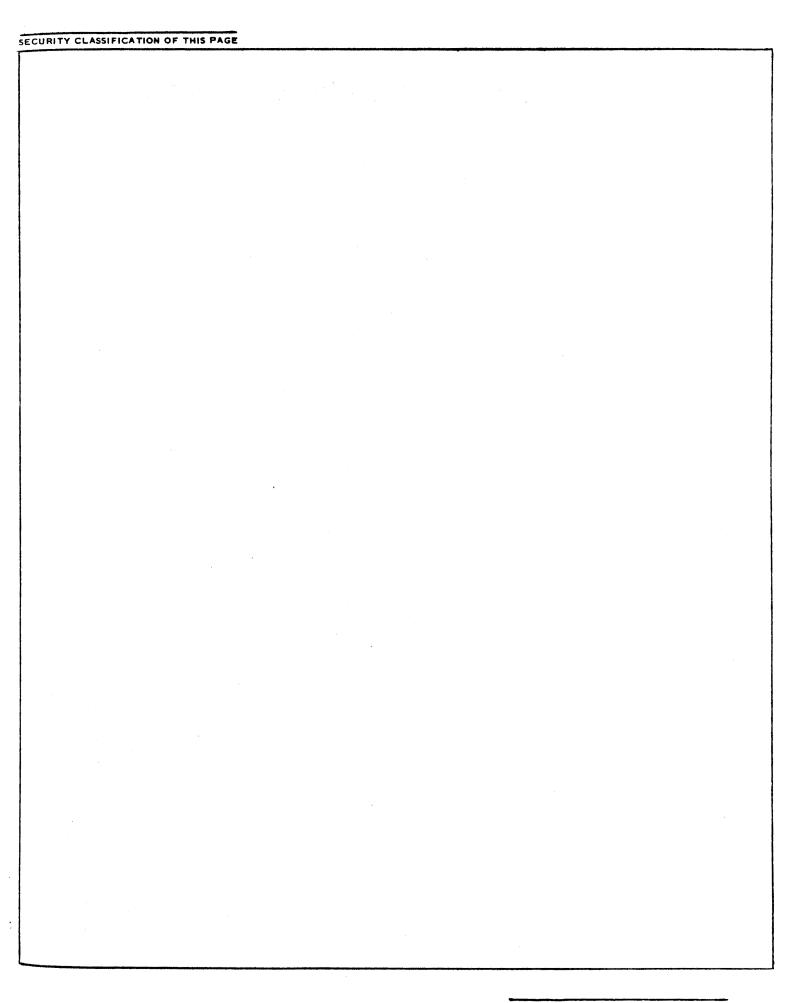
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ABSTRACT

The deposition on a smooth surface of particles with appreciable settling velocities $V_{\rm c}$ and small Froude numbers Vg^2/gh , where h is the height of the source in a neutrally stable boundary layer, was studied in a meteorological wind tunnel. The measured longitudinal deposition rates of the deposited particles were closely predicted by an approximate model, which relates the deposition rate of settling particle plumes to the diffusion of passive plumes with no reflection from the ground. The lateral dispersion rates of the settling particle plumes were found, however, to be smaller than those of passive plumes.

KEY WORDS

Deposition, Particles, Dispersion, Atmospheric Diffusion, Particle Plumes, Gaussian Models, Wind-Tunnel Simulation

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WIND-TUNNEL RESEARCH ON THE MECHANICS OF PLUMES IN THE ATMOSPHERIC SURFACE LAYER

1 INTRODUCTION

Atmospheric diffusion and deposition on the ground of particle-plumes with appreciable settling (free-fall) velocities emitted from elevated sources is of considerable importance in many problems.

The motion and the diffusion of such particles in a turbulent field are very complex phenomena. They are affected by the size of the particles, relative to the size of the turbulent eddies, their inertia and added mass, the turbulent velocity field and the crossing of the turbulent eddies by the free-falling particles, which attenuates their diffusion relative to that of ideal tracers. Similarly, the deposition rate of particles on the ground is a function of their concentration near the ground, the settling velocity, the detailed nature of turbulence near the ground, the surface roughness and the forces between the surface and the particulates at very small distances. Due to the complexity of the problem, it is usually treated by approximate semiempirical models, which have many restrictions. Evaluation of such models, as well as the ability to develop improved models, depend on the availability of experimental data. Due to the inherent difficulties and high cost of full-scale atmospheric diffusion experiments, such data is, however, very difficult to obtain.

Similar difficulties of studying atmospheric flows and atmospheric diffusion of gases have stimulated the use of specially designed wind tunnels for physical simulation of these phenomena.

This work is a preliminary attempt to study some cases of diffusion of particulates in a neutral atmosphere by physical simulation in a meteorological wind tunnel. Preliminary analysis has revealed certain limitations and constraints of such physical simulation (Poreh and Cermak, 1984). The experimental work of the current study was therefore restricted to the simpler case of small particles with appreciable settling velocities, diffusing from elevated sources in a neutral turbulent boundary layer over a smooth, sticky surface. These restrictions eliminate reflection of particles from the surface and re-entrainment into the air stream.

The report discusses the necessary criteria for the simulation of particle-plumes in wind tunnels, describes the experimental techniques and procedures used in the study, presents the results of the simulation as well as a very simple statistical model which exhibits the effect of the basic parameters on the ground-level distribution of particulates.

2 WIND-TUNNEL SIMULATION OF PARTICLE-PLUMES IN A NEUTRALLY STABLE ATMOSPHERIC SURFACE LAYER

2.1 General

Simulation of diffusion in wind-tunnel models requires, of course, that the surface-layer flow be correctly simulated in the model. The requirements for simulating neutrally-stable flows are well known (Cermak, 1971, 1975).^{2,3} In summary, they are: matching the mean and turbulent flow characteristics of the Atmospheric Surface Layer (ASL) with those of the wind-tunnel boundary layer, up to a height of the order of 4 times the height of the investigated layer, or, when the entire ASL is simulated, up to the edge of the surface boundary layer, which on the average is estimated to be of the order of 600 m (Counihan, This is achieved by using relatively long wind-tunnel test sections, and installing spires or vortex generators at the entrance to the test section, to produce the appropriate momentum deficiency and to roughly match, as early as possible, the velocity distributions in the upstream section of the model and the ASL. The equivalent roughness and topography in the physical model are then matched with the prototype roughness and topography using the same geometric scale, R_{τ} , for δ , for the roughness and for the topography

$$R_{L} = \frac{\delta_{m}}{\delta_{p}} = \frac{Zo_{m}}{Zo_{p}} = \frac{L_{m}}{L_{p}} . \tag{1}$$

If the Reynolds number in the model is sufficiently large, so that

$$\frac{V^*Zo_m}{v} > 10 \tag{2}$$

where V* is the shear velocity, and

$$\frac{U\delta}{v} > 10^5 \tag{3}$$

where U is the mean velocity, the dimensionless mean and turbulent velocity distributions in the model, after a certain distance, of the order of 10 δ , from the beginning of the test section will be approximately similar to those in the lower part of the ASL, provided R_L is sufficiently small ($\stackrel{<}{\leftarrow}$ 0.01).

The above requirements are also sufficient for approximate simulation of the diffusion of passive tracers in a neutral ASL up to a distance of approximately 5 kms (Cermak, 1975). 3

To simulate the diffusion of particles with appreciable settling velocity V_{g} , it is also required to match in the model and in the atmosphere the following dimensionless parameters:

- (1) The settling velocity ratio, V_g/U , (2) The Froude number, V_g^2/gL , and
- (3) The Reynolds number of the relative motion of these particles.

It is relatively easy to meet the first requirement. The second requirement implies that the velocity scale in the model must be proportional to the square root of the geometric scale. This requirement implies that the value of the Reynolds numbers in the small-scaled model would in many cases be below the critical value required for a correct simulation of the turbulence in the ASL.

There are, however, some important cases for which the requirements (2) and (3) need not be matched in the model and thus approximate simulations of the diffusion and ground deposition of the particulates can be obtained by matching only the dimensionless velocity ratio (1).

The Case of Small Froude Numbers

The dimensionless Froude number $\,V_g^2/gL\,$ may be interpreted to be the ratio of the particle response time (or distance) to the characteristic time (or size) of the turbulent eddies. When the particle response time is very short, compared to the characteristic time of the turbulence, during which significant changes in the velocity field seen by the particle occur, the particle will be in a local equilibrium with the flow and, in the limiting case of $V_g^2/gL \rightarrow 0$, the velocity of the particle will be equal to the vectorial sum of the local velocity and the settling velocity;

$$\vec{V} = \vec{U} - V_g \vec{k} \quad . \tag{4}$$

In this case, the dispersion of the particles is expected to be independent of both the Froude number and the particle Reynolds number. Cases of very small Froude numbers are frequently encountered in many environmental phenomena and thus wind-tunnel simulation of such cases is of considerable interest.

2.3 Characteristic Response Times of Particles

The motion of a solid particle in an unsteady velocity field may be approximately described by the following equation (Soo, 1967) 13:

$$\frac{\pi}{6} d^3 \rho_p \frac{D}{Dt} \vec{V} = \frac{\pi d^2}{4} \frac{\rho}{z} c_D (\vec{U} - \vec{V}_p) | U - V_p |$$

$$+\frac{\pi}{6} d^{3} (\rho_{p} - \rho) \vec{g} + \frac{1}{2} \frac{\pi}{6} d^{3} \rho \frac{D}{Dt} (\vec{U} - \vec{V})$$
 (5)

This equation neglects the effect of the pressure gradient as well as that of the so-called Busset-history-term, which might be important under conditions of high acceleration and when the particles and fluid densities are of the same order of magnitude. When $\rho_p >> \rho$, the last term in Eq. (5), which describes the effect of the added mass on the particle acceleration, may also be neglected, and the equation of motion can be written as:

$$\frac{\mathrm{d}}{\mathrm{dt}} (\vec{\mathbf{V}}) = -\mathbf{g} \, \vec{\mathbf{k}} - \frac{3}{4} \frac{\rho}{\rho_{\mathbf{p}}} \frac{\mathbf{c}_{\mathbf{D}}}{\mathrm{d}} |\vec{\mathbf{V}} - \vec{\mathbf{U}}| \cdot (\vec{\mathbf{V}} - \vec{\mathbf{U}})$$
 (6)

The drag coefficient is a function of the Reynolds number of the relative particle motion, Re = $|\bar{V} - \bar{U}| \cdot d/\nu$. This function can usually be described, within a certain range of Reynolds numbers, as a power law:

$$C_{D} = C \cdot Re^{-n} \tag{7}$$

The power $\,$ n in this equation is 1 for small Reynolds numbers and 0 for large Reynolds numbers.

We shall define the response time of particles with appreciable settling velocity by considering the motion of particles whose speed is close to their settling velocity. Consider a particle that at t=0 is moving in stagnant air at a speed

$$\vec{V} = -V_g[(1 + \epsilon_z(0))\vec{k} + \epsilon_y(0)\vec{j}] . \qquad (8)$$

The decay of both $\epsilon_z(t)$ and $\epsilon_y(t)$ may be calculated from Eq. (5). Using the power law approximation for c_D one finds from Eq. (5) that

$$\frac{d\vec{V}}{dt} = -g\vec{k} - \frac{3}{4} \frac{\rho c_v v_g^{2-n}}{\rho_p d^{1+n}} [(1+\epsilon_z)^2 + \epsilon_y^2]^{(1-n)/2} \cdot [(1+\epsilon_z)]\vec{k} + \epsilon_y \vec{j}]$$
(9)

At large t, both ϵ_z and ϵ_y are zero so that

$$V_{g} = \left(\frac{4g}{3C} \frac{\rho_{p}}{\rho} \frac{d^{1+n}}{\nu_{n}}\right)^{1/(2-n)}$$
(10)

and one may rewrite Eq. (9) as

$$-\frac{\mathbf{v}_{\mathbf{g}}}{\mathbf{g}}\frac{\mathbf{d}}{\mathbf{d}\mathbf{t}}\left(\varepsilon_{\mathbf{z}}\mathbf{\bar{k}} + \varepsilon_{\mathbf{y}}\mathbf{j}\right) = -\mathbf{\bar{k}} + \left[\left(1+\varepsilon_{\mathbf{z}}\right)^{2} + \varepsilon_{\mathbf{y}}^{2}\right]^{(1-n)/2}\left[\left(1+\varepsilon_{\mathbf{z}}\right)\mathbf{\dot{k}} + \varepsilon_{\mathbf{y}}^{2}\mathbf{\dot{j}}\right]$$
(11)

Separating the two acceleration components, one finds that for small $\epsilon_{_{\mbox{\scriptsize V}}},$

$$\frac{d\varepsilon_{y}}{dt} = -\frac{g}{V_{g}} \varepsilon_{y}$$
 (12)

and

$$\frac{\mathrm{d}\varepsilon_{\mathbf{z}}}{\mathrm{d}\mathsf{t}} = -\frac{\mathbf{g}}{\mathbf{v}} \ (2-\mathrm{n}) \ \varepsilon_{\mathbf{z}} \tag{13}$$

The solutions of these equations are

$$\varepsilon_{\mathbf{y}}(t) = \varepsilon_{\mathbf{y}}(0) \exp[-t/(V_{\mathbf{g}}/g)]$$
 (14)

and

$$\varepsilon_{\mathbf{z}}(t) = \varepsilon_{\mathbf{z}}(0) \exp[-(2-n)t/(V_{\mathbf{g}}/g)]$$
 (15)

One may thus define two characteristic response times T and T, which are measures of the time it takes particles falling at a relative speed $V_{\mathbf{g}}$, to adjust to new field conditions, as

$$T_{y} = \frac{V_{g}}{g} \tag{16}$$

and

$$T_{z} = \frac{V_{g}}{(2-n)g} \tag{17}$$

One may also conclude from the above analysis that when the Reynolds number of the relative motion of particle is small (n = 1), the response of the particles will be isotropic, namely,

$$T_{y} = T_{z} = T = \frac{V_{g}}{g} \tag{18}$$

We shall refer to T as the nominal response time of the particles.

When the Reynolds number increases and the inertial effects become significant, n decreases and the response time of the particles to horizontal velocity, which changes according to Eq. (17), would be larger than its response to vertical velocity fluctuations. For very large Reynolds numbers (n = 0) the ratio between the horizontal and vertical response times will be 2.

2.4 The Range of Froude Number Independence

We assume that when the response time of the free falling particles is small compared to the time it takes the particles to cross the energy-containing eddies, the diffusion process would be independent of both the Froude number and the particle's Reynolds number.

Denoting by ℓ , the smallest significant eddy size and assuming that a characteristic travel time of a particle within this eddy is ℓ/V_g , our assumption should be valid when

$$\frac{V^2}{g\ell} = k \ll 1 . \tag{19}$$

Csanady (1963), (also see Pasquill, (1974), 0 p. 152), estimated that the particle would fully respond to the turbulent motion when

$$\frac{V_g^2}{g\ell} < \frac{1}{2\pi} \qquad . \tag{20}$$

The diffusion of a continuous plume from an elevated source at a height h above the ground is primarily determined by the energy containing eddies whose size is of the order of h. If one neglects the contribution to the diffusion process of eddies whose size is

$$\ell < 0.2 \text{ h} , \qquad (21)$$

one finds that the effect of $V_g^2/g\ell$ may be neglected when

$$\frac{V^2}{\frac{g}{gh}} < 0.0328 . (22)$$

Another criterion related to the effect of the fall velocity on diffusion has been derived by Smith (1961), ¹² (also see Pasquill, (1974), pp. 135-151). ¹⁰ According to Smith, the long-time growth of a cluster of particles descending in a turbulent field is attenuated by the factor $(1 + \beta^2 V_g^2/(U^2)^1/4$, where β is the ratio of the Lagrangian to the Eulerian integral time scales. For $\beta = 5$ and

$$\frac{V}{U} < 0.1$$
, (23)

the effect of the fall velocity on the expansion rate of a cluster is expected to be smaller than 10 percent. The effect of the fall velocity on continuous particle plumes is expected to be smaller than its effect on clusters. Thus, it will be assumed at this stage, that when both Eq. (22) and Eq. (23) are satisfied, the diffusion of a continuous particle plume can be independent of the Froude number and of the particle's Reynolds number. It also follows that approximate simulations of the diffusion of such plumes can be obtained by matching only the ratio of the velocity ratio $V_{\rm g}/U$ in the model and atmosphere.

Such approximate simulations will not include, of course, the full effect of turbulent eddies which are much smaller than 0.2 h. For this reason, they cannot be used to study the relative diffusion of clouds (two-particle diffusion problems), where the effect of the small eddies cannot be neglected.

3.1 General

Models for diffusion and deposition of particle plumes, composed of particles with appreciable settling velocities, are generally based on similar models for diffusion of passive tracers. They either use the differential equation describing the mean conservation of mass together with some type of closure, such as the K-Theory (Godson, 1958), or they use a statistical approach like the Gaussian model (Csanady, 1963; Overcamp, 1976).

Gaussian models are widely used for predicting dispersion of passive tracers and we have therefore decided to analyze our experimental data using the simplest possible Gaussian model. The simplest available Gaussian models are based on the assumption that the vertical distributions of particle plumes can be described by a Gaussian function, except that the plumes tilt down at a slope of V_g/U , where V_g is the settling velocity. The use of such models has turned out, however, to be problematic, due to the boundary conditions at ground level. $\textbf{Chamberlain (1953)}^{\textbf{5}} \ \textbf{proposed} \quad \textbf{that the rate of deposition on the ground}$ is proportional to the ground-level concentration (the concentration in the air just above the ground). The constant of proportionality is the deposition velocity $V_{\mbox{\scriptsize d}}$ which has to be determined from experiments or theory. In addition, one has to account for the effect of the ground on the plume, which is described in the case of passive tracers $(V_0 = 0)$ emitted from z = h by an image source at z = -h. In cases when $V_d \neq V_g$ the adoption of these assumptions violate the mass conservation equation and complicated models were developed to calculate the appropriate strength of an image area source which will satisfy the conservation of mass (Overcamp, 1976).9

Since the present study is limited to the case of particles with appreciable fall velocity, one can simply overcome this problem by considering only the motion of the real plume and completely ignore the image plume and the assumption of Chamberlain. Furthermore, since we limit the study to small Froude numbers, the values of $\sigma_{\rm Z}$ and $\sigma_{\rm y}$ are assumed to be the same as in corresponding cases of passive particles.

Consider an ASL in which the diffusion of a tracer from an elevation is described by

$$C^{y}(x,z) = \frac{Q}{(2\pi)^{\frac{1}{2}}\sigma_{z}U} \exp\left(-\frac{(h-z)^{2}}{2\sigma_{z}^{2}}\right)$$
 (24)

where $C^{\mathbf{y}}$ is the cross-wind integrated concentration

$$C^{y} = \int_{-\infty}^{\infty} C(y) dy, \qquad (25)$$

Since the lateral diffusion is usually Gaussian, namely

$$C(y) = C_{\text{max}} \exp(-\frac{y^2}{2\sigma_v^2})$$
, (26)

the cross-wind integrated concentration is given by

$$C^{\mathbf{y}} = (2\pi)^{\frac{1}{2}} \cdot C_{\max} \sigma_{\mathbf{y}} . \tag{27}$$

The probability of a particle emitted at $\,h\,$ to pass, at a given distance $\,x\,$ between the elevations $\,z\,$ and $\,z+dz\,$ is given by

$$P(z)dz = \frac{1}{\sqrt{2\pi} \sigma_z(x)} \exp(-\frac{(h-z)^2}{2\sigma_z^2}) dz$$
 (28)

Since particles in a particle-plume are on the average settling down at a velocity V_g , we shall assume that the probability of particles depositing between x and x+dx is equal to the probability P(z)dz for $z = V_g x/U$ and $dz = (V_g/U)dx$. Substitution in Eq. (28) gives:

$$P_{x} = \frac{1 V_{g}}{\sqrt{2\pi} \sigma_{z} U} \exp \left[-\frac{\left(h - \frac{V_{g}}{U} x\right)^{2}}{2\sigma_{z}^{2}} \right]$$
(29)

It must be realized that this model is an approximate one and should be limited to large values of fall velocities, as Eq. (29) does not exactly satisfy the continuity equation. Namely

$$\int_{-\infty}^{\infty} P_{X} dx = 1 + E , \qquad (30)$$

where E is an error which depends on $\sigma_z(x)$ and V_g/U .

Numerical integration of Eq. (30) for the experimental range 0.11 < V $_g/U$ < 0.045 shows that for this range E \leqq +3%. The error increases for smaller values of V $_g/U$ (E = 10% at V $_g/U$ = 0.006). It also increases when the rate of growth of σ_z with x does (see Eq. (38)).

At any rate, the errors for relatively large full velocities are estimated to be much smaller than the uncertainties in the values of the various variables or the accuracy of the Gaussian model (Eq. (24)). Thus, the mass inconsistency of the model will be ignored at this stage.

Using dimensionless variables

$$\sigma^* = \sigma/h \quad \text{and} \quad x^* = x/h \tag{31}$$

Eq. (29) becomes

$$P(x^*) = \frac{V_g/U}{\sqrt{2\pi}\sigma_z^*} \exp \left[-\frac{(1-\frac{g}{U} \frac{x}{h})^2}{2\sigma_z^{*2}} \right]$$
(32)

A particle-plume with $\sigma_z \rightarrow 0$ will deposit according to Eq. (29) at

$$\frac{x}{h} \frac{V}{U} = 1 . (33)$$

If the velocity in the boundary layer is described by a power law

$$\frac{\mathbf{u}}{\mathbf{U}_{\text{REF}}} = \left(\frac{\mathbf{z}}{\mathbf{Z}_{\text{REF}}}\right)^{\mathbf{m}} \tag{34}$$

where m is a positive number (usually between 0.1 and 0.3). A plume with $\sigma_z \to 0$ would deposit in such a velocity field at a closer distance

$$\frac{x}{h} \frac{Vg}{U} = \frac{1}{(1+m)}$$

To account for this effect, we shall replace Eq. (33) by

$$P(x^*) = \frac{(1+m)V_g/U}{\sqrt{2\pi} \sigma_z^*} \exp \left[- \frac{(1 - (1+m) \frac{V_g}{U} \frac{x}{h})^2}{2\sigma_z^{*2}} \right]$$
(35)

3.2 On the Values of σ_z and σ_y

The value of σ_Z , for both passive tracers and particulates, is expected to be determined by the atmospheric stability, the surface roughness (Z_O) the thickness of the atmospheric boundary layer (δ) and the height of the source (h). Thus, for a given stability and surface roughness, one expects to find in the literature dimensionless expressions for σ such as

$$\frac{\sigma}{\delta} = F(\frac{x}{\delta}, \frac{h}{\delta}) . \tag{36}$$

Instead, both $\sigma_z(x)$ and $\sigma_y(x)$ are generally described by dimensionally non-homogeneous functions of x and y. Within a limited range of x it is usually assumed that

$$\sigma_{z} = ax^{b}$$
 and $\sigma_{v} = cx^{d}$ (37)

where a, b, c, and d are independent of h and δ . We shall also assume that σ_z and σ_y in the atmosphere are approximately independent of h and use, for length scales in meters, the values

$$a = 0.62$$
 $b = 0.6$ $c = 0.23$ and $d = 0.85$ (38)

which provide a good approximation, in the range of $10^3 < x(m) < 10^4$, to the equations proposed by Briggs $(1973)^1$ for diffusion in a neutral atmosphere for open country. We shall, however, assume that σ is a function of the boundary layer thickness δ which is of the order of 600 m in the atmosphere (Counihan, 1974), 6 in correlating the atmosphere and the wind tunnel, where δ is of the order of 1 m. Accordingly we assume that

$$\frac{\sigma_z}{\delta} = k \left(\frac{x}{\delta}\right)^b$$
 and $\frac{\sigma_y}{\delta} = e \left(\frac{x}{\delta}\right)^d$ (39)

where

$$k = a(600)^{b-1} = 0.048$$

and

$$e = C(600)^{d-1} = 0.088.$$

The dimensionless spread σ_z^* is thus given by

$$\sigma_z^{\dagger} = \frac{\sigma_z}{h} = k(\frac{\delta}{h})^{1-b} x^{\dagger b} . \tag{40}$$

4 EXPERIMENTAL FACILITIES, PROCEDURES AND THE EXPERIMENTAL PROGRAM

4.1 Wind Tunnel

The experiments were conducted in the Meteorological Wind Tunnel (MWT) at Colorado State University. Design and operation of the wind tunnel are described in detail by Cermak (1981). Elevation and plan views of the MWT are shown in Figure 1.

A very fine screen was installed at the entrance to the MWT test section. The screen produced a considerable pressure drop, which reduced the pressure in the test section below pressure outside the tunnel.

Spires were installed downstream of the screen during the diffusion tests to produce a third turbulent boundary layer in the tunnel.

4.2 Particles

Expanded polystyrene particles of an average diameter of 1 mm were used in this study. The particles, supplied by the Department of Research and Development, Arco Chemical Company, Newtown Square, Pennsylvania, were initially sorted into groups by the following procedure. The particles were released from an elevated source in a uniform flow and allowed to deposit on the floor of a small wind-tunnel, which was covered with open elongated containers, as shown in Figure 2(a). The fall velocity, of the groups of particles found in each container, was initially estimated by $V_{\rm g}=Uh/\bar{x}$. About 200 particles from each group were then released from a 4 mm ID brass tube installed in the MWT at an angle $\alpha=\tan(V_{\rm g}/U)$ (see Figure 2b). The brass tube was connected to a plastic tube which ended outside the tunnel. The difference between the outside pressure and the pressure in the test section produced a flow of air in the tube which was adjusted, by changing the length of the tube, to produce an average exit velocity of the order of U.

The tube acted like a small vacuum cleaner and the particles were easily sucked in by the tube and then injected in the tunnel. The nominal fall velocity of each group of particles was then corrected using the average deposition distance in this experiment. The distribution of the particles suggested that the fall velocities in each group were distributed in the range $V_g(1\pm E)$, where V_g is the average fall velocity. The value of E was approximately 0.10 for the groups of particles with fall velocities of the order of 0.3 m/s. It was, however, much larger for groups of particles with fall velocities of the order of 0.6 m/s, since the ratio of the width of the containers, shown in Figure 2(a), to the distance x, was in these cases larger.

The distance \bar{x} in this configuration was on the average 2.5 m and h/\bar{x} varied between 0.12 m to 1.5 m.

It is estimated that the accuracy of this procedure for determining the average value of V_{ρ} for each group is of the order of 7 percent.

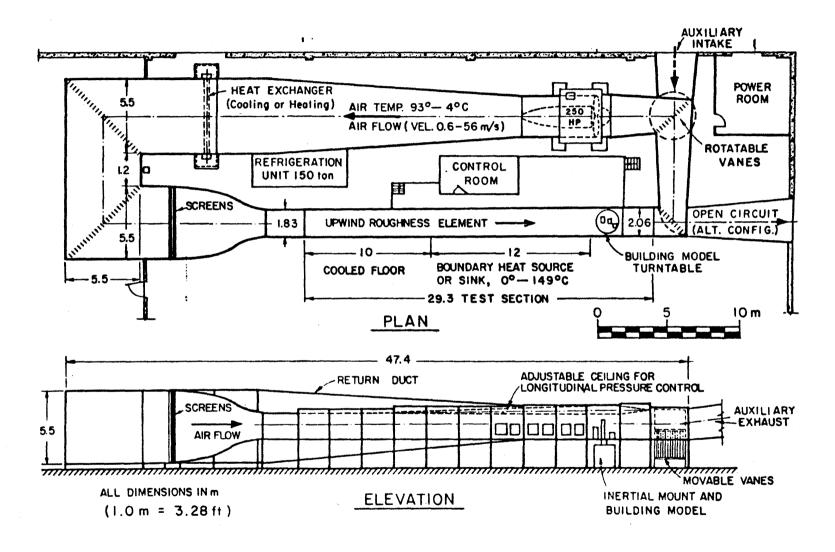


Figure 1. Meteorological Wind Tunnel, Fluid Dynamics and Diffusion Laboratory, Colorado State University

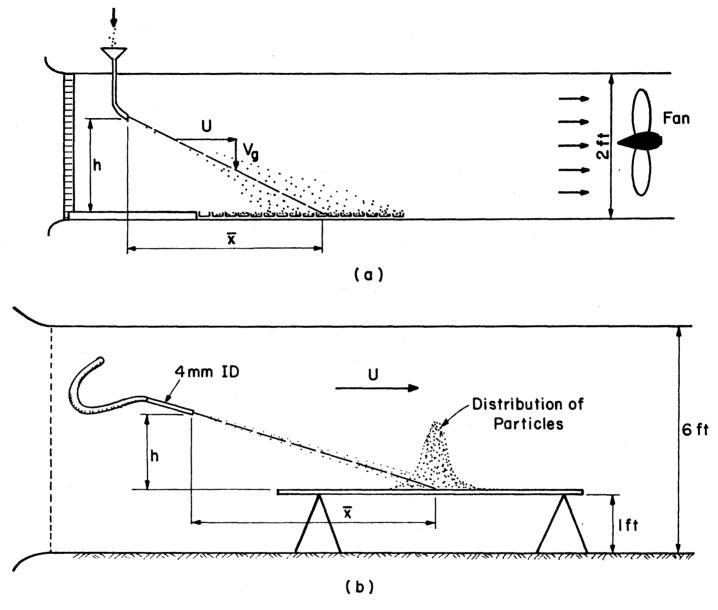


Figure 2. Experimental configurations for (a) sorting the particles and (b) determining their average fall-velocity.

4.3 The Velocity Profile in the Wind Tunnel

Typical mean velocity profiles in the wind tunnel, measured with a calibrated Thermo-system hot wire Model 1050, are shown in Figure 3. We have not used any roughness elements to increase the roughness length of the wind-tunnel floor in order to facilitate the measurement of the particle deposition on the floor. For this reason the velocity profile was relatively flat and is approximately described by Eq. (41) with a power m = 0.12.

The wind velocities in the tunnel in the experiments were in the range U = 3.00 - 7.00 m/s, where U is the mean velocity at the height of the source.

4.4 Deposition Measurements

Particles were injected into the flow, using the method described earlier, at an angle $\,^{\rm V}$ /U. The average air speed of the air flowing through the tube was $\,^{\rm U}$. A few thousand particles were injected at each run.

A light-colored grid was drawn on the black floor of the wind tunnel, which was then covered with a thin layer of machine oil. Particles touching the floor adhered to it and could not move. It was relatively easy to count the number of particles (n) between two lateral lines $x \pm \Delta x/2$ and the number of particles (m) between two longitudinal lines $y(x) \pm \Delta y/2$. The step Δx was 0.5 ft up to x = 13 ft and 1 ft after x = 13 ft. The step Δy was 0.5 in. up to 12 ft and 1 in. after 12 ft. The mean position $\bar{Y}(x)$ and the standard deviation of the lateral distribution at each distance from the source x, was calculated using the equations

$$\bar{Y} = \Sigma(my)/n$$

and

$$\sigma^2 = \frac{\sum m(Y_i - \bar{Y})^2}{(n-1)} . \tag{41}$$

Variance of the population $(n\to\infty)$ was assumed as given by the right-hand side of the above equation. The number of particles which had deposited at the very small and very large distances from the source was relatively small. Thus, the estimate of σ is not very accurate. Figure 4 shows two typical lateral distributions of particles which demonstrate this point. Figure 5 shows the measured distributions of $\sigma(x)$ for three identical runs (Runs 1-3). It clearly shows an increased uncertainty in the estimate of σ at small and large distances.

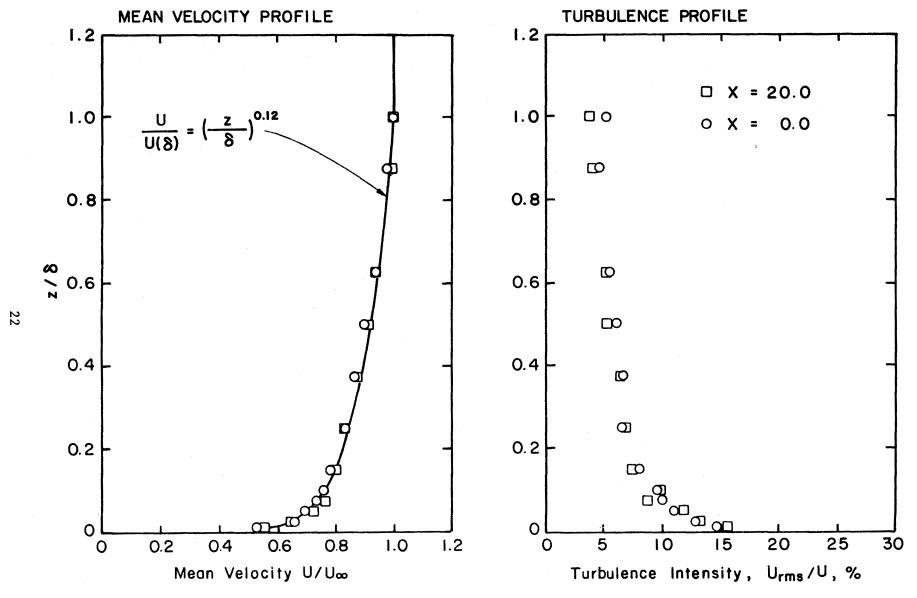
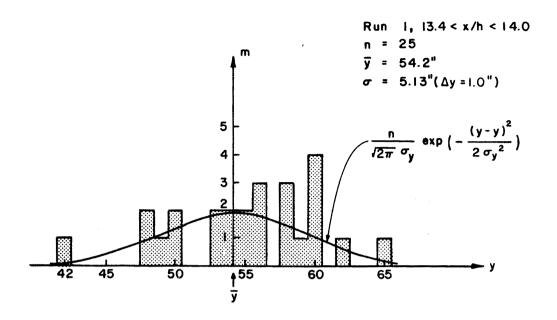


Figure 3. Mean velocity and turbulence profiles in the wind tunnel.



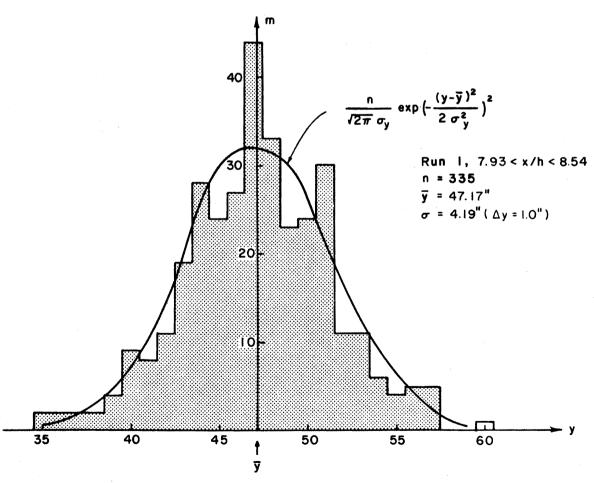


Figure 4. Typical lateral distribution of particles.

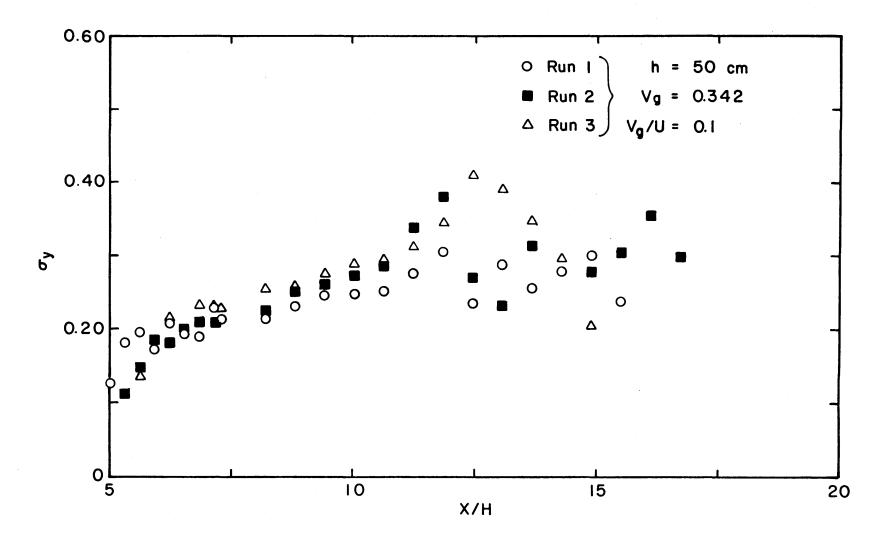


Figure 5. Measured values of $\sigma_y(x^*)$ in three identical runs.

4.5 The Experimental Program

The experimental program was composed of 16 runs, in which the deposition of 6 groups of particles released from 2 heights, at the same dimensionless mean velocity field, was measured.

The mean velocities in these runs were selected to produce five different velocity ratios V_J/U . Note that the mean velocity U_J is the velocity at the height of the source z = h.

The values of the various parameters in each run are given in Table 1. The measured longitudinal distribution of the particles on the floor of the wind tunnel and the values of \bar{Y} and $\sigma_y(x)$ are presented in Table 2.

Table I
The Experimental Program

Run	h	V _g			
No.	(m)	m/sec	V _g /U	V _g /gh	N
1	0.50	.34	.10	.024	2326
	0.50	.34	.10	.024	2396
3	0.50	. 34	.10	.024	4083
4	0.50	. 42	.11	.035	2504
2 3 4 5 6 7 9	0.50	.300	.10	.018	2311
6	0.50	.65	.10	.087	4605
7	0.50	.61	.10	.076	3499
9	0.50	.34	.075	.024	2718
10	0.50	.34	.06	.024	6117
11	0.375	.34	. 10	.029	2799
12	0.375	.28	.10	.021	1132
13	0.375	.32	.075	.029	2966
14	0,375	.61	. 10	. 10	1705
15	0.375	.42	.11	.047	2008
16	0.375	.32	.06	.029	3187
17	0.375	.32	.047	.029	4133

Table 2. The experimental results.*

RUN NO. = 1

H=.	500 VG= /U)= .10	- .342 0 ≥N=	VG**2/(G*H)	= .024		NO. = 2	•		
ı	х/н	N	SGNO/H	YA/H	H≖. (VG	500 VG=. /U)= .100		/G**2/(G*H): 2393	024
•	,	7	1077	2 007	I	X/H	н	SGNO/H	YA/H
1234567890123456789012	233444556677890123456789 	3868444632504784882549 12479452382462845321 113332211	.0277924800165644199937792488016577934800165644199934906577964065779640657796406577964065779640657796406577964065779640657796406577964065779640657796406577964065779640657796406577964065779640657799999999999999999999999999999999999	2561395576630824318574 8697115123902715251553 01222222353344455667778 01222222333344455667778	12345678901234567890123	244556672890123456789012 369258173962845840739 55566677889001223345566	61077401074617301091013 13672461074617301091013 1113322211	225888814438095B23515885 507475888814438095B2357181588 2588426264785873679676 2588426264785873679676 2588426666666666666666666666666666666666	GSOSGR. TOBBETBES STANGER TO COMPS & SOCIETA TO COMPS STANGER TO COMPS & SOCIETA TO COMPS AND CO
H=,		3 .342 0	VG**2/(G*H) 4083	= .024	11=	N NO. = .500 VG= G/U)= .10	4 :•373 00 ≰N:	VG**2/(G*H =2504)= .023
I	X/H	H	SGNO/H	YA/H	I	х/н	И	SGNO/H	YA/H
1234567850123456789012	233344556467890123456789 70334925817394284042849 455554666778899011223345	69.5455197.05149233392780 258512279390113264312 12222545432211	2114938271063625552588 910929922740636255588 10223443225578944456140 1022344322557894455148 10223534557894455148 10223544322557894459500 10223557894459500	190300001314707457559908 7342757905471807887948 80000000111112255445454 100000000111112255445454 1000000000000000000000000000000	12345678901123456789	555566678901234567 5555666777889012234 51113962840628 51113962840628	050277330806823738708 04770794189446174610 11122352911	1504551080006168002051 0714168000110016168002051 07464718000110016168002051 07508744021001016168002051	11111000000000000000000000000000000000

*VG
$$\equiv$$
 V_g; SGNO \equiv σ _y; YA \equiv \bar{y} ; H \equiv h.

Table 2 (Continued)

Н≕.		5 , 299	<u>45**2/(g*</u> H)= .013	H=	N NO. = .500 YG= G/U)= .10	5 :.650	VG**2/(9*H =4605)= .036
ı	У Б У≃ , 10.	:=H ≥ C H	SGNO/H	YA/H	1	х/н	N	SGNO/H	YA/H
123456789012345678901	3344556678901234456789 03692566778901233445 555566677889001233345	83390308400569.2299007 1117701569.2299	.35577 .35587 .356883 .40134 .3184349 .21249 .2224421 .222442 .2	3169775598372509040036 99188430810372240904 11112222234435330 11112222222222222222	123456789012345678901	45566789012345678901 92581739628406284073951739517740 56667788990012233455667889901 111111111111111111222222	7362807867330122980427017676045 11234443322211	50463B1061759369575492150268590 0479829313271856925773034194934 4442253535353444647721306286953474 544226353535354443454534	467.5003310900244783704488745731460 087.8005148937755550080080105140023 970398999899900001100121213557 111111111111111111111111111110100000000
H=,		7 .610 D ZN=:	VG**2/(G*H 3499)= .076	H=.	NO. = 9 500 VG= 7U)= .075	342 (5 ≤N=2		
I	жин	N	SGNO/H	YA/H	7	X/H	N	SGNO/H	YA/H
123456789012345678901234	\$255667890123456789012345 \$2556677788.96212344567890123345556677788.96212334555.667888	009116836654483364167519 1123333522111	.4057 .42130 .42130 .21334 .22438 .22459 .22459 .22459 .22459 .329718 .339719 .3397114 .339733 .33114 .331329 .33129 .33129 .33129 .33129 .33129 .33129 .33129 .33129 .33129 .33129 .33129 .33	560509335499204179093327 8979797986336304303250342 1111111111222222222222222	12345678901234567890123456789012345678	34455667890123456789012345667889701233456 55556667788900122334566788970112334456 511111111111111111111222222222222	13750320089450651556680520545611290379 113334151001786328956744332111111 11	00048437955045045595074444600000000000000000000000000000000	1111CRCRCRCRCRCRCRCRCRCRCRCRCRCRCRCRCRC

Table 2 (Continued)

RUN	NO. = 1	0			คบห	! NO. = 11	l		
	500 VG= 3/U)= .06	.342 0 £N=	VG**2/(G*H =6117)= .024		375 VG= . 3/U)= .100	324) ≰N=	VG**2/(G*H)= 2799	.029
I	X/H	И	SGNO/H	YA/H	I	X/H	и	SGNO/H	YA/H
123456789012345678901234567890 1111111111112222222222233333333333333	5840628406284073951739628440628407395173962840628407395173962840628407395173962840628517395173962840628407395173951739628406284073951739517396677899012334456677899001123334456677899001123334456677899000000000000000000000000000000000	5553213784405294387879455878009379422870111122235322222221111111	00002850694788199879285851069057725240140 0006436391986662575468494753484609197497 00064855802353577397491487014299119744970 0000.0000000000000000000000000000000	000509097947544587485501008855750759900050905754755754458745850100404467479551000050585074795510568907741958100000000000000000000000000000000000	1234567890123456789012345678	7789901122344568901345789023 445555667778899911123456420864313 90111234566789023	2459181276267918547691250545 112222211211	007985750672515074932300000 000704269852232305460800000 0075M5810812968705460800000 0075M5810812968705450800000	11000000000000000000000000000000000000
41 42 43 44	30.94 31.55 32.16	20 425 27 27 27 25	0.000 0.000 0.000 0.000	0.000 0.000 0.000	H= .	1 NO. = 13 375 VG= 3/U)= .07	.324	VG**2/(G*H)= 2966	.029
45 46 47	32.77 33.38 33.99	25 13 18	0.000 0.000 0.000	0.000 0.000 0.000	I	X/H	н	SGNO/H	YA/H
H=		.2 281)0 £n	VG**2/(G*H =1132	1)= .022	1234567B	5.89 6.371 7.522	35 16 26 54 76 86	0.000 0.000 0.000 0.3685 0.3562 0.4555	11112C222222
I	X/H	N	SGNO/H	YA/H	10	8.74	128 122 152 186	.4647 @ .4890 .2377	2.778 2.789 2.890
12345678901234567890	789901112234456890111233	34054397649402294331 123668999098602432211	00000000000000000000000000000000000000	555453515850145739 555451353178305441 4445788999999110235 111050460000000000000000	11111111122222222222	7456890134578902346789 9990134578902346789 111123456678902346789 111123456678902346789	13522211 135222211	**************************************	04040860989380577000 9050956094865908057000 80990910334435657000 80990910334435657000

Table 2 (Continued)

H=.	NO. = 14 375 VG=4 /U)= .100	609 V	/G**2/(G *H))= .101	H=	JN NO. = =.375 VG VG/U)= .1	=.373	VG**2/(G*) =2008	н)= .038			
I	X/H	N	SGNO/H	YA/H	I	X/H	И	SGNO/H	YA/H			
1234567890123456789012345678	7899011122344568901345789901112344568900134571778899901112345566797788999011112345667890011111111111111111111111111111111111	12334545156164686005805454072 123456164686005805454072	00006816089599599536400000 0007256808959959953640000 00073445555648758863040000 0000000000000000000000000000000	445473153725852333344221992200000 -445473105509188044059000000 -444445555556477788890000000 -11122222222222222223333000000	123456789012345678901234	7789990112223445568 44555566777788899013345667 1011234-2086 111234-111111111111111111111111111111111	3613663974532572119830542 111122111111111111111111111111111111	0000515380988583852200000 0002555575485178846800000 000743098415089468700000 000745555754855532245444.0000	345D41B94C0546B059500000 9554690B5C4055B074B500000 4446657778B9999C0111100000			
					RUN	NO. = 17						
RU	N NO. = :	16			H=.375 VG=.324 VG**2/(G*H)= .029 (VG/U)= .047 ≤N=4133							
	.375 VG= G/U)= .00	=,324 50	VG**2/(g*) =3187	H)= .029	I	X/H	N	SGNO/H	YAZH			
I	X/H	N	SGNO/H	YA/H	1 2 3	7.11 7.52 7.92 8.33	470	0.000	1.456 1.456			
12345678901234567890123456789012345678	011122344568901345789023467891235678012 37159371531986420864319753198642086531 66777788990111234566789900123445678990123 11111111111111222222222222233333	44628521783172505783169593319759537548 1222212111111	0000920 0000920 0000920 00009212497 00009227549497 0000000000000000000000000000000000	11122222222222222222222222222222222222	34567890123456789012345678901234567890123	### ##################################	47.27876714448433816575150541584153912771330 12579224888997567536411584153912771330	000055952939016871182078682368537393025000 000045995293927445033392958625339225041000 00004515157464329221792558653357286225041000 000040434344445555566666667777778676688977	\$33DGQ39D13D08B01745518B79177360416739000 \$555045675BC4063498B506C7466152CQ7559734000 \$447764545555649554455544556500151CC55000 \$11120000000000000000000000000000000			

5 ANALYSIS OF THE RESULTS

5.1 The Analytical Model

The very simple analytical expression for the probability of deposition, which gives the relative cross-wind concentration on the ground per unit length, makes it easy to evaluate the effect of the various variables on the deposition pattern. Of course, the restrictions of the model should be recalled before using this expression.

The dimensionless distribution $P(x^*)$ can be written as

$$P(x^*) = \frac{nh}{Ndx} = \frac{(1+m)}{(2\pi)^{\frac{1}{2}}} \frac{V_g}{U} \frac{h}{\sigma_z} \exp \left[-\frac{(1-\frac{(1+m)V_g x}{Uh})^2}{2(\sigma_z/h)^2} \right] . \quad (42)$$

Since the variation of the first factor in this equation is relatively slow, the position of maximum deposition, X_{\max} , is primarily determined by the second factor and is expected to be at

$$\frac{X_{\text{max}}}{h} = e \cdot \frac{U}{(1+m)V_g}$$
 (43)

where e is a coefficient which is smaller than 1.

Figure 6 shows the dependence of X_{max}^{*} on the relative fall velocity V /U, according to Eq. (42). It also shows the approximate solution (43), with e = 1. One sees that e varies between 0.77 to 0.96 in the range 0.02 < V_g/U < 0.1.

The maximum deposition rate, at that point, is approximately given by

$$P(x^{*})_{max} = \frac{(1+m)}{(2\pi)^{\frac{1}{2}}} \frac{V_{g}}{U \sigma^{*}(x_{max}^{*})}$$
(44)

Using Eq. (44), one finds that

$$P(x^*)_{\max} = \frac{(1+m)^{1+b}}{k\sqrt{2\pi}} \left(\frac{g}{U}\right)^{1+b} \left(\frac{h}{\delta}\right)^{(1-b)}$$
(45)

Figure 7 shows the exact theoretical solution for $P(x^*)_{max}$ for $h/\delta = 0.5$. It also shows that the approximate solution (Eq. (45)) deviates from the exact solution by a small fraction only. Figure 8 shows the dimensionless distribution $P(x^*)$ for three velocity ratios

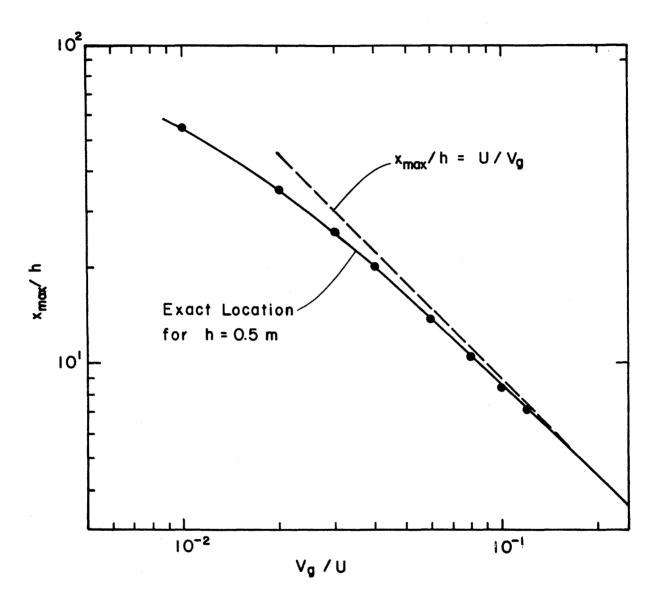


Figure 6. The dependence of the position of maximum deposition x^{*}_{max} on $V_{g}/U.$

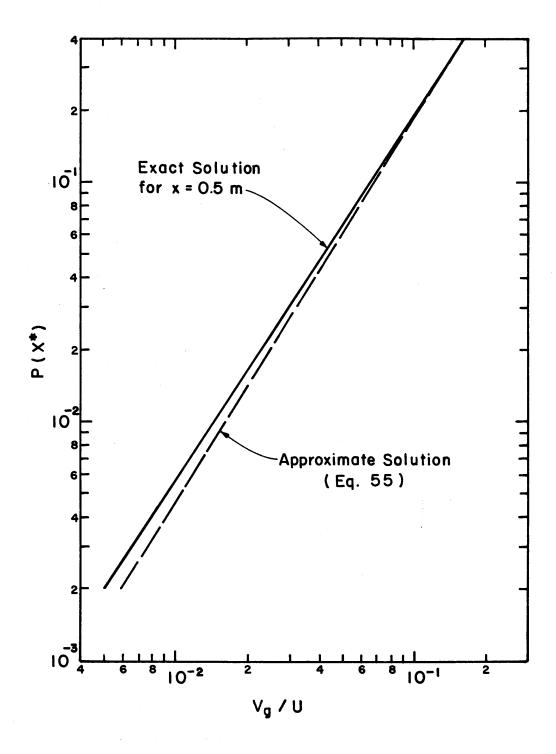


Figure 7. The dependence of $P(x^*)_{max}$ on V_g/U .

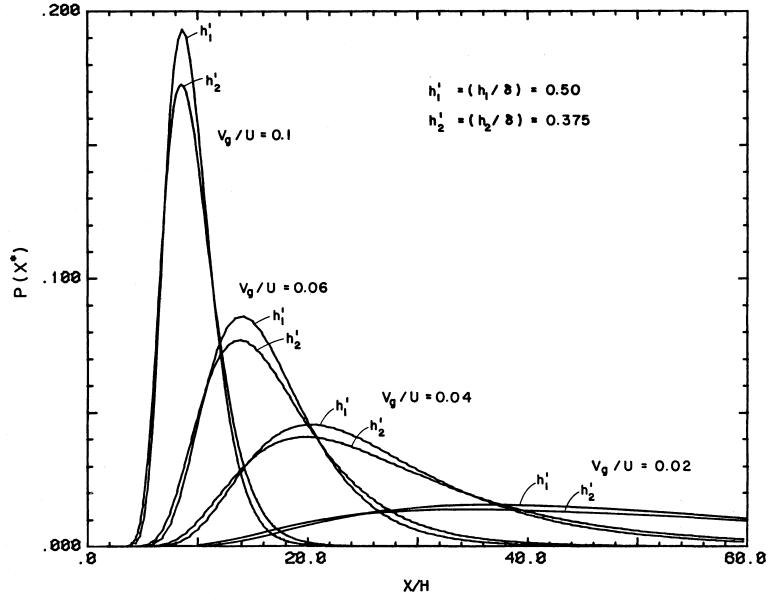


Figure 8. The dimensionless distribution $P(x^*)$ for different velocity ratios and different source heights.

and two values of h. The figure clearly demonstrates that the velocity ratio is the most significant parameter that affects the longitudinal dimensionless probability of the particle distribution. The function $P(x^*)$ data for h=0.5 m is also plotted in Figure 9, using log-log coordinates.

5.2 The Measured Longitudinal Deposition

Before comparing the measured longitudinal deposition of the particles with the model (Eq. (35)), attention should be given to the effect of possible errors in the estimated average values of $_{\rm g}^{\rm V}/_{\rm g}^{\rm U}$ for each group of particles as well as to the effect of the distribution of $_{\rm g}^{\rm V}/_{\rm g}^{\rm U}$ in each group.

We have seen earlier that the position of the maximum concentration x_{max}^{\star} is proportional to hU/V_g . Thus, the error in x_{max}^{\star} is proportional to values of the errors in estimating these parameters. The maximum of $P(x^{\star})$ is proportional to $(V_g/U)^{1.6}$ and thus a 10% error in V_g/U will produce a 16% error in $P(x^{\star})_{max}$.

Fractional errors in estimating V/U might, however, cause dramatic changes in the value of $P(x^*)$ at particular locations x^* , smaller or larger than x^* as demonstrated in Figure 10. Thus, the agreement between the experimental and theoretical results should be evaluated by the differences in x^* and $P(x^*)$ and by the general shape of the distribution $P(x^*)$ and not by the differences between the values of $P(x^*)$ at small and large distances.

We have mentioned earlier that the distribution of the velocity ratio of particles within each group was much larger for particles with large fall velocities. To demonstrate the effect of the distribution of V_g/U within each group we have plotted in Figure 11 the theoretical distributions for three groups, each composed of two mono-dispersed subgroups with fall velocities $V_g/U=0.1\ (1\pm\epsilon);\ \epsilon=0,\ 0.1\ and\ 0.2.$ One clearly sees that while the maximum concentration and its location decrease with the nonuniformity of the particles, the small concentrations at very small and very large distances increase with increasing nonuniformity.

The measured relative dimensionless cross-wind concentrations of the particles on the wind-tunnel floor, $C^{y}(x^{*})$, which are equivalent to the deposition longitudinal probability $P(x^{*})$ are presented in Figures 12-22 together with the theoretical predictions of the model, assuming that all the particles in each group have the same fall velocity and that the value of σ is given by Eq. (40).

Figure 12 presents the measurements from Runs 1, 2, 3, and 5, which had the same estimated mean relative fall velocity $V_g/U = 0.10$. It is noted that Runs 1, 2, and 3, in which the same particles were used, gave almost identical longitudinal concentration distributions. The location

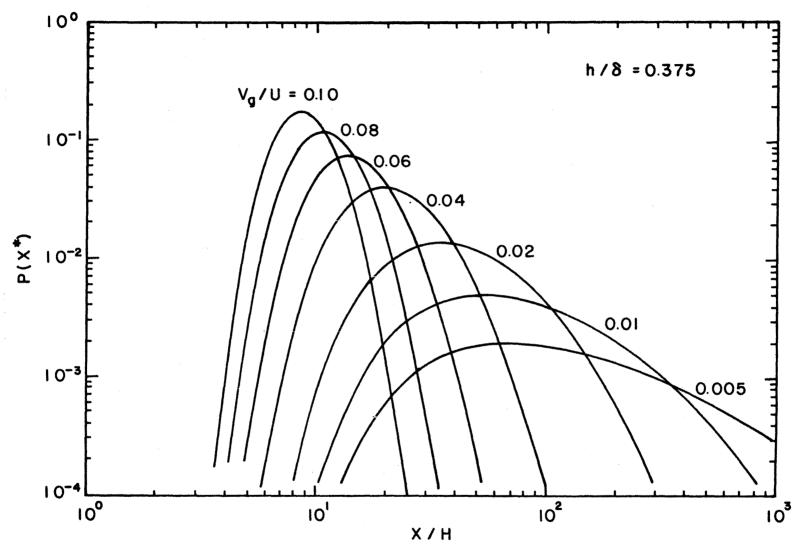


Figure 9. The effect of V_g/U on the longitudinal deposition of particles (Eq. (53)).

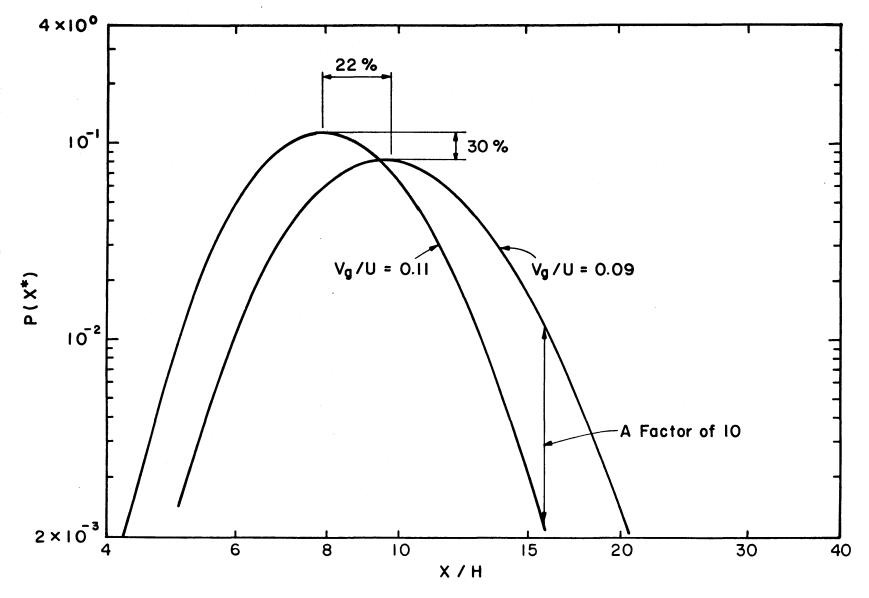


Figure 10. The effect of small changes in V_g/U on $P(x^*)$.

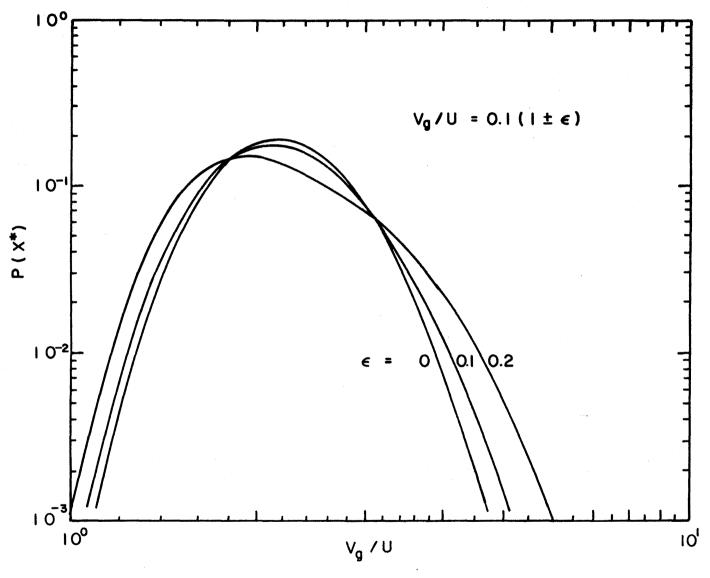
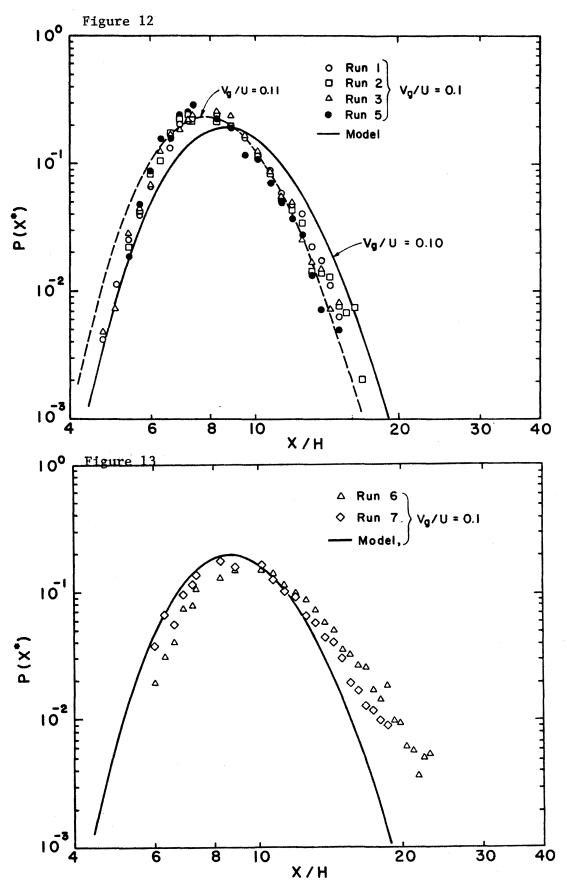
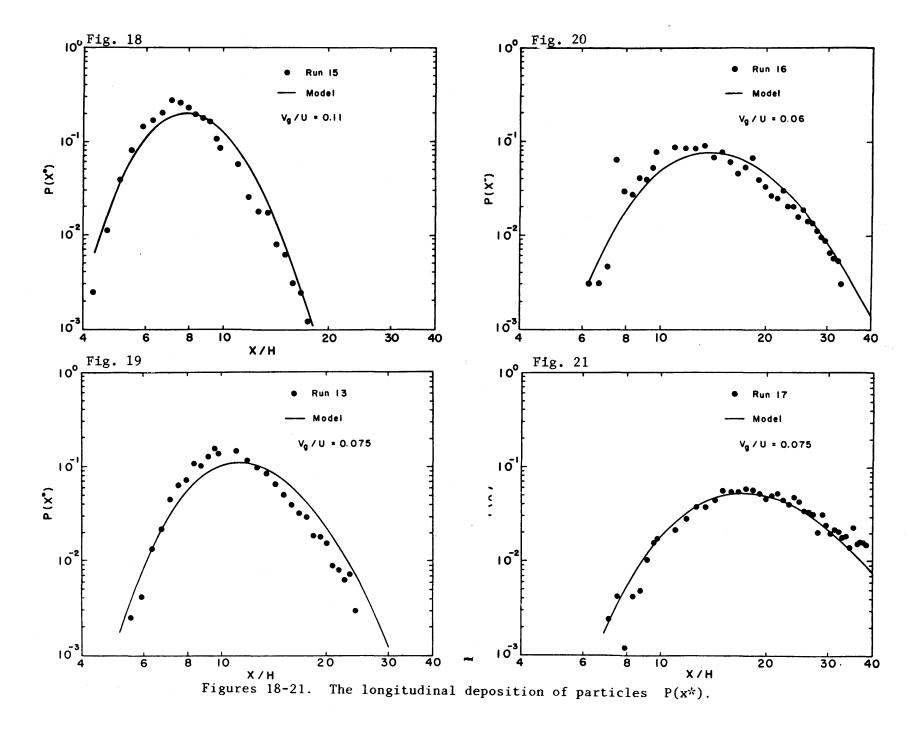


Figure 11. The combined distributions of two equal mono-dispersed groups of particles with fall velocities $V_g/U=0.1(1\pm\epsilon)$.



Figures 12-13. The longitudinal deposition of the particles $(V_g/V=0.1,\ h/\delta=0.5).$

Figures 14-17. The longitudinal deposition of particles $P(x^*)$.



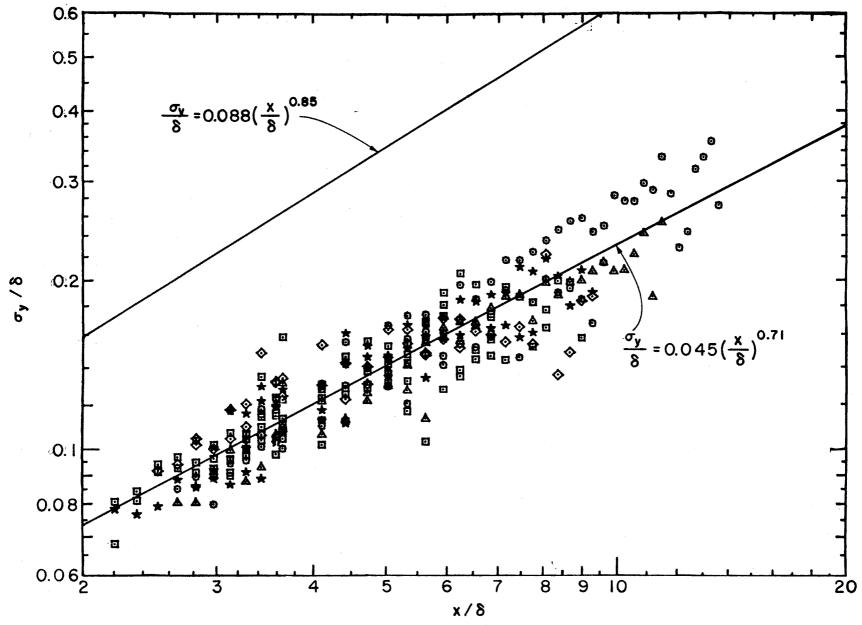


Figure 22. The lateral dispersion of particles (Runs 1-17).

of the maximum concentration in Run 5 was only slightly closer to the source.

The theoretical model appears to describe very well the general features of the longitudinal distribution of the particles. One notes, however, that the model predicts a maximum deposition at slightly larger distances than in the measurements.

If one uses, however, in the theoretical model a slightly higher velocity ratio, $V_{\rm c}/U = 0.11$, for example, instead of 0.10, the agreement between the model and the data is highly improved, as shown in the figure.

One can attribute the differences between the measurements and the model to several causes:

- (1) The approximate nature of the model. We have a priority estimated that the model will overpredict the distances at which the particles would deposit and pointed out that the model is not exactly mass consistent.
- (2) An incorrect estimate of σ_{2} .
- (3) Errors in the determination of U, V_g and h.
- (4) A combination of the above factors.

Figure 13 shows the deposition distributions measured in Runs 6 and 7. The estimated mean relative fall velocity for these groups of particles was the same; $V_g/U=0.1$. The value of V_g and therefore the Froude number V_g^2/gh was, however, larger than in the previous runs (Fr = 0.018 in Run 5, 0.024 in Runs 1, 2, and 3, 0.076 in Run 7 and 0.087 in Run 6). The two figures show a systematic change in the concentration profiles with the fall velocity or Froude number. In particular one observes a higher concentration value in Runs 6 and 7 at large values of x*.

Some of the differences between the runs may be attributed to the factors mentioned earlier. It is quite possible that the average value of V_g/U in Runs 6 and 7 was closer to 0.9. There are, however, two additional factors which could have affected the diffusion of the particles having larger absolute values of V_g (Runs 6 and 7):

- (1) The effect of the Froude number V_g^2/gh
- (2) A possible effect of the larger nonuniformity of fall velocities in these groups (see section 4.2).

An increased Froude number is expected to decrease the fluctuations of the particles and thus to decrease σ . Such an effect should reduce the area on which the particles deposit and increase $P(x^*)$. Since we have observed in the experiments the opposite effect, we cannot attribute the change in the deposition pattern to the increased value of

the Froude number. On the other hand, we have noted earlier that these groups had a much wider distribution of fall velocities, and as shown in Figure 11 a wider distribution could produce a similar effect to the one observed in Figure 13.

Figures 14-21 compare the measurements of the longitudinal distribution with prediction of the model for the rest of the runs. The Froude numbers for these runs were relatively small except for Run 14 (see Table 1). Indeed, one sees in Figure 17 that Run 14 produces slightly larger values of $P(X^*)$ at larger distances as observed earlier in Run 7.

Although the measurements at many locations deviate from those predicted by the model, the agreement between the experimental data and the model can be considered to be satisfactory, taking into consideration the limitations of the model.

5.3 The Measured Lateral Diffusion

Assuming that the lateral distribution of particles at a given distance x is approximately normal, we have calculated the value of $\sigma_{\mathbf{v}}(\mathbf{x})$ at different values of x for the different runs. As noted earlier (see Figure 4), the number of particles at small and large distances from the source was not sufficient for obtaining a good estimate of $\sigma_{\mathbf{v}}$ from the standard deviation of the sample and we have thus omitted from the graph 70 data points (out of 385) at large and small distances from the source.

According to the assumption that $\sigma_y(x)$ for small particles is equal to σ_y for a passive tracer, and our further assumption that for a passive tracer in a neutrally stable flows $\sigma_y = f(\delta,x)$ and independent of h, as described in Eq. (39); or, $\sigma_y'/\delta = e(x/\delta)^d$, we have plotted in Figure 22 the variation of σ/δ versus x/δ . (Note that δ was 1.0 m in all the experiments.) Although the experimental scatter in the figure is relatively large, it appears that the general trend of the data can be described by such a power law. However, as seen from the graph, the measured lateral diffusion of the particles is much smaller than the estimated value for passive tracers (e = 0.088 and d = 0.85, which were calculated using Briggs' data (1973). Using a least-squares estimator, we have found that the particle data gives e = 0.045 and d = 0.71. When the 72 data points at large x/δ were included in the analysis, the values of d decreased slightly to 0.68 whereas the value of e did not change.

This very large difference between our estimate for passive tracers and the particles diffusion may be attributed to the following causes:

(1) The lateral dispersion in wind tunnels with finite widths, $b/\delta=2$ in our case, can be much smaller than in atmospheric flows, as the wind tunnel simulates the mechanical turbulence and not the meandering of the mean velocity. This is particularly true for relatively smooth boundaries. Thus it is possible that our

estimate of σ_y for passive tracer is not applicable to this windtunnel simulation.

- (2) As shown earlier, the response time of the falling particles to horizontal velocity fluctuations could be larger than their response to vertical velocity fluctuations. The Reynolds number of the falling particles was between 20 and 40. Thus, it is quite possible that although the vertical dispersion of the particle-plume is equal to that of a passive plume, the Froude number in the experiments was not sufficiently small to ensure the same equality between the lateral dispersion of passive tracers and the particles.
- (3) Inspite of the relatively small fall velocity, the particles experienced a decreased diffusivity due to eddy crossing.

Lack of direct measurements of both σ_y and σ_z in the wind tunnel for passive plumes at the same flow configuration (roughness and Reynolds numbers), and lack of experiments at smaller Froude numbers, make it impossible to decide whether the good agreement between the longitudinal deposition in the theoretical model and in the experimental results is not partially due to the particular choice of σ_z and whether the failure of the model to describe the lateral diffusion is due to the generally reduced lateral diffusion in wind-tunnels or whether it is due to the decreases lateral diffusivity of the particles.

5.4 Conclusions and Recommendations

The deposition of particles with appreciable fall velocities emitted from elevated sources in a neutrally stable boundary layer was measured experimentally. The longitudinal distributions of the dimensionless cross-wind integrated concentration of the particles on the ground were described by a simple model, which assumes that the vertical spread of the particle plumes with small Froude numbers is equal to that of passive plumes except that the particles settle at a mean velocity V_g. The lateral spread rates of the particle plumes, however, were found to be smaller than those predicted of passive plumes.

It should be stressed, however, that the estimated values of σ_Z and σ_Z for passive plumes were estimated from field data and were not measured directly in the wind tunnel. Thus, it is recommended that similar experiments be carried out for a wider range of Froude numbers and relative fall velocities and that simultaneous measurements of σ_Z and σ_Z for passive tracers be carried at the same wind-tunnel configuration.

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